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General Tips. This section covers the following topics: o How to Calibrate a Tool (TCP). o How to Calibrate a Reference Frame. o Tips for Collision Detection. o Tips Importing STEP or IGES files. o How to change the Simulation Speed. o How to calculate the Cycle Time of a program. Define a Tool (TCP) The robot Tool Center Point (or TCP) is the point used for robot positioning in any robot ...

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