

Probability cheatsheet

Introduction to Probability and Combinatorics

Sample space — The set of all possible outcomes of an experiment is known as the sample space of the experiment and is denoted by S .

Event — Any subset E of the sample space is known as an event. That is, an event is a set consisting of possible outcomes of the experiment. If the outcome of the experiment is contained in E , then we say that E has occurred.

Axioms of probability For each event E , we denote $P(E)$ as the probability of event E occurring.

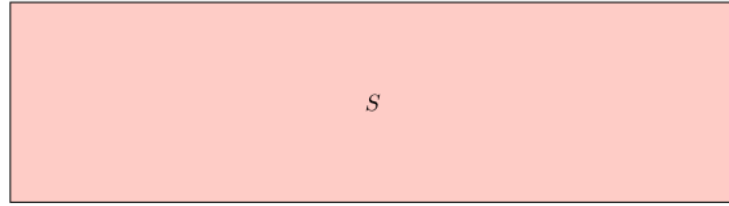
Axiom 1 — Every probability is between 0 and 1 included, i.e:

$$0 \leq P(E) \leq 1$$



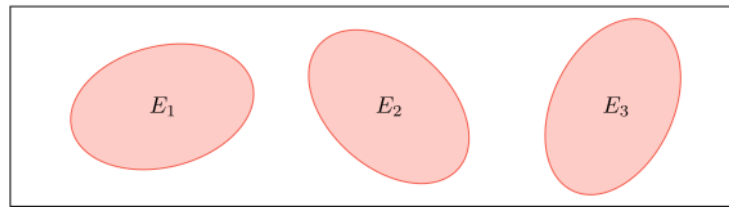
Axiom 2 — The probability that at least one of the elementary events in the entire sample space will occur is 1, i.e:

$$P(S) = 1$$



Axiom 3 — For any sequence of mutually exclusive events E_1, \dots, E_n , we have:

$$P\left(\bigcup_{i=1}^n E_i\right) = \sum_{i=1}^n P(E_i)$$



Permutation — A permutation is an arrangement of r objects from a pool of n objects, in a given order. The number of such arrangements is given by $P(n, r)$, defined as:

$$P(n, r) = \frac{n!}{(n - r)!}$$

Combination — A combination is an arrangement of r objects from a pool of n objects, where the order does not matter. The number of such arrangements is given by $C(n, r)$, defined as:

$$C(n, r) = \frac{P(n, r)}{r!} = \frac{n!}{r!(n - r)!}$$

Remark: we note that for $0 \leq r \leq n$, we have $P(n, r) \geq C(n, r)$.

Conditional Probability

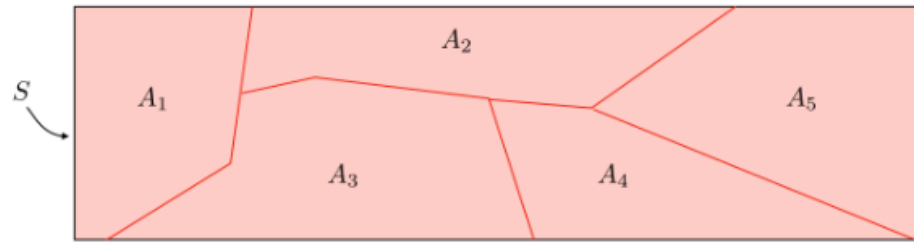
Bayes' rule — For events A and B such that $P(B) > 0$, we have:

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Remark: we have $P(A \cap B) = P(A)P(B|A) = P(A|B)P(B)$.

Partition — Let $\{A_i, i \in [1, n]\}$ be such that for all i , $A_i \neq \emptyset$. We say that $\{A_i\}$ is a partition if we have:

$$\forall i \neq j, A_i \cap A_j = \emptyset \quad \text{and} \quad \bigcup_{i=1}^n A_i = S$$



Remark: for any event B in the sample space, we have $P(B) = \sum_{i=1}^n P(B|A_i)P(A_i)$.

