

Chapter 4 roadmap

1. Introduction and Network Service Models
2. Routing Principles
3. Hierarchical Routing
4. The Internet (IP) Protocol
5. Routing in the Internet
6. What's Inside a Router
7. IPv6
8. Multicast Routing
9. Mobility



Routing

Routing protocol

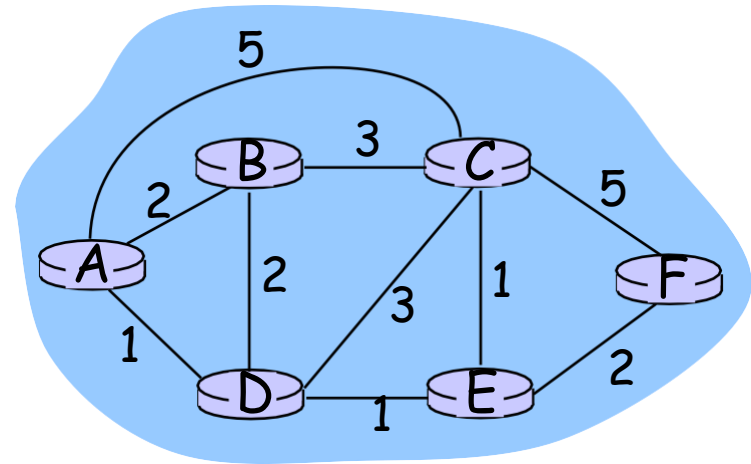
Goal: determine "good" path
(sequence of routers) thru
network from source to dest.

Graph abstraction for
routing algorithms:

graph nodes are
routers

graph edges are
physical links

link cost: delay, \$ cost,
or congestion level



"good" path:

typically means minimum
cost path

other def's possible



Routing Algorithm classification

Global or decentralized information?

Global:

all routers have complete topology, link cost info

"link state" algorithms

Decentralized:

router knows physically-connected neighbors, link costs to neighbors

iterative process of computation, exchange of info with neighbors

"distance vector" algorithms

Static or dynamic?

Static:

routes change slowly over time

Dynamic:

routes change more quickly

periodic update
in response to link cost changes



A Link-State Routing Algorithm

Dijkstra's algorithm

net topology, link costs
known to all nodes

accomplished via "link
state broadcast"

all nodes have same info
computes least cost paths
from one node ("source") to
all other nodes

gives **routing table** for
that node

iterative: after k
iterations, know least cost
path to k dest.'s

Notation:

$c(i,j)$: link cost from node i
to j . cost infinite if not
direct neighbors

$D(v)$: current value of cost
of path from source to
dest. v

$p(v)$: predecessor node
along path from source to
 v , that is next v

N : set of nodes whose
least cost path definitively
known



Dijsktra's Algorithm

1 **Initialization:**

2 $N = \{A\}$

3 for all nodes v

4 if v adjacent to A

5 then $D(v) = c(A,v)$

6 else $D(v) = \text{infinity}$

7

8 **Loop**

9 find w not in N such that $D(w)$ is a minimum

10 add w to N

11 update $D(v)$ for all v adjacent to w and not in N :

12 $D(v) = \min(D(v), D(w) + c(w,v))$

13 /* new cost to v is either old cost to v or known

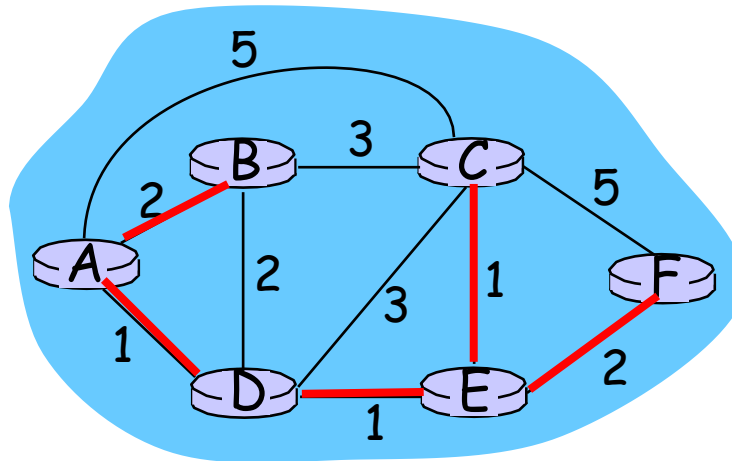
14 shortest path cost to w plus cost from w to v */

15 **until all nodes in N**

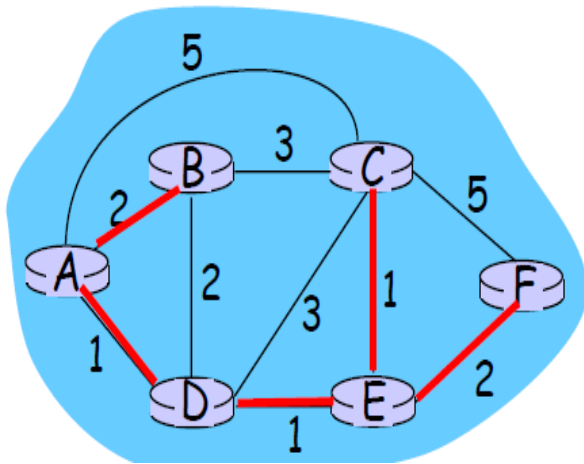


Dijkstra's algorithm: example

Step	start N	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
→ 0	A	2,A	5,A	1,A	infinity	infinity
→ 1	AD	2,A	4,D		2,D	infinity
→ 2	ADE	2,A	3,E			4,E
→ 3	ADEB		3,E			4,E
→ 4	ADEBC					4,E
5	ADEBCF					



Least Cost Path and forwarding Table for Node A



Destination	Link
B	(A,B)
C	(A, D)
D	(A, D)
E	(A, D)
F	(A, D)

