# High Performance Scientific computing Lecture 4

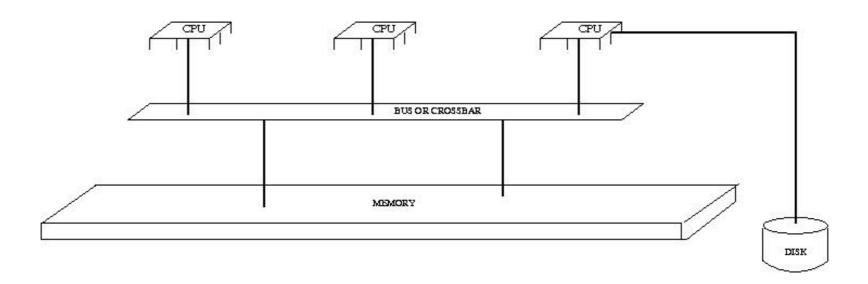
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### Introduction to Parallel Programming

## Shared-Memory Processing

Each processor can access the entire data space

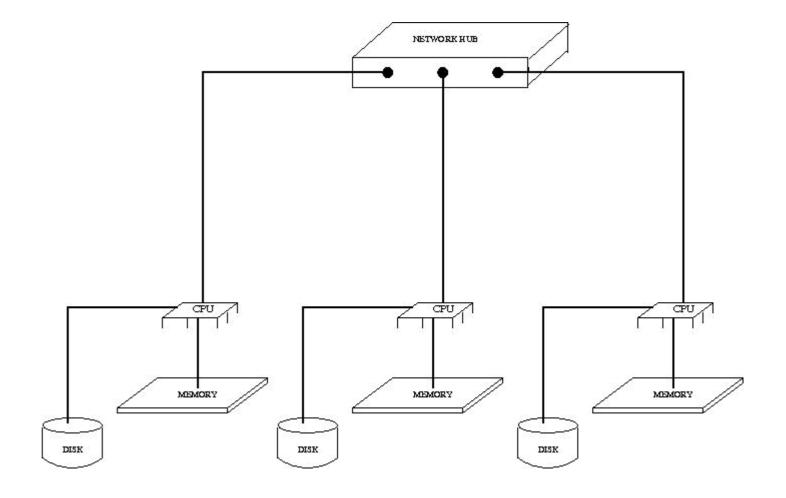
- Pro's
  - Easier to program
  - Amenable to automatic parallelism
  - Can be used to run large memory serial programs
- Con's
  - Expensive
  - Difficult to implement on the hardware level
  - Processor count limited by contention/coherency (currently around 512)
  - Watch out for "NU" part of "NUMA"



## Distributed – Memory Machines

- Each node in the computer has a locally addressable memory space
- The computers are connected together via some high-speed network
  - Infiniband, Myrinet, Giganet, etc..

- Pros
  - Really large machines
  - Size limited only by gross physical considerations:
    - Room size
    - Cable lengths (10's of meters)
    - Power/cooling capacity
    - Money!
  - Cheaper to build and run
- Cons
  - Harder to programData Locality



#### MPPs (Massively Parallel Processors)

Distributed memory at largest scale. Often shared memory at lower hierarchies.

- IBM BlueGene/L (LLNL)
  - 131,072 700 Mhz processors
  - 256 MB or RAM per processor
  - Balanced compute speed with interconnect