Extended form of Bayes' rule — Let $\{A_i, i \in [1, n]\}$ be a partition of the sample space. We have:

$$P(A_k|B) = \frac{P(B|A_k)P(A_k)}{\sum_{i=1}^n P(B|A_i)P(A_i)}$$

Independence — Two events A and B are independent if and only if we have:

$$P(A \cap B) = P(A)P(B)$$

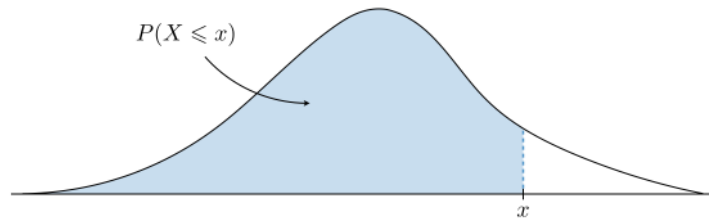
Random Variables

Definitions

Random variable — A random variable, often noted X , is a function that maps every element in a sample space to a real line.

Cumulative distribution function (CDF) — The cumulative distribution function F , which is monotonically non-decreasing and is such that $\lim_{x \rightarrow -\infty} F(x) = 0$ and $\lim_{x \rightarrow +\infty} F(x) = 1$, is defined as:

$$F(x) = P(X \leq x)$$



Remark: we have $P(a < X \leq B) = F(b) - F(a)$.

Probability density function (PDF) — The probability density function f is the probability that X takes on values between two adjacent realizations of the random variable.

Relationships involving the PDF and CDF

Discrete case — Here, X takes discrete values, such as outcomes of coin flips. By noting f and F the PDF and CDF respectively, we have the following relations:

$$F(x) = \sum_{x_i \leq x} P(X = x_i) \quad \text{and} \quad f(x_j) = P(X = x_j)$$

On top of that, the PDF is such that:

$$0 \leq f(x_j) \leq 1 \quad \text{and} \quad \sum_j f(x_j) = 1$$

Continuous case — Here, X takes continuous values, such as the temperature in the room. By noting f and F the PDF and CDF respectively, we have the following relations:

$$F(x) = \int_{-\infty}^x f(y) dy \quad \text{and} \quad f(x) = \frac{dF}{dx}$$

On top of that, the PDF is such that:

$$f(x) \geq 0 \quad \text{and} \quad \int_{-\infty}^{+\infty} f(x) dx = 1$$

Expectation and Moments of the Distribution

In the following sections, we are going to keep the same notations as before and the formulas will be explicitly detailed for the discrete **(D)** and continuous **(C)** cases.

Expected value — The expected value of a random variable, also known as the mean value or the first moment, is often noted $E[X]$ or μ and is the value that we would obtain by averaging the results of the experiment infinitely many times. It is computed as follows:

$$(D) \quad E[X] = \sum_{i=1}^n x_i f(x_i) \quad \text{and} \quad (C) \quad E[X] = \int_{-\infty}^{+\infty} x f(x) dx$$

Generalization of the expected value — The expected value of a function of a random variable $g(X)$ is computed as follows:

$$(D) \quad E[g(X)] = \sum_{i=1}^n g(x_i) f(x_i) \quad \text{and} \quad (C) \quad E[g(X)] = \int_{-\infty}^{+\infty} g(x) f(x) dx$$

k^{th} moment — The k^{th} moment, noted $E[X^k]$, is the value of X^k that we expect to observe on average on infinitely many trials. It is computed as follows:

$$(D) \quad E[X^k] = \sum_{i=1}^n x_i^k f(x_i) \quad \text{and} \quad (C) \quad E[X^k] = \int_{-\infty}^{+\infty} x^k f(x) dx$$

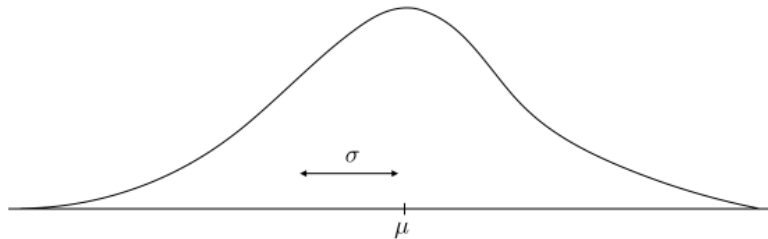
Remark: the k^{th} moment is a particular case of the previous definition with $g : X \mapsto X^k$.

