

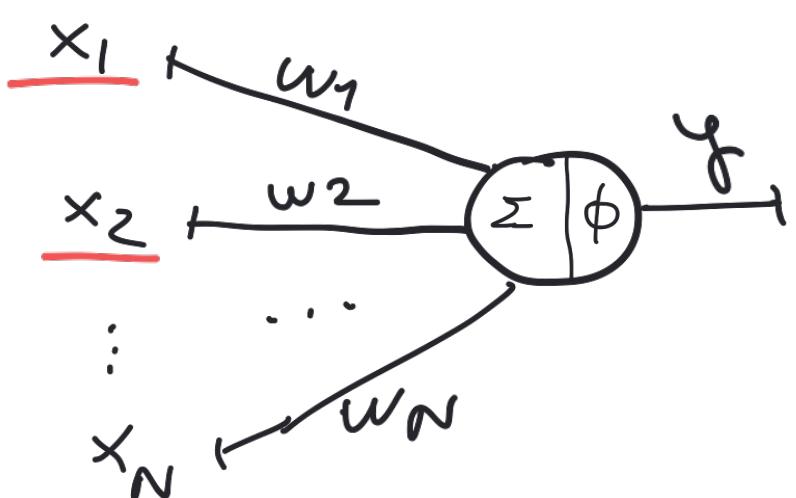
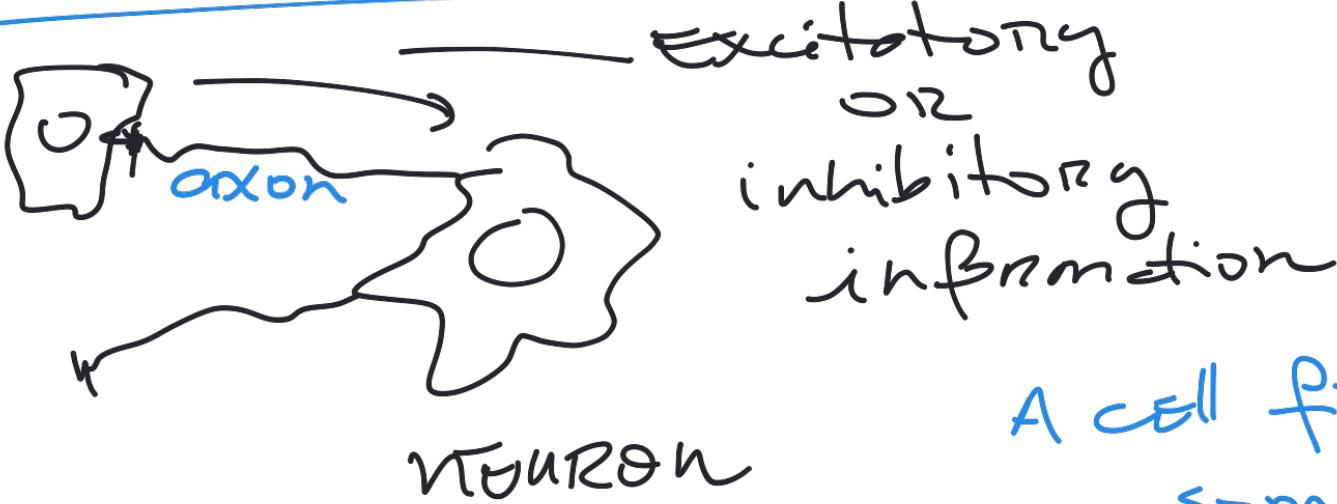
Linear Discriminant Function

- Fisher's Linear Discriminant
 - ↳ sometimes also referred to as Linear Discriminant Analysis
(LDA)

Assumptions fisher's Linear Discriminant:

- ① works best if classes are Gaussian-distributed.
- ② BUT it still works even if classes are overlapping.