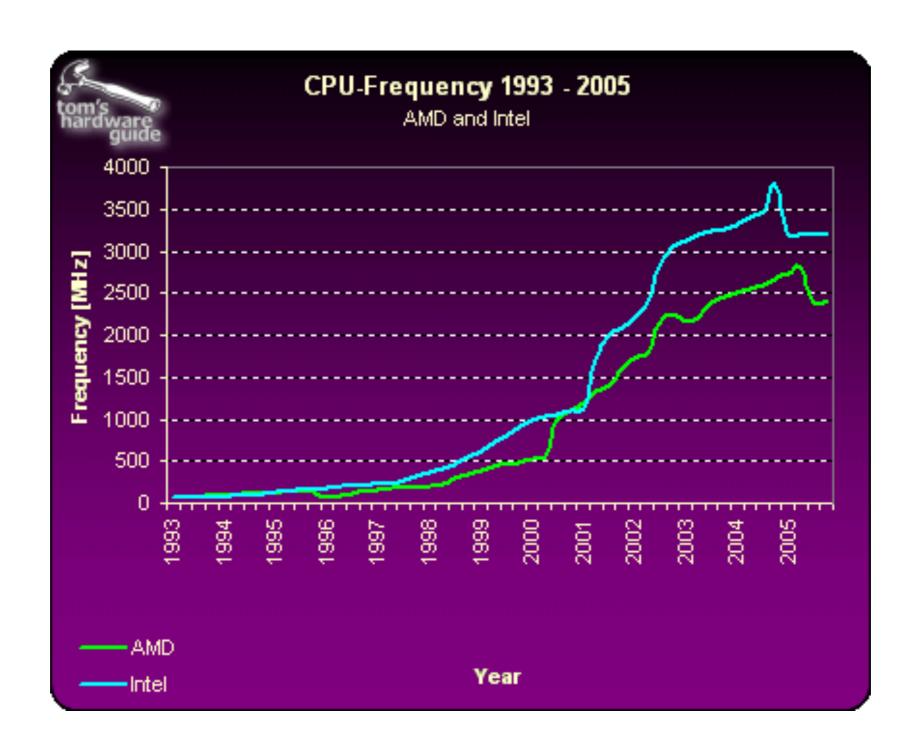
- Red Storm (Sandia National Labs)
  - 12,960 Dual Core 2.4 Ghz Opterons
  - 4 GB of RAM per processor
  - Proprietary SeaStar interconnect

# GPGPU Computing (General Purpose Graphics Processing unit)

# **GPU Evolution**

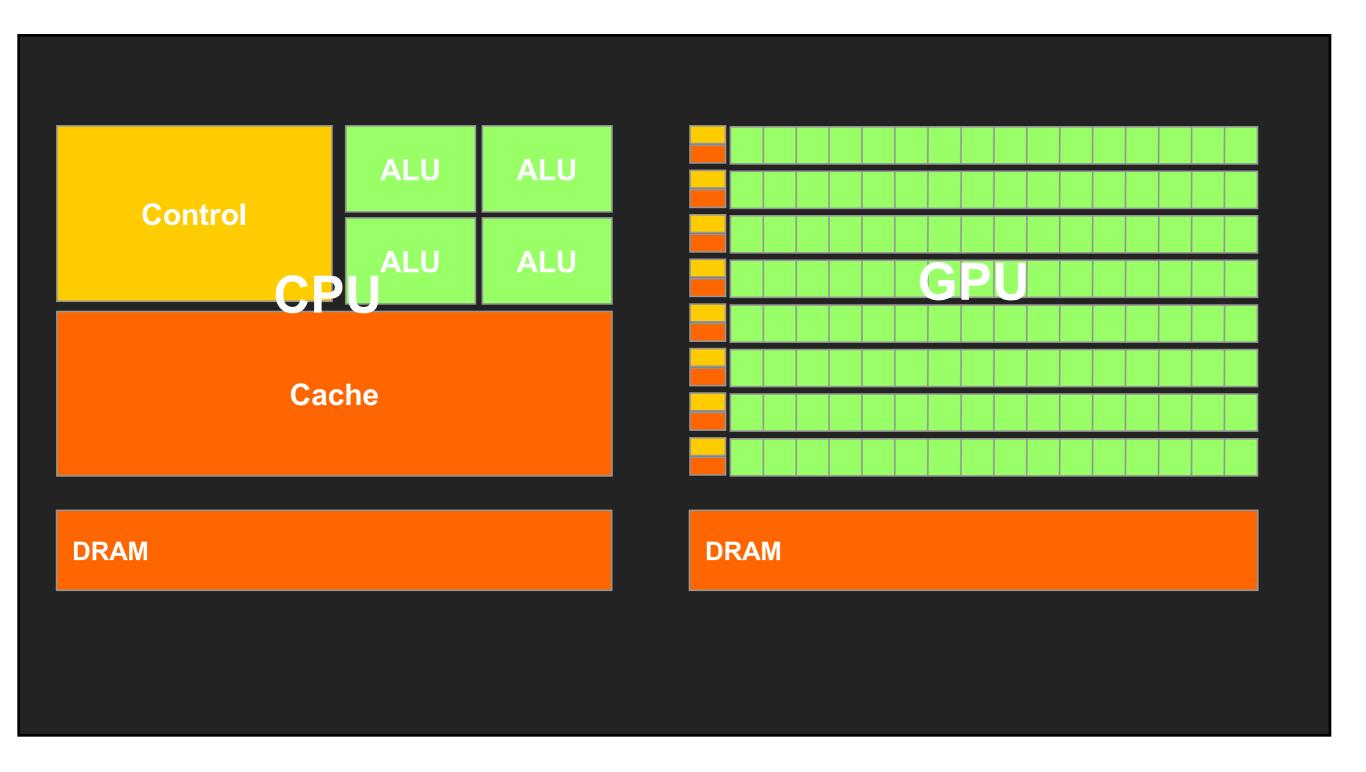
- The Graphic Processing Unit (GPU) is a processor that was specialized for processing graphics.
- The GPU has recently evolved towards a more flexible architecture.
- Opportunity: We can implement \*any algorithm\*, not only graphics.
- Works on SIMD (Single Instruction Multiple Data) approach.
- Challenge: obtain efficiency and high

