



<http://algs4.cs.princeton.edu>

## 2.2 MERGESORT

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- ▶ *mergesort*
- ▶ *bottom-up mergesort*
- ▶ *sorting complexity*
- ▶ *divide-and-conquer*

# Two classic sorting algorithms: mergesort and quicksort

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Critical components in the world's computational infrastructure.

- Full scientific understanding of their properties has enabled us to develop them into practical system sorts.
- Quicksort honored as one of top 10 algorithms of 20<sup>th</sup> century in science and engineering.

Mergesort. [today]



Quicksort. [next lecture]





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## 2.2 MERGESORT

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- ▶ *mergesort*
- ▶ *bottom-up mergesort*
- ▶ *sorting complexity*
- ▶ *divide-and-conquer*

# Mergesort

## Basic plan.

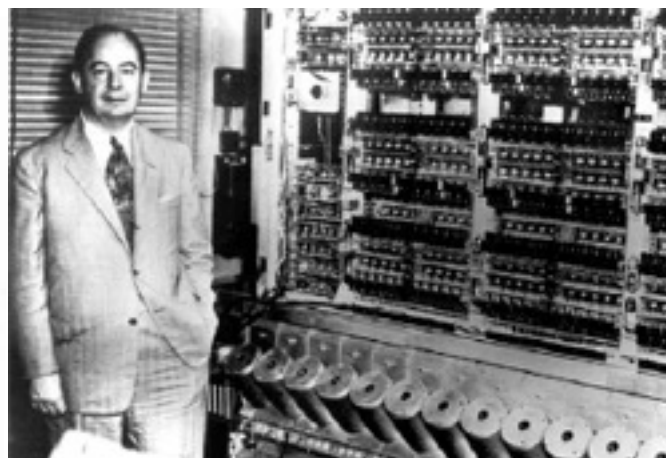
- Divide array into two halves.
- **Recursively** sort each half.
- Merge two halves.

input	M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
sort left half	E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E
sort right half	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
merge results	A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Mergesort overview

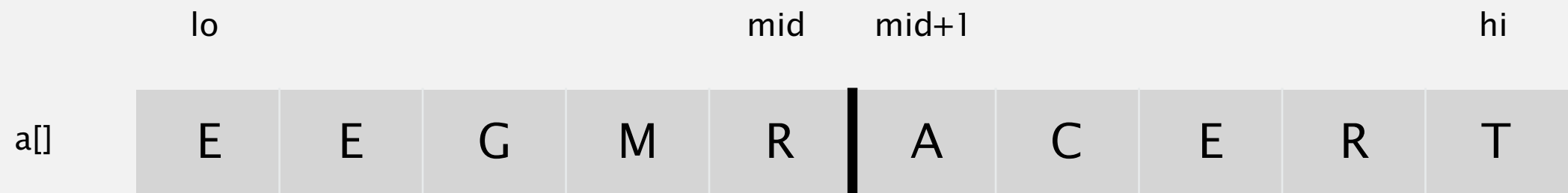
First Draft  
of a  
Report on the  
EDVAC

John von Neumann

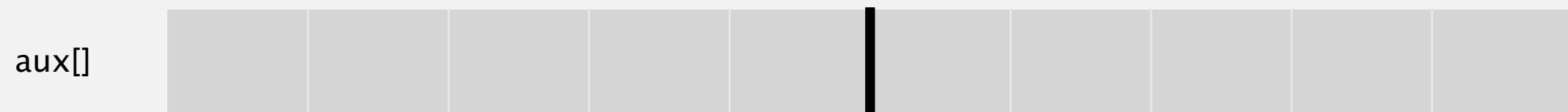


# Merging demo

**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .



## copy to auxiliary array



# Merging demo

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**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .

a[]

E	E	G	M	R	A	C	E	R	T
---	---	---	---	---	---	---	---	---	---

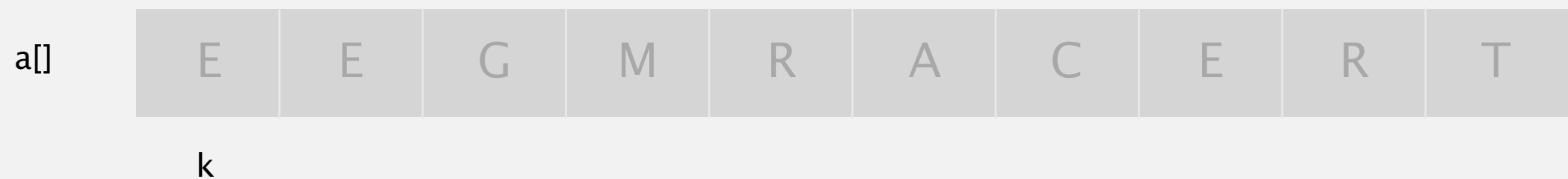
aux[]

E	E	G	M	R		A	C	E	R	T
---	---	---	---	---	--	---	---	---	---	---

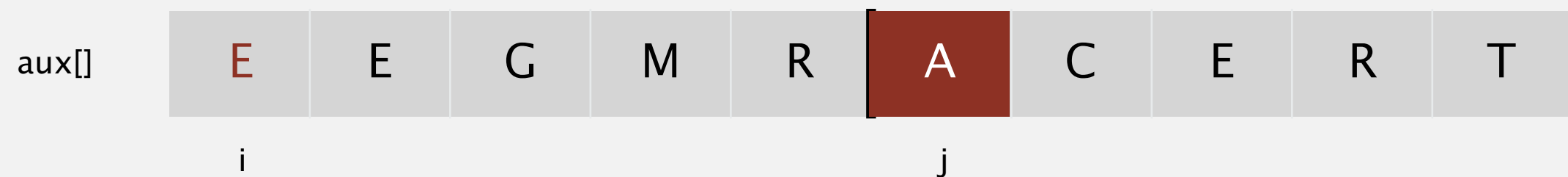
# Merging demo

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**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .



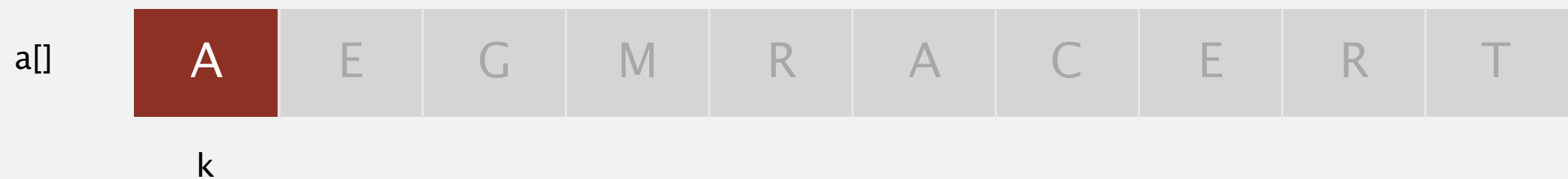
**compare minimum in each subarray**



# Merging demo

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**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .



**compare minimum in each subarray**

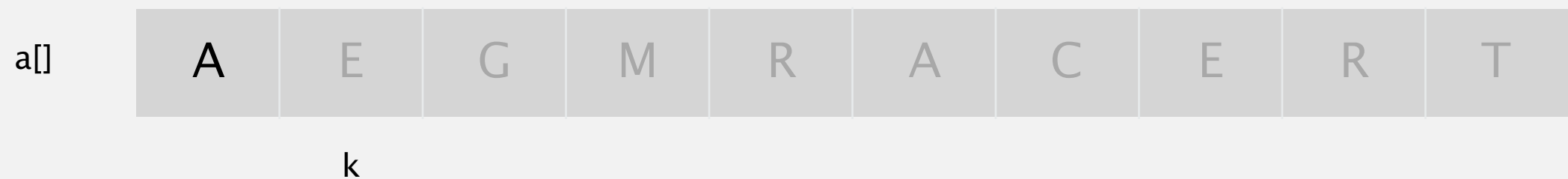




# Merging demo

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**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .



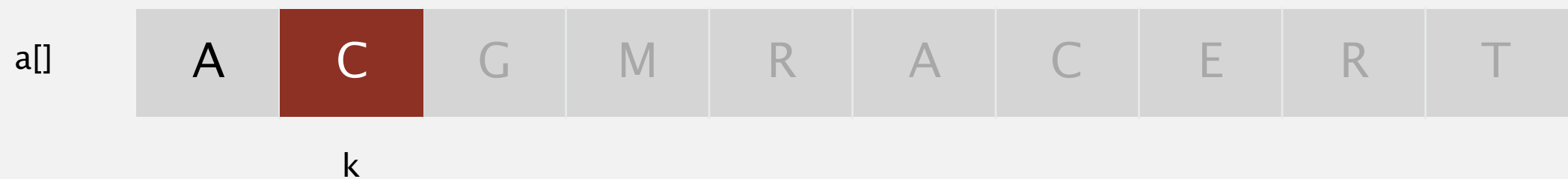
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# Merging demo

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**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .

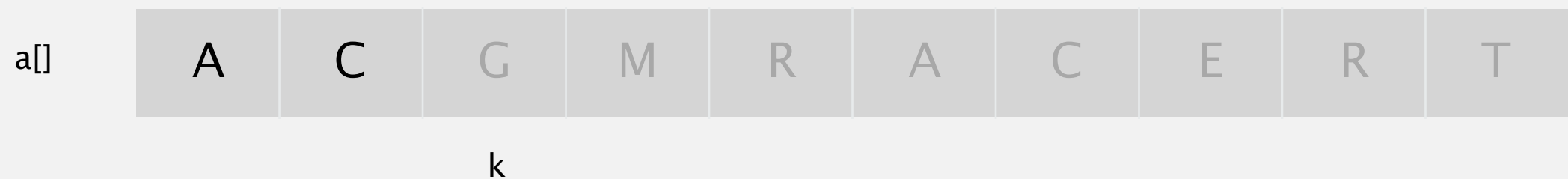


compare minimum in each subarray



# Merging demo

**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .



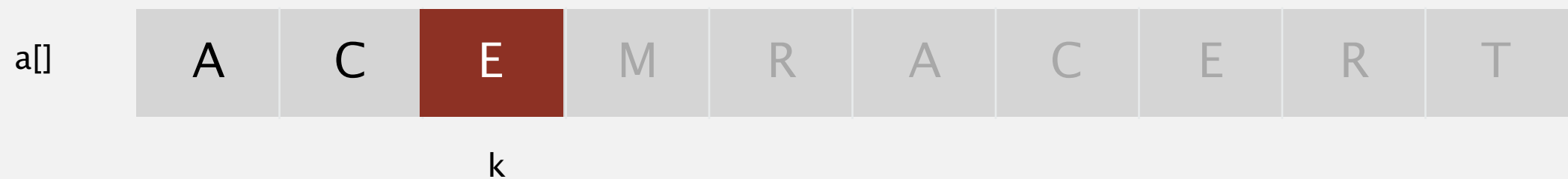
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# Merging demo

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**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .



