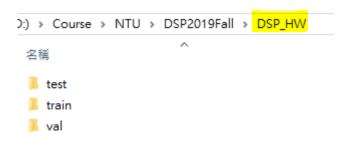
# DSP2019 FP r08921005 黄國郡

Explain how to execute program clearly

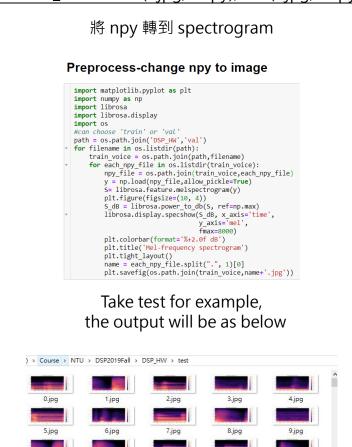
The all source code are in r08921005.ipynb,

TA can just open it, and realize what I do.



The important will be described as below. The architecture of my program in folder:

DSP\_HW->train(\*.jpg, \*.npy), test(\*.jpg, \*.npy), val(\*.jpg, \*.npy) ()→is the content in folder



# Load model def load\_model(model,filename): model.load\_state\_dict(torch.load(filename)) return model net = Net(num\_classes=len(traindata.classes)) # initialize your network net = load\_model(net,"weight.pth") # whether to use GPU or not? device = 'cpu' if torch.cuda.is\_available(): device = 'cuda' else: device = 'cpu' print("use",device,"now!") net.to(device) Evaluate on validation data net.eval() correct = 0 with torch.no\_grad(): for batch\_idx, (data, target) in enumerate(valloader): data = data.to(device) target = target.to(device) output = net(data) pred = output.data.max(1, keepdim=True)[1]

In this part, we can load the model which we trained before, the upper code just take "weight.pth" for example.

Then, we can load the model to validate the \*jpg in val to output is validation accuracy.

correct += pred.eq(target.data.view\_as(pred)).sum()
acc = correct.item() / len(valloader.dataset)
print("Validation Classification Accuracy: %f"%(acc))

#### Put result in dictionary type and write in csv file

```
In []: # Testing
    net.eval()
    result = {}
    import collections
    def sortedDictValues(adict):
        keys = adict.keys()
        keys.sort()
        return [dict[key] for key in keys]

with torch.no_grad():
    for idx, (data,) in enumerate(testloader):
        data = data.to(device)
        target = target.to(device)
        output = net(data)
        pred_idx = output.data.max(1, keepdim=True)[1]
        pred_class = idx_to_class[pred_idx.cpu().numpy()[0][0]]
        index = os.path.split(testlist[idx])[1][:-4]
        result[int(index)] = classes2label[pred_class]
        result = dict(sorted(result.items()))
```

#### Write the result to csv

```
In []: import csv
with open('2019_12_07.csv', 'w') as csvfile:
    fieldnames = ['id', 'category']
    writer = csv.DictWriter(csvfile, fieldnames=fieldnames, lineterminator = '\n')
    writer.writeheader()
    for key in result.keys():
        csvfile.write("%s,%s\n"%(key,result[key]))
```

# DSP2019\_FP\_r08921005 黄國郡

- 1 Settings for generating spectrograms (at least 2 settings)
  - 1.1 利用 librosa.feature.melspectrogram python library 將個 npy 檔轉成 jpg 檔

```
librosa.feature.melspectrogram

librosa.feature.melspectrogram(y=None, sr=22050, S=None, n_fft=2048, hop_length=512, win_length=None, window='hann', center=True, pad_mode='reflect', power=2.0, **kwargs) [source]
```

總共做了兩次第一次都使用 default,第二次將 hop\_length 調為 **1024** 使 Overlap 從 75%變為 50%

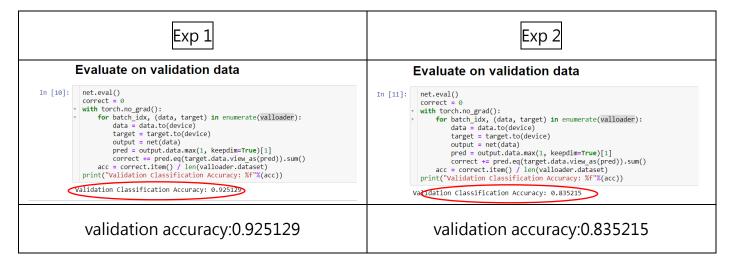
Overlap 主要被 hop\_length parameter 控制

EX:The default frame length is 2048 (for STFT operations), and the default hop is 512, which results in 75% overlap.

