

This is Start

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7 微分方程

7.1 基本概念

$$\begin{cases} \frac{dy}{dx} = 2x \\ x = 1, y = 2 \end{cases} \Rightarrow y = 2x + 1$$

函數，函數導數，自變量關係的方程**微分方程**

最高階導數的階數**微分方程的階**

$F(x, y', \dots, y^{(n)}) = 0$ **一般形式**

函數**微分方程的解**

函數含常數，常數個數同階數**微分方程的通解**

確定常數的通解**微分方程的通解**

7.2 可分離變量的微分方程

$$\frac{dy}{dx} = 2x \Rightarrow dy = 2x dx \Rightarrow$$

$$\frac{dy}{dx} = 2xy^2 \Rightarrow \frac{dy}{y^2} = 2x dx \Rightarrow$$

$$g(y) dy = f(x) dx \Rightarrow y = \varphi(x)$$

$$G(y) = F(x) + C \Rightarrow y = \Phi(x)$$

7.3 齊次方程

$$\frac{dy}{dx} = \varphi\left(\frac{y}{x}\right)$$

$$\frac{dy}{dx} = \frac{ax+by+c}{a_1x+b_1y+c_1}$$

7.4 一階 \mathbb{R} 性微分方程

$\frac{dy}{dx} + P(x)y = Q(x)$ 關於函數，函數導數是一次方程一階 \mathbb{R} 性微分方程

$Q(x) = 0$ 時**齊次方程**

$y = Ce^{-\int P(x)dx}$ **齊次通解**，設 $C = \mu(x)$

$$\mu(x) = \int Q(x) e^{\int P(x)dx} dx + C_2$$

$y = \left(\int Q(x) e^{\int P(x)dx} dx + C_2\right) e^{-\int P(x)dx}$ **非齊次通解**

$\frac{dy}{dx} + P(x)y = Q(x)y^n$ **伯努利方程**

$\frac{dy}{dx}y^{-n} + P(x)yy^{-n} = Q(x)$ $z = y^{1-n}, z' = (1-n)y^{-n}\frac{dy}{dx} = \frac{z'}{1-n} + P(x)z = Q(x)$ 一階 \mathbb{R} 性微分方程

7.5 可降階的高階微分方程

$$y^{(n)} = f(x) \Rightarrow y^{(n-1)} = \int f(x) dx$$

$$y'' = f(x, y') \quad \underline{y' = p, y'' = p'} \quad p' = f(x, p)$$

$$y'' = f(y, y') \quad \underline{y' = p, y'' = p \frac{dp}{dy}} \quad p \frac{dp}{dy} = f(y, p) \quad \underline{p = y' = \varphi(y, c_1)}$$

7.6 高階性微分方程

二階微分方程

$$\frac{d^2y}{dx^2} + P(x)\frac{dy}{dx} + Q(x)y = f(x)$$

解的結構

$y = C_1y_1(x) + C_2y_2(x)$ 是解

$y = C_1 y_1(x) + C_2 y_2(x)$ 无关特解是通解

$y = C_1 y_1(x) + C_2 y_2(x) + \cdots + C_n y_n(x)$ 无关特解是通解

$y = Y(x) + y^*(x)$ 齐次通, 非齐特, 非齐通

$$\frac{d^2 y}{dx^2} + P(x) \frac{dy}{dx} + Q(x) y = f_1(x) + f_2(x)$$

$y = y_1^*(x) + y_2^*(x)$ 特解, 特解, 特解

常数变易法

$$Y(x) = C_1 y_1(x) + C_2 y_2(x)$$

$$Y(x) = v_1(x) y_1(x) + v_2(x) y_2(x)$$

$$\begin{cases} y_1 v_1' + y_2 v_2' = 0 \\ y_1' v_1 + y_2' v_2 = f \end{cases} \Rightarrow \begin{vmatrix} y_1 & y_2 & 0 \\ y_1' & y_2' & f \end{vmatrix} \xrightarrow{W = y_1 y_2' - y_1' y_2} \begin{cases} v_1' = -\frac{y_2 f}{W} \\ v_2' = \frac{y_1 f}{W} \end{cases} \Rightarrow \begin{cases} v_1 = -\int \frac{y_2 f}{W} dx + c_1 \\ v_2 = \int \frac{y_1 f}{W} dx + c_2 \end{cases}$$

$$\begin{cases} v_1 y_1 = \left(-\int \frac{y_2 f}{W} dx + c_1\right) y_1 \\ v_2 y_2 = \left(\int \frac{y_1 f}{W} dx + c_2\right) y_2 \end{cases} \Rightarrow Y(x) = c_1 y_1 + c_2 y_2 - y_1 \int \frac{y_2 f}{W} dx + y_2 \int \frac{y_1 f}{W} dx$$