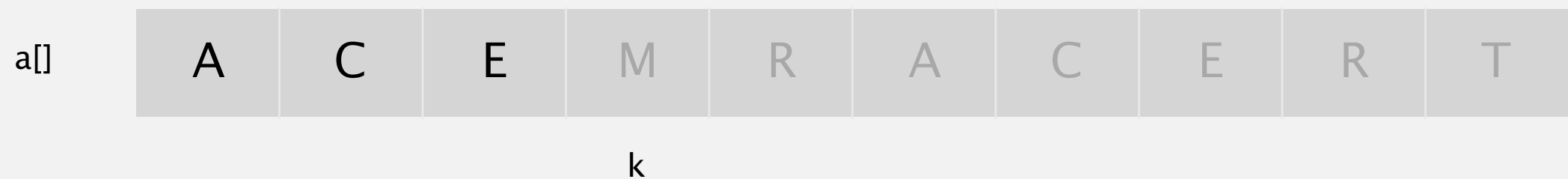
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# Merging demo

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**Goal.** Given two sorted subarrays  $a[\text{lo}]$  to  $a[\text{mid}]$  and  $a[\text{mid}+1]$  to  $a[\text{hi}]$ , replace with sorted subarray  $a[\text{lo}]$  to  $a[\text{hi}]$ .



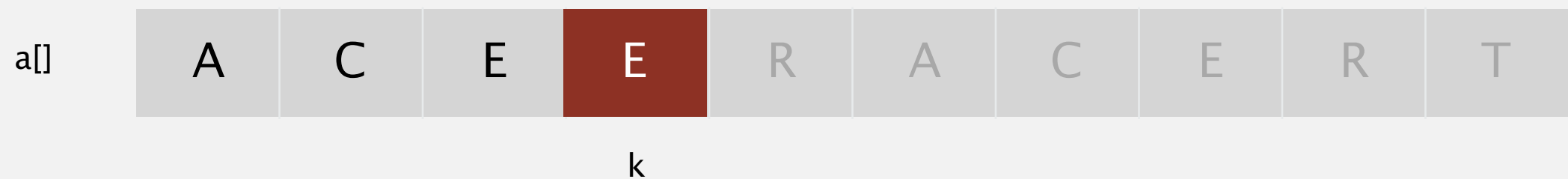
**compare minimum in each subarray**



# Merging demo

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**Goal.** Given two sorted subarrays  $a[lo]$  to  $a[mid]$  and  $a[mid+1]$  to  $a[hi]$ , replace with sorted subarray  $a[lo]$  to  $a[hi]$ .



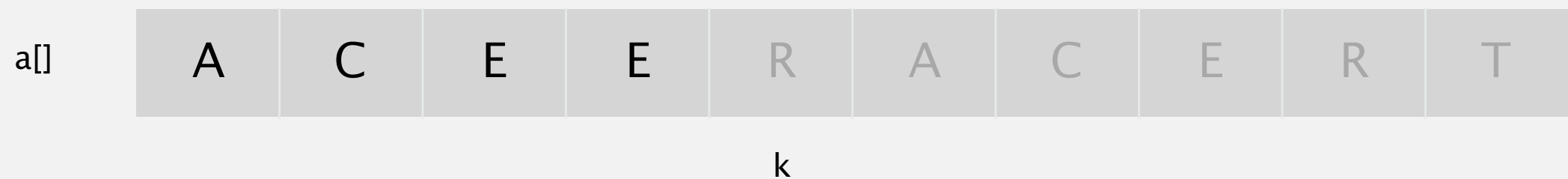
compare minimum in each subarray



# Merging demo

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**Goal.** Given two sorted subarrays  $a[lo]$  to  $a[mid]$  and  $a[mid+1]$  to  $a[hi]$ , replace with sorted subarray  $a[lo]$  to  $a[hi]$ .



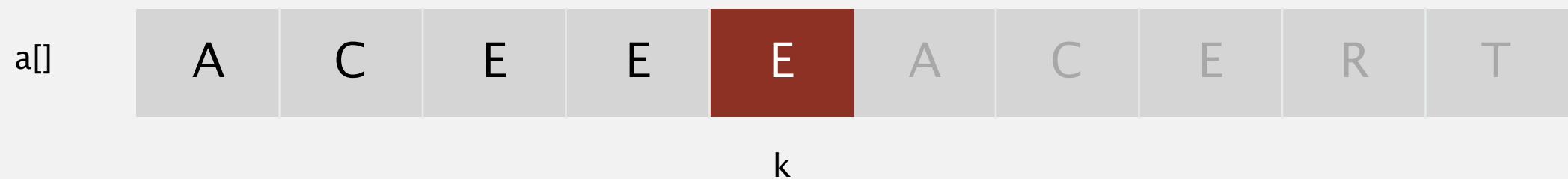
compare minimum in each subarray



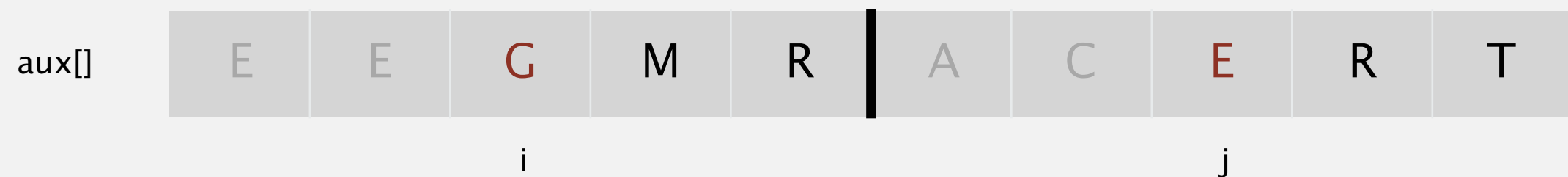
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compare minimum in each subarray

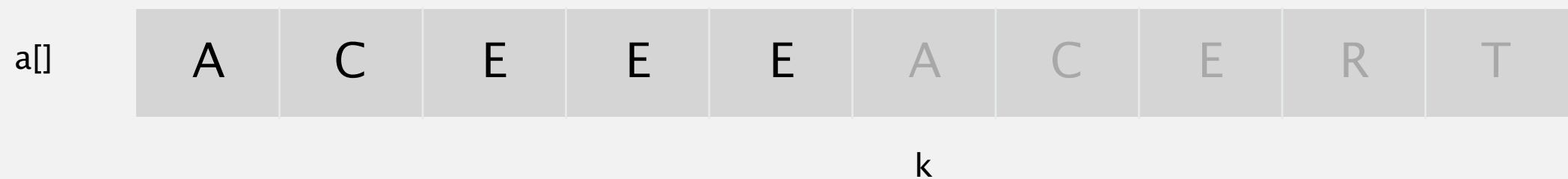




# Merging demo

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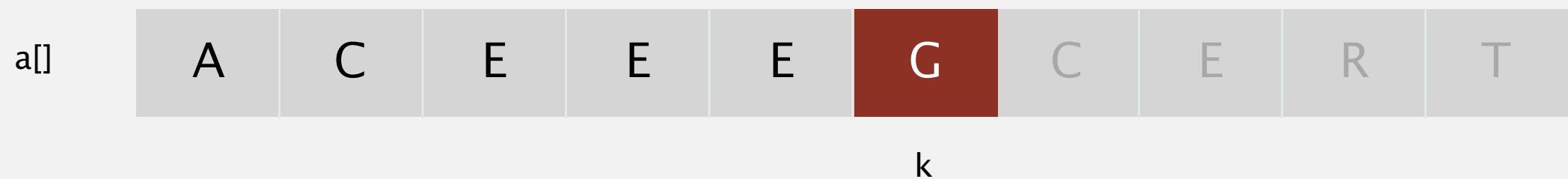
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# Merging demo

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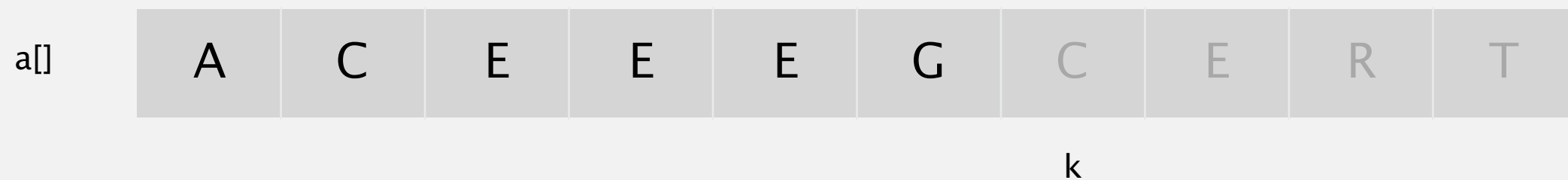
compare minimum in each subarray



