On Bias and Variance for Regression

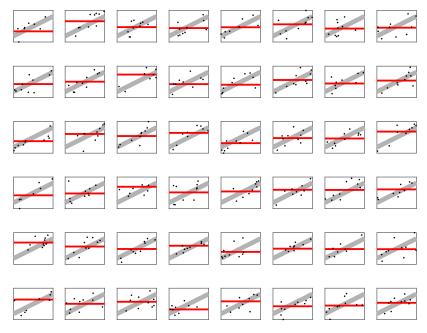
CS189/289A: Introduction to Machine Learning

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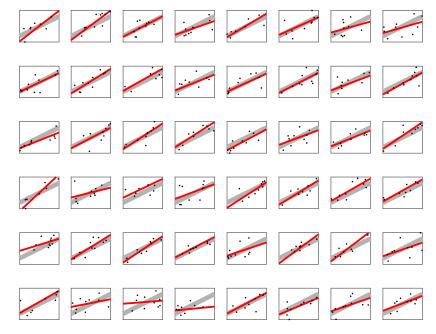
UC Berkeley

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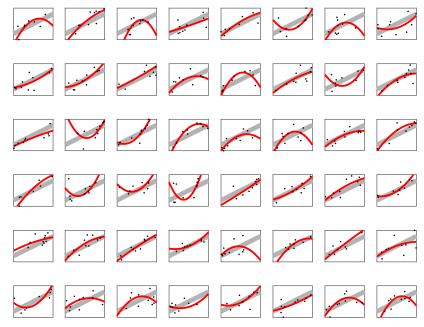
Fitting A Model over Multiple Datasets: p = 0



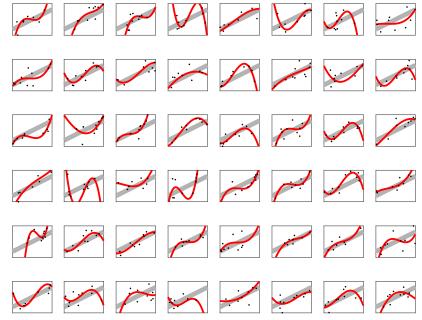
Fitting A Model over Multiple Datasets: p = 1



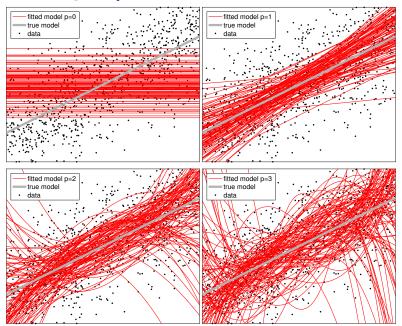
Fitting A Model over Multiple Datasets: p = 2



Fitting A Model over Multiple Datasets: p = 3



Model Quality Assessment and Model Selection



Task: Regressor Variation upon Data Selection

ightharpoonup Observation model of random variables (X,Y):

$$Y = f(X) + N \tag{1}$$

The true function f(x) is fixed but unknown, the noise N is zero-mean, independent and identically distributed.

▶ Observation dataset *D* of *n* random samples:

$$D = (X_1, Y_1; X_2, Y_2; \dots; X_n, Y_n).$$
 (2)

ightharpoonup Regressor h tries to approximate f and is dependent upon D:

$$h(x;D) \approx f(x)$$
. (3)

For an arbitrary point x, not necessarily in D, its Y is random:

$$Y = f(x) + N. (4)$$

► How much deviation is expected from *h*'s prediction of *Y*?

$$E[(h(x;D)-Y)^2] = ?$$
 (5)

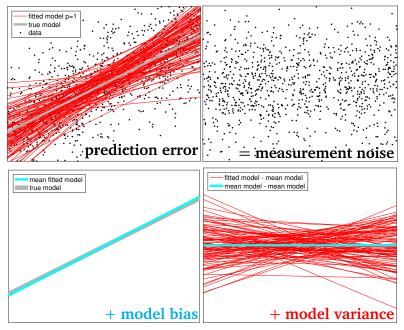
Metric: Prediction Error of A Regressor

▶ How good is h(x; D) at estimating response Y?

$$\varepsilon(x;h) = E[(h(x;D) - Y)^2] \tag{6}$$

- ▶ It measures the difference between the regressor prediction and the measured data, averaged over all possible training data sets of a particular sample size *n*.
- ► The metric varies with *x*, the location in the data space.
- ► The randomness comes from the dataset *D* used to estimate *h* and the inherent uncertainty in the target measurement *Y*.

