

## Lec 2/1

Wednesday, February 1, 2017 09:09

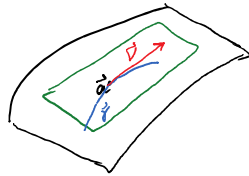
↖ a set S

**Proposition:** Suppose that a hypersurface in  $\mathbb{R}^{n+1}$  is given by  $F(\vec{x}) = 0$ .

If  $\vec{a} \in S$ , then the equation of hyperplane tangent to S at  $\vec{a}$  is

$$\nabla F(\vec{a}) \cdot (\vec{x} - \vec{a}) = 0.$$

Informal proof:



given a vector  $\vec{v}$  in tangent hyperplane  
we can find a smooth curve

$$\vec{\gamma}: (-\epsilon, \epsilon) \rightarrow S \subseteq \mathbb{R}^{n+1} \text{ with}$$

$$\vec{\gamma}(0) = \vec{a}, \quad \vec{\gamma}'(0) = \vec{v}$$

Then consider the composite

$$\begin{array}{c} (-\epsilon, \epsilon) \xrightarrow{\vec{\gamma}} S \subseteq U \xrightarrow{F} \mathbb{R} \\ \underbrace{\hspace{10em}} \\ \text{constant 0 function} \end{array}$$

$$\frac{d(F \circ \vec{\gamma})}{dt}(t) = 0$$

|| chain rule

$$0 = D F(\vec{a}) D \vec{\gamma}(0) = \nabla F(\vec{a}) \cdot \vec{v} = \nabla F(\vec{a}) \cdot \vec{\gamma}'(0)$$

So  $\nabla F(\vec{a})$  is perpendicular to  $\vec{v}$  arbitrary vector in tangent hyperplane

$\Rightarrow \nabla F(\vec{a})$  is normal to hyperplane.

Eqn of hyperplane w/ normal vector  $\nabla F(\vec{a})$  and passing thru  $\vec{a}$  is:

$$\nabla F(\vec{a}) \cdot (\vec{x} - \vec{a}) = 0 \quad (*)$$

Compare this w/ previous form:

$$\text{Surface } S = \{ \vec{x} \in \mathbb{R}^n \mid z = f(\vec{x}) \}$$

$$f: U \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$$

$$= \{ f(\vec{x}) - z = 0 \}$$

Suppose  $\vec{b} \in U$ . Then  $(\vec{b}, f(\vec{b})) \in S$

Call  $F(\vec{x}, z) = f(\vec{x}) - z$

eqn of tangent hyperplane given by (\*) is

$$\nabla F(\vec{b}, f(\vec{b})) \cdot (\vec{x}, z) - (\vec{b}, f(\vec{b})) = 0$$

observe:  $\partial_i F = \partial_i f$  for  $i=1, \dots, n$

$$\partial_{n+1} F = -1$$

so 
$$\nabla F(\vec{b}, f(\vec{b})) = (\partial_1 f, \partial_2 f, \dots, \partial_n f, -1)$$
  

$$= \nabla f, -1$$

$$(\nabla f(\vec{b}), -1) \cdot (\vec{x} - \vec{b}, z - f(\vec{b})) = 0$$

$$\nabla f(\vec{b}) \cdot (\vec{x} - \vec{b}) - z + f(\vec{b}) = 0$$

$$z = f(\vec{b}) + \nabla f(\vec{b}) \cdot (\vec{x} - \vec{b})$$

2.1 #6: Suppose  $f$  is 3 times differentiable on an open interval containing  $a$

$$1) \lim_{h \rightarrow 0} \frac{f(a+2h) - 2f(a+h) + f(a)}{h^2} = f''(a)$$

$$2) \lim_{h \rightarrow 0} \frac{f(a+3h) - 3f(a+2h) + 3f(a+h) - f(a)}{h^3} = f^{(3)}(a)$$