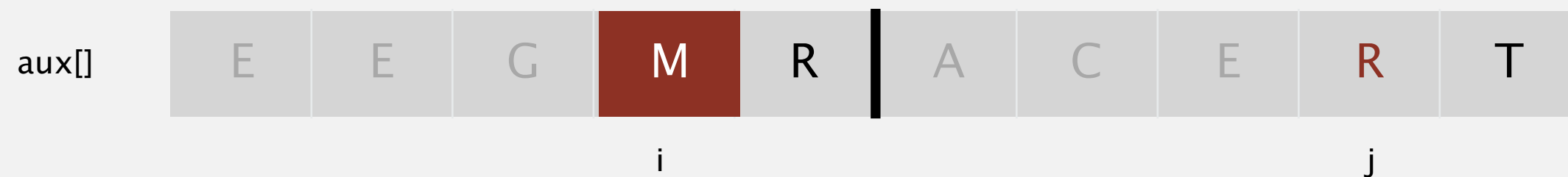
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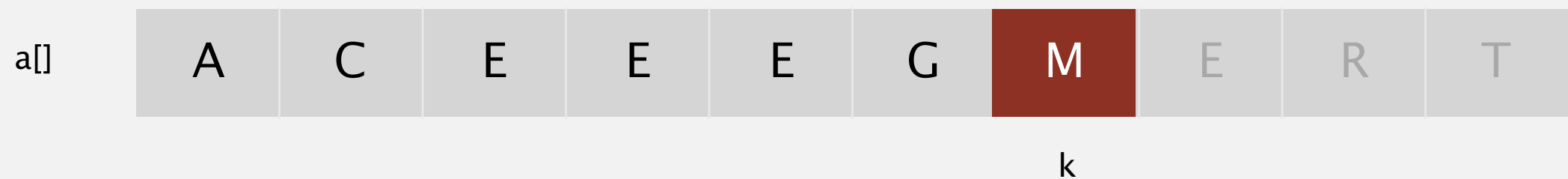
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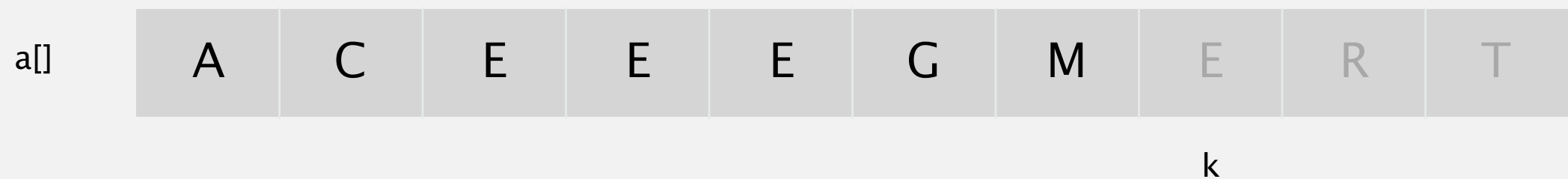
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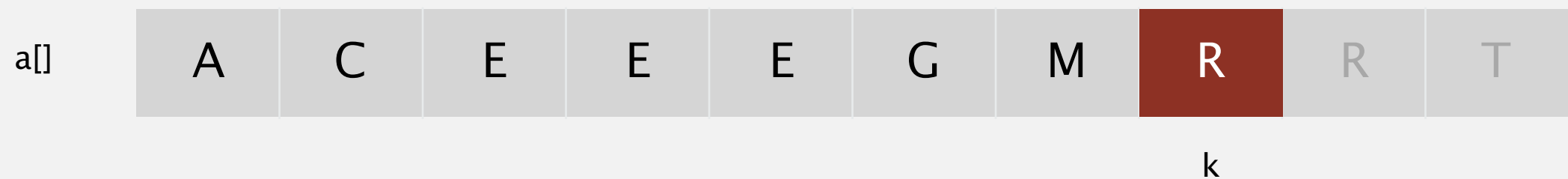
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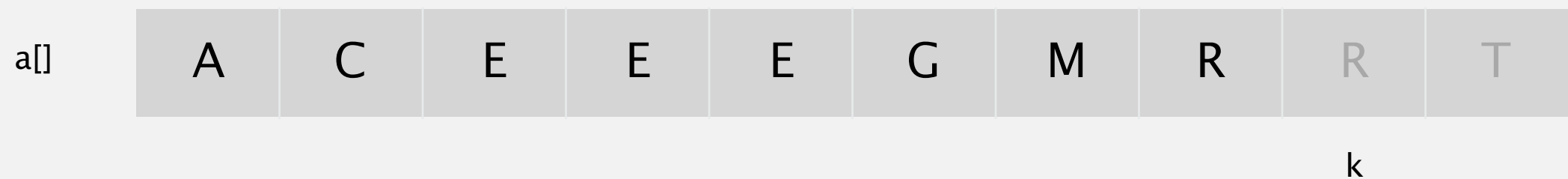
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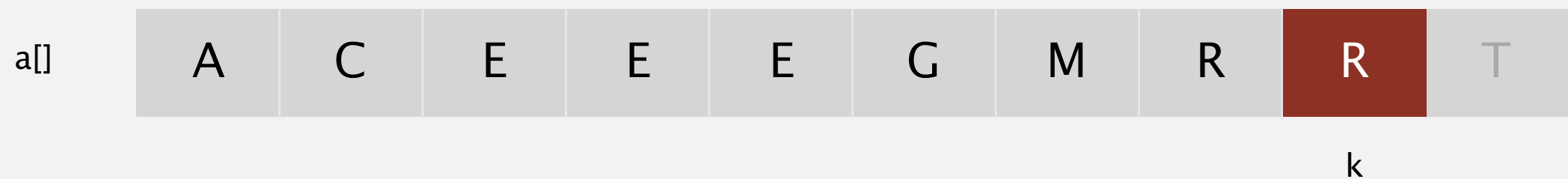
one subarray exhausted, take from other



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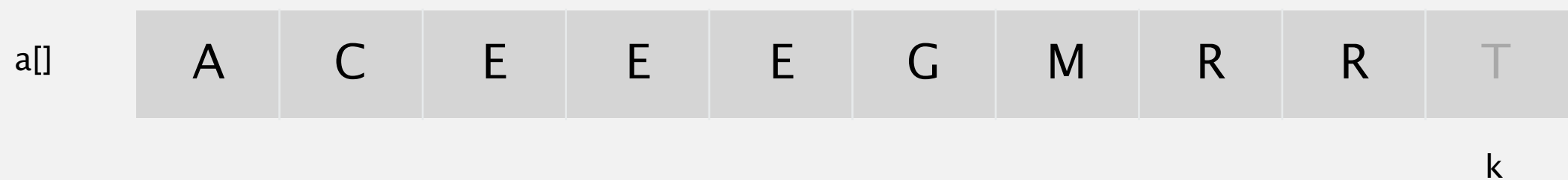




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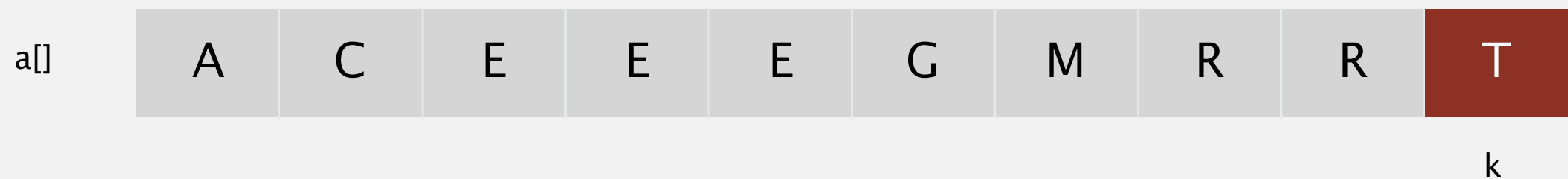
one subarray exhausted, take from other



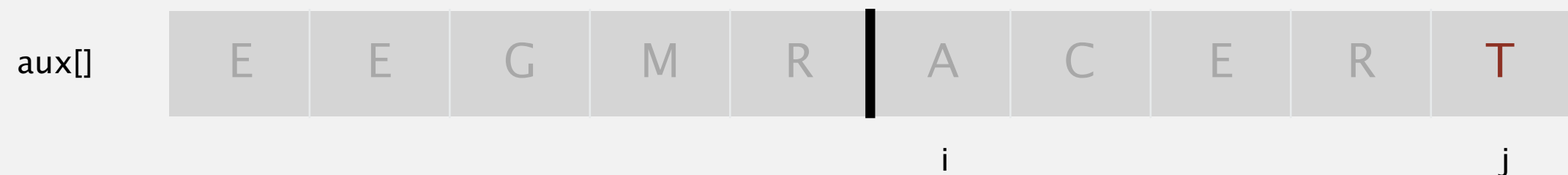
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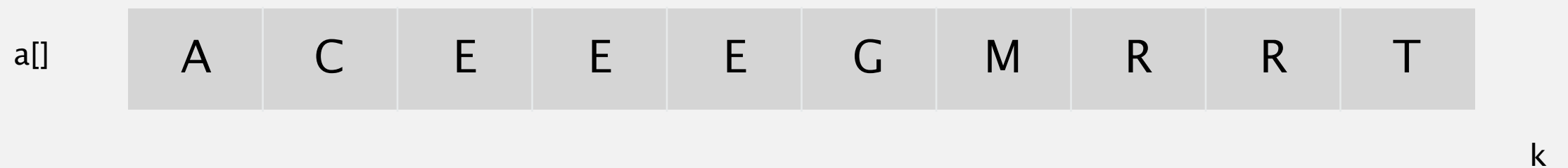
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# Merging demo

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**Goal.** Given two sorted subarrays  $a[lo]$  to  $a[mid]$  and  $a[mid+1]$  to  $a[hi]$ , replace with sorted subarray  $a[lo]$  to  $a[hi]$ .



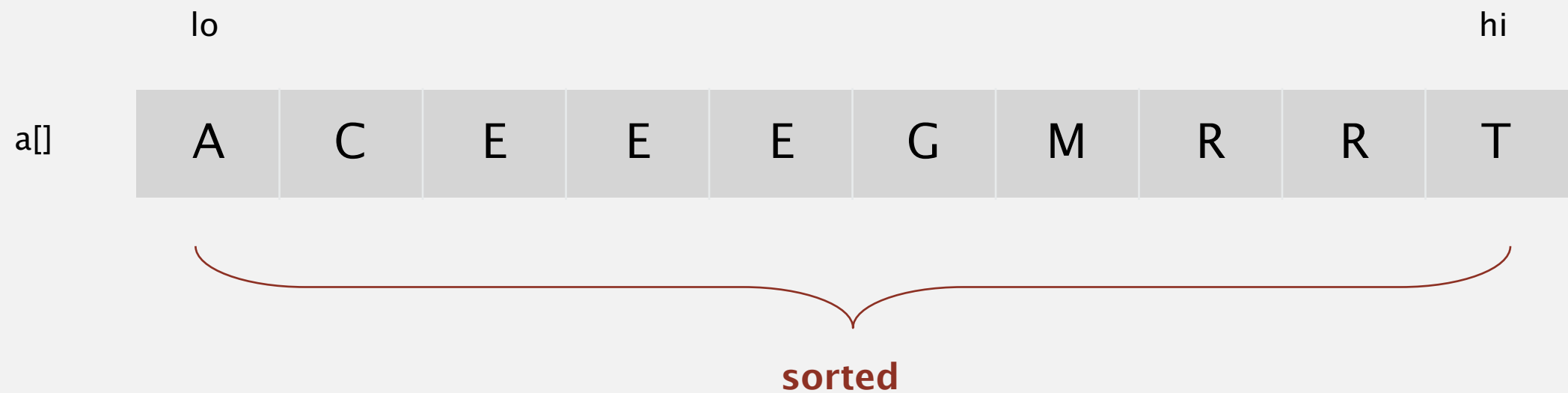
**both subarrays exhausted, done**



# Merging demo

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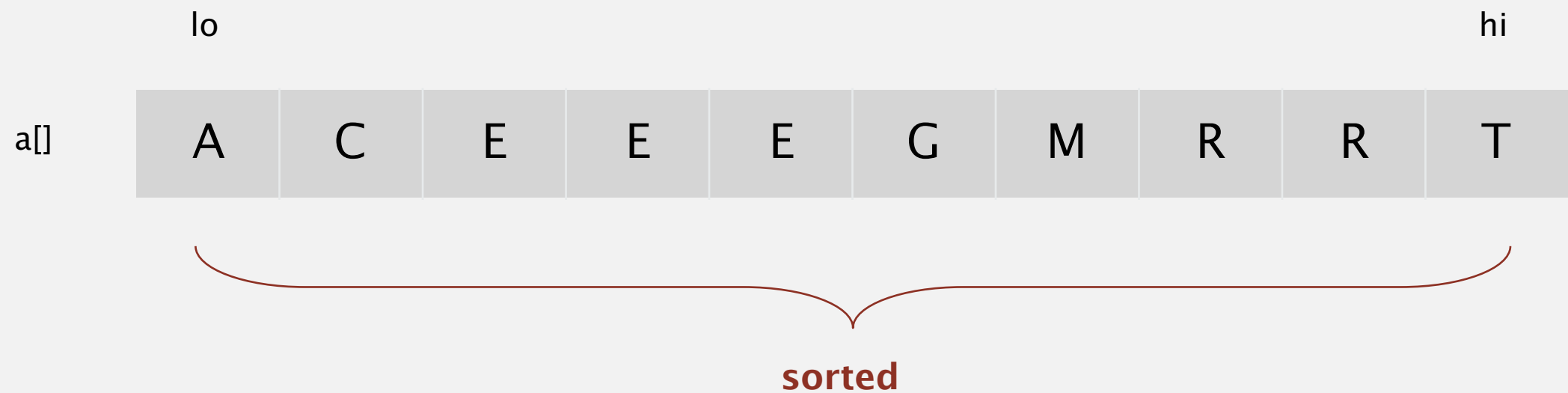
**Goal.** Given two sorted subarrays  $a[lo]$  to  $a[mid]$  and  $a[mid+1]$  to  $a[hi]$ , replace with sorted subarray  $a[lo]$  to  $a[hi]$ .