7.7 常系数齐次线性微分方程

$$y'' + P(x) y' + Q(x) y = 0 \Rightarrow y'' + p y' + q y = 0$$

$$y = e^{rx}$$

$$(e^{rx})' = r e^{rx}$$

$$(r^2 + pr + q) e^{rx} = 0$$

$$\begin{cases} p^2 - 4q > 0, r_{1,2} = \frac{-p \pm \sqrt{p^2 - 4q}}{2} \\ p^2 - 4q = 0, r_1 = r_2 = -\frac{p}{2}, y_2 = e^{r_1 x} \mu(x), \mu'' = 0 \\ p^2 - 4q < 0, r_{1,2} = \alpha \pm \beta i, e^{(i\theta)} = \cos(\theta) + i \sin(\theta), \overline{y_1} = \frac{1}{2}(y_1 + y_2), \overline{y_1} = \frac{1}{2i}(y_1 - y_2) \end{cases}$$

$$\begin{cases} p^2 - 4q > 0, y = C_1 y_1 + C_2 y_2 = C_1 e^{r_1 x} + C_2 e^{r_2 x} \\ p^2 - 4q = 0, y = C_1 y_1 + C_2 \mu y_1 = (C_1 x + C_2) e^{r_1 x} \\ p^2 - 4q < 0, y = C_1 \overline{y_1} + C_2 \overline{y_2} = e^{\alpha x} (C_1 \cos(\beta x) + C_2 \sin(\beta x)) \end{cases}$$

n 阶常系数齐次微分方程

$$y^n + p_1 y^{n-1} + p_2 y^{n-2} + \cdots + p_{n-1} y' + p_n y = 0$$

$$\begin{cases} D, \frac{d}{dx} \\ Dy, \frac{dy}{dx} \\ D^n y, \frac{d^n y}{dx^n} \end{cases}$$

$$(D^n + p_1 D^{n-1} + \cdots + p_{n-1} D + p_n) y = 0 \Rightarrow L(D) y = 0, \text{微分算子 } D \text{ 的 } n \text{ 次多项式}$$

$$D e^{rx} = r e^{rx}, \dots, D^n e^{rx} = r^n e^{rx} \Rightarrow (r^n + p_1 r^{n-1} + \cdots + p_{n-1} r + p_n) e^{rx} = L(r) e^{rx} = 0 \Rightarrow L(r) = 0$$

$$\begin{cases} \text{单实根} & C e^{rx} \\ k \text{ 重实根} & (C_1 + C_2 x + \cdots + C_k x^{k-1}) e^{rx} \\ \text{单复根} & e^{\alpha x} (C_1 \cos(\beta x) + D_1 \sin(\beta x)) \\ k \text{ 重复根} & e^{\alpha x} ((C_1 + C_2 x + \cdots + C_k x^{k-1}) \cos(\beta x) + (D_1 + D_2 x + \cdots + D_k x^{k-1}) \sin(\beta x)) \end{cases}$$

7.8 常系数非齐次线性微分方程

$$y'' + p y' + q y = f(x)$$

$$p_m(x) = a_0 x^m + a_1 x^{m-1} + \cdots + a_m$$

$$\begin{cases} e^{\theta i} = \cos(\theta) + i \sin(\theta) \\ e^{-\theta i} = \cos(\theta) - i \sin(\theta) \end{cases} \Rightarrow \begin{cases} \cos(\theta) = \frac{1}{2}(e^{\theta i} + e^{-\theta i}) \\ \sin(\theta) = \frac{1}{2i}(e^{\theta i} - e^{-\theta i}) \end{cases} \Rightarrow \begin{cases} \cos(\omega x) P = \frac{P}{2}(e^{\omega x i} + e^{-\omega x i}) \\ \sin(\omega x) Q = \frac{Q}{2i}(e^{\omega x i} - e^{-\omega x i}) \end{cases}$$

