

Recall: $\hat{\theta}$ is sufficient for θ if $f(x_1, \dots, x_n | \hat{\theta})$ is indep of θ .

Ex: $X_1, X_2, X_3 \stackrel{iid}{\sim} \text{Bernoulli}(\theta)$.

show that $\hat{\theta} = X_1 + 2X_2 + X_3$ is not a sufficient estimator of θ .

my try: $f(x_1, x_2, x_3 | \hat{\theta}) = \frac{f(x_1, x_2, x_3)}{g(\hat{\theta})} = \frac{\theta \cdot \theta \cdot \theta}{g(\hat{\theta})}$

Sol: Try $(x_1, x_2, x_3) = (1, 0, 1) \Rightarrow \hat{\theta} = 2$.

$$f(x_1, x_2, x_3 | \hat{\theta}) = \frac{\theta^2(1-\theta)}{P(\hat{\theta}=2)} = \frac{\theta^2(1-\theta)}{(1-\theta)^2\theta + \theta^2(1-\theta)} = \frac{\theta}{(1-\theta)+\theta} = \theta \text{ depends on } \theta.$$

Theorem 10.4 The statistic $\hat{\theta}$ is a sufficient estimator of θ iff the joint pdf/pmf of the RS X_1, \dots, X_n can be factored s.t.

$$f(x_1, \dots, x_n; \theta) = g(\hat{\theta}, \theta) \cdot h(x_1, \dots, x_n)$$

Where $g(\hat{\theta}, \theta)$ depends on only $\hat{\theta}, \theta$

$h(x_1, \dots, x_n)$ does not depend on θ .

$X_1, \dots, X_n \stackrel{iid}{\sim} \text{Poisson}(\lambda)$.

$$f(x_1, \dots, x_n; \lambda) = \prod_{i=1}^n \frac{\lambda^{x_i} e^{-\lambda}}{x_i!} = \underbrace{\lambda^{\sum_{i=1}^n x_i} e^{-n\lambda}}_{g(\hat{\lambda}, \lambda)} \cdot \underbrace{\frac{1}{\prod_{i=1}^n x_i!}}_{h(x)} \Rightarrow \sum_{i=1}^n x_i \text{ is a sufficient estimator of } \lambda.$$

Ex: Let $X_1, \dots, X_n \stackrel{iid}{\sim} f(x; \theta) = \frac{\theta}{(1+x)^{\theta+1}}$ $0 < \theta < \infty$
 $0 \leq x < \infty$

$$f(x_1, \dots, x_n; \theta) = \prod_{i=1}^n \frac{\theta}{(1+x_i)^{\theta+1}} = \theta^n \cdot \frac{1}{\prod_{i=1}^n (1+x_i)^{\theta+1}} = \frac{\theta^n}{\left(\prod_{i=1}^n (1+x_i)\right)^{\theta+1}} \Rightarrow \prod_{i=1}^n (1+x_i) \text{ is sufficient for } \theta.$$

$g(\hat{\theta}, \theta) \cdot 1$

Remark: sufficient statistic is not unique. any one-to-one function

or a sufficient statistic is sufficient.

$$\begin{aligned} f(x_1, \dots, x_n; \theta) &= g(\hat{\theta}, \theta) h(x_1, \dots, x_n) \\ &= g(\underbrace{T^{-1}(T(\hat{\theta}))}_{|||}, \theta) h(x_1, \dots, x_n) \text{ if } T \text{ is 1-1.} \\ &= g(T(\hat{\theta}), \theta) \end{aligned}$$

For the previous example, can take $\hat{\theta} = \log\left(\prod_{i=1}^n (1-x_i)\right) = \sum_{i=1}^n \log(1-x_i)$

Ex: $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$. Let σ^2 be a constant. (known).

Show that \bar{X} is sufficient for μ .

Sol:
$$f(x_1, \dots, x_n; \mu) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}$$

$$= \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2\right]$$

$$= \underbrace{\frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2\sigma^2} \sum_{i=1}^n x_i^2\right]}_{h(x_1, \dots, x_n)} \underbrace{\exp\left[\frac{\sqrt{2\sigma^2}}{2\sigma^2} (2\mu n\bar{x} + n\mu^2)\right]}_{g(\bar{x}, \mu)}$$

$$\star = \sum_{i=1}^n (x_i - \mu)^2$$

$$= \sum_{i=1}^n x_i^2 - 2 \sum_{i=1}^n x_i \mu + \sum_{i=1}^n \mu^2$$

$$= f(x_i) - 2\mu(n\bar{x}) + n\mu^2$$

so \bar{X} is sufficient.

Section 10.7 method of moments:

Notation (4.3): r -th moment of a RV X about the origin is $E(X^r) \equiv \mu'_r$

The r -th sample moment of a sample X_1, \dots, X_n is $\frac{x_1^r + \dots + x_n^r}{n} \equiv m'_r$

(MOM): Equate sample to population moments.

if a pop. has r parameters, then the MOM consists of solving the system of equations $m'_k = \mu'_k$ where $k \in \{1, \dots, r\}$. for the r params.

Example: Poisson dist w/ parameter λ . $r=1$ (one parameter).

$m_1 = \mu_1 \Rightarrow \bar{X} = \lambda.$ so the MOM estimator for λ is $\bar{X}.$