# Merging demo

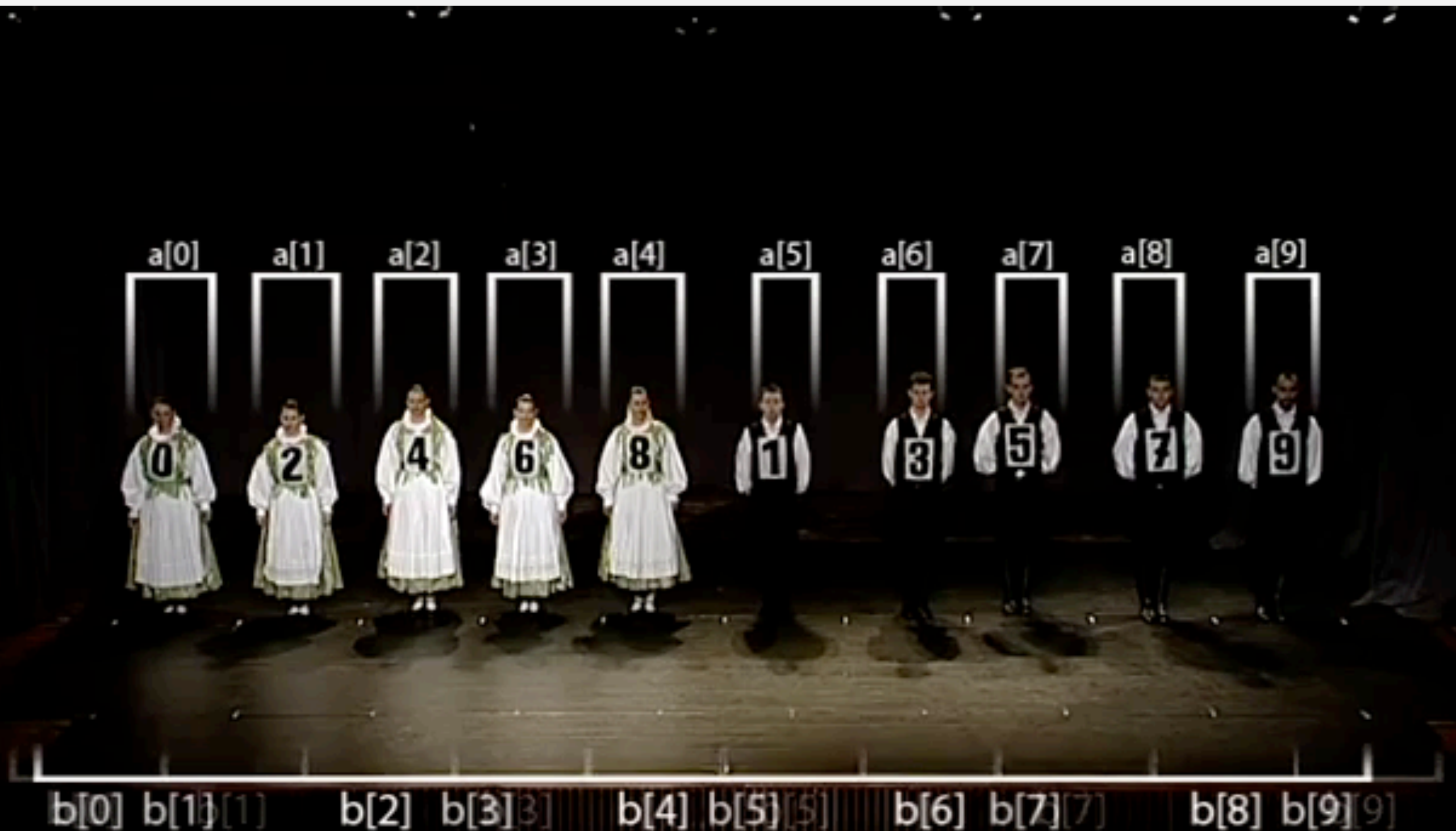
---

**Goal.** Given two sorted subarrays  $a[lo]$  to  $a[mid]$  and  $a[mid+1]$  to  $a[hi]$ , replace with sorted subarray  $a[lo]$  to  $a[hi]$ .



# Mergesort: Transylvanian-Saxon folk dance

---



# Merging: Java implementation

```
private static void merge(Comparable[] a, Comparable[] aux, int lo, int mid, int hi)
{
    for (int k = lo; k <= hi; k++)
        aux[k] = a[k];
    copy

    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if (i > mid)
            a[k] = aux[j++];
        else if (j > hi)
            a[k] = aux[i++];
        else if (less(aux[j], aux[i]))
            a[k] = aux[j++];
        else
            a[k] = aux[i++];
        merge
    }
}
```



# Assertions

---

**Assertion.** Statement to test assumptions about your program.

- Helps detect logic bugs.
- Documents code.

**Java assert statement.** Throws exception unless boolean condition is true.

```
assert isSorted(a, lo, hi);
```

**Can enable or disable at runtime.**  $\Rightarrow$  No cost in production code.

```
% java -ea MyProgram    // enable assertions
% java -da MyProgram    // disable assertions (default)
```

**Best practices.** Use assertions to check internal invariants;

assume assertions will be disabled in production code. 

do not use for external  
argument checking



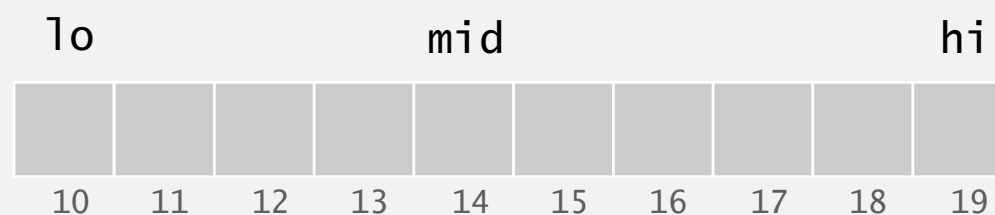
# Mergesort: Java implementation

---

```
public class Merge
{
    private static void merge(...)
    { /* as before */ }

    private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
    {
        if (hi <= lo) return;
        int mid = lo + (hi - lo) / 2;
        sort(a, aux, lo, mid);
        sort(a, aux, mid+1, hi);
        merge(a, aux, lo, mid, hi);
    }

    public static void sort(Comparable[] a)
    {
        Comparable[] aux = new Comparable[a.length];
        sort(a, aux, 0, a.length - 1);
    }
}
```



# Mergesort: trace

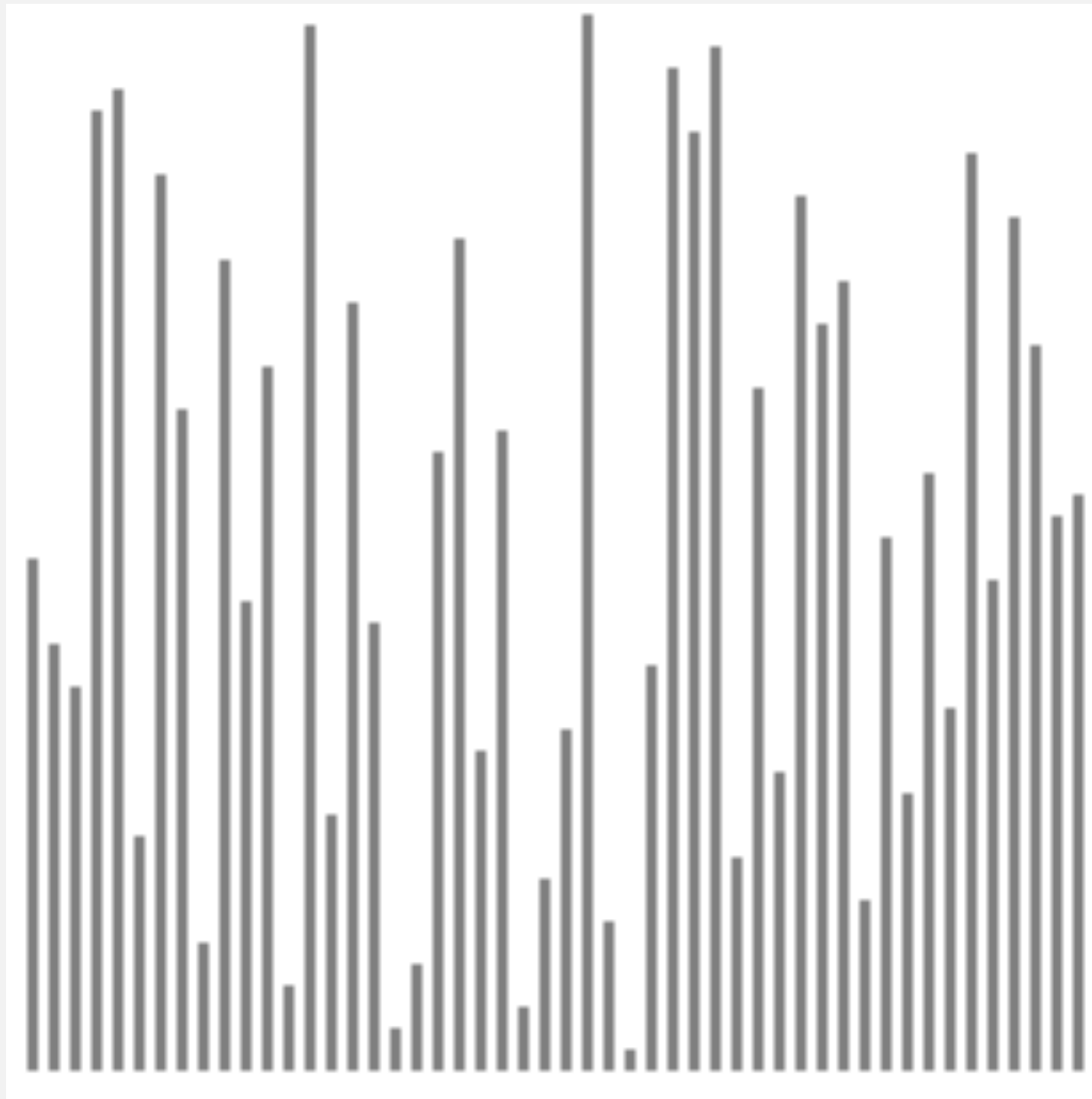
	a[]															
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
	E	M	R	G	E	S	O	R	T	E	X	A	M	P	L	E
	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
	E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
	E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
	E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
	E	G	M	R	E	O	R	S	T	E	X	A	M	P	L	E
	E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E
	E	E	G	M	O	R	R	S	E	T	X	A	M	P	L	E
	E	E	G	M	O	R	R	S	E	T	A	X	M	P	L	E
	E	E	G	M	O	R	R	S	A	E	T	X	M	P	L	E
	E	E	G	M	O	R	R	S	A	E	T	X	M	P	E	L
	E	E	G	M	O	R	R	S	A	E	T	X	E	L	M	P
	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
	A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