函数 (多项式) 共轭, 倒数共轭; 两对共轭, 乘积共轭; $e^{\alpha+\theta i}$ 与 $e^{\alpha-\theta i}$ 共轭

$f(x) = e^{\lambda x} P_m(x)$	$y^* = R_l(x) e^{\lambda x}$ $R''x + (2\lambda + p)R'x + (\lambda^2 + p\lambda + q)R(x) = p_m(x)$ $y^* = x^k P_m(x) e^{\lambda x}$
$f(x) = e^{\lambda x} [P_l(x) \cos(\omega x) + Q_n(x) \sin(\omega x)]$	$f(x) = e^{\lambda x} \left[\left(\frac{P}{2} + \frac{Q}{2i} \right) e^{\omega x i} + \left(\frac{P}{2} - \frac{Q}{2i} \right) e^{-\omega x i} \right]$ $f(x) = \left(\frac{P}{2} + \frac{Q}{2i} \right) e^{\lambda x + \omega x i} + \left(\frac{P}{2} - \frac{Q}{2i} \right) e^{\lambda x - \omega x i}$ $f(x) = \left(\frac{P}{2} + \frac{Q}{2i} \right) e^{(\lambda + \omega i)x} + \left(\frac{P}{2} - \frac{Q}{2i} \right) e^{(\lambda - \omega i)x}$ $f(x) = P_1 e^{(\lambda + \omega i)x} + Q_2 e^{(\lambda - \omega i)x} \quad (P_1, Q_2 \text{共轭})$ $y_1^* = x^k R_m e^{(\lambda + \omega i)x} \quad (m = \max\{P_l, Q_n\})$ $y_2^* = x^k \overline{R_m} e^{(\lambda - \omega i)x}$ $y^* = y_1^* + y_2^* = x^k e^{\lambda x} (R_m e^{\omega x i} + \overline{R_m} e^{-\omega x i})$ $y^* = x^k e^{\lambda x} [R_m (\cos(\omega x) + i \sin(\omega x)) + \overline{R_m} (\cos(\omega x) - i \sin(\omega x))]$ $y^* = x^k e^{\lambda x} \left(R_m^{(1)} \cos(\omega x) + R_m^{(2)} \sin(\omega x) \right)$

7.9 欧拉方程

$$x^n y^{(n)} + p^1 x^{n-1} y^{(n-1)} + \cdots + p^{n-1} x y' + p^n y = f(x)$$

$$x = e^t, t = \ln x$$

$$\frac{dy}{dx} = \frac{dy}{dt} \frac{dt}{dx} = \frac{1}{x} \frac{dy}{dt} \quad D \text{表示} \frac{d}{dt} \quad \begin{cases} xy' = Dy \\ x^2 y'' = (D^2 - D)y \\ x^3 y''' = (D^3 - 3D^2 + 2D)y \\ \cdots \\ x^k y^{(k)} = (D^n + c_1 D^{n-1} + \cdots + C_{n-1} D)y \end{cases}$$

7.10 常系数线性微分方程组

$$\begin{cases} \frac{d^2 x}{dt^2} + \frac{dy}{dt} - x = e^t, \\ \frac{d^2 y}{dt^2} + \frac{dx}{dt} + y = 0, \end{cases}$$

$$\text{记} \frac{d}{dt} \text{为} D \Rightarrow \begin{cases} (D^2 - 1)x + Dy = e^t \\ Dx + (D^2 + 1)y = 0 \end{cases}$$

8 向量代数与空间解析几何

8.1 向量及其线性运算

8.1.1 向量的概念

大小, 方向, 向量, \overrightarrow{AB}

与起点无关, 自由向量

向量的大小, 向量的模, $|\overrightarrow{AB}|$, 单位向量, 零向量

$\overrightarrow{OA} = a, \overrightarrow{OB} = b, \angle AOB < \pi$ 向量夹角, $(\widehat{a, b}) = 0 \text{ or } \pi, a \text{ 与 } b \text{ 平行, 同起点共线}$
 $= \frac{\pi}{2}, a \text{ 与 } b \text{ 垂直}$

8.1.2 向量的运算

向量的加减法

$c = a + b$ 三角形法则

$a + b = b + a$ 交换

$(a + b) + c = a + (b + c)$ 分配

$a - b = a + (-b)$ 负向量

$|a \pm b| < |a| + |b|$

向量与数的乘法

$|\lambda a| = |\lambda| |a|$

$\lambda(\mu a) = \mu(\lambda a) = (\lambda\mu)a$

$|\lambda(\mu a)| = |\mu(\lambda a)| = |(\lambda\mu)a| = |\lambda\mu| |a|$

$(\lambda + \mu)a = \lambda a + \mu a, \lambda(a + b) = \lambda a + \lambda b$

$a \neq 0, a // b \Leftrightarrow \exists \text{ 唯一实数 } \lambda, b = \lambda a$

空间直角坐标系

$[O; i, j, k]$ 右手规则, 卦限

$\overrightarrow{OM} = r = xi + yj + zk$ 坐标式分解, 分向量, $r = (x, y, z), M(x, y, z)$ 坐标, r 为 M 关于 O 向径

