Answer



Lena.bmp



Robert's Operator Thresholds:25:



Prewitt's Edge Detector Thresholds:100



Sobel's Edge Detector Thresholds:100:



Frei and Chen's Gradient Operator Thresholds:100



Kirsch's Compass Operator Thresholds:300



Robinson's Compass Operator Thresholds:100



Nevatia-Babu 5x5 Operator Thresholds:15000

Description& Algorithm

Implement following edge detectors with thresholds:

(a) Robert's Operator: 25

Roberts operators: two 2x2 masks to calculate gradient

$$f'(x) = \lim_{\Delta x \to 0} \frac{f(x + \Delta x) - f(x)}{\Delta x}$$



$$f'(x) \approx f(x+1) - f(x)$$

Figure 7.21 Masks used for the Roberts operator

gradient magnitude:
$$\sqrt{r_1^2+r_2^2}$$

Where r_1 , r_2 are values from first, second masks respectively.

(b) Prewitt's Edge Detector: 100

Prewitt edge detector: two 3x3 masks in row, column directions.







Figure 7.22 Prewitt edge detector masks.

Gradient magnitude: $g = \sqrt{p_1^2 + p_2^2}$

Gradient direction: $\theta = arctan(p_1/p_2)$ clockwise w.r.t. column axis Where p_1 , p_2 are values from first, second masks respectively.

(c) Sobel's Edge Detector: 100

Sobel edge detector: two 3x3 masks in row, column directions.





Figure 7.23 Sobel edge detector masks.

Gradient magnitude: $g = \sqrt{s_1^2 + s_2^2}$

Gradient direction: $\theta = arctan(s_1/s_2)$ clockwise w.r.t. column axis Where s_1 , s_2 are values from first, second masks respectively.

(d) Frei and Chen's Gradient Operator: 100

Frei and Chen edge detector: two in a set of nine orthogonal masks (3×3) .





Figure 7.24 Frei and Chen gradient masks.

Gradient magnitude: $g = \sqrt{f_1^2 + f_2^2}$

Gradient direction: $\theta = arctan(f_1/f_2)$ clockwise w.r.t. column axis Where f_1 , f_2 are values from first, second masks respectively.

(e) Kirsch's Compass Operator: 300

Kirsch edge detector: set of eight compass template edge

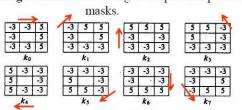


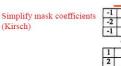
Figure 7.25 Kirsch compass masks.

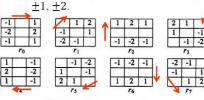
e: $g = \max_{n \to -0.7} k_n$ compass

Gradient magnitude: $g = \max_{n,n=0,...,7} k_n$ Gradient direction: $\theta = 45^{\circ}$ argmax k_n

(f) Robinson's Compass Operator: 100

Robinson edge detector: compass template mask set with only 0,





Done by only four masks since negation of each mask is also a mask. Gradient magnitude and direction same as Kirsch operator.

(g) Nevatia-Babu 5x5 Operator: 15000

Nevatia and Babu: set of six 5x5 compass template masks.

						-	-		
100	100	100	100	100	100	100	100	100	100
100	100	100	100	100	100	100	100	78	-32
0	0	0	0	0	100	92	Q	-92	-100
100	-100	-100	-100	-100	32	-78	-100	-100	-100
100	-100	-100	-100	-100	-100	-100	-100	-100	-100
		0°					30°		
100	100	100	32	-100	-100	-100	0	100	100
100	100	92	-78	-100	-100	-100	0	100	100
100	100	0	-100	-100	-100	-100-	0	100	100
100	78	-92	-100	-100	-100	-100	0	100	100
100	-32	-100	-100	-100	-100	-100	0	100	100
		60°				NACCE OF STREET	-90°		
-100	32	100	100	100	100	100	100	100	100
-100	-78	92	100	100	-32	78	100	100	100
-100	-100	-5	100	100	-100	-92	10	92	100
-100	-100	-92	78	100	-100	-100	/100	-78	32
-100	-100	-100	-32	100	-100	-100	-100	-100	-100
-60°					-30°				

Homework 9

R08921005 黃國郡

Code description

本次作業使用 python3.7,IDE 使用 Spyder

- (a) Main function:
 - 1. 先建立好每一種會用到 neighbor(2*2,3*3,5*5)
 - 2. 將 lena 當作 input 給每一個 operator
 - 3. 將每個 output 存起來

```
215 if __name__ == '__main__':
    neighbor_2 = createNeighbor(1, 2)
    neighbor_5 = createNeighbor(-1, *)
    neighbor_5 = createNeighbor(-2, *)

220    lena = cv2.imread('lena.bmp', cv2.IMREAD_GRAYSCALE)

221    robert = robert_operator(lena, 2)

222    cv2.imwrite('Robert.bmp', robert)

224

225    prewitt = prewitt_operator(lena, 100)

226    cv2.imwrite('Prewitt.bmp', prewitt)

227

228    sobel = sobel_operator(lena, 100)

229    cv2.imwrite('Sobel.bmp', sobel)

230    frei_chen = frei_chen_operator(lena, 100)

231    frei_chen = frei_chen_operator(lena, 100)

232    cv2.imwrite('Frei_and_Chen.bmp', frei_chen)

233

234    kirsch = kirsch_operator(lena, 100)

235    cv2.imwrite('Kirsch.bmp', kirsch)

236

237    robinson = robinson_operator(lena, 100)

238    cv2.imwrite('Robinson.bmp', robinson)

240    nevatia_babu = nevatia_babu_operator(lena, 1000)

241    cv2.imwrite('Nevatia-Babu.bmp', nevatia_babu)
```