result after recursive call

# Mergesort: animation

---

50 random items



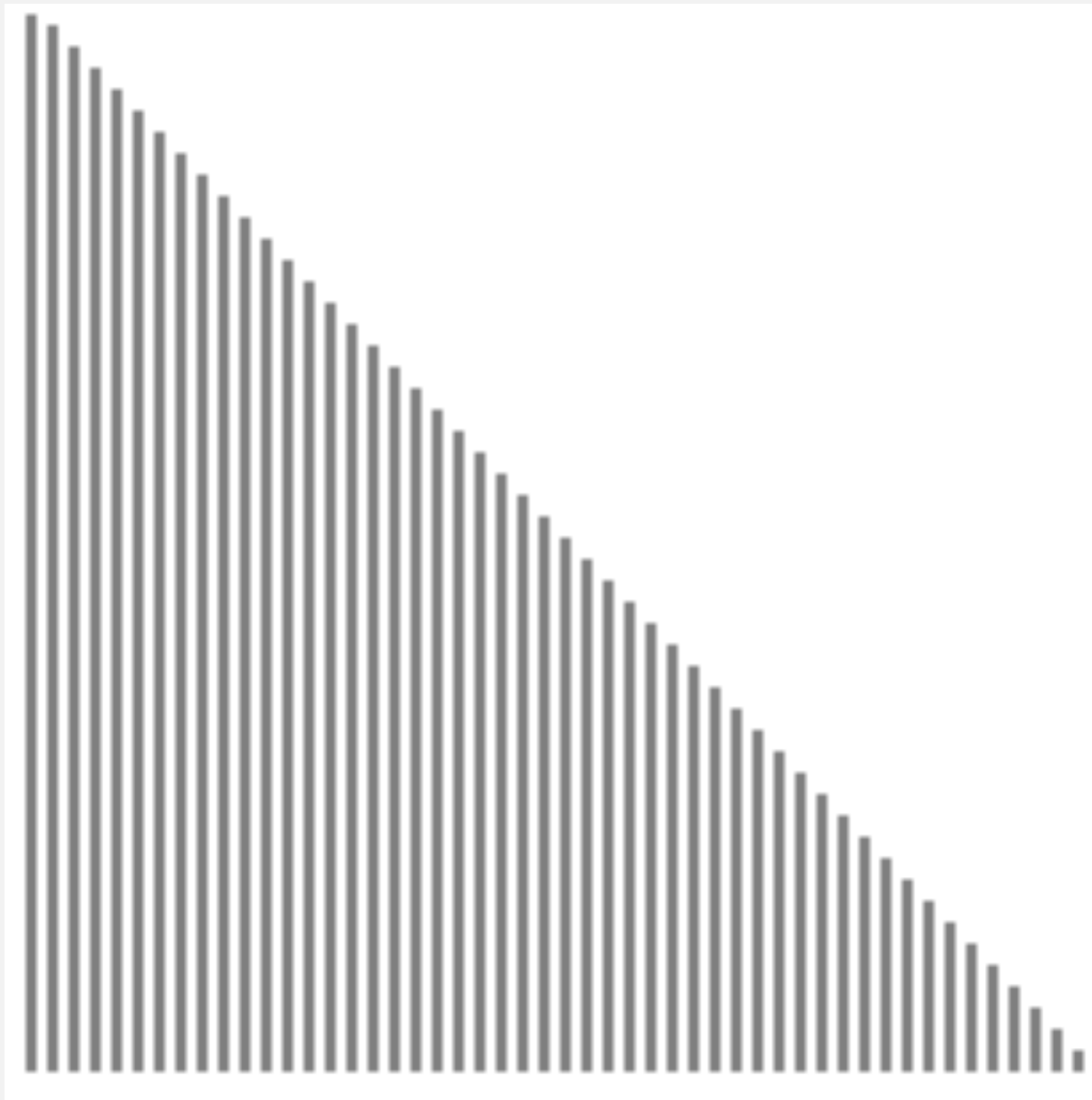
<http://www.sorting-algorithms.com/merge-sort>

- ▲ algorithm position
- in order
- current subarray
- not in order



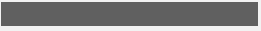
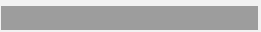
# Mergesort: animation

---

50 reverse-sorted items



<http://www.sorting-algorithms.com/merge-sort>

-  algorithm position
-  in order
-  current subarray
-  not in order

# Mergesort: empirical analysis

---

## Running time estimates:

- Laptop executes  $10^8$  compares/second.
- Supercomputer executes  $10^{12}$  compares/second.

	insertion sort ( $N^2$ )			mergesort ( $N \log N$ )		
computer	thousand	million	billion	thousand	million	billion
home	instant	2.8 hours	317 years	instant	1 second	18 min
super	instant	1 second	1 week	instant	instant	instant

**Bottom line.** Good algorithms are better than supercomputers.


# Mergesort analysis: number of compares

---

**Proposition.** Mergesort uses  $\leq N \lg N$  compares to sort an array of length  $N$ .


**Pf sketch.** The number of compares  $C(N)$  to mergesort an array of length  $N$  satisfies the recurrence:

$$C(N) \leq C(\lceil N/2 \rceil) + C(\lfloor N/2 \rfloor) + N - 1 \quad \text{for } N > 1, \text{ with } C(1) = 0.$$

  
left half                  right half                  merge

We solve this simpler recurrence, and assume  $N$  is a power of 2:

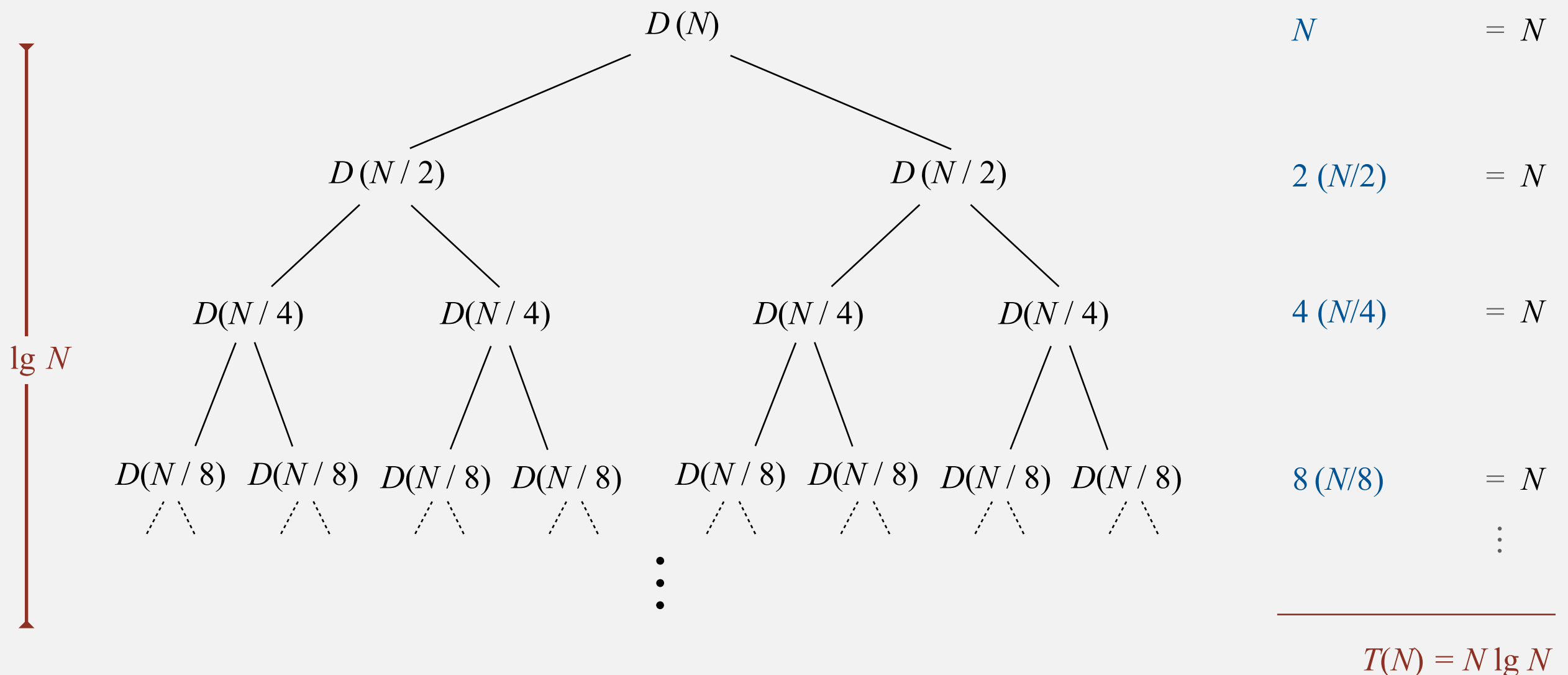
$$D(N) = 2 D(N/2) + N, \text{ for } N > 1, \text{ with } D(1) = 0.$$

 result holds for all  $N$   
(analysis cleaner in this case)

# Divide-and-conquer recurrence

**Proposition.** If  $D(N)$  satisfies  $D(N) = 2 D(N/2) + N$  for  $N > 1$ , with  $D(1) = 0$ , then  $D(N) = N \lg N$ .

**Pf by picture.** [assuming  $N$  is a power of 2]



# Divide-and-conquer recurrence

---

**Proposition.** If  $D(N)$  satisfies  $D(N) = 2 D(N/2) + N$  for  $N > 1$ , with  $D(1) = 0$ , then  $D(N) = N \lg N$ .

**Pf by telescoping.** [assuming  $N$  is a power of 2]

$$\begin{aligned} \text{For } n > 1: \quad \frac{T(n)}{n} &= \frac{2T(n/2)}{n} + 1 \\ &= \frac{T(n/2)}{n/2} + 1 \\ &= \frac{T(n/4)}{n/4} + 1 + 1 \\ &\dots \\ &= \frac{T(n/n)}{n/n} + \underbrace{1 + \dots + 1}_{\log_2 n} \\ &= \log_2 n \end{aligned}$$



# Divide-and-conquer recurrence

---

**Proposition.** If  $D(N)$  satisfies  $D(N) = 2 D(N/2) + N$  for  $N > 1$ , with  $D(1) = 0$ , then  $D(N) = N \lg N$ .

