CIM long_anc PH anc h.err 3 6 8 10 4 5 9 7.5 -log10(p.val) 2.5 100 0 25507510026 position [cM] 50 1001500 40 80 1200 30 60 901200 25 50 75100 50 100 50 100 0 50100150 0 50 100 Ó 50 100 Ò