

some special matrices

① Diagonal matrix

Diagonal elements are non zero, rest are zeros
square matrix

Ex - $A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}_{2 \times 2}$

Properties

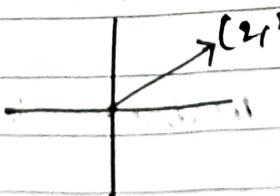
a) Powers $\rightarrow A^{100} = \begin{bmatrix} 1^{100} & 0 \\ 0 & 2^{100} \end{bmatrix}$

b) Eigen values: Diagonal values are eigen values

$$A = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}_{2 \times 2}$$

② Multiplication by vector:

When vector multiplied by diagonal matrix
the vector components will get scaled
by diagonal values

Ex  Vector $(2, 2)$

Multiply by $(2, 8) \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix}$

Vector $(2 \times 2, 4 \times 2) = (4, 8)$

d) Multiplication by diagonal matrix with diagonal matrix

$$\text{Ex} \rightarrow \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \times \begin{bmatrix} c & 0 \\ 0 & d \end{bmatrix}$$

$$= \begin{bmatrix} ac & 0 \\ 0 & bd \end{bmatrix}$$

② Orthogonal matrix -

- square matrix
- if matrix is orthogonal, then the vectors will be at 90° to each other
- Ex \rightarrow $\begin{bmatrix} a \\ c \end{bmatrix}, \begin{bmatrix} b \\ d \end{bmatrix} \therefore (a, c) \rightarrow \text{vector 1}$
 $\qquad\qquad\qquad (c, d) \rightarrow \text{vector 2}$
 - both vector will be at 90°
 - How to know?
 - When you dot product, then it will be zero
- $a \cdot b + c \cdot d = 0$ (dot product = 0)
- both vectors will be unit vectors
 i.e. $\sqrt{a^2 + c^2} = 1$ & $\sqrt{b^2 + d^2} = 1$
- Example of orthogonal matrix & checking the properties.

$$= \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}, \theta = 30^\circ$$

$$= \begin{bmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} = \begin{bmatrix} |a| & |b| \\ c & d \end{bmatrix} \quad v_1 \quad v_2$$

I Property

$$\Rightarrow a \cdot b + c \cdot d = 0$$

$$\frac{\sqrt{3}}{2} \times \frac{1}{2} - \frac{1}{2} \times \frac{\sqrt{3}}{2} = 0$$

II property

both are unit vectors

$$\Rightarrow \sqrt{a^2 + c^2} = 1 \text{ & } \sqrt{b^2 + d^2} = 1$$

$$\Rightarrow \sqrt{\left(\frac{\sqrt{3}}{2}\right)^2 + \left(-\frac{1}{2}\right)^2} = 1 \text{ & } \sqrt{\left(\frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2} = 1$$

Hence the given matrix is orthogonal

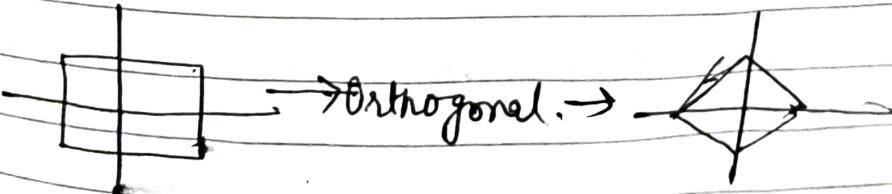
Properties of orthogonal

$$1) A^T = A^{-1}$$

2) When applied as linear transformation, it gives perfect rotation.

Ex when we use this orthogonal matrix ie $\begin{bmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$

it will give perfect rotation of $\theta = 30^\circ$



③ Symmetric matrix

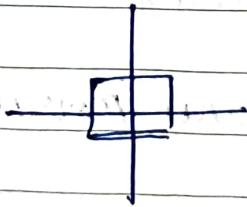
- square matrix whose transpose is same
 $\rightarrow \underline{A = A^T}$

$$\text{Ex} \rightarrow A = \begin{bmatrix} a & c \\ c & d \end{bmatrix} \rightarrow A^T = \begin{bmatrix} a & c \\ c & d \end{bmatrix}$$

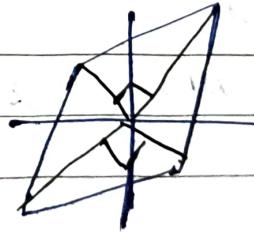
Properties

- 1) Eigen values of symmetric matrix are always real, not complex
- 2) Eigen vectors of symmetric matrix are always orthogonal
- Unlike, Diagonal & orthogonal matrix whose transformations are scaling and rotation, the transformation by symmetric is complex (at some side squish expand)

