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EDUCATION

Bharati Vidyapeeth's College of Engineering (GGSIPU)

Bachelor of Technology in Information Technology; GPA: 8.3/10.0

New Delhi, India Expected May 2021

Montfort Sr. Sec. School New Delhi, India

PCM, Computer Science; Percentage: 94.2 April 2003 - May 2017

SKILLS

• Languages: Python, C, C++, HTML, CSS, JavaScript Technologies: Arduino, Raspberry Pi, Git, GitHub, ROS

• Libraries: Flask, TensorFlow, Keras, Scikit-Learn, Numpy, Pandas, Jupyter, OpenCV, Matplotlib, TKinter

PROFESSIONAL EXPERIENCE

SUEZ India New Delhi, India

Software Development Intern

June 2019 - Present

- Talking Network: A utility tool to facilitate studying of pipeline diagrams by using voice feedback about parameters of pipelines.
 - * Worked on a utility tool to promote usability and make readability of blueprint of pipeline networks easier.
 - * Used Google Voice API to do text-to-speech conversion and fetched dynamically changing data in an Android App from a central server.

PROJECTS

- ROS_PacBOT (ongoing): A Project developed using the Robotics Operating System. The bots are simulated using the Gazebo Simulator and trained to play the Pacman game using Reinforcement Learning techniques.
- CraSOS: CraSOS is a standalone device with the capabilities of accident prevention, detection and recovery.
 - o Rider Rating on basis of speed of riding, braking intensity etc.
 - o Camera on helmet used to click pictures of overspeeding and oddly behaving cars and their number plates.
 - On collision detection, SOS message(containing location, medical info) generated and sent to helpline numbers and 3 chosen emergency contact numbers.
 - $\circ\,$ Information broadcasted using BLE Beacon & nearby notifications to call for all help possible.
- Real Time Object Detection: Real time all as well as custom object detection on live feed from a USB webcam achieving 15-20 fps.
- Who's Cuter: A Cats VS Dogs classifier implemented using CNN from scratch with a test set accuracy of 81% on a dataset of 8000 training images.
- Lane-Detection-App: A lane lines detection software to determine drivable areas for autonomous robots.

VOLUNTEER EXPERIENCE

Head, RNIS, Developer Student Clubs by Google Developers - BVP

New Delhi, India

Robotics and Intelligent Systems

Third: Hack@BVP 2.0

Winner: Robo Soccer

May 2019 - Present

- Heading a team of 10 technical executives and 300 student members
- Responsible for organising events and mentor workshops in the field of robotics and machine learning
- Organised and Mentored a Hardware Hackathon on Arduino Day 2018 with 40+ participating teams from 8 different colleges
- Judged an intra-college Ideathon event with 20+ participating teams.

ADDITIONAL EXPERIENCE & ACHIEVEMENTS

Finalist: SKYHACK August 2018

Qualified for the Finals among the top 5 teams nationally for the Hackathon organised by the Chhattisgarh Government in Raipur.

AIC@36Inc

Secured Third position at BVCOE's Hackathon organised by CSE department.

October 2018
CSE DEPT, BVCOE

Winner: Technovation at Innerve

October 2017, 2018

Won the first position at IGDTUW's Techfest in the Ideathon event for two years consecutively

IGDTUW October 2018

Second: Ideathon at InnovisionWon the second position at NSUT's Techfest in the Ideathon event.

E-Cell, NSUT

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2017

Won the first position in Robo Soccer at IGDTUW, MSIT, BVCOE, CIC.

IGDTUW, MSIT, BVCOE, CIC