Variance — The variance of a random variable, often noted $\text{Var}(X)$ or σ^2 , is a measure of the spread of its distribution function. It is determined as follows:

$$\text{Var}(X) = E[(X - E[X])^2] = E[X^2] - E[X]^2$$

Standard deviation — The standard deviation of a random variable, often noted σ , is a measure of the spread of its distribution function which is compatible with the units of the actual random variable. It is determined as follows:

$$\sigma = \sqrt{\text{Var}(X)}$$

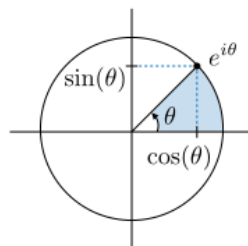


Characteristic function — A characteristic function $\psi(\omega)$ is derived from a probability density function $f(x)$ and is defined as:

$$(D) \quad \psi(\omega) = \sum_{i=1}^n f(x_i) e^{i\omega x_i} \quad \text{and} \quad (C) \quad \psi(\omega) = \int_{-\infty}^{+\infty} f(x) e^{i\omega x} dx$$

Euler's formula - For $\theta \in \mathbb{R}$, the Euler formula is the name given to the identity:

$$e^{i\theta} = \cos(\theta) + i \sin(\theta)$$



Revisiting the k^{th} moment — The k^{th} moment can also be computed with the characteristic function as follows:

$$E[X^k] = \frac{1}{i^k} \left[\frac{\partial^k \psi}{\partial \omega^k} \right]_{\omega=0}$$

Transformation of random variables — Let the variables X and Y be linked by some function. By noting f_X and f_Y the distribution function of X and Y respectively, we have:

$$f_Y(y) = f_X(x) \left| \frac{dx}{dy} \right|$$

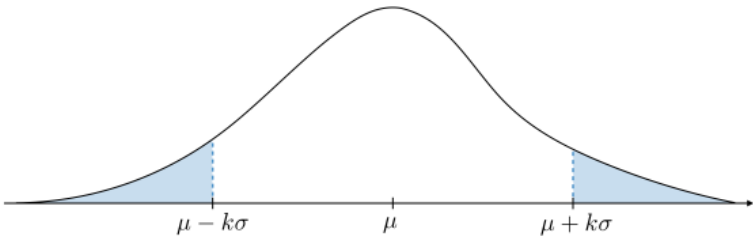
Leibniz integral rule — Let g be a function of x and potentially c , and a, b boundaries that may depend on c . We have:

$$\frac{\partial}{\partial c} \left(\int_a^b g(x) dx \right) = \frac{\partial b}{\partial c} \cdot g(b) - \frac{\partial a}{\partial c} \cdot g(a) + \int_a^b \frac{\partial g}{\partial c}(x) dx$$

Probability Distributions

Chebyshev's inequality — Let X be a random variable with expected value μ . For $k, \sigma > 0$, we have the following inequality:

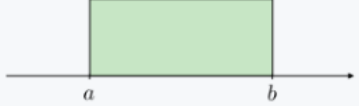
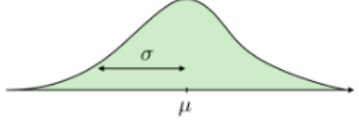

$$P(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$



Discrete distributions — Here are the main discrete distributions to have in mind:

