

Lecture 17: Follow the Leader and Follow the Regularized Leader

Lecturer: M. K. Hanawal

Scribes: Setu Hitesh Dave

Disclaimer: *These notes have not been subjected to the usual scrutiny reserved for formal publications. They may be distributed outside this class only with the permission of the Instructor.*

17.1 Recap

Online Mirror Descent

- For each round $t=1,2,3,\dots,T$
- Player ω_t , Environment C_t
- Player update, $\nabla\Phi(\tilde{\omega}_{t+1}) \leftarrow \nabla\Phi(\omega_t) - \eta\nabla\Phi(\omega_t)$
- $\omega_{t+1} \leftarrow \underset{k}{\text{Proj}}(\tilde{\omega}_{t+1})$

17.2 Fenchel - Legendre Conjugate

- If $f : \tau \rightarrow \mathbb{R}$, where C is a convex set and f is convex function, $C \subseteq \mathbb{R}^d$
- F-L conjugate is, $f^*(y) = \sup_{x \in C} (\langle y, x \rangle - f(x))$
- **Note:** Supremum are not always defined.

$$f^*(\nabla f(x)) = \langle \nabla f(x), x \rangle - f(x)$$

Young Inequality,

$$ab \leq \frac{a^p}{p} + \frac{b^q}{q}$$

$$a, b \geq 0, \frac{1}{p} + \frac{1}{q} = 1; a, b \in \mathbb{R}$$

For $p=q=2$, it boils down to $AM \geq GM$.

$$\text{i.e. } ab \leq \frac{a^2}{2} + \frac{b^2}{2}$$

take, $a^2 = c; b^2 = d$

- Convex combination : $\lambda x + (1 - \lambda)y$, $(1 - \lambda)$ is conjugate of λ

17.3 Holder's Inequality

$$\sum_{i=1}^{\infty} x_i y_i \leq \|x\| \|y\| \quad (17.1)$$

- Cauchy schwarz inequality can be obtained from this holder's inequality 17.1 Through the 17.1,

we are trying to emphasis the norm of dual space V^* by: $f^*(x) = \sup_{x \in V/\{0\}} \frac{f(x)}{\|x\|}$

17.4 Follow the leader

17.4.1 Regret for generalized cost function

- For round t , player $\omega_t = \arg \min_{\omega \in K} \sum_{s=1}^{t-1} C_s(\omega)$.
- Regret bound after revealing C_t ,

$$Regret(u, T) = \sum_{t=1}^T C_t(\omega_t) - \sum_{t=1}^T C_t(u) \quad (17.2)$$

Lemma 17.1 For any $u \in K$, $\sum_{t=1}^T (C_t(\omega_t) - C_t(u)) \leq \sum_{t=1}^T (C_t(\omega_t) - C_t(\omega_{t+1}))$,
 $\omega_{t+1} = \arg \min_{\omega} \sum_{s=1}^t C_s(\omega)$

- After rearranging the inequality in Lemma 17.1 $\sum_{t=1}^T C_t(\omega_{t+1}) \leq \sum_{t=1}^T C_t(u)$
- For $T=1$, $C_1(\omega_2) \leq C_1(u) \forall u, \omega_2 = \arg \min_{\omega} C_1(\omega)$.
- After induction on T , $\sum_{t=1}^{T-1} C_t(\omega_{t+1}) \leq \sum_{t=1}^{T-1} C_t(u)$.
- For a particular $u = \omega_{T+1}$, $\sum_{t=1}^{T-1} C_t(\omega_{t+1}) \leq \sum_{t=1}^{T-1} C_t(\omega_{T+1})$.
- Add $C_T(\omega_{T+1})$ on both side ,

$$\sum_{t=1}^T C_t(\omega_{t+1}) \leq \sum_{t=1}^T C_t(\omega_{T+1})$$

$$\sum_{t=1}^T C_t(\omega_{t+1}) \leq \sum_{t=1}^T C_t(u) \forall u$$

- Hence, $\omega_{T+1} = \arg \min_{\omega} \sum_{t=1}^T C_t(\omega)$

17.4.2 Quadratic cost function

$$C_t(\omega) = \frac{1}{2(t-1)\omega} \|\omega - z_t\|^2, \quad z_t \in K, \quad \|z_t\| \leq B \quad (17.3)$$

