CIM long PH anc h.err 3 6 8 10 4 5 9 7.5--log10(p.val) 2.5 50 100 0 25507510025 position [cM] 40 80 1200 30 60 901200 25 50 75100 50 1001500 0 50100150 0 50 100 50 100 Ó 50 100