

$$T \in L(V, V) \quad \dim V = n$$

two bases of V $\{v_1, \dots, v_n\}, \{w_1, \dots, w_n\}$

$$T \xrightarrow{\{v_i\}} A$$

$$T \xrightarrow{\{w_i\}} B$$

$$B = X^{-1} A X$$

\downarrow
invertible

where $X =$ transition matrix (σ_{ij})
s.t. $w_j = \sum_{i=1}^n \sigma_{ij} v_i$

$$\delta_{kj} = 1 \text{ if } k=j, 0 \text{ if } k \neq j$$

$\dim V = 2, T \in L(V, V)$ wrt $\{u_1, u_2\}$ basis of V .

$$\begin{cases} T(u_1) = u_1 - u_2 \\ T(u_2) = u_1 \end{cases} \quad \text{determines } T.$$

$$v = \lambda_1 u_1 + \lambda_2 u_2 \quad T(v) = \lambda_1 u_1 - \lambda_1 u_2 + \lambda_2 u_1$$

$$T \xrightarrow{\{u_i\}} A = \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix}$$

$\begin{matrix} \text{1, 1, 1} \\ \text{in } \mathbb{Q} \\ \text{(can be} \\ \text{checked)} \end{matrix}$ $\begin{cases} w_1 = 3u_1 - u_2 = u_1 + u_1 + u_1 - u_2 \\ w_2 = u_1 + u_2 \end{cases}$

$$X = \begin{pmatrix} 3 & 1 \\ -1 & 1 \end{pmatrix}$$

$$u_1 = \frac{1}{4}w_1 + \frac{1}{4}w_2$$

$$u_2 = -\frac{1}{4}w_1 + \frac{3}{4}w_2$$

$$X^{-1} = \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ \frac{1}{4} & \frac{3}{4} \end{pmatrix}$$

$$B = \begin{matrix} & X^{-1} & & A & & X \\ = & \frac{1}{4} & \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix} & \begin{pmatrix} 3 & 1 \\ -1 & 0 \end{pmatrix} \end{matrix}$$

$$= \frac{1}{4} \begin{pmatrix} 2 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ -1 & 0 \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} 5 & 2 \\ -7 & -2 \end{pmatrix}$$

$$= \begin{pmatrix} 5/4 & 1/2 \\ -7/4 & -1/2 \end{pmatrix} \quad \text{or maybe it should be } \begin{pmatrix} 5/4 & 3/4 \\ -7/4 & -1/4 \end{pmatrix}$$

Precursors:

$$\mathcal{N}(T) = \{v \in V : T(v) = 0\}$$

$$T(V) = \{w \in W : \exists v \in V \text{ s.t. } T(v) = w\}$$

Fundamental Theorem of Linear Transformations

Let $T \in L(V, W)$, $\dim_F V = n$, $\dim_F W = m$

$$\text{then } \dim_F \mathcal{N}(T) + \dim_F T(V) = \dim V$$

Proof $\mathcal{N}(T)$ subsp. of V . choose a basis $\{v_1, \dots, v_p\}$

extend this to a basis of V by $\{u_1, \dots, u_{n-p}\}$.

$T(v_i) = 0$. $\{T(u_1), \dots, T(u_{n-p})\}$ form a basis
 of $T(V)$. for one, they are generators
 since $w \in T(V)$ is $T(\lambda_1 v_1 + \dots + \lambda_p v_p + \mu_1 u_1 + \dots + \mu_{n-p} u_{n-p})$
 $= \sum_{i=1}^{n-p} \mu_i T(u_i)$. Second, they are lin. indep.

Since if $\sum \mu_i T(u_i) = 0$ then $T(\sum \mu_i u_i) = 0$

so $\sum \mu_i u_i \in \mathcal{N}(T)$ and so equals $\sum \lambda_i v_i$, so

$\sum \mu_i u_i - \sum \lambda_i v_i = 0$ but $\{v_i, u_i, \dots\}$ are a
 basis so $\lambda_i, \mu_i = 0$ (in particular, $\mu_i = 0$). ■

Cor: $T \in L(V, V)$ $\dim_F V = n$, then the following are equiv.

- (1) T invertible
- (2) T injective
- (3) T surjective

something to think about:

$$T \in L(V, W)$$

T injective iff $\exists L \in L(W, V)$ s.t. $L \circ T = I_V$

T surjective iff $\exists R \in L(W, V)$ s.t. $T \circ R = I_W$