Suggested Solution: Apply L'H repeatedly:

$$1) \lim_{h \rightarrow 0} \frac{2f'(a+2h) - 2f'(a+h)}{2h} = \lim_{h \rightarrow 0} \frac{2f''(a+2h) - f''(a+h)}{1} \stackrel{f'' \text{ continuous}}{=} 2f''(a) - f''(a) = f''(a)$$

$$2) \text{ 3-fold application gives } \lim_{h \rightarrow 0} \frac{9f^{(3)}(a+3h) - 8f^{(3)}(a+2h) + f^{(3)}(a+h)}{2}$$

assuming  $f^{(3)}(x)$  is continuous at  $x=a$  gives this equal to  $f^{(3)}(a)$

open  $\mathbb{R}^2$

assuming  $f(x)$  is continuous at  $x=a$  gives this equation.  $f(a)$

**Theorem:** Let  $f: U \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}$  and  $(a,b) \in U$ , and suppose that  $\partial_1 f$ ,  $\partial_2 f$ , and  $\partial_2 \partial_1 f$  are defined on  $U$  and  $\partial_2 \partial_1 f$  is continuous at  $(a,b)$ . Then  $\partial_1 \partial_2 f(a,b)$  is defined and equal to  $\partial_2 \partial_1 f(a,b)$ .

Proof: 
$$\begin{aligned} \partial_2 \partial_1 f(a,b) &= \lim_{y \rightarrow b} \frac{\partial_1 f(a,y) - \partial_1 f(a,b)}{y-b} \\ &= \lim_{y \rightarrow b} \frac{\lim_{x \rightarrow a} \frac{f(x,y) - f(a,y)}{x-a} - \lim_{x \rightarrow a} \frac{f(x,b) - f(a,b)}{x-a}}{y-b} \\ &= \lim_{y \rightarrow b} \lim_{x \rightarrow a} \frac{f(x,y) - f(a,y) - f(x,b) + f(a,b)}{(x-a)(y-b)} \} F(x,y) \end{aligned}$$

$F(x,y)$  defined on  $\overbrace{B_\infty(r, (a,b))}^S \cap \{y \neq b, x \neq a\}$  for some  $r > 0$

Strategy: show that a stronger version of this limit exists:

i.e. show  $\lim_{(x,y) \rightarrow (a,b), (x,y) \in S} F(x,y)$  exists.

$$\forall (x,y) \in S \ \forall \epsilon > 0 \ \exists \delta > 0 \text{ s.t. } 0 < |x-a| < \delta, 0 < |y-b| < \delta \Rightarrow |F(x,y) - L| < \epsilon$$

$$\lim_{y \rightarrow b} \lim_{x \rightarrow a} F(x,y) = \partial_2 \partial_1 f(a,b)$$

$$\Leftrightarrow \forall \epsilon > 0 \ \exists \delta > 0, \delta_y > 0 \text{ s.t.}$$

$$0 < |x-a| < \delta, 0 < |y-b| < \delta \Rightarrow |F(x,y) - \partial_2 \partial_1 f(a,b)| < \epsilon$$

Define  $\psi(x) = f(x,y) - f(x,b)$ ,  $(x,y) \in B_\infty(r, (a,b))$

$$F(x,y) = \frac{\psi(x) - \psi(a)}{(x-a)(y-b)} \stackrel{\text{MVT on } x}{=} \frac{\psi'(x_1)(x-a)}{(x-a)(y-b)} \text{ where } x_1 \text{ between } x \text{ and } a$$

and  $\psi'(x_1) = \partial_1 f(x_1, y) - \partial_1 f(x_1, b)$

$$\stackrel{\text{MVT on } y}{=} \partial_2 \partial_1 f(x_1, y_1) \text{ where } y_1 \text{ between } y \text{ and } b$$

hence  $F(x,y) = \partial_2 \partial_1 f(x,y)$

$$|F(x,y) - \partial_2 \partial_1 f(a,b)| = |\partial_2 \partial_1 f(x,y) - \partial_2 \partial_1 f(a,b)| < \epsilon$$

provided  $(x,y) \in B_\delta(a,b)$  for some  $\delta$ .  
 $\downarrow \wedge (x \neq a, y \neq b)$

because  $\partial_2 \partial_1 f$  is continuous.

so part 1 is proved.

stronger limit exists

$$\text{Now } \partial_1 \partial_2 f(a,b) = \lim_{x \rightarrow a} \lim_{y \rightarrow b} F(x,y) \stackrel{\downarrow}{=} \lim_{y \rightarrow b} \lim_{x \rightarrow a} F(x,y) = \partial_2 \partial_1 f(a,b).$$