Distribution	$P(X = x)$	$\psi(\omega)$	$E[X]$	$\text{Var}(X)$	Illustration
$X \sim \mathcal{B}(n, p)$	$\binom{n}{x} p^x q^{n-x}$	$(pe^{i\omega} + q)^n$	np	npq	
$X \sim \text{Po}(\mu)$	$\frac{\mu^x}{x!} e^{-\mu}$	$e^{\mu(e^{i\omega} - 1)}$	μ	μ	

Continuous distributions — Here are the main continuous distributions to have in mind:

Distribution	$f(x)$	$\psi(\omega)$	$E[X]$	$\text{Var}(X)$	Illustration
$X \sim \mathcal{U}(a, b)$	$\frac{1}{b-a}$	$\frac{e^{i\omega b} - e^{i\omega a}}{(b-a)i\omega}$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$	
$X \sim \mathcal{N}(\mu, \sigma)$	$\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$	$e^{i\omega\mu - \frac{1}{2}\omega^2\sigma^2}$	μ	σ^2	
$X \sim \text{Exp}(\lambda)$	$\lambda e^{-\lambda x}$	$\frac{1}{1 - \frac{i\omega}{\lambda}}$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$	

Jointly Distributed Random Variables

Joint probability density function — The joint probability density function of two random variables X and Y , that we note f_{XY} , is defined as follows:

$$(D) \quad \boxed{f_{XY}(x_i, y_j) = P(X = x_i \text{ and } Y = y_j)}$$

$$(C) \quad \boxed{f_{XY}(x, y) \Delta x \Delta y = P(x \leq X \leq x + \Delta x \text{ and } y \leq Y \leq y + \Delta y)}$$

Marginal density — We define the marginal density for the variable X as follows:

$$(D) \quad \boxed{f_X(x_i) = \sum_j f_{XY}(x_i, y_j)} \quad \text{and} \quad (C) \quad \boxed{f_X(x) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dy}$$

Cumulative distribution — We define cumulative distribution F_{XY} as follows:

$$(D) \quad \boxed{F_{XY}(x, y) = \sum_{x_i \leq x} \sum_{y_j \leq y} f_{XY}(x_i, y_j)} \quad \text{and} \quad (C) \quad \boxed{F_{XY}(x, y) = \int_{-\infty}^x \int_{-\infty}^y f_{XY}(x', y') dx' dy'}$$

Conditional density — The conditional density of X with respect to Y , often noted $f_{X|Y}$, is defined as follows:

$$\boxed{f_{X|Y}(x) = \frac{f_{XY}(x, y)}{f_Y(y)}}$$

Independence — Two random variables X and Y are said to be independent if we have:

$$\boxed{f_{XY}(x, y) = f_X(x) f_Y(y)}$$

Moments of joint distributions — We define the moments of joint distributions of random variables X and Y as follows:

$$(D) \quad \boxed{E[X^p Y^q] = \sum_i \sum_j x_i^p y_j^q f(x_i, y_j)} \quad \text{and} \quad (C) \quad \boxed{E[X^p Y^q] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} x^p y^q f(x, y) dy dx}$$

Distribution of a sum of independent random variables — Let $Y = X_1 + \dots + X_n$ with X_1, \dots, X_n independent. We have:

$$\boxed{\psi_Y(\omega) = \prod_{k=1}^n \psi_{X_k}(\omega)}$$

Covariance — We define the covariance of two random variables X and Y , that we note σ_{XY}^2 or more commonly $\text{Cov}(X, Y)$, as follows:

$$\boxed{\text{Cov}(X, Y) \triangleq \sigma_{XY}^2 = E[(X - \mu_X)(Y - \mu_Y)] = E[XY] - \mu_X \mu_Y}$$

Correlation — By noting σ_X, σ_Y the standard deviations of X and Y , we define the correlation between the random variables X and Y , noted ρ_{XY} , as follows:

$$\boxed{\rho_{XY} = \frac{\sigma_{XY}^2}{\sigma_X \sigma_Y}}$$

Remark 1: we note that for any random variables X, Y , we have $\rho_{XY} \in [-1, 1]$.

Remark 2: If X and Y are independent, then $\rho_{XY} = 0$.