The Perceptron Algorithm



A cell fires if passes
some threshold

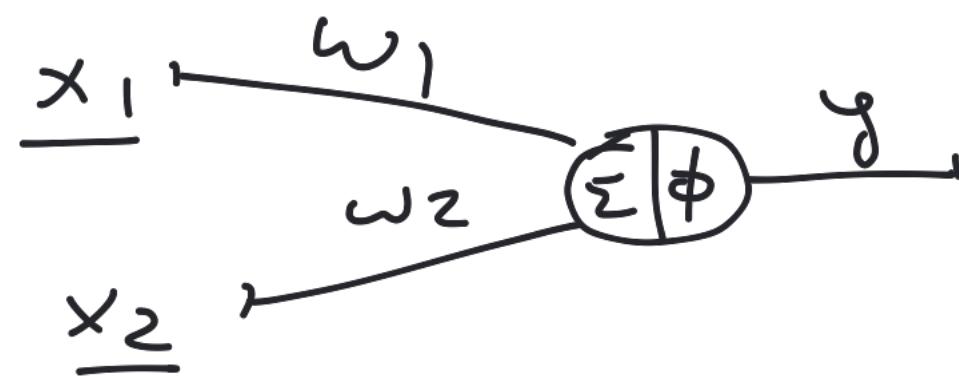
↳ we characterize
this with an

activation $\phi(x)$
function

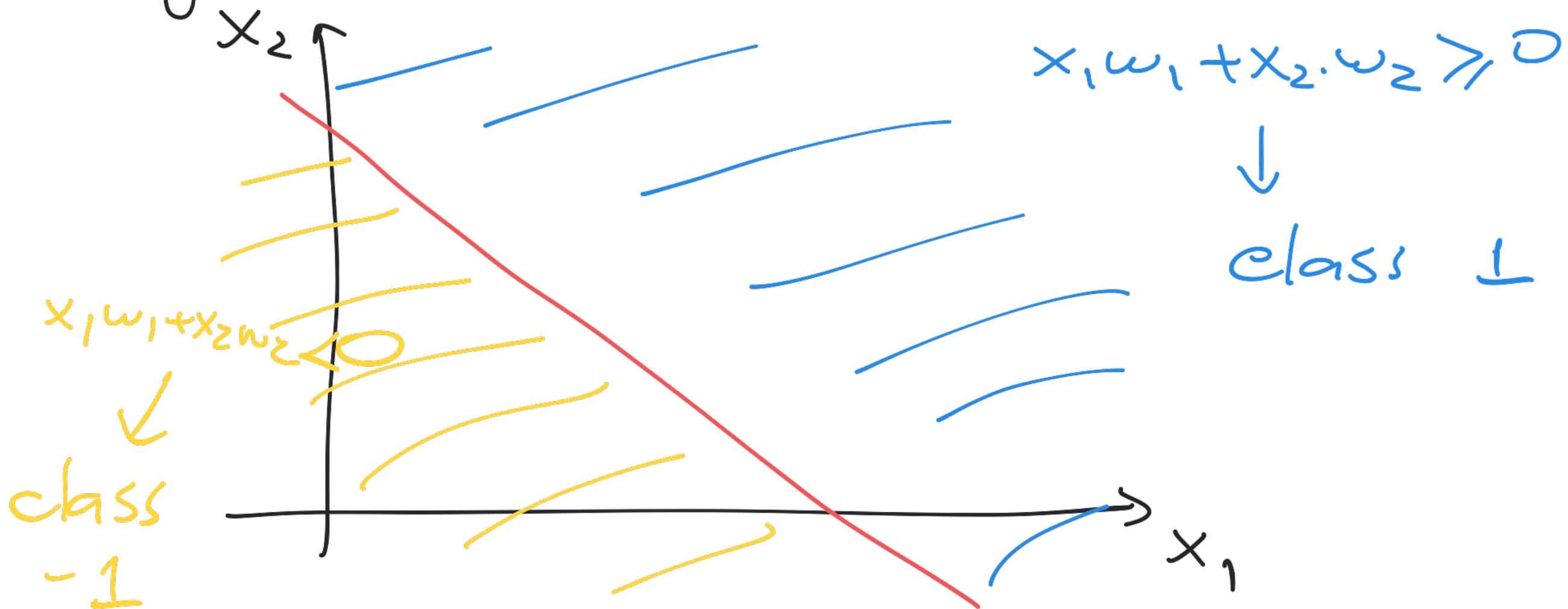
$$y = \phi\left(\sum_{i=1}^n w_i \cdot x_i\right)$$