- Exp 1. Generate a magnitude spectrum using the hanning window function with a FFT length of 2048 and overlapping of 75% between segments
- Exp 2. Generate a phase spectrum using the hanning window function with a FFT length of 2048 and overlapping of 50% between segments

在 network 不變的情況下只是單純 dataSource 下去 train 得到不同的結果

overlapping 50% 的 validation 效果比 overlapping 75%原本差



# DSP2019 FP r08921005 黄國郡

- 2 Settings for your neural network (at least 1 setting)
  - 2.1 Please include implementation details like architecture(LeNet/VGGNet/...), optimizer(Adam/SGD/...), initialization, learning rate, etc.
  - 2.2 全部的實驗都在 LeNet 架構下完成(在 validate 階段測其實都差不多的結果,唯一很特別是:SGD, learning rate: 0.001 可能 overfitting 了!最後 accuracy 只有 0.088640)

```
Exp 1
                                  optimizer:SGD, learning rate: 0.05
                                                                                                                                                                          Exp 2
                                                                                                                                                                                                        optimizer:SGD, learning rate: 0.001
     net = Net(num_classes=len(traindata.classes)) # initialize your network
                                                                                                                                                                                net = Net(num classes=len(traindata.classes)) # initialize your network
     # Whether to use GPU or not?
device = 'cpu'
                                                                                                                                                                                 # Whether to use GPU or not?
device = 'cpu'
     if torch.cuda.is available():
                                                                                                                                                                                if torch.cuda.is available():
             device =
                                                                                                                                                                                        device =
                                                                                                                                                                                else:
     else:
     device = 'cpu'
print("use",device,"now!")
                                                                                                                                                                                        device = 'cpu
                                                                                                                                                                                print("use",device,"now!")
      net.to(deviće)
                                                                                                                                                                                 net.to(device)
     optimizer optim.SGD(net.parameters(), [r=0.05] setup your optimizer criterion = nn.Crossentropytoss() # setup your criterion
                                                                                                                                                                                optimize = optim.SGD(net.parameters(), lr=0.001) setup your optimizer criterion = nn.crossEntropyLoss() # setup your criterion
                      Evaluate on validation data
                                                                                                                                                                                                     Evaluate on validation data
                                                                                                                                                                                    In [21]:
                                                                                                                                                                                                       net.eval()
                        correct = 0
with torch.no_grad():
    for batch_idx, (data, target) in enumerate(valloader):
        data = data.to(device)
        target = target.to(device)
        output = net(data)
                                                                                                                                                                                                      correct = 0
with torch.no_grad():
    for batch_idx, (data, target) in enumerate(valloader):
        data = data.to(device)
        target = target.to(device)
        output = net(data)
        pred = output.data.max(1, keepdim=True)[1]
        correct += pred.eq(target.data.view_as(pred)).sum()
        acc = correct.item() / len(valloader.dataset)
print("Validation Classification Accuracy: %f"%(acc))
                         output = net(uata,
pred = output.data.max(1, keepdim=True)[1]
correct += pred.eq(target.data.view_as(pred)).sum()
acc = correct.item() / len(valloader.dataset)
print("Validation Classification Accuracy: %f"%(acc))
               Validation Classification Accuracy: 0.925129
                                                                                                                                                                                                   Validation Classification Accuracy: 0.088640
Exp 3
                              optimizer: Adam, learning rate: 0.05
                                                                                                                                                                      Exp 4
                                                                                                                                                                                                    optimizer: Adam, learning rate: 0.001
     In [6]:    net = Net(num_classes=len(traindata.classes)) # initialize your network
                                                                                                                                                                                      net = Net(num_classes=len(traindata.classes)) # initialize your network
                      device =
                                                                                                                                                                                     device = 'cpu'
if torch.cuda.is_available():
    device = 'cuda'
else:
    device = 'cpu'
print("use",device,"now!")
net.to(device)
optimizer = optim. Adam(net.parameters(), lr=0.001) # tup your optimizer
criterion = non.ceassEntropyLoss() # setup your ertterion
                                                                                                                                                                                       device =
                      if torch.cuda.is available():
                             device = 'cuda
                      device = 'cpu'
print("use",device,"now!")
net.to(device)
                      optimizer = optim.Adam(net.parameters(), 1r=0.05) & etup your optimizer criterion = nn.trussintropytoss() & animu worm criterion
                   use cuda now!
                                                                                                                                                                                   use cuda now!
                                Evaluate on validation data
                                                                                                                                                                                        In [10]:
                                                                                                                                                                                                          net.eval()
correct = 0
with torch.no_grad():
    for batch_idx, (data, target) in enumerate(valloader):
        data = data.to(device)
        target = target.to(device)
        output = net(data)
        nred = output.data.max(1, keepdim=True)[1]
                   In [21]: net.eval()
                                   correct = 0
with torch.no.grad():
    for batch_idx, (data, target) in enumerate(valloader):
        data = data.to(device)
        target = target.to(device)
        output = net(data)
        pred = output.data.max(1, keepdim=True)[1]
        correct += pred.eq(target.data.view_as(pred)).sum()
        acc = correct.item() / len(valloader.dataset)
        print("Validation Classification Accuracy: %f"%(acc))
                                    with torch.no
                                                                                                                                                                                                           output - Net(uata, max(1, keepdim=True)[1]
correct += pred.eq(target.data.view_as(pred)).sum()
acc = correct.item() / len(valloader.dataset)
print("Validation classification Accuracy: %f"%(acc))
                                                                                                                                                                                                        Calidation Classification Accuracy: 0.947074
                             Validation Classification Accuracy: 0.895214
```

