Statistics of a flexible polymer

Consider a flexible polymer chain in three dimensions. The chain is composed of consecutive straight segments, all of equal length l, each denoted by the vector \vec{R}_i , i = 1, ..., N. At segment joints, the two segments are free to equally rotate in any orientation, however, there is a correlation on the plane defined by the two segments

$$\langle \vec{R}_{i+1} \cdot \vec{R}_i \rangle = l^2 \cos \alpha,$$

where the constant α is the average angle between two consecutive segments.

1. Show that

$$\langle \vec{R}_{i+2} \cdot \vec{R}_i \rangle = l^2 \cos^2 \alpha.$$

2. Given that the end to end distance on the chain can be written as $\vec{R} = \sum_{i=1}^{N-1} \vec{R}_i$, show that,

$$\langle R^2 \rangle = (N-1)l^2 \left[\frac{1 + \cos \alpha}{1 - \cos \alpha} - \frac{2\cos \alpha}{N-1} \frac{1 - (\cos \alpha)^N}{(1 - \cos \alpha)^2} \right]$$

3. In the long chain limit, $N\gg 1$ and for small α , show that the average square end to end distance reduces to

$$\langle R^2 \rangle = 2Nll_p = (Nl/2l_p)(2l_p)^2,$$

by defining $l_p \approx 2l/\alpha^2$. This is precisely the result for a freely jointed chain of $Nl/2l_p$ segments of length $2l_p$. Provide an interpretation of this result.

$$\langle R^2 \rangle = (N-1)e^2 + e^2 \left[\sum_{i=1}^{N-1} \left(\sum_{j=1}^{i-1} (\omega_i \theta_i)^{i-j} + \sum_{j=i+1}^{N-1} (\omega_j \theta_j)^{i-j} \right) \right]$$

$$= (N-1)l + l^{2} \int_{i=1}^{2} \frac{1 - (40)t}{1 - 40} - (40)t -$$

$$|C|^{2} = (N-1)\ell^{2} + \ell^{2} (N-1)(\omega \theta - (\omega \theta)^{N-1})$$

$$\langle R^2 \rangle = (N-1)l \left\{ 1 + (N-1) \left(\omega_1 \theta - (\omega_1 \theta) \right) \right\}$$

$$1 - \omega_1 \theta$$

 $\langle R^{2} \rangle = (N-1)k^{2} + \frac{1}{1-\omega_{0}\theta}$ $\frac{1}{2}(\omega_{0}\theta)^{1-1} = \frac{1}{2}(\omega_{0}\theta) = 4\omega_{0} \times \frac{1-(\omega_{0}\theta)}{2}(\omega_{0}\theta) = 1$ $\frac{1}{j^{2}} = \frac{1}{k^{2}} = \frac{1-(\omega_{0}\theta)}{1-(\omega_{0}\theta)} = \frac{1}{2} = \frac{1-(\omega_{0}\theta)}{1-(\omega_{0}\theta)} = \frac{1-(\omega_{0}\theta)}{1-(\omega_{0}\theta)} = \frac{1-(\omega_{0}\theta)}{1-(\omega_{0}\theta)} = \frac{1}{2} = \frac{1-(\omega_{0}\theta)$