Bias and Variance Decomposition Aspects



Bias-Variance Decomposition: Basics

► *N* and *Y* at any given *x*:

$$E[N] = 0 \tag{7}$$

$$E[Y] = E[f(x) + N] = f(x)$$
 (8)

$$V[Y] = V[f(x) + N] = V[N]$$
 (9)

For any random variable *X*, the following equation holds:

$$V[X] = E[(X - E[X])^{2}] = E[X^{2}] - E[X]^{2}$$

$$\downarrow \qquad (10)$$

$$E[X^{2}] = V[X] + E[X]^{2}$$

$$(11)$$

Bias-Variance Decomposition Equation

Take expectation over random dataset *D* and noisy *Y* at given *x*:

$$E[(h(x;D)-Y)^2] \tag{12}$$

$$= E[h(x;D)^{2}] + E[Y^{2}] - 2 \cdot E[h(x;D) \cdot Y]$$
 (13)

$$= E[h(x;D)]^{2} + V[h(x;D)]$$
 (14)

$$+ E[Y]^2 + V[Y]$$
 (15)

$$-2 \cdot E[h(x;D)] \cdot E[Y] \Leftarrow h(x;D), Y \text{ are independent } (16)$$

$$= (E[h(x;D)] - E[Y])^{2} + V[h(x;D)] + V[Y]$$
(17)

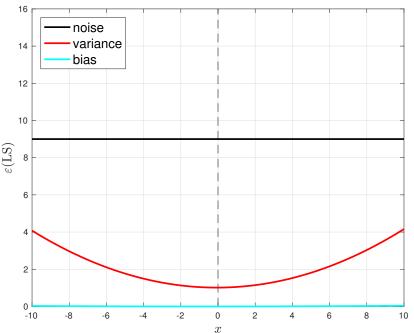
$$= \underbrace{(E[h(x;D)] - f(x))^{2}}_{\text{bias}^{2} \text{ of method}} + \underbrace{V[h(x;D)]}_{\text{variance of method}} + \underbrace{V[N]}_{\text{irreducible error}}$$
(18)

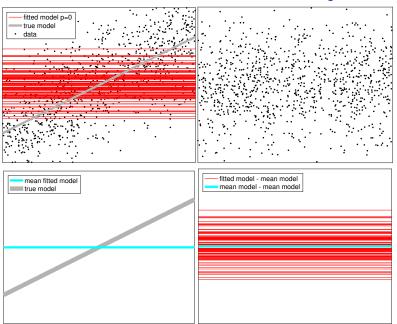
Bias-Variance Decomposition Intuitions

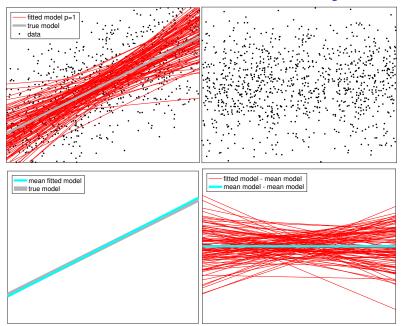
The prediction metric can be decomposed into three terms.

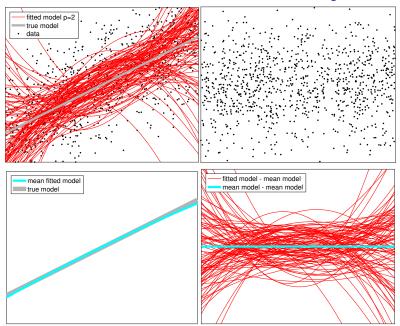
- 1. The **bias of the method** measures the **accuracy** of the prediction with respect to the true value. A low bias means that on average the regressor h(x) accurately estimates f(x).
- 2. The variance of the method measures the stability of the prediction. A low variance means that the prediction does not change much as the training set varies. An un-biased method (bias = 0) could have a large variance.
- 3. The **irreducible error** measures the **precision** of the prediction. A low irreducible error means that the prediction can be very precise to the true value.

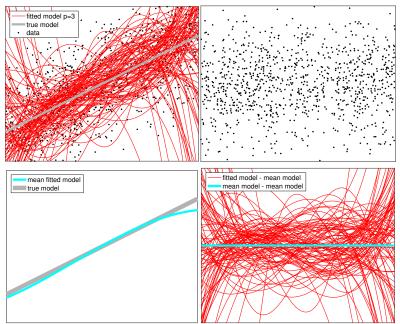
Bias vs. Variance, Interpolation vs. Extrapolation



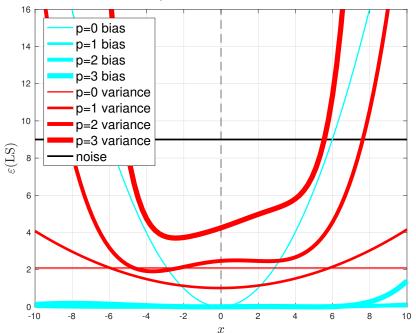




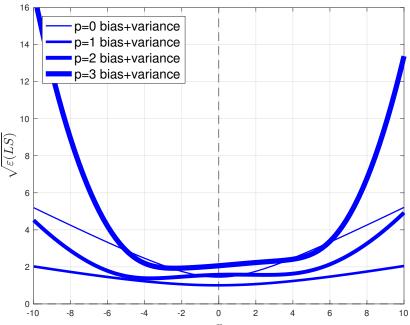




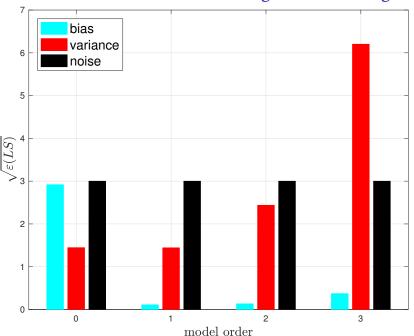
Variation of Bias/Variance Over Model Order