利用坐标向量的线性运算

$$a = (a_x, a_y, a_z), b = (b_x, b_y, b_z) \begin{cases} a + b = (a_x + b_x, a_y + b_y, a_z + b_z) \\ a - b = (a_x - b_x, a_y - b_y, a_z - b_z) \\ \lambda a = (\lambda a_x, \lambda a_y, \lambda a_z) \end{cases}$$

向量的模, 方向角, 投影

向量的模与两点间的距离

$r = (x, y, z), |r| = \sqrt{x^2 + y^2 + z^2}$

$A = (x_1, y_1, z_1), B = (x_2, y_2, z_2), |AB| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$

方向角与方向余弦

r 与三条坐标轴的夹角 α, β, γ 称为 r 的方向角

$(\cos \alpha, \cos \beta, \cos \gamma) = \frac{1}{|r|} (x, y, z), \cos *$ 方向余弦

向量在轴上的投影

$$\begin{cases} (a)_u = |a| \cos \varphi \\ (a + b)_u = (a)_u + (b)_u = |a| \cos \varphi + |b| \cos \varphi \\ (\lambda a)_u = \lambda (a)_u \end{cases}$$

8.2 数量积 向量积 混合积

8.2.1 两向量的数量积

$$\begin{aligned}
 a \cdot b &= |a| |b| \cos \theta \text{数量积} \\
 \begin{cases} a \cdot a = |a|^2 \\ a, b \neq 0, a \cdot b = 0 \Leftrightarrow a \perp b \\ a \cdot b = b \cdot a \text{交}\mathbb{F} \\ (a+b) \cdot c = a \cdot c + b \cdot c \text{分配} \\ (\lambda a) \cdot b = \lambda (a \cdot b) \text{结合} \end{cases} \\
 a &= (a_x, a_y, a_z) \Rightarrow a \cdot b = a_x b_x + a_y b_y + a_z b_z \\
 b &= (b_x, b_y, b_z) \Rightarrow \cos \theta = \frac{a \cdot b}{|a| |b|} = \frac{a_x b_x + a_y b_y + a_z b_z}{\sqrt{a_x^2 + a_y^2 + a_z^2} \sqrt{b_x^2 + b_y^2 + b_z^2}}
 \end{aligned}$$

8.2.2 两向量的向量积

$$\begin{aligned}
 |c| &= |a| |b| \sin \theta \\
 c &= a \times b \text{向量积} \\
 \begin{cases} a \times a = 0 \\ a, b \neq 0, a \times b = 0 \Leftrightarrow a // b \\ a \times b = -b \times a \\ (a+b) \times c = a \times c + b \times c \\ (\lambda a) \times b = a \times (\lambda b) = \lambda (a \times b) \end{cases} \\
 a \times b &= (a_y b_z - a_z b_y, a_z b_x - a_x b_z, a_x b_y - a_y b_x) \\
 a &= (a_x, a_y, a_z) \Rightarrow \\
 b &= (b_x, b_y, b_z) \Rightarrow \begin{vmatrix} i & j & k \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}
 \end{aligned}$$

8.2.3 向量的混合积

$$\begin{aligned}
 (a \times b) \cdot c &= [abc], \text{向量的混合积} \\
 |[abc]| &= |a| |b| \sin(\widehat{a, b}) |c| \cos(\widehat{a \times b, c}), a, b, c \text{ 右手系模大于0} \\
 [abc] &= (a \times b) \cdot c \\
 a &= (a_x, a_y, a_z) \Rightarrow \\
 b &= (b_x, b_y, b_z) \Rightarrow \\
 c &= (c_x, c_y, c_z) \Rightarrow \begin{vmatrix} a_x & a_y & a_z \\ b_x & b_y & b_z \\ c_x & c_y & c_z \end{vmatrix}
 \end{aligned}$$