(b) createNeighbor:

給定上下屆,就可以取出區塊的位置標號

```
13 def createNeighbor(start, end):
14     x = list(range(start, end))
15     return list(itertools.product(x, repeat=2))
```

(c) Robert:

1.每個 pixel 的 neighbor 對應 2*2 的

mask ,

- 2.乘上 mask 上的值並加總
- 3.最後 mask 的值分別平方開根號
- 4.得 gradient magnitude。
- 5.if magnitude < threshold →改成 255

```
18 def robert_operator(img, threshold):
         r, c = img.shape
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        robert_img = np.zeros(img.shape, dtype=np.uint8)
        r1_mask = [-1, 0, 0, r2_mask = [0, -1, 1,
                          ge(r):
              for j in r
                   candidate = []
                   for m, n in neighbor_2:
                               <= i+m < r and 0 <= j+n < c:
                              candidate.append(img[i+m][j+n])
                              candidate.append(0)
                   r1 =
                   r2 =
                   for k in range(len(candidate)):
    r1 += int(candidate[k]) * r1_mask[k]
    r2 += int(candidate[k]) * r2_mask[k]
                   value = math.sqrt((r1**2) + (r2**2))
                   if (value < threshold):</pre>
                        robert_img[i][j] =
         return robert_img
```

- (d) Prewitt · Sobel · Frei and Chen:
 - 1. 不同於 Robert's operator 的地方方在於這三個是用 3*3 的 mask 而 Robert's operator 是用 2*2 的 mask
 - 2. 這三個 operator 彼此之間 mask 權重不同,可以得到不同的結果。

```
00 def frei_chen_operator(img, threshold):
       r, c = img.shape
      frei_chen_img = np.zeros(img.shape, dtype=np.uint8)
      number = math.sqrt(2)
      f1_{mask} = [-1, -number, -1,
                    l, number,
      f2_{mask} = [-1, 1]
                   -number, 0, number,
      for i in range(r):
    for j in range(c):
                candidate = []
                for m, n in neighbor_3:
                        0 <= i+m < r and 0 <= j+n < c:</pre>
                         candidate.append(img[i+m][j+n])
                         candidate.append(0)
                f1 =
                f2 =
                for k in range(len(candidate)):
    f1 += int(candidate[k]) * f1_mask[k]
                     f2 += int(candidate[k]) * f2_mask[k]
                value = math.sqrt((f1**2) + (f2**2))
if (value < threshold):</pre>
                     frei_chen_img[i][j] =
      return frei_chen_img
```

```
prewitt_operator(img, threshold):
                                                           66 def sobel_operator(img, threshold):
r, c = img.shape
                                                                  r, c = img.shape
prewitt_img = np.zeros(img.shape, dtype=np.uint8)
                                                                  sobel_img = np.zeros(img.shape, dtype=np.uint8)
p1_mask = [-1, -1, -1, 0, 0,
                                                                  s1_mask = [-1, -2, -1, 0, 0, 0, s2_mask = [-1, 0, 1, -2, 0, 2, for i in range(r):
p2_mask = [-1, 0, 1
for i in range(r):
     for j in range(c):
                                                                       for j in range(c):
         candidate = []
                                                                           candidate = []
         for m, n in neighbor_3:
                                                                            for m, n in neighbor_3:
                  0 <= i+m < r and 0 <= j+n < c:</pre>
                                                                                     <= i+m < r and 0 <= j+n < c:
                  candidate.append(img[i+m][j+n])
                                                                                     candidate.append(img[i+m][j+n])
                  candidate.append(0)
                                                                                    candidate.append(0)
         p1 =
                                                                           s1 =
         p2 =
                                                                           s2 =
         for k in range(len(candidate)):
                                                                           for k in range(len(candidate)):
                                                                                s1 += int(candidate[k]) * s1_mask[k]
s2 += int(candidate[k]) * s2_mask[k]
              p1 += int(candidate[k]) * p1_mask[k]
              p2 += int(candidate[k]) * p2_mask[k]
         value = math.sqrt((p1**2) + (p2**2))
                                                                           value = math.sqrt((s1**2) + (s2**2))
                                                                            if (value < threshold):</pre>
         if (value < threshold):</pre>
                                                                                sobel_img[i][j] =
              prewitt_img[i][j] =
return prewitt_img
```

(e) Kirsch \ Robinson:

- 1. 用 3*3 的 mask 來做 edge detection
- 2. 用 8 個 3*3 的 mask, 每個 mask 罩在每個 pixel 上都會有 gradient magnitude
- 3. 取 max(gradient magnitude) · 和 threshold 做比較來來決定 pixel 值
- 4. <threshold 設 255

(f) Nevatia and Babu:

- 1. 用 6 個 5*5 的 mask 找出哪個 mask 對該 pixel 值有最大的 gradient magnitude
- 2. 拿該 magnitude 去和 threshold 做比較,
- 3. < threshold 設 255