Variation of Prediction Error with Model Order



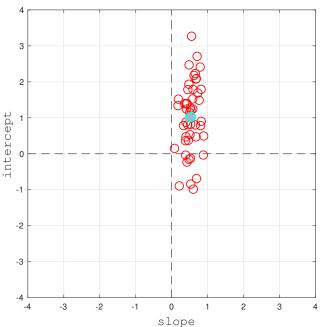
Bias and Variance: Underfitting vs. Overfitting



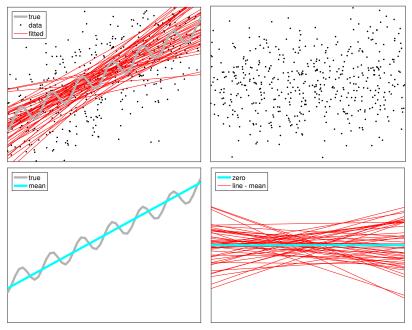
Fitting A Line Over 10 Points in 48 Random Sets



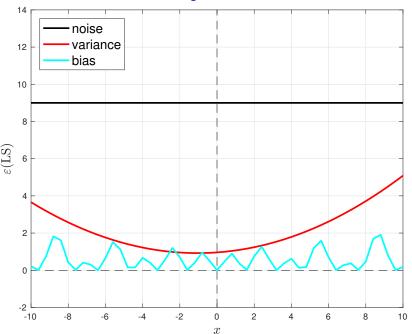
Random Variable h in the Model Space: n = 10



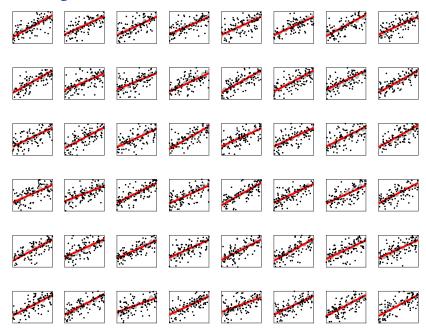
Bias-Variance Decomposition Aspects: n = 10



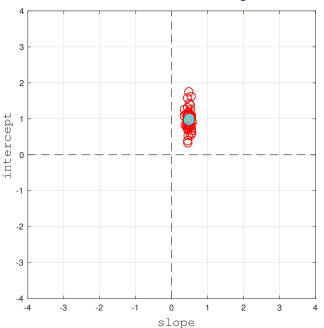
Bias-Variance Decomposition Results: n = 10



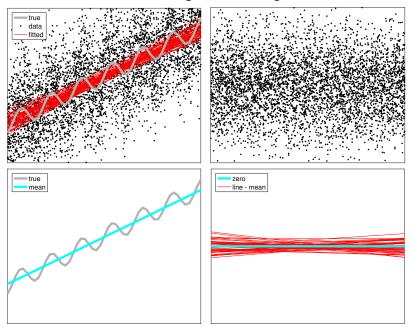
Fitting A Line Over 100 Points in 48 Random Sets



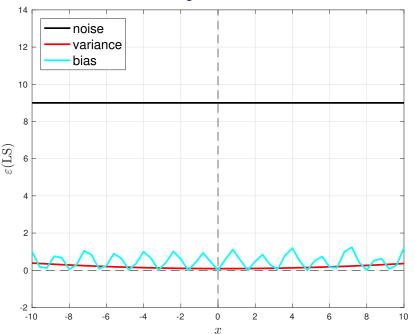
Random Variable h in the Model Space: n = 100



Bias-Variance Decomposition Aspects: n = 100



Bias-Variance Decomposition Results: n = 100



Understanding Model Estimation

- 1. Under-fitting = much bias; most overfitting = much variance
- 2. Training error reflects bias but not variance; test error reflects both; low training error can fool you when you've overfitted
- 3. Variance $\rightarrow 0$ as $n \rightarrow \infty$
- 4. If *h* can fit *f* exactly, for many distributions, bias \rightarrow 0 as $n \rightarrow \infty$. If *h* cannot fit *f* well, bias is large at most points
- Adding a good feature reduces bias Adding a bad feature rarely increases it
- 6. Adding a feature usually increases variance
 Don't add a feature unless it reduces bias more
- 7. Can't reduce irreducible error, hence its name
- 8. Noise in test set affects only *V*[*N*] Noise in training set affects bias and variance.
- 9. For real-world data, *f* is rarely knowable and noise model might be wrong, so we can't actually calculate bias and variance. But we can test algorithms on synthetic data.