8.3 平面及其方程

8.3.1 曲面方程与空间曲线方程的概念

$$\begin{aligned}
 F(x, y, z) = 0, \text{曲面 } S \text{ 上点满足方程, 不在曲面 } S \text{ 上点不满足方程} \Rightarrow \text{曲面 } S \text{ 的方程} \\
 \begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases} \Rightarrow \text{曲线 } C \text{ 的方程}
 \end{aligned}$$

8.3.2 平面的点法式方程

$$\begin{aligned}
 \text{向量垂直平面, 平面的法线向量} \\
 n = (A, B, C) \quad \text{法向量} \\
 \overrightarrow{M_0 M} = (x - x_0, y - y_0, z - z_0) \quad \text{平面上点} \Rightarrow A(x - x_0) + B(y - y_0) + C(z - z_0) = 0 \text{平面的点法式方程}
 \end{aligned}$$

8.3.3 平面的一般方程

$Ax + By + Cz + D = 0$ 平面的一般方程

$\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$ 平面的截距式方程

8.3.4 平面的夹角

平面法向量的夹角, 平面的夹角 ($0 \leq \theta \leq \frac{\pi}{2}$)

$\Pi_1, n_1 = (A_1, B_1, C_1), \Pi_2, n_2 = (A_2, B_2, C_2), \cos \theta = |\widehat{(n_1, n_2)}| = \frac{|A_1A_2 + B_1B_2 + C_1C_2|}{\sqrt{A_1^2 + B_1^2 + C_1^2}\sqrt{A_2^2 + B_2^2 + C_2^2}}$ 平面夹角

$$\begin{aligned} d &= \left| \frac{\overrightarrow{P_1P_0}}{|n|} \right| |\cos \theta| \\ &= \frac{|\overrightarrow{P_1P_0} \times n|}{|n|} \\ &= \frac{|A(x_0 - x) + B(y_0 - y) + C(z_0 - z)|}{\sqrt{A^2 + B^2 + C^2}} \\ &= \frac{|Ax_0 + By_0 + Cz_0 + D|}{\sqrt{A^2 + B^2 + C^2}} \end{aligned}$$

8.4 空间直线及其方程

8.4.1 空间直线的一般方程

$$\begin{cases} A_1x + B_1y + C_1z + D_1 = 0 \\ A_2x + B_2y + C_2z + D_2 = 0 \end{cases}$$

8.4.2 空间直线的对称式方程与参数方程

向量平行直线, 直线的方向向量

$$\begin{aligned} \overrightarrow{M_oM} &= (x - x_0, y - y_0, z - z_0) \\ S &= (m, n, p) \end{aligned} \Rightarrow \begin{cases} \frac{x - x_0}{m} = \frac{y - y_0}{n} = \frac{z - z_0}{p} = t, \text{ 对称式, 点向式方程} \\ \begin{cases} x = x_0 + mt \\ y = y_0 + nt \\ z = z_0 + pt \end{cases} \text{ 参数方程} \end{cases}$$

8.4.3 两直线夹角

$L_1, s_1 = (A_1, B_1, C_1), L_2, s_2 = (A_2, B_2, C_2), \cos \theta = |\widehat{(s_1, s_2)}| = \frac{|A_1A_2 + B_1B_2 + C_1C_2|}{\sqrt{A_1^2 + B_1^2 + C_1^2}\sqrt{A_2^2 + B_2^2 + C_2^2}}$ 直线夹角

8.4.4 直线与平面夹角

直线和投影直线的夹角, 直线与平面夹角

$$\begin{aligned} \varphi &= \left| \frac{\pi}{2} - (\vec{s}, \vec{n}) \right| \\ s &= (m, n, p) \\ n &= (A, B, C) \end{aligned} \Rightarrow \begin{aligned} \sin \varphi &= \frac{|Am + Bn + Cp|}{\sqrt{A^2 + B^2 + C^2}\sqrt{m^2 + n^2 + p^2}} \\ \frac{A}{m} &= \frac{B}{n} = \frac{C}{p} \text{ 垂直} \end{aligned}$$

8.4.5 例

$$\left. \begin{aligned} A_1x + B_1y + C_1z + D_1 &= 0 & I \\ A_2x + B_2y + C_2z + D_2 &= 0 & II \end{aligned} \right\} L \Rightarrow A_1x + B_1y + C_1z + D_1 + \lambda(A_2x + B_2y + C_2z + D_2) = 0 \text{ 过 } L \text{ 平面束, 不含 } II$$

