**Blink / Sleep Monitor Project: Setup**

**With RPi Model 4 and 64 Bit OS (Lite)**

1. Prepare Raspberry Pi Imager to create OS Image in SD card.

* Download link: <https://www.raspberrypi.com/software/>

1. Download OS image.

* Go to <https://www.raspberrypi.com/software/>. On ‘Manually install OS image’ select ‘see all download options’
* On Raspberry Pi OS (64 bit), download the **Raspberry Pi OS Lite**

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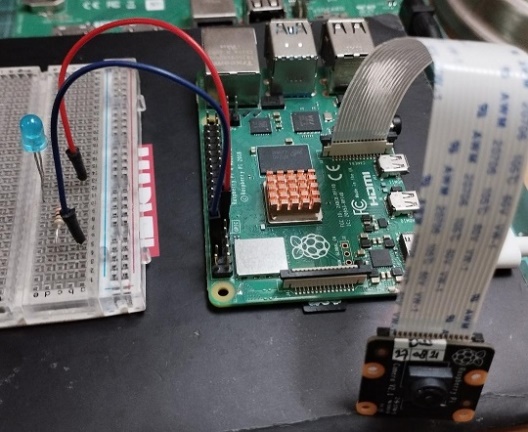
1. Create image on SD card using Pi Imager. In imager software:

* Erase the SD Card.
* Select the downloaded OS.
* Operating System: Select ‘Custom’ and select downloaded OS file (in zip format):
* Storage: Select appropriate SD Card.
* Press the setting icon.



* + - Set hostname (leave default or make a note of your custom hostname).
    - Enable ssh.
    - Check password authentication.
    - Set username and password for the existing Wifi (for automatic connect) after first boot.
    - Complete the rest (local setting, etc).
* Press ‘Write’ to write the OS image to SD card.

1. Setup the RPi 4, camera and GPIO components like the following. Note that the program asume the upright orientation of camera is with the cable connection at the top side.



1. Setup the GPIO components like the following. Refer to <https://pinout.xyz/>

* Connect the Resistor (around 220-330 ohm) to Cathode of the LED.
* Connect another end of resistor to RPi GPIO Pin 6 (GND).
* Anode of the LED to RPi Header Pin 11 (GPIO 17).

1. Install SD Card in RPi.

**Note: The next steps can be done directly on RPi using external monitor (connect HDMI) and keyboard or via terminal from host computer using SSH.**

1. Power-on the RPi. Connect the power to USB-C Connecter
2. If using SSH from host computer (skip this if using external monitor and keyboard)

* Open the terminal and type: ssh pi@raspberrypi
* Enter the pasword.

1. Enter config, type sudo raspi-config. Enter Interface Options >

* Interface Options > Legacy Camera > Enable camera and SSH
* Interface Options > SSH > Enable SSH
* Interface Options > I2C > Enable
* Reboot the Raspi and connect to RPi again using SSH as in Step 6.

1. Update and upgrade. Type:

sudo apt update (wait until complete) then sudo apt full-upgrade (wait until complete).

1. Install Git. Type:

sudo apt install git

1. Clone the Git repository in user root directory. Type:

git clone <https://github.com/vilerareza/sleep_awaker_pi.git>

1. Install PIP. Type:

sudo apt install python3-pip

1. Install Numpy. Type:

sudo apt-get install libatlas-base-dev

pip install numpy

1. Install OpenCV. Type:

pip install opencv-python-headless==4.6.0.66

sudo apt-get install libopenjp2-7

sudo apt-get install ffmpeg

sudo apt-get install libgtk-3-dev

1. Install Dlib. Type:

wget <https://github.com/prepkg/dlib-raspberrypi/releases/latest/download/dlib_64.deb>

sudo apt install -y ./dlib\_64.deb

sudo rm dlib\_64.deb

1. Install scipy. Type:

sudo apt-get install python3-scipy

1. Reboot the RPi. After sometime, enter the RPi using SSH again.

sudo reboot now

1. Transfer the face detector weight file to RPi

* Download the shape\_predictor\_68\_face\_landmarks.dat to your computer from

<https://drive.google.com/drive/folders/1A1MD7km-gClkIR8z_8pUJcV8gRpX-cZv?usp=sharing>

* Transfer the downloaded file from your computer to your RPi using SCP. Open new cmd terminal at your computer. Depending on the location of the downloaded file at your computer, type the following and enter the password when prompted:

scp "<path to the weight file at your computer>" pi@raspberrypi:/home/pi/

**for example:**

scp "E:/vscode/eye\_blink\_detection/shape\_predictor\_68\_face\_landmarks.dat" pi@raspberrypi:/home/pi/

**TEST RUN THE PROGRAM**

cd sleep\_awaker\_pi/

python start\_cam\_v2.py

**Possible Issues**

1. Checking available camera. Type:

vcgencmd get\_camera

Above command should output

**supported=1 detected=1, libcamera interfaces=0**

1. Camera not detected.

Type: sudo nano /boot/config.txt

Enter the following lines to the opened file:

dtoverlay=imx708

camera\_auto\_detect=0

When done, press:

* Ctrl+X
* Y
* Enter