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Digital Image Formation And Processing - Report

Abstract

Roosa Kuusivaara & Väinö-Waltteri Granat: Digital Image Formation And Processing - Report
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This report documents the work done in the Digital Image Formation And Processing assignment as a part of the Advanced signal processing laboratory course. In this assignment we familiarized ourselves with basics of digital image formation from raw sensor data as well as image processing.

Keywords: Image processing, Image formation.

The originality of this thesis has been checked using the Turnitin Originality Check service.

Contents

1	Intro	oduction	1
2	Methodology		2
	2.1	Overview of the pipeline	2
	2.2	Reading images and converting to doubles	2
	2.3	Image visualization and Bayer mosaic	2
	2.4	Sliding window	4
	2.5	Scatterplots and regression	5
	2.6	Transformation and reverse transformation	5
	2.7	DCT denoising	5
	2.8	Demosaicking	5
	2.9	White balancing	5
	2.10	Contrast and saturation correction	5
3	Resu	ılts	6
4	Cone	clusions	7

1 Introduction

In this report we describe our work done in the 'Digital Image Formation and Processing' laboratory assignment for the Advanced Signal Processing Laboratory course. In this assignment we implemented a basic raw image formation and processing pipeline in Matlab to construct RGB images from raw sensor data.

2 Methodology

In this section we will present our implementation of the image processing pipeline, by going over the main parts of the Matlab code as well as explaining the the decisions we took when requirements we ambigious.

2.1 Overview of the pipeline

Figure 2.1 shows the complete image processing and formation pipeline that we are going to introduce in this report. The following sections will go over the different parts of the pipeline. The pipeline takes in raw sensor data of Bayer arrays in RGGB format and produces RGB images. In addition to image formation the pipeline also performs focusing, white balancing and contrast and saturation correction.

2.2 Reading images and converting to doubles

The first part of the pipeline is loading the images (outoffocus.tiff and natural.tiff) using Matlab's imread function, and then converting the pixel values to double precision by using im2double function. The convertion ensure that pixel values are represented as floating-point numbers between 0 and 1.

```
1 % 1. Load image and convert to double
2 focus = imread('images/outoffocus.tiff');
3 focus = im2double(focus);
4
5 natural = imread('images/natural.tiff');
6 natural = im2double(natural);
```

2.3 Image visualization and Bayer mosaic

The second part starts with creating a figure with two subplots. The *imshow* function is used with [] to scale the pixel values automatically for better visualization. For illustrating the Bayer mosaic arrays the image is separated into its color channels (red, green 1, green 2 and blue). After separating the color channels, the next step is to create figures to illustrate the Bayer mosaic arrays for each color channel separately.

```
1 % 2. Visualize Images, Bayer mosaic array
2 % Define the block size
3 figure;
4 subplot(1,2,1); imshow(focus, []); title('out of focus image');
```

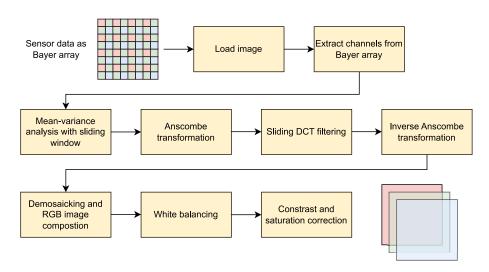


Figure 2.1 Our image processing and formation pipeline

```
subplot (1,2,2); imshow(natural, []); title ('natural');
6
7 % 3. Separe image into subchannels
  R_{-}focus = focus(1:2:end, 1:2:end);
8
   G1_{\text{focus}} = \text{focus} (1:2:\text{end}, 2:2:\text{end});
10 G2_{focus} = focus(2:2:end, 1:2:end);
   B_{-}focus = focus(2:2:end, 2:2:end);
11
12
13 R_{-}nat = natural (1:2:end, 1:2:end);
14 \text{ G1\_nat} = \text{natural}(1:2:\text{end}, 2:2:\text{end});
   G2_{nat} = natural(2:2:end, 1:2:end);
   B_{-}nat = natural (2:2:end, 2:2:end);
16
17
18
   % Illustrare the bayer array
19
20 % Plot channels
21 figure;
   subplot (2,2,1); imshow (R_focus, []); title ('Red');
   subplot (2,2,2); imshow (G1_focus, []); title ('Green 1');
23
   subplot(2,2,3); imshow(G2_focus, []); title('Green 2');
24
   subplot (2,2,4); imshow (B_focus, []); title ('Blue');
25
   sgtitle ("Out of focus image");
26
27
28
  figure;
   subplot (2,2,1); imshow (R_nat, []); title ('Red');
   subplot(2,2,2); imshow(G1\_nat, []); title('Green 1');
30
   subplot(2,2,3); imshow(G2\_nat, []); title('Green 2');
   subplot (2,2,4); imshow(B_nat, []); title('Blue');
32
```

```
33 sgtitle ("Natural image");
```

2.4 Sliding window

In this section we are analyzing each subchannel of the out-of-focus and natural images using a sliding window operator. For both natural image and out-of-focus image we are calling *calculateScatterPlot* function for each color channel.

The function defines a sliding window analysis using the *blockproc* function in Matlab. The window size is set to [2, 2], and *calculateMeanVar* function is defined to calculate the mean and variance for each window. The results are then reshaped to create scatter plots.

```
1
   % 4. Calculate scatter plots
   function [meanValues, varianceValues] = calculateScatterPlot(
      channel)
       % Define the window size for sliding window analysis
4
       windowSize = [2, 2];
6
       % Define a function to calculate mean and variance for each
          window
       calculateMeanVar = @(block\_struct) [mean(block\_struct.data]
8
           (:)), var(block_struct.data(:))];
9
10
       % Apply the sliding window operator using blockproc
       meanVarResults = blockproc(channel, windowSize,
11
          calculateMeanVar);
12
       % Extract mean and variance values
13
14
       meanValues = meanVarResults(:, 1);
15
       varianceValues = meanVarResults(:, 2);
16
17
       % Reshape the results for scatterplot creation
18
       meanValues = meanValues (:);
       varianceValues = varianceValues(:);
19
   end
20
```

2.5 Scatterplots and regression

In this part we calculate the regression lines for each subchannel using the calculateRegression function. Then, by using produceScatterPlot function we create scatter plots. [kesken]

2.6 Transformation and reverse transformation

2.7 DCT denoising

```
function [denoised] = DCTImageDenoising(image, lambda,
      transformBlockSize)
2
3
       % Create a custom function to be applied to each block
       fun = @(block_struct) idct2(thresholdDCT(block_struct.data,
4
          lambda));
5
       % Apply the function to each block
       denoised = blockproc(image, transformBlockSize, fun);
   end
8
9
   function denoised = thresholdDCT(input, lambda)
10
11
12
       % Apply DCT to the block
       dctBlock = dct2(input);
13
14
15
       % Threshold the DCT coefficients
       dctBlock(abs(dctBlock) < lambda) = 0;
16
       denoised = dctBlock;
17
18 end
```

2.8 Demosaicking

2.9 White balancing

2.10 Contrast and saturation correction

3 Results

In this section we will present the results from our image processing pipeline and also do some analysis on why we got the kinds of results that we did.

4 Conclusions