8.5 曲面及其方程

8.5.1 曲面研究的基本问题

轨迹到方程, 方程到形状

$$x^2 + y^2 + z^2 = R^2 \text{ 球面}$$

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = R^2 \text{ 球面}$$

$$Ax^2 + Ay^2 + Az^2 + Dx + Ey + Fz + G = 0 \text{ 一般球面}$$

8.5.2 旋转曲面

平面上曲线绕直线旋转一周, 母线, 轴, 旋转曲面

$$f(y, z) = 0 \Rightarrow f(\pm\sqrt{x^2 + y^2}, z) = 0 \text{ 圆台}$$

相交直线 L 绕 R 旋转一周, 交点顶点, 夹角 $(0 < \alpha < \frac{\pi}{2})$ 半顶角

$$z^2 = a^2(x^2 + y^2) \text{ 圆锥}$$

$$\left. \begin{aligned} \frac{x^2}{a^2} - \frac{z^2}{b^2} = 1 \text{ 双曲线} &\Rightarrow \left. \begin{aligned} \frac{(x^2+y^2)^2}{a^2} - \frac{z^2}{b^2} = 1 \text{ 单叶双曲面} \\ \frac{x^2}{a^2} - \frac{(z^2+y^2)^2}{b^2} = 1 \text{ 双叶双曲面} \end{aligned} \right\} \text{ 两种二次} \end{aligned} \right\}$$

8.5.3 柱面

$x^2 + y^2 = R^2$ 圆柱面, 准线 (定曲线), 母线

$$y^2 = ax \text{ 抛物柱面}$$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 \text{ 椭圆柱面}$$

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1 \text{ 双曲柱面}$$

三种二次

8.5.4 二次曲面九

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = z^2 \text{ 椭圆锥面}$$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = z \text{ 椭圆抛物面}$$

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = z \text{ 双曲抛物面}$$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1 \text{ 椭球面}$$

8.6 空间曲线及其方程

8.6.1 空间曲线一般方程

$$\begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases}$$

8.6.2 空间曲线参数方程

$$\begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases} \Rightarrow \begin{cases} x = a \cos \theta \\ y = a \sin \theta \\ z = b\theta \end{cases} \text{ 螺旋线, } 2\pi b \text{ 螺距}$$

空间曲线参数方程

$$\Gamma \begin{cases} x = \varphi(t) \\ y = \psi(t) \\ z = \omega(t) \end{cases} \Rightarrow \begin{cases} x = \sqrt{[\varphi(t)]^2 + [\psi(t)]^2} \cos \theta \\ y = \sqrt{[\varphi(t)]^2 + [\psi(t)]^2} \sin \theta \\ z = \omega(t) \end{cases} \text{ 曲面}$$

$$\Gamma \begin{cases} x = a \sin \varphi \\ y = 0 \\ z = a \cos \varphi \end{cases} \Rightarrow \begin{cases} x = \sqrt{[a \sin \varphi]^2 + [0]^2} \cos \theta = a \sin \varphi \cos \theta \\ y = \sqrt{[a \sin \varphi]^2 + [0]^2} \sin \theta = a \sin \varphi \sin \theta \\ z = a \cos \varphi, \end{cases} \quad \text{球面}$$

8.6.3 空间曲线在坐标面投影

$H(x, y) = 0$ 投影柱面

$$\begin{cases} H(x, y) = 0 \\ z = 0 \end{cases} \quad \text{投影曲线}$$

9 多元函数微分及其应用

9.1 多元函数的基本概念

9.1.1 平面點集 n 維空間

平面點集

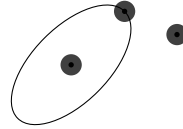
R^2 坐標平面

$C = \{(x, y) | x^2 + y^2 < r^2\}$ 平面點集

$U(P_0, \delta) = \{P | PP_0 < \delta\}$ 鄰域

$\dot{U}(P_0, \delta) = \{P | 0 < PP_0 < \delta\}$ 去心鄰域

$\exists U(P), U(P) \subset E, P \in E$ 內點
 $\exists U(P), U(P) \cap E = \emptyset, P \notin E$ 外點
 $P \in R^2, P = P_1 \cap P_2$
 $E \subset R^2 \left. \begin{array}{l} \exists U(P_1), U(P_1) \subset E \\ \exists U(P_2), U(P_2) \cap E = \emptyset \end{array} \right\}, P \in E$ 邊界點



E 邊界點的全體, ∂E 邊界點, ∂E

$\forall \delta > 0, \dot{U}(P, \delta) \cap E \neq \emptyset$ 總有 E 中的點, $P \in E$ 聚點 (內點和邊界)