#### Peak CPU Performances have reached a bottleneck



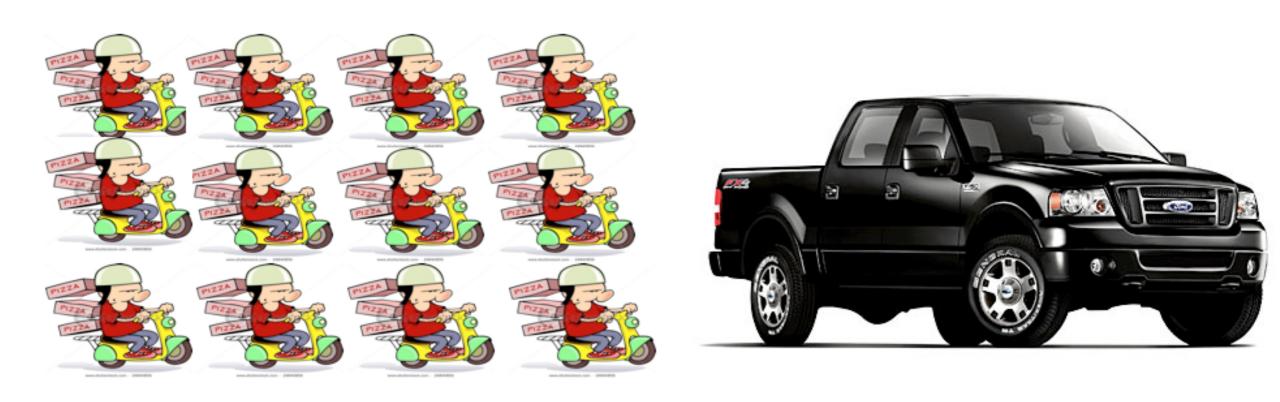
Source: www. tomshardware.com

#### Comparison of CPU vs GPU Architecture



Source: Prof. Wen-mei W. Hwu UIUC

#### GPU CPU Analogy



GPU CPU

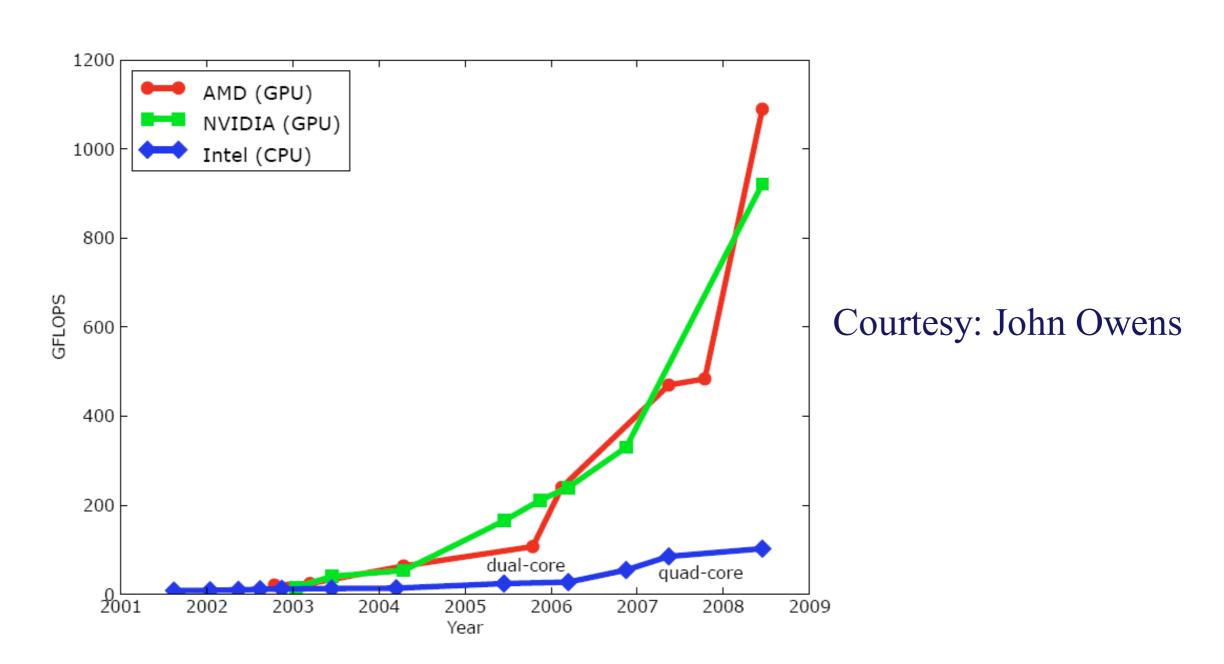
It is more effective to deliver Pizza's through light duty scooters rather than big truck. Similarly effective to use several lightweight GPU processors for parallel tasks.