Ex



\rightarrow Symmetric matrix



- It is a mixture of transformations

Ex 2: Covariance matrix is symmetric matrix

EIGEN DECOMPOSITION

- Before that, you must understand matrix decomposition
- & Before that, you must know matrix composition.
- We have already studied that :-
 - Ex: we have 2 matrices & multiply

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} k & l \\ m & n \end{bmatrix}$$

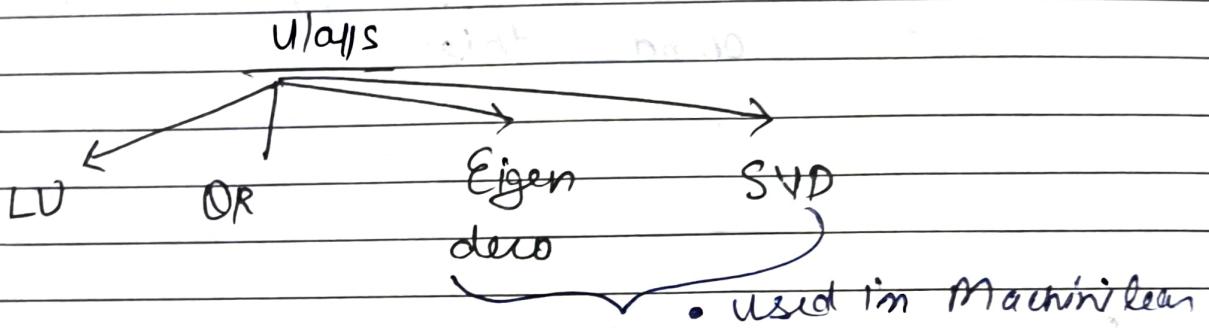
- Left \Rightarrow Right
- result right
- Our matrix made by first left matrix multiplied / applied then right left matrix applied

* Matrix decomposition

- We have complex matrix, we are decomposing into simpler matrix

• Ex: $D = A \cdot B \cdot C$

- famous ways for matrix decomposition



* Eigen Decomposition

- special type of matrix decomposition
- mathematical eqⁿ $\rightarrow A$ (matrix)
- 2 criterias for A
 - 1) Square matrix
 - 2) Diagonizable
- If these 2 criterias are true, then you can write A matrix as

$$\therefore A = V \Lambda V^{-1}$$

- V is a matrix whose columns are eigen vectors of A
- Λ is diagonal matrix whose entries are

eigen values of A

- V^{-1} is inverse of V

Ex • $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

- It's eigen values λ_1 & λ_2
- and its eigen vectors are :-

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \text{ & } \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}$$

- $A = V \Lambda V^{-1}$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = V \begin{bmatrix} x_1 & x_2 \\ y_1 & y_2 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} x_1 & x_2 \\ y_1 & y_2 \end{bmatrix}^{-1}$$

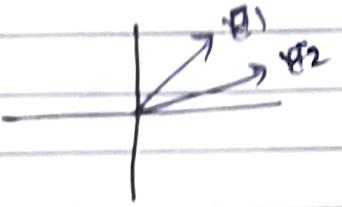
- Basically, you are decomposing A matrix into these 3 matrix, if given criteriae are true.

* What is diagonalize
($n \times n$)

- Matrix is diagnizable when it should have n linearly independent vectors
- Meaning: let's say we have 2×2 matrix, then it is diagnizable when the 2 eigen vectors ~~are~~ have different

direction.

Ex :



diagonizable



Non diagonalizable

- You have already studied this

We know eigen vector $\Rightarrow [A\vec{v} = \lambda\vec{v}]$

Let's say we have to eigen vector:-

$$\text{Q1. Eigen vector } 1 \rightarrow A\vec{v}_1 = \lambda_1 \vec{v}_1$$

$$\cdot \quad \cdot \quad \cdot \quad 2 \rightarrow A\vec{v}_2 = \lambda_2 \vec{v}_2$$

- Basically, you can write this together in matrix form.

$$[A\mathbf{v} = \mathbf{v}\Lambda]$$

where $\mathbf{v} = [\vec{v}_1 \quad \vec{v}_2]$ & $\mathbf{v}_1 = [v_1 \quad v_2], \mathbf{v}_2 = [v_3 \quad v_4]$

$$\mathbf{v} \Rightarrow \begin{bmatrix} x_1 & x_2 \\ y_1 & y_2 \end{bmatrix}$$

$\vec{v}_1 \quad \vec{v}_2$

$$\Lambda \Rightarrow \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

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$$\Rightarrow A\Lambda = V\Lambda$$

Multipplied with $\boxed{A \cdot A^{-1}}$

$$\Rightarrow \boxed{A = V\Lambda V^{-1}} \rightarrow \text{Eigen decomposition}$$