- By definition, $\omega_{T+1} = \arg \min_{\omega} \sum_{t=1}^T \frac{1}{t} \|\omega - z_t\|^2$

Claim 17.2

$$\omega_t = \frac{1}{t-1} \sum_{s=1}^{t-1} z_s \quad (17.4)$$

Proof: followed by the given equations

$$\begin{aligned} \sum_{t=1}^T \frac{1}{t} \|\omega - z_t\|^2 &= 0 \\ \sum_{s=1}^t (\omega - z_s) &= 0, \quad (t-1)\omega = \sum_s z_s \\ \omega &= \frac{1}{t-1} \sum_s z_s \end{aligned}$$

Using induction on T,

$$\begin{aligned} \Rightarrow \omega_{t+1} &= \frac{1}{t} \sum_{s=1}^t z_s \\ &= \frac{t-1}{t} \sum_{s=1}^{t-1} z_s \\ &= \frac{t-1}{t} \frac{1}{t-1} \sum_{s=1}^{t-1} z_s + \frac{1}{t} z_t \\ \omega_{t+1} &= \frac{t-1}{t} \omega_t + \frac{1}{t} z_t \end{aligned}$$

Now for given cost function,

$$\begin{aligned} \sum_{t=1}^T (C_t(\omega_t)) - (C_t(\omega_{t+1})) &= \frac{1}{2} \sum_{t=1}^T \|\omega_t - z_t\|^2 - \frac{1}{2} \sum_{t=1}^T \|\omega_{t+1} - z_t\|^2 \\ &= \frac{1}{2} \sum_{t=1}^T \|\omega_t - z_t\|^2 - \frac{1}{2} \sum_{t=1}^T \left\| \left(\frac{t-1}{t} \right) \omega_t - z_t + \frac{1}{t} z_t \right\|^2 \\ &= \frac{1}{2} \sum_{t=1}^T \|\omega_t - z_t\|^2 - \frac{1}{2} \sum_{t=1}^T \left(1 - \frac{1}{t} \right)^2 \|\omega_t - z_t\|^2 - \left(1 - \frac{1}{t} \right) z_t \\ &= \frac{1}{2} \sum_{t=1}^T \left(1 - \left(1 - \frac{1}{t} \right)^2 \right) \|\omega_t - z_t\|^2 \end{aligned}$$

$$\sum_{t=1}^T (C_t(\omega_t)) - (C_t(\omega_{t+1})) = \frac{1}{2} \sum_{t=1}^T (1 - (1 - \frac{1}{t})^2) \|\omega_t - z_t\|^2 \quad (17.5)$$

17.4.3 Cauchy schwarz inequality

$$\begin{aligned} \|\omega - z_t\|^2 &= \|\omega_t\|^2 + \|z_t\|^2 - 2 \langle \omega_t, z_t \rangle \\ &\leq \|\omega_t\|^2 + \|z_t\|^2 + 2 \|\omega_t\| \|z_t\| \end{aligned}$$

Using 17.5 , schwarz inequality and $\|z_t\| \leq B$,

$$\begin{aligned} \|\omega - z_t\|^2 &\leq \frac{1}{1} \sum_{t=1}^T (1 - 1 - \frac{1}{t} + \frac{2}{t}) (4B^2) \\ &\leq 2B^2 \sum_{t=1}^T \frac{2}{t} \\ &\leq 4B^2 (1 + \log(T)) \end{aligned}$$

Corollary 17.3 Consider running FTL on an Online Quadratic Optimization problem with $S = R^d$ and let $B = \max z_t$. Then, the regret of FTL with respect to all vectors $u \in R^d$ is at most $4B^2 (\log(T) + 1)$

17.5 Follow the regularized leader(FTRL)

- Player at t round, $\omega_t = \arg \min_{\omega \in K} \sum_{s=1}^T C_s(\omega) + \Psi(\omega)$
- $\Psi(\omega)$ is regularized weighted scalar with η
- Environment chooses $C_t = \langle \omega_t, z_t \rangle$
- Player chooses, $\Psi(\omega) = \frac{1}{2\eta} \|\omega\|^2$.