#### **GPU Performance**

Peak performance increase

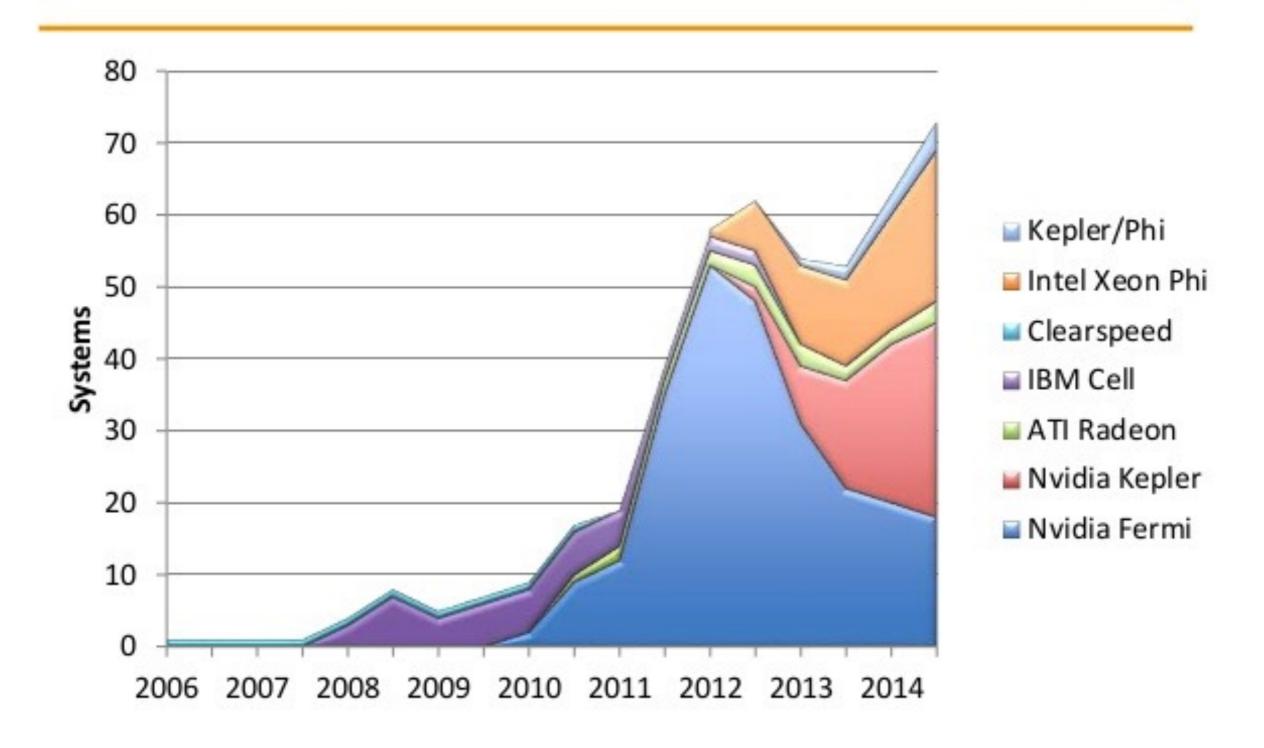
Calculation ~ I TFlop on Desktop

Memory Bandwidth ~ I50 GB/s



#### **ACCELERATORS**

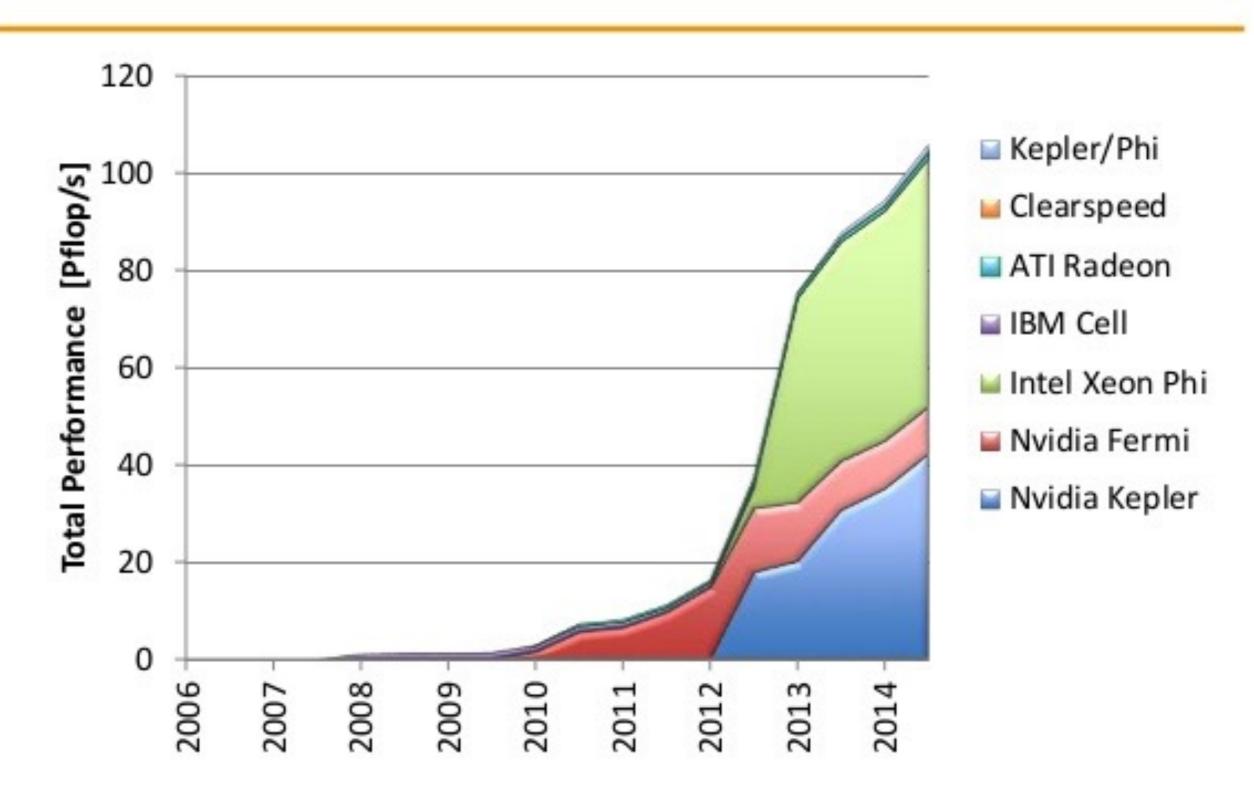




source: top500.org

#### PERFORMANCE OF ACCELERATORS





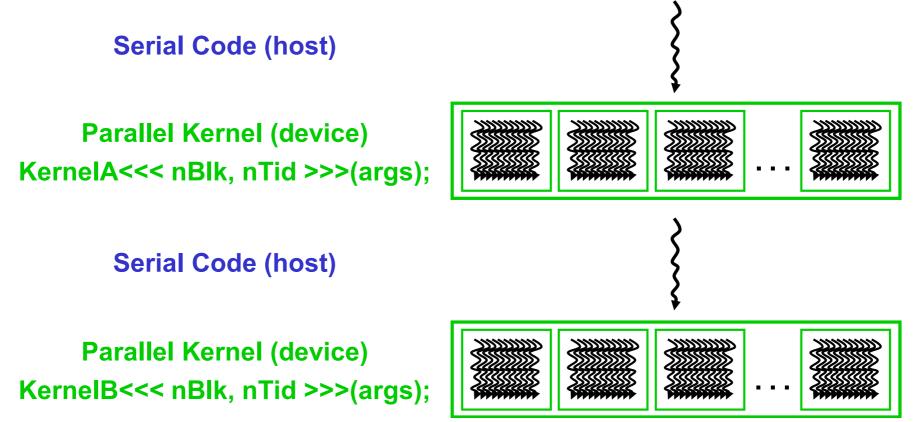
source: top500.org

# Compute Unified Device Architecture (CUDA)

- CUDA set of APIs (application program interface) to use GPU's for general purpose computing
- Developed and released by NVIDIA Inc. Works only on NVIDIA GPU hardware
- Works on commercial GPU's and as well as specialized ones for scientific computing (Tesla)
- CUDA compiler supports C programming language. Extensions to FORTRAN are possible.
- Opensource alternative is OpenCL.

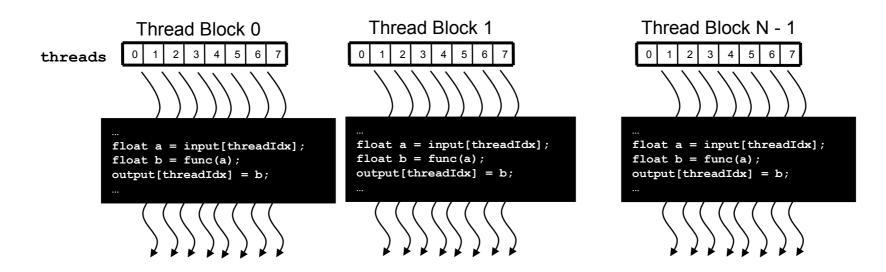
### CUDA/ OpenCL Execution Model

- Combination of Host (CPU) and Device(GPU) code
- Parallel portions of the code are expressed as device kernels and they run on many threads