$$\phi(x) = \begin{cases} 1, & x \geq 0 \\ 0, & x < 0 \end{cases}$$

1958
ADALINE

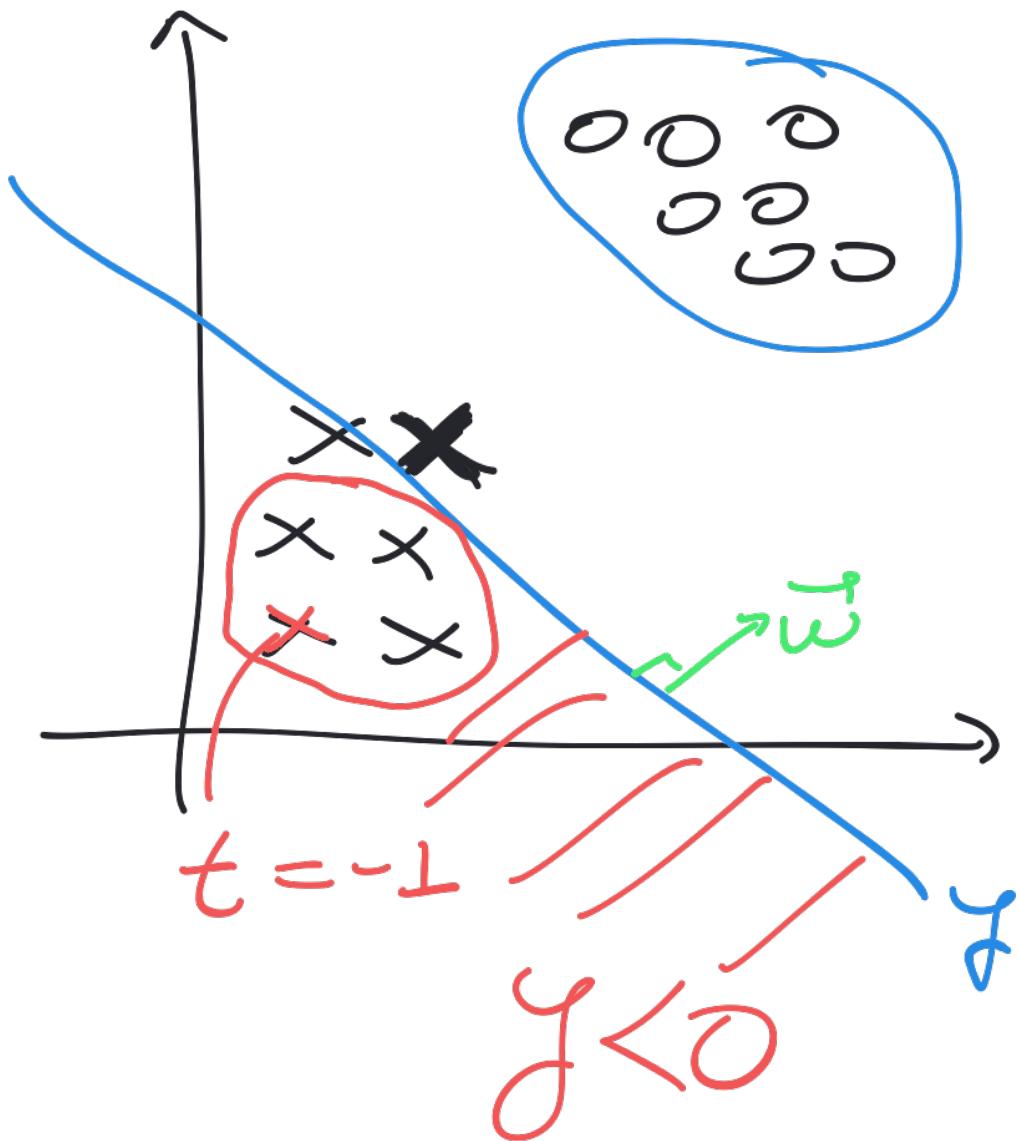


$$y = \phi(x_1 w_1 + x_2 w_2)$$



$$\{x_i, t_i\}_{i=1}^N$$

, $t_i \in \{-1, 1\}$
class labels



o-class
-1
x-class-1

$$y = \vec{w}^T x_i + b$$



$$(\vec{w}^T x_i + b) \cdot t_i > 0$$

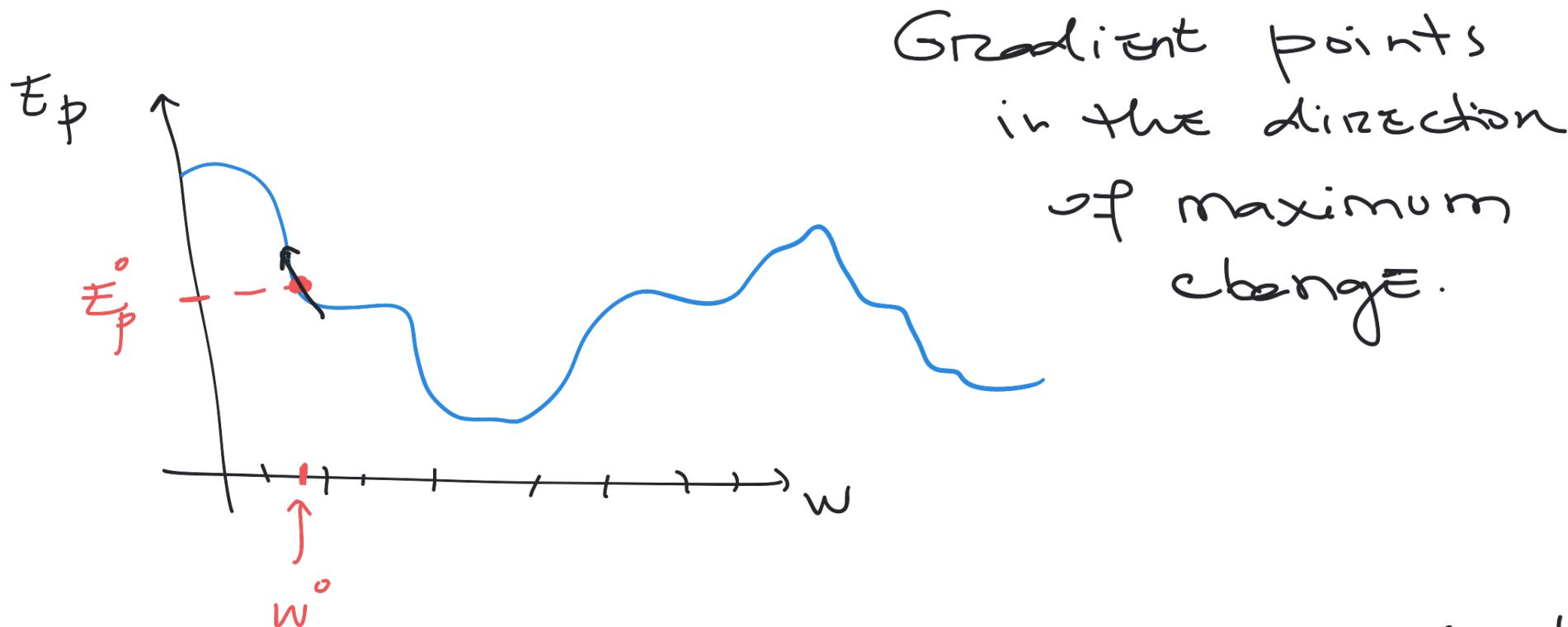
↳ this holds for all x_i that are correctly classified (on the right side of the boundary)

$$E_p(w, b) = - \sum_{n \in M} (w^T x_n + b) \cdot t_n$$

$M \equiv$ set of all misclassified points.

$$\boxed{\arg \min_{w, b} E_p(w, b)}$$

- ① First randomly select parameters w, b for the boundary.
- ② Compute the $E_p(w, b)$
- ③ Update w^{t+1} and b^{t+1} in the direction that minimizes E_p .