**Pf by induction.** [assuming  $N$  is a power of 2]

- Base case:  $N = 1$ .
- Inductive hypothesis:  $D(N) = N \lg N$ .
- Goal: show that  $D(2N) = (2N) \lg (2N)$ .

$$D(2N) = 2 D(N) + 2N$$

given

$$= 2 N \lg N + 2N$$

inductive hypothesis

$$= 2 N (\lg (2N) - 1) + 2N$$

algebra

$$= 2 N \lg (2N)$$

QED

# Mergesort analysis: number of array accesses

---

**Proposition.** Mergesort uses  $\leq 6 N \lg N$  array accesses to sort an array of length  $N$ .

**Pf sketch.** The number of array accesses  $A(N)$  satisfies the recurrence:

$$A(N) \leq A(\lceil N/2 \rceil) + A(\lfloor N/2 \rfloor) + 6N \text{ for } N > 1, \text{ with } A(1) = 0.$$

**Key point.** Any algorithm with the following structure takes  $N \log N$  time:

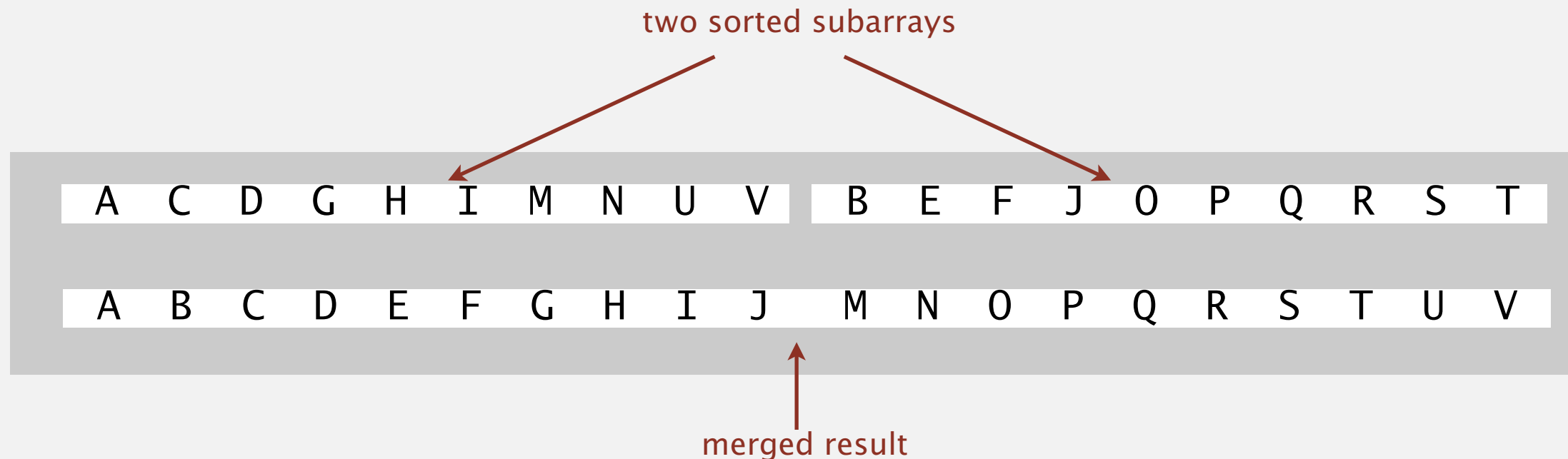
```
public static void f(int N)
{
    if (N == 0) return;
    f(N/2);      ← solve two problems
    f(N/2);      ← of half the size
    linear(N);   ← do a linear amount of work
}
```

**Notable algorithms.** FFT, hidden-line removal, Kendall-tau distance, ...

# Mergesort analysis: memory

**Proposition.** Mergesort uses extra space proportional to  $N$ .

**Pf.** The array `aux[]` needs to be of length  $N$  for the last merge.



**Def.** A sorting algorithm is **in-place** if it uses  $\leq c \log N$  extra memory.

**Ex.** Insertion sort, selection sort, shellsort.

**Challenge 1 (not hard).** Use `aux[]` array of length  $\sim \frac{1}{2} N$  instead of  $N$ .

**Challenge 2 (very hard).** In-place merge. [Kronrod 1969].

# Stability: mergesort

---

**Proposition.** Mergesort is **stable**.

```
public class Merge
{
    private static void merge(...)
    { /* as before */ }

    private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
    {
        if (hi <= lo) return;
        int mid = lo + (hi - lo) / 2;
        sort(a, aux, lo, mid);
        sort(a, aux, mid+1, hi);
        merge(a, aux, lo, mid, hi);
    }

    public static void sort(Comparable[] a)
    { /* as before */ }
}
```

**Pf.** Suffices to verify that merge operation is stable.

# Stability: mergesort

**Proposition.** Merge operation is **stable**.

```
private static void merge(...)
{
    for (int k = lo; k <= hi; k++)
        aux[k] = a[k];

    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if      (i > mid)                a[k] = aux[j++];
        else if (j > hi)                a[k] = aux[i++];
        else if (less(aux[j], aux[i])) a[k] = aux[j++];
        else                            a[k] = aux[i++];
    }
}
```

0	1	2	3	4	5	6	7	8	9	10
A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	B	D	A <sub>4</sub>	A <sub>5</sub>	C	E	F	G

**Pf.** Takes from left subarray if equal keys.

# Mergesort: practical improvements

---

## Use insertion sort for small subarrays.

- Mergesort has too much overhead for tiny subarrays.
- Cutoff to insertion sort for  $\approx 10$  items.

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1)
    {
        Insertion.sort(a, lo, hi);
        return;
    }
    int mid = lo + (hi - lo) / 2;
    sort (a, aux, lo, mid);
    sort (a, aux, mid+1, hi);
    merge(a, aux, lo, mid, hi);
}
```

# Mergesort: practical improvements

---

## Stop if already sorted.

- Is largest item in first half  $\leq$  smallest item in second half?
- Helps for partially-ordered arrays.

A	B	C	D	E	F	G	H	I	J	M	N	O	P	Q	R	S	T	U	V
A	B	C	D	E	F	G	H	I	J	M	N	O	P	Q	R	S	T	U	V

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort (a, aux, lo, mid);
    sort (a, aux, mid+1, hi);
    if (!less(a[mid+1], a[mid])) return;
    merge(a, aux, lo, mid, hi);
}
```

# Mergesort: practical improvements

Eliminate the copy to the auxiliary array. Save time (but not space) by switching the role of the input and auxiliary array in each recursive call.

```
private static void merge(Comparable[] a, Comparable[] aux, int lo, int mid, int hi)
{
    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if (i > mid)          aux[k] = a[j++];
        else if (j > hi)      aux[k] = a[i++];
        else if (less(a[j], a[i])) aux[k] = a[j++];
        else                  aux[k] = a[i++];
    }
}
```

← merge from a[] to aux[]

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort (aux, a, lo, mid);
    sort (aux, a, mid+1, hi);
    merge(a, aux, lo, mid, hi);
}
```

↑  
assumes aux[] is initialize to a[] once,  
before recursive calls

↑  
switch roles of aux[] and a[]



# Java 6 system sort

---

Basic algorithm for sorting objects = mergesort.

- Cutoff to insertion sort = 7.
- Stop-if-already-sorted test.
- Eliminate-the-copy-to-the-auxiliary-array trick.

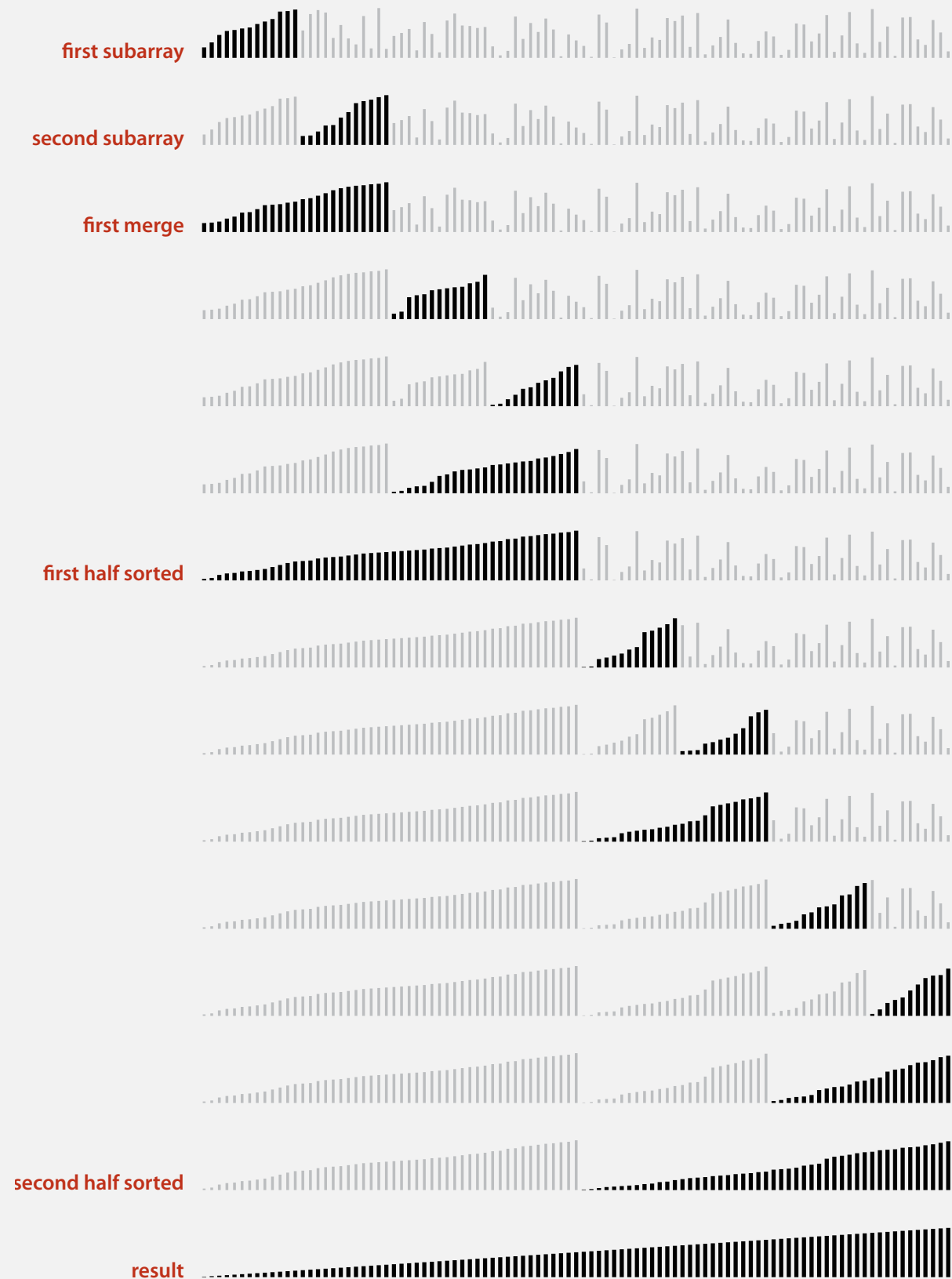
**Arrays.sort(a)**



<http://hg.openjdk.java.net/jdk6/jdk6/jdk/file/tip/src/share/classes/java/util/Arrays.java>

# Mergesort with cutoff to insertion sort: visualization

---





<http://algs4.cs.princeton.edu>

## 2.2 MERGESORT

---

- ▶ *mergesort*
- ▶ *bottom-up mergesort*
- ▶ *sorting complexity*
- ▶ *divide-and-conquer*

# Bottom-up mergesort

## Basic plan.

- Pass through array, merging subarrays of size 1.
- Repeat for subarrays of size 2, 4, 8, ....

					a[i]															
					0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
<b>sz = 1</b>					M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 0, 0, 1)					E	M	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 2, 2, 3)					E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 4, 4, 5)					E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 6, 6, 7)					E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 8, 8, 9)					E	M	G	R	E	S	O	R	E	T	X	A	M	P	L	E
merge(a, aux, 10, 10, 11)					E	M	G	R	E	S	O	R	E	T	A	X	M	P	L	E
merge(a, aux, 12, 12, 13)					E	M	G	R	E	S	O	R	E	T	A	X	M	P	L	E
merge(a, aux, 14, 14, 15)					E	M	G	R	E	S	O	R	E	T	A	X	M	P	E	L
<b>sz = 2</b>					E	G	M	R	E	S	O	R	E	T	A	X	M	P	E	L
merge(a, aux, 0, 1, 3)					E	G	M	R	E	O	R	S	E	T	A	X	M	P	E	L
merge(a, aux, 4, 5, 7)					E	G	M	R	E	O	R	S	A	E	T	X	M	P	E	L
merge(a, aux, 8, 9, 11)					E	G	M	R	E	O	R	S	A	E	T	X	M	P	E	L
merge(a, aux, 12, 13, 15)					E	G	M	R	E	O	R	S	A	E	T	X	E	L	M	P
<b>sz = 4</b>					E	E	G	M	O	R	R	S	A	E	T	X	E	L	M	P
merge(a, aux, 0, 3, 7)					E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
merge(a, aux, 8, 11, 15)																				
<b>sz = 8</b>					A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X
merge(a, aux, 0, 7, 15)																				

# Bottom-up mergesort: Java implementation

---

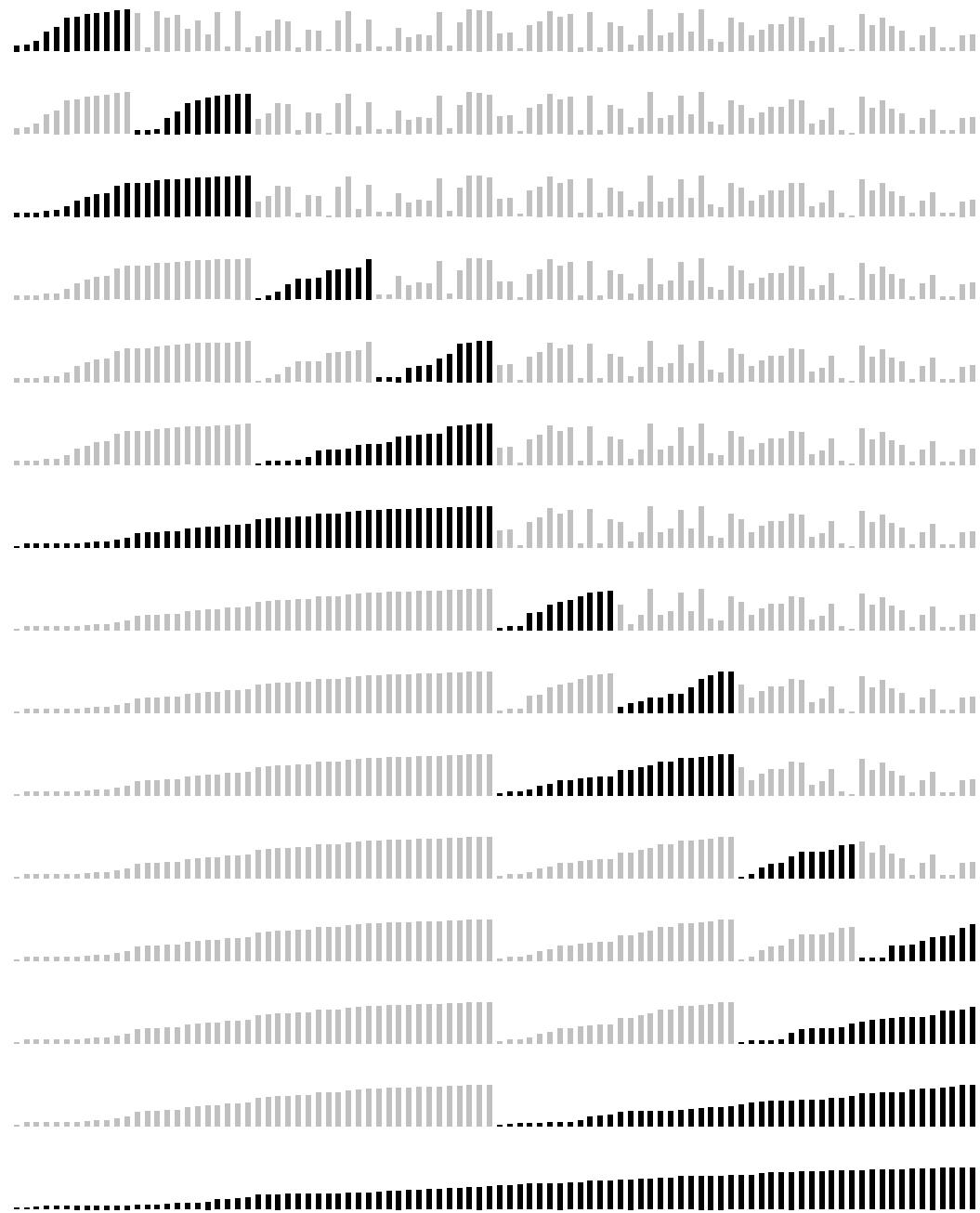
```
public class MergeBU
{
    private static void merge(...)
    { /* as before */ }

