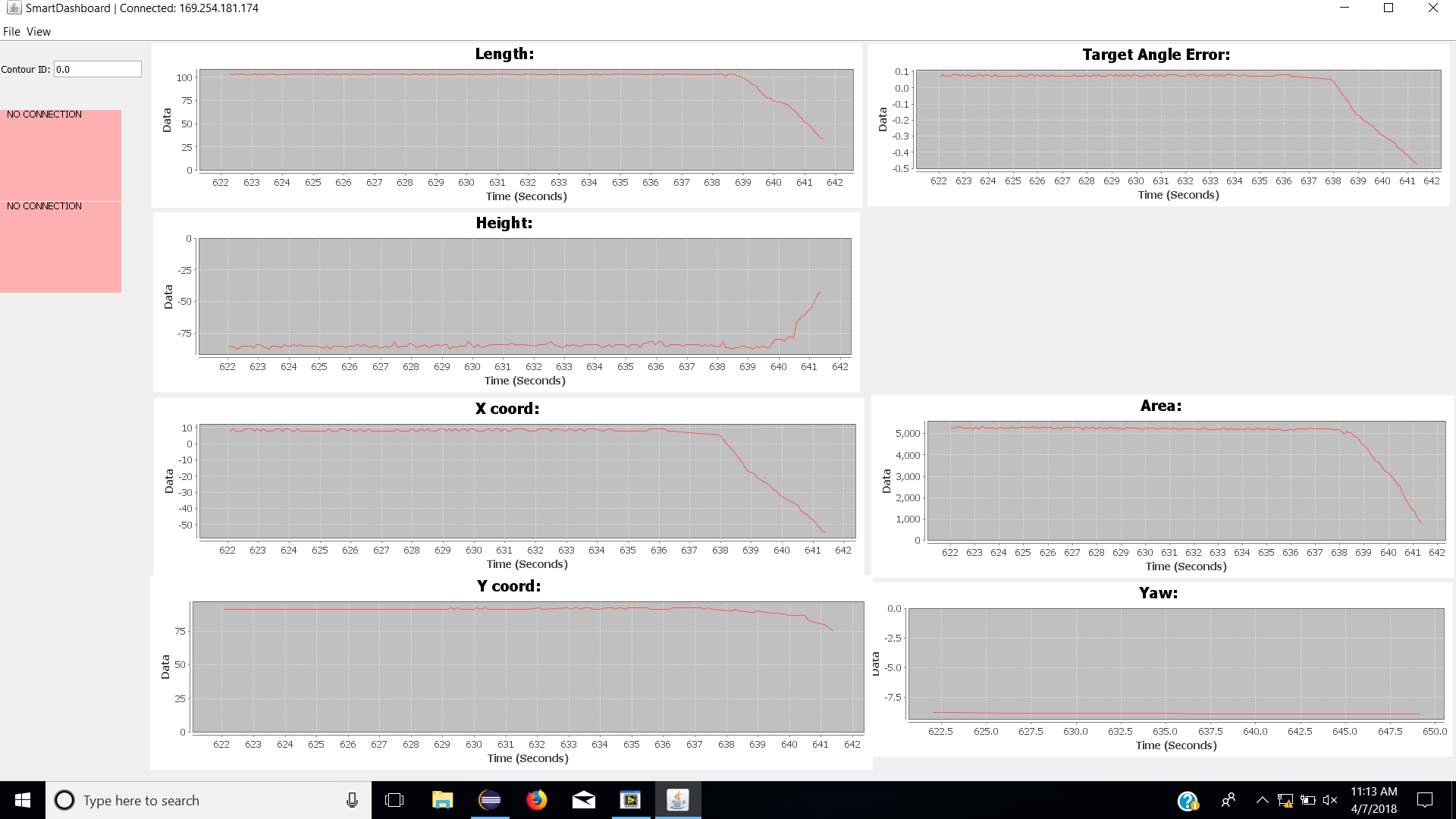
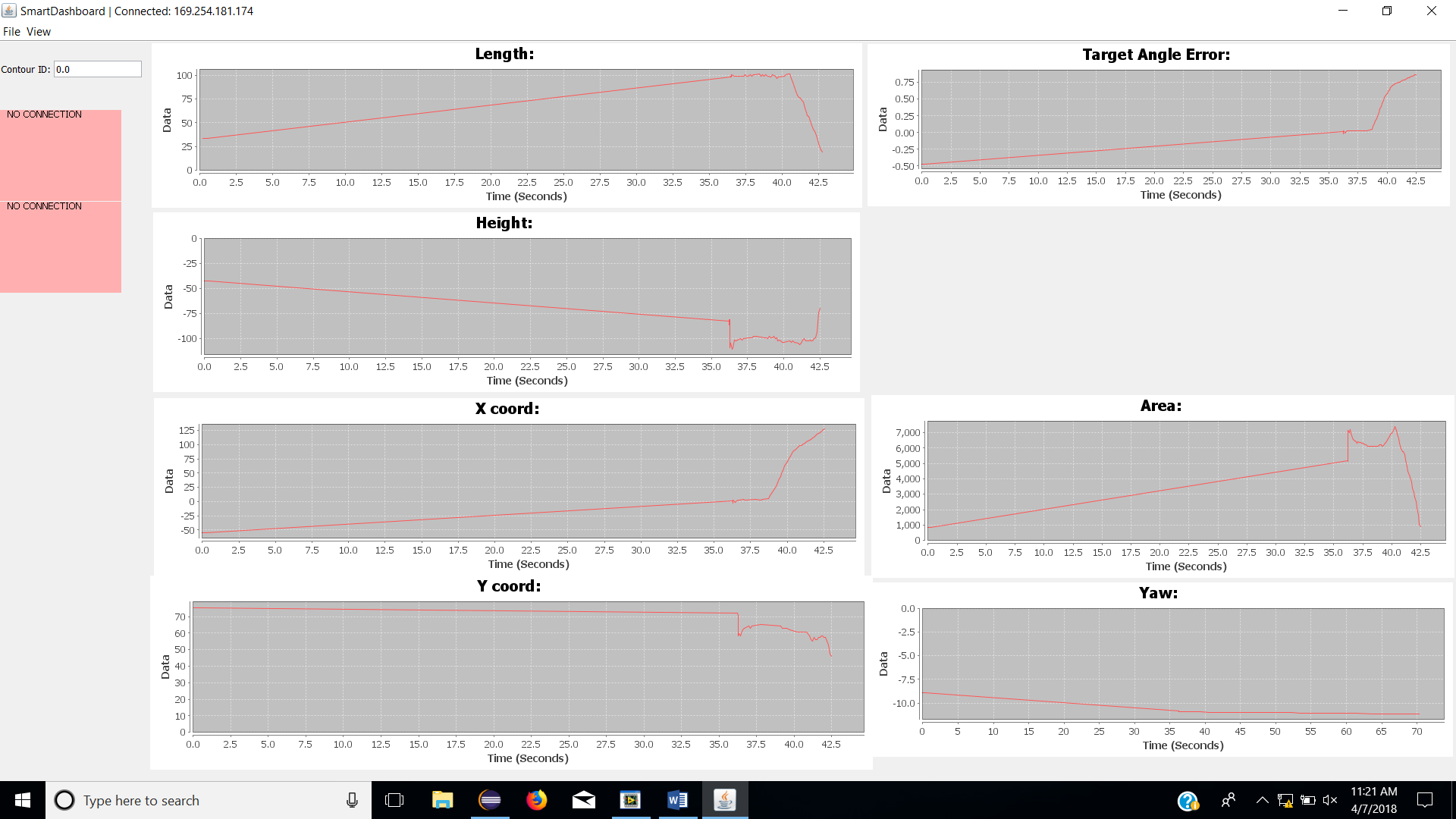
