Lecture 06: State

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Section 1: Introduction to State

In this chapter, we extend our mini-language with the concept of **state**. Until now, our language has been purely functional, where expressions are evaluated to produce values without side effects. By adding state, we can:

- 1. Store and update values in memory
- 2. Observe changes to data over time
- 3. Model real-world systems that have changing state

Expressions vs. Commands

Our language extension introduces a new distinction:

- Expressions: Compute values (e.g., x + 1, let x = 42 in x * 2)
- Commands: Perform actions with side effects (e.g., var x = 42, x <- 42, print x)

This distinction is common in many programming languages:

```
# Expression (computes a value)
x + 1

# Command (performs an action)
var x = 42
x <- 42</pre>
```

Section 2: Commands and Command Sequences

To implement state, we introduce two new syntactic categories:

- 1. Commands: Individual actions that can modify state
- 2. Command Sequences: Ordered lists of commands to be executed in sequence

Commands in Our Language

We implement three basic command types:

1. Variable Declaration: Declares a new variable and initializes it

var x = 42

2. **Assignment**: Updates a variable with a new value (only if already declared)

x <- 10

3. **Print**: Outputs the value of an expression

print x + 1

Command Sequences

Command sequences represent multiple commands separated by semicolons:

TODO: also use an assignemnt in the example

```
var x = 10;
var y = x + 5;
print v
```

This sequence declares x, then declares y as x + 5 (which is 15), and finally prints the value of y.

Grammar Extensions

We extend our language grammar to support commands and sequences:

```
?program: command_seq
?command_seq: command
           | command ";" command seq
?command: vardecl
        | assign
        | print
vardecl: "var" IDENTIFIER "=" expr
assign: IDENTIFIER "<-" expr
print: "print" expr
```

AST Representation

We represent commands and command sequences with these AST node types:

```
@dataclass
class VarDecl:
    name: str
    expr: Expression
@dataclass
class Assign:
    name: str
    expr: Expression
@dataclass
class Print:
    expr: Expression
```

```
@dataclass
class CommandSequence:
    first: Command
    rest: Optional[CommandSequence] = None

type Command = VarDecl | Assign | Print
```

Section 3: The Store Model of State

To represent state, we use the "store model":

- 1. Environment: Maps variable names to locations (memory addresses)
- 2. **Store**: Maps locations to values

This two-level indirection allows multiple variables to refer to the same location or for a variable's value to change without changing its location.

The State as a Functional Dataclass

Our implementation uses a State dataclass to manage the store in a functional style:

• The store is **not** a dictionary, but a function from locations to values (or raises an error if not found), just like the environment is a function from names to locations. This ensures a fully functional approach.

```
@dataclass(frozen=True)
class State:
   store: Callable[[int], Any]
   next loc: int
def empty_store() -> Callable[[int], Any]:
   def store fn(loc: int) -> Any:
       raise ValueError(f"Location {loc} not allocated")
   return store_fn
def empty state() -> State:
   return State(store=empty_store(), next_loc=0)
```

```
def alloc(state: State, value: Any) -> tuple[int, State]:
    loc = state.next_loc
    prev_store = state.store

def new_store(l: int) -> Any:
    if l == loc:
        return value
    return prev_store(l)

return loc, State(store=new_store, next_loc=loc + 1)
```

```
def update(state: State, loc: int, value: Any) -> State:
   state.store(loc) # will raise if not found
   prev store = state.store
   def new store(l: int) -> Any:
       if 1 == loc:
            return value
        return prev_store(1)
   return State(store=new_store, next_loc=state.next_loc)
def lookup(state: State, loc: int) -> Any:
   return state.store(loc)
```

Recall environment and binding

```
# Environment now maps to locations (store addresses)
type Environment = Callable[[str], int]
def empty environment() -> Environment:
   def env(name: str) -> int:
        raise ValueError(f"Undefined identifier: {name}")
    return env
def bind(env: Environment, name: str, loc: int) -> Environment:
    def new env(n: str) -> int:
       if n == name:
            return loc
        return env(n)
    return new_env
```

Section 4: Evaluating Expressions with State

When evaluating expressions in a stateful language, we need to pass both the environment and the state:

```
def evaluate_expr(expr: Expression, env: Environment, state: State) -> int:
# ...
```

Variable lookup now has two steps:

- 1. Use the environment to find the location
- 2. Use the state to look up the value at that location

```
case Var(name):
    # Look up variable's location and then its value in the state

try:
    loc = lookup_env(env, name)
    return lookup(state, loc)

except ValueError as e:
    raise ValueError(f"Variable error: {e}")
```

Section 5: Executing Commands

Commands modify the state or produce output. The <code>execute_command</code> function returns both the updated environment and state as a tuple:

```
env, state = execute_command(cmd, env, state)
```

- env is the updated environment (with new variable bindings, if any)
- state is the updated state (with new or updated values)

You can access the first and second components of the tuple as env and state respectively. **Note:** The print command is not part of the mathematical semantics; it is just an aid for using the interpreter.

The Variable Declaration Command

The variable declaration command (var x = expr) creates a new variable and initializes it. If the variable already exists, it is an error.

The Assignment Command

The assignment command (<-) only updates an existing variable. If the variable does not exist, it is an error.

The Print Command

The print command evaluates the expression and prints its value. It does not affect the environment or state.

Command Sequences

Executing a command sequence involves:

- 1. Executing the first command
- 2. Executing the rest of the sequence with the updated environment and state

```
def execute_command_seq(seq: CommandSequence, env: Environment, state: State) -> tuple[Environment, State]:
    env, state = execute_command(seq.first, env, state)
    if seq.rest:
        return execute_command_seq(seq.rest, env, state)
    return env, state
```

Section 6: Examples of State in Action

Let's look at some examples that demonstrate the power of state:

Example 1: Basic Declaration, Assignment, and Printing

```
var x = 42;
print x
```

This simple example shows creating a variable and reading its value. The output is 42.

Example 2: Updating Variables

```
var x = 10;
var y = x + 5;
print y;
x <- 20;
print x;
print y
```

This example demonstrates that changing x doesn't automatically change y, even though y was defined in terms of x. The output is:

```
15
20
15
```

The value of y remains 15 because the expression x + 5 was evaluated at the time of declaration.

Example 3: Let Expressions in Commands

```
var x = let y = 5 in y * 2;
print x
```

This example shows how we can use let expressions within commands. The output is 10.

Section 7: Differences from Previous Chapters

Adding state represents a significant shift in our language:

Stateful (Ch. 6)
Values can change over time
Commands have side effects
Expressions may evaluate differently
Environment maps names to locations
More expressive

Section 8: Conclusion and Next Steps

Adding state to our mini-language significantly increases its expressiveness, making it capable of modeling real-world problems that involve change over time. In the next chapter, we'll build upon this foundation by adding control flow structures like loops and conditionals.

With state, environment, and control flow, our language will have all the essential ingredients of a complete programming language.