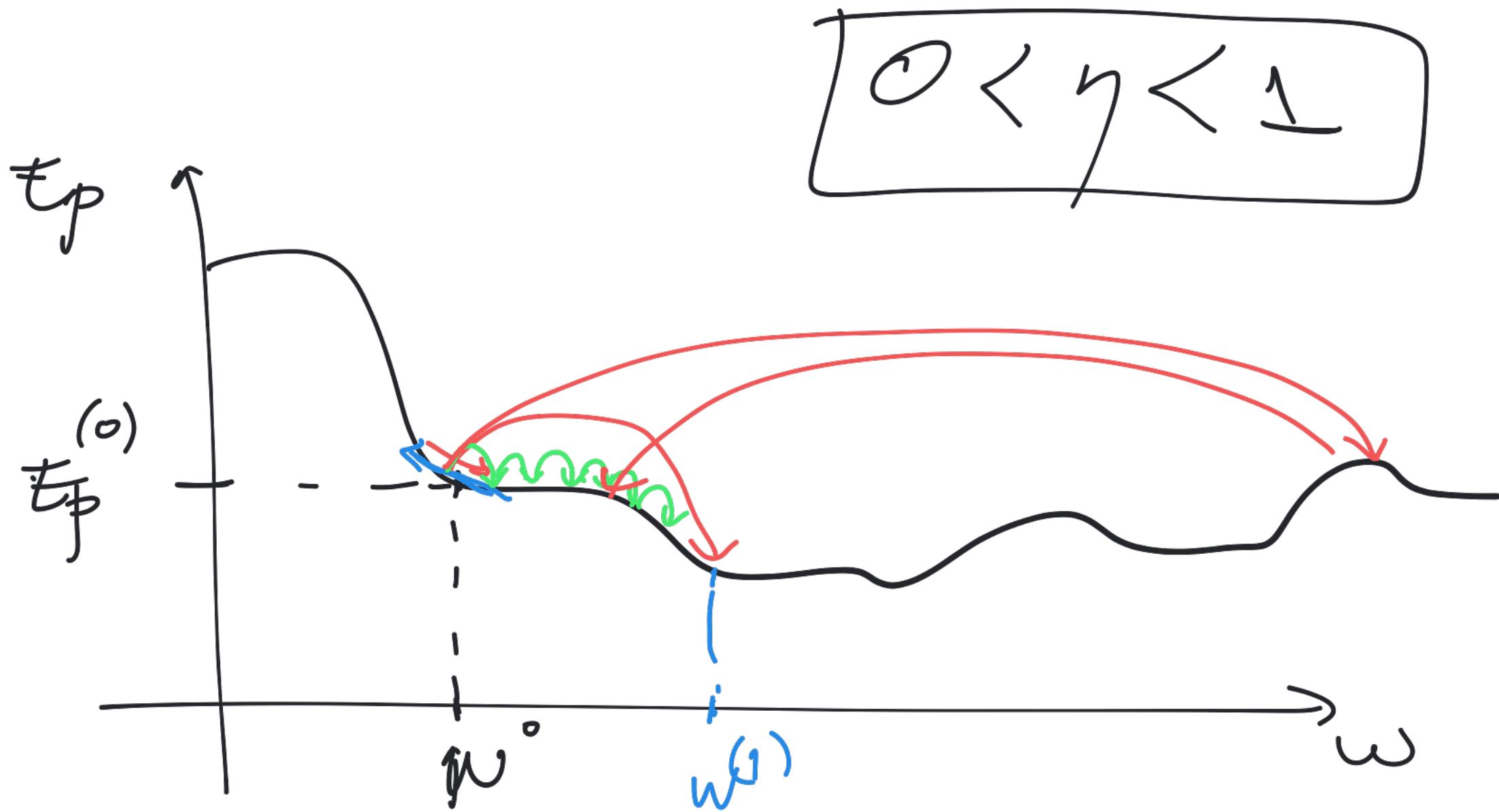
We want to move in the opposite direction of gradient.

$$w^{(t+1)} \leftarrow w^{(t)} - \gamma \frac{\partial E_p(w, b)}{\partial w}$$

$$b^{(t+1)} \leftarrow b^{(t)} - \gamma \cdot \frac{\partial E_p(w, b)}{\partial b}$$

γ = learning rate

controls the speed or the "step" size in the negative direction of gradient



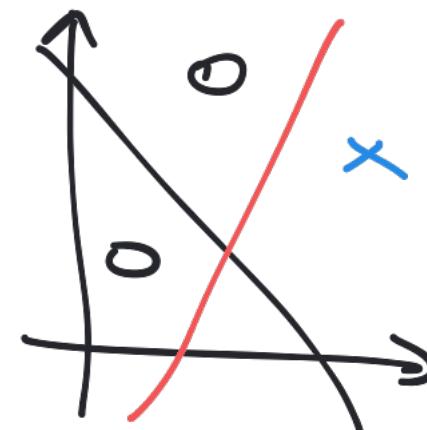
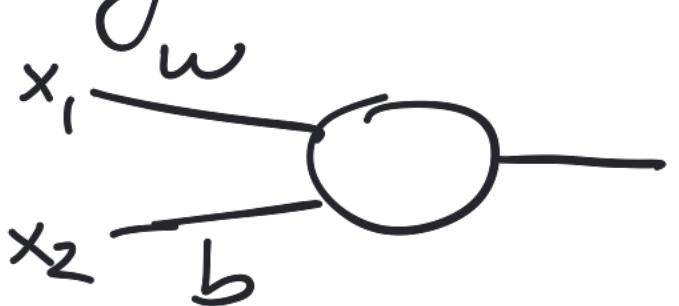
- if γ is large : it's faster but chaotic behavior.
- if γ is small : it takes longer to find a solution.