    public static void sort(Comparable[] a)
    {
        int N = a.length;
        Comparable[] aux = new Comparable[N];
        for (int sz = 1; sz < N; sz = sz+sz)
            for (int lo = 0; lo < N-sz; lo += sz+sz)
                merge(a, aux, lo, lo+sz-1, Math.min(lo+sz+sz-1, N-1));
    }
}
```

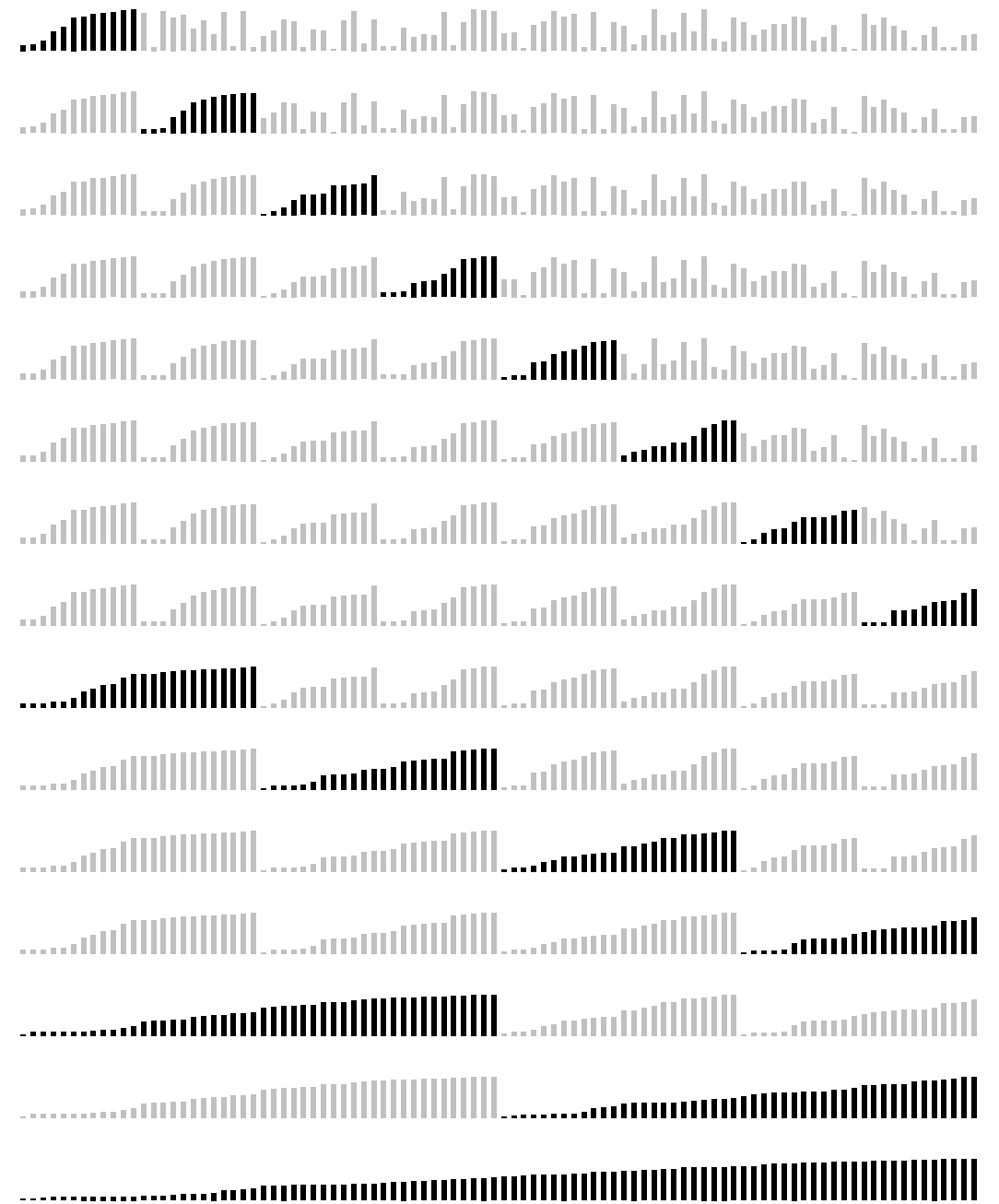
**Bottom line.** Simple and non-recursive version of mergesort.

# Mergesort: visualizations

---



top-down mergesort (cutoff = 12)



bottom-up mergesort (cutoff = 12)

# Natural mergesort

---

**Idea.** Exploit pre-existing order by identifying naturally-occurring runs.

**input**

1	5	10	16	3	4	23	9	13	2	7	8	12	14
---	---	----	----	---	---	----	---	----	---	---	---	----	----

**first run**

1	5	10	16	3	4	23	9	13	2	7	8	12	14
---	---	----	----	---	---	----	---	----	---	---	---	----	----

**second run**

1	5	10	16	3	4	23	9	13	2	7	8	12	14
---	---	----	----	---	---	----	---	----	---	---	---	----	----

**merge two runs**

1	3	4	5	10	16	23	9	13	2	7	8	12	14
---	---	---	---	----	----	----	---	----	---	---	---	----	----

**Tradeoff.** Fewer passes vs. extra compares per pass to identify runs.

# Timsort

---

- Natural mergesort.
- Use binary insertion sort to make initial runs (if needed).
- A few more clever optimizations.



**Tim Peters**

Intro

-----

This describes an adaptive, stable, natural mergesort, modestly called timsort (hey, I earned it <wink>). It has supernatural performance on many kinds of partially ordered arrays (less than  $\lg(N!)$  comparisons needed, and as few as  $N-1$ ), yet as fast as Python's previous highly tuned samplesort hybrid on random arrays.

In a nutshell, the main routine marches over the array once, left to right, alternately identifying the next run, then merging it into the previous runs "intelligently". Everything else is complication for speed, and some hard-won measure of memory efficiency.

...

**Consequence.** Linear time on many arrays with pre-existing order.

**Now widely used.** Python, Java 7, GNU Octave, Android, ....

<http://hg.openjdk.java.net/jdk7/jdk7/jdk/file/tip/src/share/classes/java/util/Arrays.java>



## Envisage: Engineering Virtualized Services

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### Proving that Android's, Java's and Python's sorting algorithm is broken (and showing how to fix it)

🕒 February 24, 2015   📁 Envisage   ✍️ Written by Stijn de Gouw. 💰 \$s

Tim Peters developed the **Timsort hybrid sorting algorithm** in 2002. It is a clever combination of ideas from merge sort and insertion sort, and designed to perform well on real world data. TimSort was first developed for Python, but later ported to Java (where it appears as `java.util.Collections.sort` and `java.util.Arrays.sort`) by **Joshua Bloch** (the designer of Java Collections who also pointed out that **most binary search algorithms were broken**). TimSort is today used as the default sorting algorithm for Android SDK, Sun's JDK and OpenJDK. Given the popularity of these platforms this means that the number of computers, cloud services and mobile phones that use TimSort for sorting is well into the billions.

# Sorting summary

---

	inplace?	stable?	best	average	worst	remarks
selection	✓		$\frac{1}{2} N^2$	$\frac{1}{2} N^2$	$\frac{1}{2} N^2$	$N$ exchanges
insertion	✓	✓	$N$	$\frac{1}{4} N^2$	$\frac{1}{2} N^2$	use for small $N$ or partially ordered
shell	✓		$N \log_3 N$	?	$c N^{3/2}$	tight code; subquadratic
merge		✓	$\frac{1}{2} N \lg N$	$N \lg N$	$N \lg N$	$N \log N$ guarantee; stable
timsort		✓	$N$	$N \lg N$	$N \lg N$	improves mergesort when preexisting order
?	✓	✓	$N$	$N \lg N$	$N \lg N$	holy sorting grail



<http://algs4.cs.princeton.edu>

## 2.2 MERGESORT

---

- ▶ *mergesort*