開集, 內點; 閉集, $\partial E \subset E$; 連通集, 任意點連線仍在集合;

區域, 連通開集; 閉區域, 區域和邊界;

有界集, $\forall E \subset R^2, \text{if } \exists r > 0, E \subset U(O, r), \text{then } E$ 有界集; 無界集, 不是有界集

n 維空間

$R^n = \{(x_1, x_2, \dots, x_n) | x_i \in R, i = 1, 2, \dots, n\}$ 集合

$x = (x_1, x_2, \dots, x_n) \in R^n$
 $y = (y_1, y_2, \dots, y_n) \in R^n$
 $a = (a_1, a_2, \dots, a_n) \in R^n$
 $\lambda \in R$

$$\left. \begin{array}{l} x + y = (x_1 + y_1, x_2 + y_2, \dots, x_n + y_n) \\ \lambda x = (\lambda x_1, \lambda x_2, \dots, \lambda x_n) \end{array} \right\} R^n \text{ 中 } \text{四} \text{性運算}$$

$$\rho(x, y) = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2 + \dots + (x_n - y_n)^2}$$

$$\|x\| = \rho(x, 0) = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

$$\|x - a\| \rightarrow 0, \text{ 變元趨于固定元, 記作 } x \rightarrow a$$

某正數 $\delta > 0$, 點集 $U(a, \delta) = \{x | x \in R^n, \rho(x, a) < \delta\}$, a 的 δ 鄰域

定義 $\text{四} \text{性}$ 預算的集合, n 維空間

9.1.2 多元函數的概念

D 定義域

$D \subset R^2$, 映射 $f: D \rightarrow R$, 稱 $\text{四} \text{元}$ 函數, x, y 自變量

記 $\text{四} z = f(x, y), (x, y) \in D$ z 因變量

函數值 $f(x, y)$ 全體, $f(D) = \{z | z = f(x, y), (x, y) \in D\}$ 值域

$D \subset R^n$, 映射 $f: D \rightarrow R$, 稱 $\text{四} n$ 元函數 ($n \geq 2$ 多元函數),

記 $\text{四} z = f(x_1, x_2, \dots, x_n) = f(\mathbf{x}), \mathbf{x}(x_1, x_2, \dots, x_n) \in D$

多元函數 $\mu = f(\mathbf{x})$, 有意義的變元 \mathbf{x} 的點集, 自然定義域

空間點集 $\{(x, y, z) | z = f(x, y), (x, y) \in D\}$, 二元函數 $z = f(x, y)$ 的圖形

9.1.3 多元函數的極限

$f(x, y)$ 定義域 D , $P_0(x_0, y_0)$ 是 D 聚點
 $\text{if } \exists A, \forall \varepsilon > 0, \exists \delta > 0,$
 $\text{when } \text{點 } P(x, y) \in D \cap \dot{U}(P_0, \delta),$
 $|f(P) - A| = |f(x, y) - A| < \varepsilon$
 $\text{then } A$ 稱 $\text{四} \text{元}$ 函數 $f(x, y)$ 在 $(x, y) \rightarrow (x_0, y_0)$ 極限,
 $\text{記 } \text{四} \lim_{(x, y) \rightarrow (x_0, y_0)} f(x, y) = A$

任意方向趨近

9.1.4 多元函數的連續性

$f(P) = f(x, y)$ 定義域 $D, P_0(x_0, y_0) \in D$ 聚點, $P_0 \in D$, $\lim_{(x,y) \rightarrow (x_0,y_0)} f(x, y) = f(x_0, y_0)$,
 then $f(x, y)$ 在 $P_0(x_0, y_0)$ 連續
 $f(x, y)$ 定義域 D, D 內每一點都是聚點, $f(x, y)$ 在 D 內每一點連續, $f(x, y)$ 在 D 內連續
 $f(x, y)$ 定義域 $D, P_0(x_0, y_0) \in D$ 聚點, if $f(x, y)$ 在 $P_0(x_0, y_0)$ 不連續, then $P_0(x_0, y_0) \in D$ 間斷點
 常數, 不同自變量的一元基本初等函數, 有限次四則運算和複合運算, **多元初等函數**
 一切多元初等函數在**定義區域** (定義域 D 的區域或閉區域) 連續 $\rightarrow \lim_{P \rightarrow P_0} f(P) = f(P_0)$
 有界閉區域 D , 多元連續函數, D 上有界, 取得最大值, 最小值 (**最值**)
 性質 有界閉區域 D , 多元連續函數, 能取得介於最大值和最小值間的任何值 (**介值**)
 有界閉區域 D , 多元連續函數, D 上一致連續 (**一致連續**)