* What if that A is symmetric

- $A \rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix}$
 - square ✓
 - symmetric ✓
- Eqn still remain true $\rightarrow A = V\Lambda V^{-1}$
- But it is called spectral decomposition
- Specialities of components of A
 - $V \rightarrow$ is matrix of vectors, and vectors are orthogonal
 - $\Lambda \rightarrow$ is a diagonal matrix.
 - $V^{-1} \rightarrow$ Orthogonal matrix
- That means, the symmetric matrix is decomposed into orthogonal and diagonal matrix
- It means, that's why which defines the complex transformation of symmetric matrix

$$A = \underset{\text{Notation}}{\downarrow} V \underset{\text{Scaling}}{\Lambda} \underset{\text{Rotation}}{\uparrow V^{-1}}$$

- from left to right left to right
- from right to left

* Advantages of Eigen decomposition

Ex(1) An_nxn, (square matrix)

- You are tasked to find A^{1000}
- Multiply of matrix with itself is difficult
- Here, we can use eigen decomposition

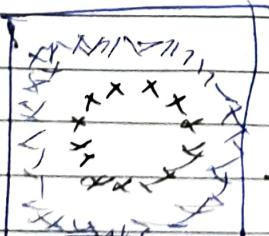
$$A = \cancel{A}^{-1} V \Lambda V^{-1}$$

$$\begin{aligned} A^{100} &= V \Lambda V^{-1} \times V \Lambda V^{-1} \times \dots \\ &= \underbrace{V \Lambda^{100} V^{-1}}_{\downarrow \text{easy to find}} \end{aligned}$$

- Conclusion - can be used for mathematical convenience.

* Kernel PCA

- combination of PCA + SVM
- solves the problem of PCA
- Kernel PCA, also works with non linear data, which PCA can't

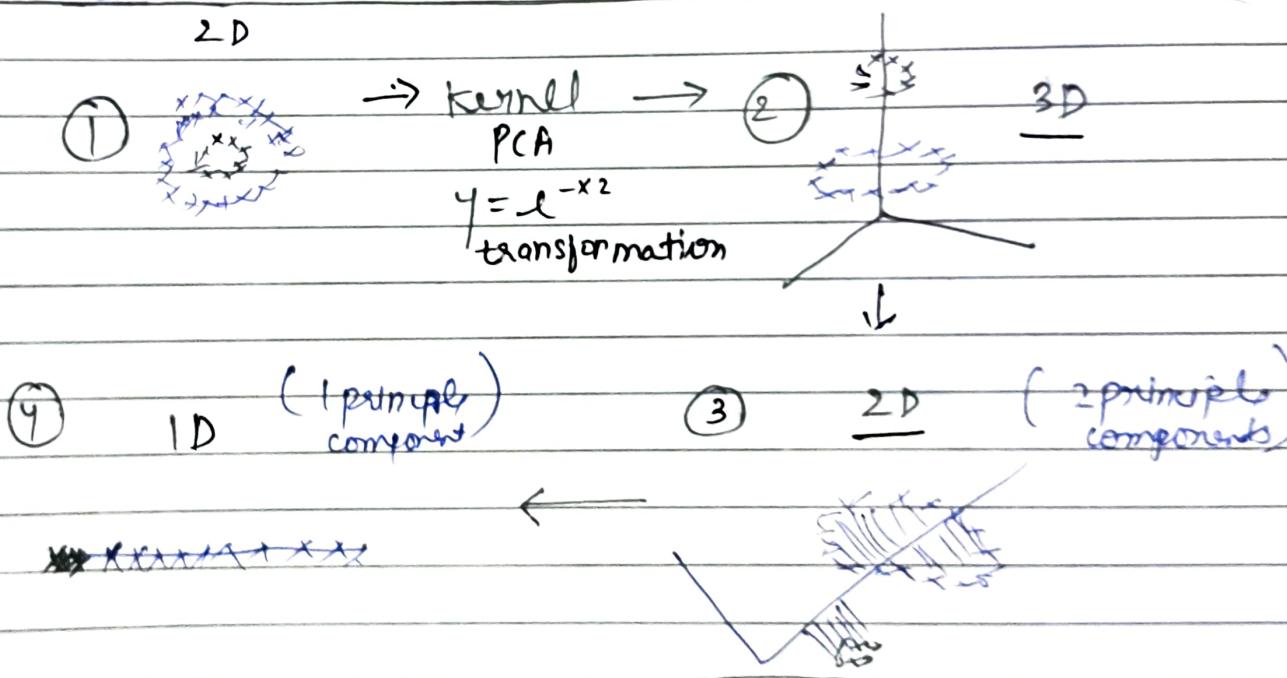


\Rightarrow Normal \Rightarrow ~~non-linear~~ \rightarrow
PCA

Original

- KernelPCA uses kernel trick of sum
- We will take 2D data to 3P then take to 1D
- On 2D, you apply mathematical fn which will take 2D to 3P, i.e $y = e^{-x^2}$
AND
- It will take up the central pts

Ex



- Above was a high level idea