- ▶ *bottom-up mergesort*
- ▶ *sorting complexity*
- ▶ *divide-and-conquer*

# Complexity of sorting

---

**Computational complexity.** Framework to study efficiency of algorithms for solving a particular problem  $X$ .

**Model of computation.** Allowable operations.

**Cost model.** Operation counts.

**Upper bound.** Cost guarantee provided by **some** algorithm for  $X$ .

**Lower bound.** Proven limit on cost guarantee of **all** algorithms for  $X$ .

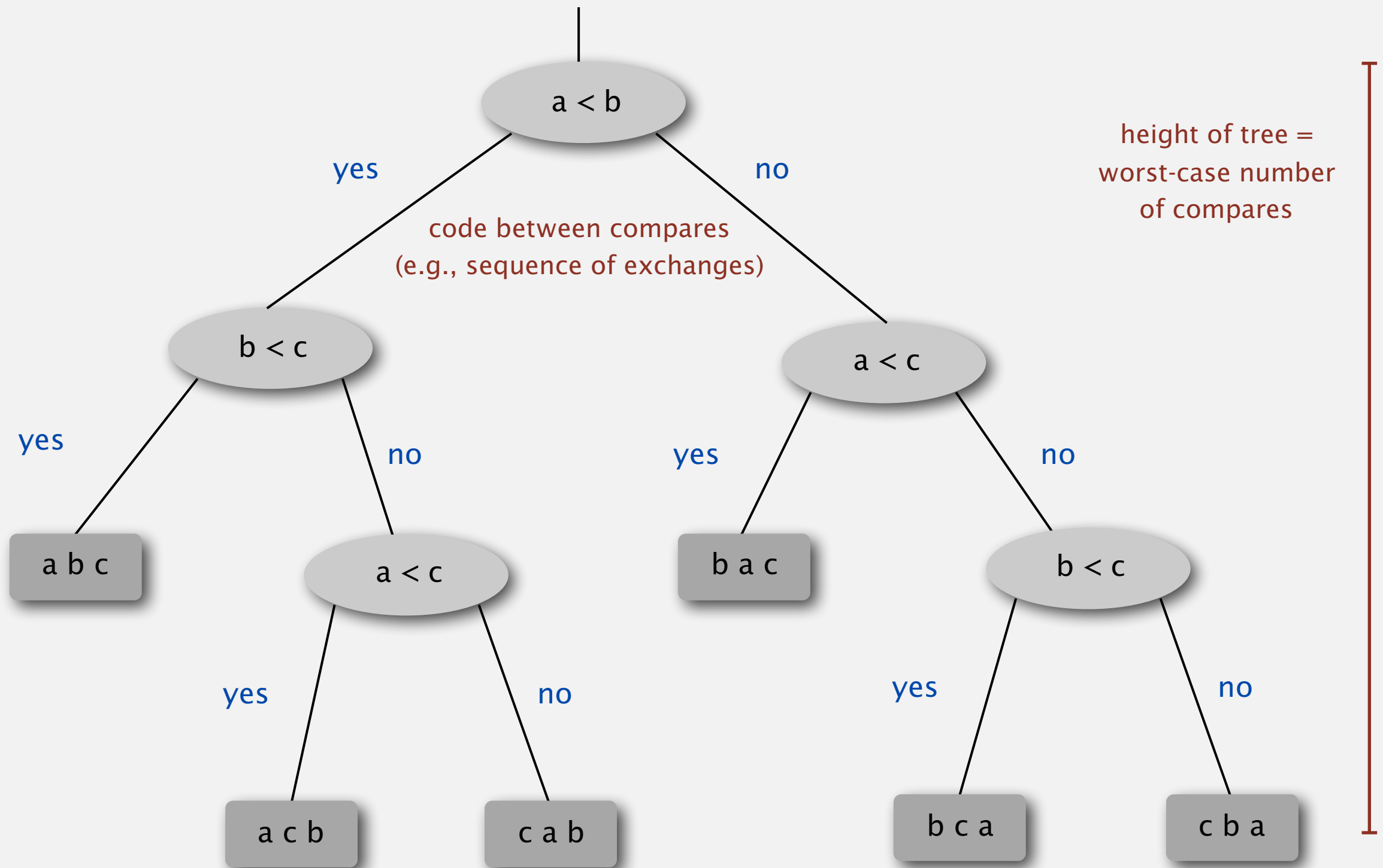
**Optimal algorithm.** Algorithm with best possible cost guarantee for  $X$ .

lower bound ~ upper bound

model of computation	<i>decision tree</i>
cost model	<i># compares</i>
upper bound	<i><math>\sim N \lg N</math> from mergesort</i>
lower bound	?
optimal algorithm	?

can access information  
only through compares  
(e.g., Java Comparable framework)

# Decision tree (for 3 distinct keys a, b, and c)

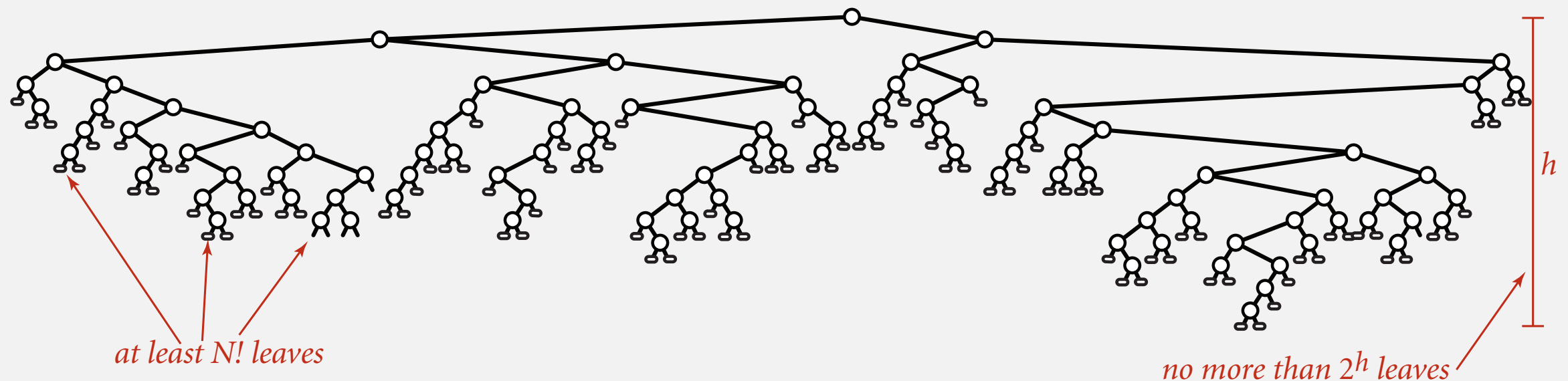


# Compare-based lower bound for sorting

**Proposition.** Any compare-based sorting algorithm must use at least  $\lg(N!) \sim N \lg N$  compares in the worst-case.

**Pf.**

- Assume array consists of  $N$  distinct values  $a_1$  through  $a_N$ .
- Worst case dictated by **height**  $h$  of decision tree.
- Binary tree of height  $h$  has at most  $2^h$  leaves.
- $N!$  different orderings  $\Rightarrow$  at least  $N!$  leaves.



# Compare-based lower bound for sorting

---

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- Binary tree of height  $h$  has at most  $2^h$  leaves.
- $N!$  different orderings  $\Rightarrow$  at least  $N!$  leaves.

$$2^h \geq \# \text{ leaves} \geq N!$$

$$\Rightarrow h \geq \lg(N!) \sim N \lg N$$

 Stirling's formula



# Complexity of sorting

---

**Model of computation.** Allowable operations.

**Cost model.** Operation count(s).

**Upper bound.** Cost guarantee provided by some algorithm for  $X$ .

**Lower bound.** Proven limit on cost guarantee of all algorithms for  $X$ .

**Optimal algorithm.** Algorithm with best possible cost guarantee for  $X$ .

<b>model of computation</b>	<i>decision tree</i>
<b>cost model</b>	<i># compares</i>
<b>upper bound</b>	$\sim N \lg N$
<b>lower bound</b>	$\sim N \lg N$
<b>optimal algorithm</b>	<i>mergesort</i>

**complexity of sorting**

**First goal of algorithm design:** optimal algorithms.



# Complexity results in context

---

**Compares?** Mergesort **is** optimal with respect to number compares.

**Space?** Mergesort **is not** optimal with respect to space usage.



**Lessons.** Use theory as a guide.

**Ex.** Design sorting algorithm that guarantees  $\sim \frac{1}{2} N \lg N$  compares?

**Ex.** Design sorting algorithm that is both time- and space-optimal?

## Complexity results in context (continued)

---

Lower bound may not hold if the algorithm can take advantage of:

- The initial order of the input.

Ex: insertion sort requires only a linear number of compares on partially-sorted arrays.

- The distribution of key values.

Ex: 3-way quicksort requires only a linear number of compares on arrays with a constant number of distinct keys. [stay tuned]

- The representation of the keys.

Ex: radix sorts require no key compares — they access the data via character/digit compares.

# Commonly-used notations in the theory of algorithms

---

notation	provides	example	shorthand for
<b>Tilde</b>	leading term	$\sim \frac{1}{2} N^2$	$\frac{1}{2} N^2$ $\frac{1}{2} N^2 + 22 N \log N + 3 N$
<b>Big Theta</b>	order of growth	$\Theta(N^2)$	$\frac{1}{2} N^2$ $10 N^2$ $5 N^2 + 22 N \log N + 3 N$
<b>Big O</b>	upper bound	$O(N^2)$	$10 N^2$ $100 N$ $22 N \log N + 3 N$
<b>Big Omega</b>	lower bound	$\Omega(N^2)$	$\frac{1}{2} N^2$ $N^5$ $N^3 + 22 N \log N + 3 N$