Theorem 17.4 Consider running FoReL on a sequence of linear functions, $f_t(\omega) = \langle \omega, z_t \rangle$ for all t with $S = R^d$, and with the regularizer $r(\omega) = \frac{1}{2\eta} \|\omega\|^2$, which yields the predictions given in 17.6

Then, for all u we have

$$R_{FTRL}(u, T) \leq \frac{1}{2\eta} \|u\|^2 + \frac{\eta}{2} \sum_{t=1}^T \|z_t\|^2, \quad \eta = \frac{u}{\sqrt[3]{T} B} \quad (17.6)$$

- When $\eta = \frac{u}{\sqrt[3]{T} B}$, Regret as per 17.6 will be bounded by $\sqrt[3]{T} B u$
- Trying to convert FTRL to FTL, for $t \geq 1$ and round $t = 0$, $\omega_0 = \arg \min_u \Psi(u)$

- For $t \geq 1$, environment reveals C_t , $\omega_t = \arg \min_{\omega} \Psi(\omega) + \sum_{s=1}^{t-1} C_s(\omega)$
- For FTL, $\sum_{t=1}^T (C_t(\omega_t) - C_t(u)) \leq \sum_{t=1}^T (C_t(\omega_t) - C_t(\omega_{t+1}))$

For FTRL,

$$\begin{aligned} \Psi(\omega_0) - \Psi(u) + \sum_{t=1}^T (C_t(\omega_t) - C_t(u)) &\leq \sum_{t=1}^T (C_t(\omega_t) - C_t(\omega_{t+1})) + \Psi(\omega_0) - \Psi(\omega_1) \\ \sum_{t=1}^T (C_t(\omega_t) - C_t(u)) &\leq \sum_{t=1}^T (C_t(\omega_t) - C_t(\omega_{t+1})) + \Psi(u) - \Psi(\omega_1) \end{aligned}$$

- Now, $\Psi(\omega) = \frac{1}{2\eta} \|\omega_1\|^2 \geq 0$

$$\sum_{t=1}^T (C_t(\omega_t) - C_t(\omega_{t+1})) + \Psi(u) - \Psi(\omega_1) \leq \frac{1}{2\eta} \|u\|^2 + \sum_{t=1}^T (C_t(\omega_t) - C_t(\omega_{t+1})) \quad (17.7)$$

$$\begin{aligned} C_t(\omega_t) - C_t(\omega_{t+1}) &= \langle \omega_t, z_t \rangle - \langle \omega_{t+1}, z_t \rangle \\ &= \langle \omega_t - \omega_{t+1}, z_t \rangle \\ &\leq \|\omega_t - \omega_{t+1}\| \|z_t\| \\ &\leq \eta \|z_t\| \|z_t\|, \quad \eta \|z_t\| = \|\omega_t - \omega_{t+1}\| \end{aligned}$$

- In FTL algorithm, $C_t(\omega) = \langle \omega_t, z_t \rangle$

$$\begin{aligned} \omega_t &= \arg \min_{\omega} \sum_{s=1}^{t-1} C_s(\omega) \\ &= \arg \min_{\omega} \sum_{s=1}^{t-1} \langle \omega, z_s \rangle \end{aligned}$$

- $\omega_t = \text{Proj}_k [-\eta \sum_{s=1}^{t-1} z_s]$, $\omega_{t+1} = \text{Proj}_k [-\eta \sum_{s=1}^t z_s]$
- Using inequality, $\|\text{Proj}_k(u) - \text{Proj}_k(v)\| \leq \|u - v\|$

$$\begin{aligned} \|\omega_t - \omega_{t+1}\| &= \|\text{Proj}_k [-\eta \sum_{s=1}^{t-1} z_s] - \text{Proj}_k [-\eta \sum_{s=1}^t z_s]\| \\ &\leq \|\eta \sum_{s=1}^{t-1} z_s - \eta \sum_{s=1}^t z_s\| \\ &= \eta \|z_t\| \end{aligned}$$

Differentiate $\omega_t = \arg \min_{\omega \in K} \sum_{s=1}^T C_s(\omega) + \Psi(\omega)$ w.r.t ω ,

$$\frac{1}{\eta} \omega + \sum_{s=1}^{t-1} z_s = 0$$

$$\omega = -\eta \sum_{s=1}^{t-1} z_s$$

$$\omega = \underset{k}{Proj}[-\eta \sum_{s=1}^{t-1} z_s]$$

- This is called a lazy projection since we don't project the iterates t but only project when we need to make a prediction. This is also called Nesterov's Dual Averaging algorithm.