- 2.3 Report the validation accuracy based on different settings.
  - 上個 part 已經對不同種 dataset 得出來的 validation accuracy 做過比較,此 part 不再描述,主要針對不同 optimizer,learning rate,做比較

# DSP2019\_FP\_r08921005 黄國郡

3 What I have learned for this project.(Difficulties, interesting things, or special techniques) 我將分為以下幾點做感想整理

### 3.1 Signal vs. Spectrum

• 本次作業學到 signal 與 spectrum 之間的關係,實踐了課堂上所學所教,非常有感覺

#### 3.2 Neural Networks

- 對於 Neural Networks、CNN 的深入理解和實作,也認識到各種不同的 Network 架構 EX: LeNet/VGGNet/...
- 因為本次作業有機會讓我去對神經網路有更深入研究,甚至去看了本次作業主要所採用的
   的 Lenet 論文:<a href="http://yann.lecun.com/exdb/publis/pdf/lecun-01a.pdf">http://yann.lecun.com/exdb/publis/pdf/lecun-01a.pdf</a>

#### 3.3 GPU vs. CPU

- 本次作業我採用 GPU 來 train 然後發現其實只要改一下.cuda() 或 .cpu()其實大多的 東西不太用改,滿方便的
- 上網 survey 一下發現 GPU 比 CPU 的運算速度好以外,原來他 train 出來的 model
   也會比較好,所以 validation accuracy 也相較好了一點,但就真的只有一點,有可能是
   因為本次作業運算量比較小。
- 看了一下我電腦規格發現其實有可能是我的 CPU 本身就已經屬於高規格,所以可能不會 效能差太多

系統 ————			
處理器: 已安裝記憶體 (RAM) 系統類型: 手寫筆與觸控:	AMD Ryzen 7 2700 Eight-Core Processor 16.0 GB 64 位元作業系統,x64 型處理器 此顯示器不提供手寫筆或觸控式輸入功能。	3.20 GHz	GPU 0 NVIDIA GeForce GTX 1060 6GB 100%

3.4 To be Improve:或許 dataset 的座標軸, label, colormap 可以拿掉使判斷更精準