#### GPU threads vs CPU threads

- GPU threads are very lightweight and hence have less overheads
- For efficiency hundreds of GPU threads are required. Few in case of CPU
- We can subdivide threads into multiple blocks for shared memory cooperation.



# NVIDIA Tesla Specifications

| Features   | Tesla K20X  | Tesla K20   | Tesla K10   | Tesla M2090   | Tesla M2075    |
|--|---|-------------|---|---|----------------|
| Number and Type of<br>GPU                              | 1 Kepler GK110  |             | 2 Kepler GK104s   | 1 Fermi GPU   | 1 Fermi GPU    |
| GPU Computing<br>Applications                          | Seismic processing, CFD, CAE, Financial computing, Computational chemistry and Physics, Data analytics, Satellite imaging, Weather modeling |             | Seismic processing,<br>signal and image<br>processing, video<br>analytics | Seismic processing, CFD, CAE, Financial computing, Computational chemistry and Physics, Data analytics, Satellite imaging, Weather modeling |                |
| Peak double<br>precision floating<br>point performance | 1.31 Tflops   | 1.17 Tflops | 190 Gigaflops<br>(95 Gflops per GPU)                                      | 665 Gigaflops   | 515 Gigaflops  |
| Peak single<br>precision floating<br>point performance | 3.95 Tflops   | 3.52 Tflops | 4577 Gigaflops<br>(2288 Gflops per<br>GPU)                                | 1331 Gigaflops  | 1030 Gigaflops |
| Memory bandwidth (ECC off)                             | 250 GB/sec  | 208 GB/sec  | 320 GB/sec<br>(160 GB/sec per GPU)  | 177 GB/sec  | 150 GB/sec     |
| Memory size<br>(GDDR5)                                 | 6 GB  | 5 GB        | 8GB<br>(4 GB per GPU)   | 6 GigaBytes   | 6 GigaBytes    |
| CUDA cores   | 2688  | 2496        | 3072<br>(1536 per GPU)  | 512   | 448            |

Source: NVIDIA Inc.

## Hybrid Programming!

- Need to use distributed memory design to reach large scales.
- Leverage commodity processor shared memory at the board level.
- It is an efficient way to get a pile of flops.
- But, a little more "interesting" from programming perspective