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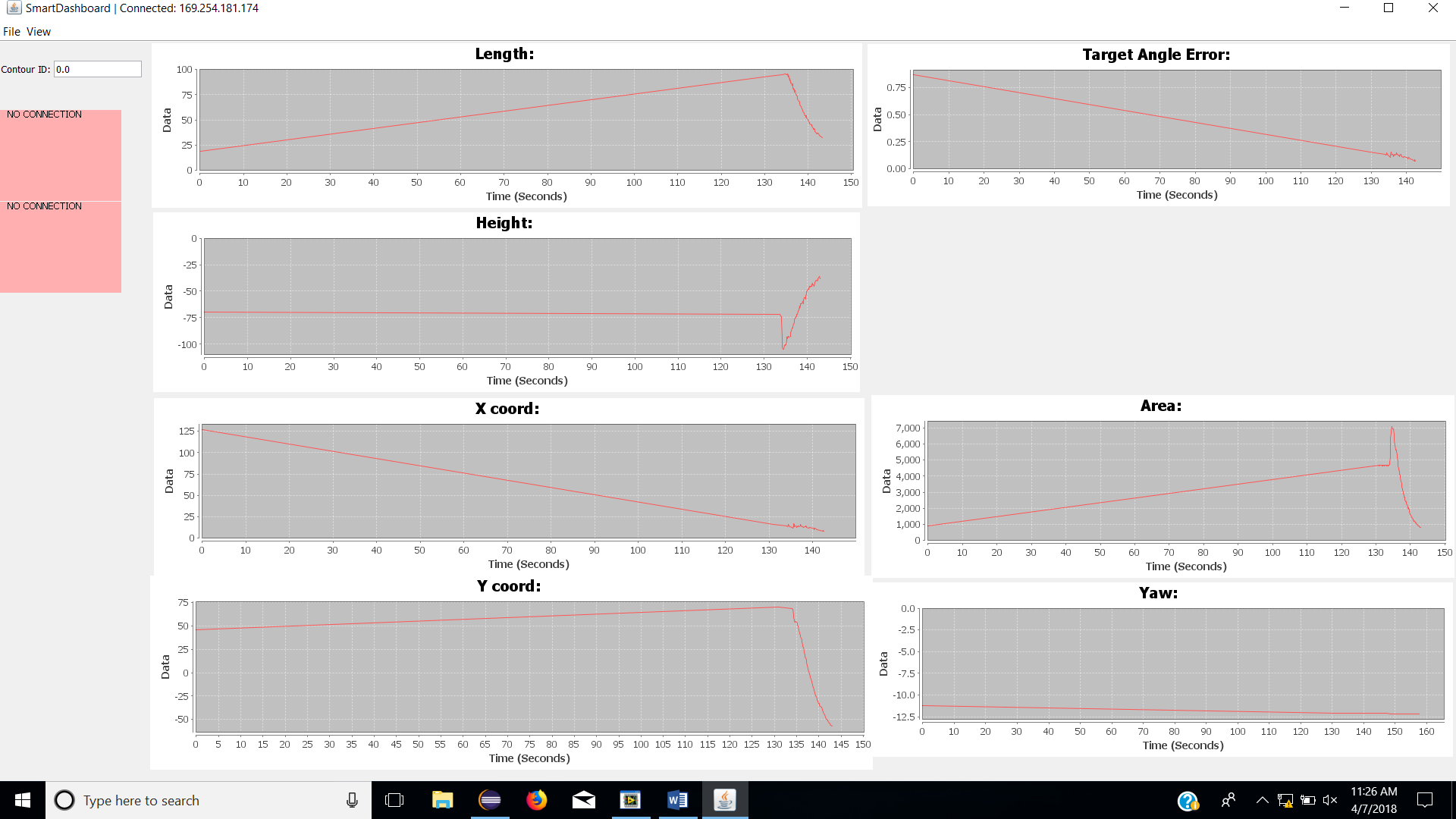
Test 1: Center to robot’s left



Test 2: Center to robot’s right



Test 3: Center to away from robot



Test 4: Center to approach robot