$$E_p(w, b) = - \sum_{n \in M} (\underline{w^T x_n} + b) \cdot \underline{t_n}$$

$$w^{(t+1)} \leftarrow w^{(t)} - \gamma \cdot \frac{\partial E_p(w, b)}{\partial w} = w^{(t)} + \gamma \cdot x_n \cdot t_n$$

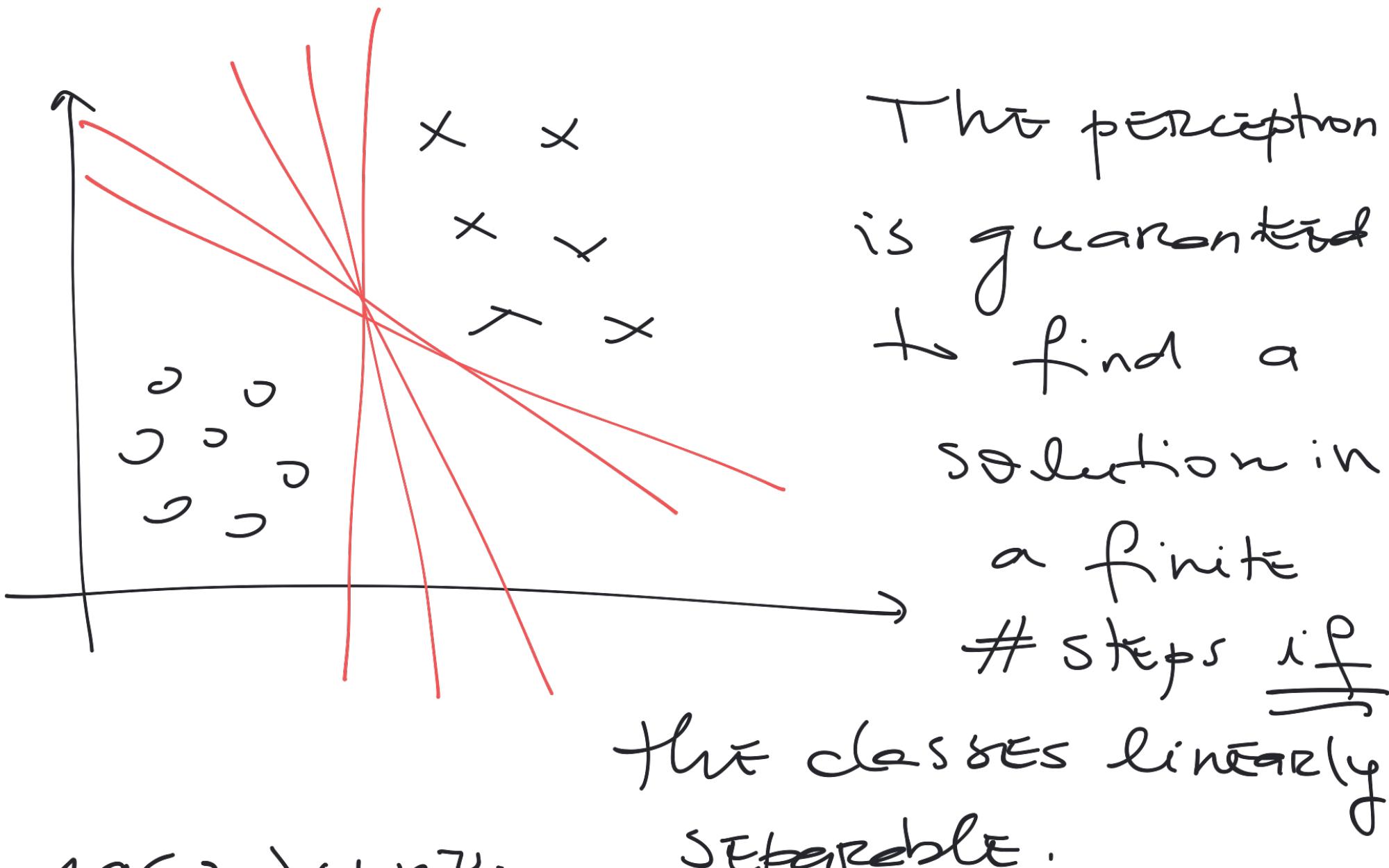
$$b^{(t+1)} \leftarrow b^{(t)} - \gamma \cdot \frac{\partial E_p(w, b)}{\partial b} = b^{(t)} + \gamma \cdot t_n$$

The perceptron updates the boundary using one sample at a time.



Online Update

If data is not linearly
separable, the perceptron
will not converge.



In 1963, Vapnik:

