

PKF on 1D multivariate oscillator

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Abstract

This notebook illustrates the use of sympkf to build and handle the PKF dynamics associated with the harmonic oscillator as 2D fields given by

$$\begin{cases} \partial_t u = v \\ \partial_t v = -u \end{cases}$$

where u and v are functions of t, x . For this dynamics, the resulting PKF system is not closed because of the cross-correlation.

1 Definition of the 1D multivariate dynamics

```
[1]: import sympy
sympy.init_printing()
```

Definition of the dynamics from sympy tools

```
[2]: from sympy import Function, Derivative, Eq, symbols
from sympkf import SymbolicPKF, t
```

```
[3]: x = symbols('x')
u = Function('u')(t,x)
v = Function('v')(t,x)
dynamics = [Eq(Derivative(u,t), v), Eq(Derivative(v,t), -u)]
dynamics
```

```
[3]:  $\left[ \frac{\partial}{\partial t} u(t, x) = v(t, x), \frac{\partial}{\partial t} v(t, x) = -u(t, x) \right]$ 
```

2 Computation of the PKF dynamics by using SymPKF

```
[4]: pkf_dynamics = SymbolicPKF(dynamics)
```

```
[5]: for equation in pkf_dynamics.in_metric:    display(equation)
```

$$\frac{\partial}{\partial t} u(t, x) = v(t, x)$$

$$\frac{\partial}{\partial t} v(t, x) = -u(t, x)$$

$$\frac{\partial}{\partial t} V_u(t, x) = 2 V_{uv}(t, x)$$

$$\frac{\partial}{\partial t} V_v(t, x) = -2 V_{uv}(t, x)$$

$$\frac{\partial}{\partial t} V_{uv}(t, x) = -V_u(t, x) + V_v(t, x)$$

$$\begin{aligned} \frac{\partial}{\partial t} g_{u,xx}(t, x) &= -\frac{2 V_{uv}(t, x) g_{u,xx}(t, x)}{V_u(t, x)} + \frac{2 \sqrt{V_v(t, x)} \mathbb{E} \left(\frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right)}{\sqrt{V_u(t, x)}} + \\ &\frac{\mathbb{E} \left(\varepsilon_v(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \right) \frac{\partial}{\partial x} V_v(t, x)}{\sqrt{V_u(t, x)} \sqrt{V_v(t, x)}} - \frac{\sqrt{V_v(t, x)} \mathbb{E} \left(\varepsilon_v(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \right) \frac{\partial}{\partial x} V_u(t, x)}{V_u^{\frac{3}{2}}(t, x)} \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial t} g_{v,xx}(t, x) &= \frac{2 V_{uv}(t, x) g_{v,xx}(t, x)}{V_v(t, x)} - \frac{2 \sqrt{V_u(t, x)} \mathbb{E} \left(\frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right)}{\sqrt{V_v(t, x)}} + \\ &\frac{\sqrt{V_u(t, x)} \mathbb{E} \left(\varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right) \frac{\partial}{\partial x} V_v(t, x)}{V_v^{\frac{3}{2}}(t, x)} - \frac{\mathbb{E} \left(\varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right) \frac{\partial}{\partial x} V_u(t, x)}{\sqrt{V_u(t, x)} \sqrt{V_v(t, x)}} \end{aligned}$$

```
[6]: for equation in pkf_dynamics.in_aspect:    display(equation)
```

$$\frac{\partial}{\partial t} u(t, x) = v(t, x)$$

$$\frac{\partial}{\partial t} v(t, x) = -u(t, x)$$

$$\frac{\partial}{\partial t} V_u(t, x) = 2 V_{uv}(t, x)$$

$$\frac{\partial}{\partial t} V_v(t, x) = -2 V_{uv}(t, x)$$

$$\frac{\partial}{\partial t} V_{uv}(t, x) = -V_u(t, x) + V_v(t, x)$$

$$\begin{aligned} \frac{\partial}{\partial t} s_{u,xx}(t, x) &= \frac{2 V_{uv}(t, x) s_{u,xx}(t, x)}{V_u(t, x)} - \frac{2 \sqrt{V_v(t, x)} s_{u,xx}^2(t, x) \mathbb{E} \left(\frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right)}{\sqrt{V_u(t, x)}} - \\ &\frac{s_{u,xx}^2(t, x) \mathbb{E} \left(\varepsilon_v(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \right) \frac{\partial}{\partial x} V_v(t, x)}{\sqrt{V_u(t, x)} \sqrt{V_v(t, x)}} + \frac{\sqrt{V_v(t, x)} s_{u,xx}^2(t, x) \mathbb{E} \left(\varepsilon_v(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \right) \frac{\partial}{\partial x} V_u(t, x)}{V_u^{\frac{3}{2}}(t, x)} \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial t} s_{v,xx}(t, x) = & -\frac{2 V_{uv}(t, x) s_{v,xx}(t, x)}{V_v(t, x)} + \frac{2 \sqrt{V_u(t, x)} s_{v,xx}^2(t, x) \mathbb{E} \left(\frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right)}{\sqrt{V_v(t, x)}} - \\ & \frac{\sqrt{V_u(t, x)} s_{v,xx}^2(t, x) \mathbb{E} \left(\varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right) \frac{\partial}{\partial x} V_v(t, x)}{V_v^{\frac{3}{2}}(t, x)} + \frac{s_{v,xx}^2(t, x) \mathbb{E} \left(\varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_v(t, x, \omega) \right) \frac{\partial}{\partial x} V_u(t, x)}{\sqrt{V_u(t, x)} \sqrt{V_v(t, x)}} \end{aligned}$$

[7]: `pkf_dynamics.internal_closure`

[7]:

$$\left\{ \mathbb{E}(\varepsilon_u(t, x, \omega) \varepsilon_v(t, x, \omega)) : \frac{V_{uv}(t, x)}{\sqrt{V_u(t, x)} \sqrt{V_v(t, x)}}, \mathbb{E} \left(\varepsilon_u(t, x, \omega) \frac{\partial}{\partial x} \varepsilon_u(t, x, \omega) \right) : 0, \mathbb{E} \left(\varepsilon_u(t, x, \omega) \frac{\partial^2}{\partial x^2} \varepsilon_u(t, x, \omega) \right) \right\}$$