

Hints

Hidden Markov Models

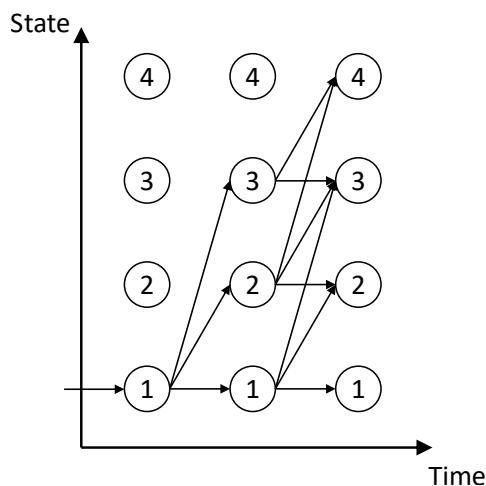
Task 1.

a) Model Parameters:

$$A = \begin{pmatrix} 0.3 & 0.5 & \underline{0.2} & 0 \\ 0 & \underline{0.4} & 0.2 & 0.4 \\ 0 & 0 & 0.3 & \underline{0.7} \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ with } \forall_i \sum_{k=1}^N a_{ik} = 1$$

$$\Pi = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \text{ with } \sum_{k=1}^N \pi_k = 1$$

b) Trellis diagram:



c) Path:

$$\begin{array}{ccccccc} \pi_1=1 & & a_{13}=0.2 & & \pi_{34}=0.7 & & \Rightarrow P(Q|\lambda) = 1 \cdot 0.2 \cdot 0.7 = 0.14 \\ \longrightarrow & \textcircled{1} & \longrightarrow & \textcircled{3} & \longrightarrow & \textcircled{4} & \\ & b_{11}=0.3 & & b_{39}=0.5 & & b_{41}=0.8 & \Rightarrow P(O|Q, \lambda) = 0.3 \cdot 0.5 \cdot 0.8 = 0.12 \end{array}$$

$$\Rightarrow P(O, Q|\lambda) = P(Q|\lambda) \cdot P(O|Q, \lambda) = 0.14 \cdot 0.12 = 0.0168$$

Task 2.

a) Class A:

$$A = \begin{pmatrix} 0.1 & 0.4 & 0.5 & 0 & 0 \\ 0 & 0.1 & 0.5 & 0.4 & 0 \\ 0 & 0 & 0.2 & 0.5 & 0.3 \\ 0 & 0 & 0 & 0.5 & 0.5 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}, \Pi = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Class B:

$$A = \begin{pmatrix} 0.3 & 0.6 & 0.1 & 0 \\ 0 & 0.3 & 0.5 & 0.2 \\ 0 & 0 & 0.3 & 0.7 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \Pi = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Class C:

$$A = \begin{pmatrix} 0.2 & 0.5 & 0.3 \\ 0 & 0.5 & 0.5 \\ 0 & 0 & 1 \end{pmatrix}, \Pi = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

b) Class A:

$$Q_1 = \{q_1, q_2, q_3\} = \{1, 3, 5\}$$

Class B:

$$Q_1 = \{q_1, q_2, q_3\} = \{1, 3, 4\}$$

$$Q_2 = \{q_1, q_2, q_3\} = \{1, 2, 4\}$$

Class C:

$$Q_1 = \{q_1, q_2, q_3\} = \{1, 2, 3\}$$

$$Q_2 = \{q_1, q_2, q_3\} = \{1, 1, 3\}$$

$$Q_3 = \{q_1, q_2, q_3\} = \{1, 3, 3\}$$

c) For a single path it holds:

$$\begin{array}{lcl} \text{production probability} & = & \text{path probability} \cdot \text{emission probability} \\ P(O, Q_i|\lambda) & = & P(Q_i|\lambda) \cdot P(O|Q_i, \lambda) \end{array}$$

Class A:

$$P(O, Q_1|\lambda) = 0.15 \cdot 9.4 \cdot 10^{-3} = 1.41 \cdot 10^{-3}$$

Class B:

$$P(O, Q_1|\lambda) = 0.07 \cdot 10.4 \cdot 10^{-3} = 0.73 \cdot 10^{-3}$$

$$P(O, Q_2|\lambda) = 0.12 \cdot 15.6 \cdot 10^{-3} = 1.87 \cdot 10^{-3}$$

Class C:

$$P(O, Q_1|\lambda) = 0.25 \cdot 5.2 \cdot 10^{-3} = 1.3 \cdot 10^{-3}$$

$$P(O, Q_2|\lambda) = 0.06 \cdot 10.8 \cdot 10^{-3} = 0.65 \cdot 10^{-3}$$

$$P(O, Q_3|\lambda) = 0.3 \cdot 5.2 \cdot 10^{-3} = 1.56 \cdot 10^{-3}$$

d) Class B, since path Q_2 has the highest probability.

e) Class A:

$$P(O|\lambda) = \sum_{\forall Q_i} P(O, Q_i|\lambda) = 1.41 \cdot 10^{-3}$$

Class B:

$$P(O|\lambda) = 0.73 \cdot 10^{-3} + 1.87 \cdot 10^{-3} = 2.6 \cdot 10^{-3}$$

Class C:

$$P(O|\lambda) = 1.3 \cdot 10^{-3} + 0.65 \cdot 10^{-3} + 1.56 \cdot 10^{-3} = 3.51 \cdot 10^{-3}$$

The number of possible paths depends on the class. The results are not comparable without normalization.