9.2 偏導數

9.2.1 偏導數的定義及其計算法

$f(x, y), P_0(x_0, y_0), (x, y) \in U(P_0, \delta)$, $\text{if } \exists \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x, y_0) - f(x_0, y_0)}{\Delta x} = A$,
 when $y = y_0, x = x_0 + \Delta x$, then $A \in \mathbb{R}$ $f(x, y)$ 在 (x_0, y_0) 對 x 的偏導數,
 函數增量 $f(x_0 + \Delta x, y_0) - f(x_0, y_0)$ 記 $\left. \frac{\partial f}{\partial x} \right|_{x=x_0, y=y_0}, f_x(x_0, y_0)$

$$\left\{ \begin{array}{l} \left. \frac{\partial f}{\partial x} \right|_{x=x_0, y=y_0} = \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x, y_0) - f(x_0, y_0)}{\Delta x} \\ \left. \frac{\partial f}{\partial y} \right|_{x=x_0, y=y_0} = \lim_{\Delta y \rightarrow 0} \frac{f(x_0, y_0 + \Delta y) - f(x_0, y_0)}{\Delta y} \end{array} \right.$$
 $f_x(x, y), f_y(x, y)$ 偏導函數, 偏導數
 偏導數記號 $\in \mathbb{R}$ 整體, 不能看成微分的商
 (一元可導連) 各偏導存在, 不一定連續

9.2.2 高階偏導數

若偏導數的偏導仍存在, 則稱為 $f(x, y)$ 的二階偏導數

$$z = f(x, y) \text{ 的偏導數 } \frac{\partial z}{\partial x} = f_x(x, y), \frac{\partial z}{\partial y} = f_y(x, y), \Rightarrow \left. \begin{array}{l} \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial x} \right) = \frac{\partial^2 z}{\partial x^2} = f_{xx}(x, y) \\ \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial y} \right) = \frac{\partial^2 z}{\partial y \partial x} = f_{yx}(x, y) \text{ (混合偏導數)} \\ \frac{\partial}{\partial y} \left(\frac{\partial z}{\partial x} \right) = \frac{\partial^2 z}{\partial x \partial y} = f_{xy}(x, y) \text{ (混合偏導數)} \\ \frac{\partial}{\partial y} \left(\frac{\partial z}{\partial y} \right) = \frac{\partial^2 z}{\partial y^2} = f_{yy}(x, y) \end{array} \right\}$$
 都是 x, y 的函數,

if $f(x, y)$ 的二階偏導數, $\frac{\partial^2 z}{\partial y \partial x}, \frac{\partial^2 z}{\partial x \partial y}$ 在 D 連續, then $(x, y) \in D, \frac{\partial^2 z}{\partial y \partial x} = \frac{\partial^2 z}{\partial x \partial y}$

$$\left. \begin{array}{l} z = \ln \sqrt{x^2 + y^2}, \frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial y^2} = 0 \\ u = \frac{1}{\sqrt{x^2 + y^2 + z^2}}, \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0 \end{array} \right\} \text{拉普拉斯方程}$$

9.3 全微分

9.3.1 全微分定義

$$\left\{ \begin{array}{l} f(x + \Delta x, y) - f(x, y) \approx f_x(x, y) \Delta x \\ f(x, y + \Delta y) - f(x, y) \approx f_y(x, y) \Delta y \end{array} \right. \quad \text{偏增量, 偏微分}$$

$$\Delta z = f(x + \Delta x, y + \Delta y) - f(x, y) \quad \text{全增量}$$

$if \quad \Delta z = f(x + \Delta x, y + \Delta y) - f(x, y) = A\Delta x + B\Delta y + o(\rho),$
 $then \quad \rho = \sqrt{(\Delta x)^2 + (\Delta y)^2}, A, B \text{ 不依赖 } \Delta x, \Delta y$
 $z = f(x, y), \text{ 在 } (x, y) \text{ 的某邻域有定义,}$
 $f(x, y) \text{ 在 } (x, y) \text{ 可微分,}$
 $A\Delta x + B\Delta y, \text{ 称为函数 } f(x, y) \text{ 全微分,}$
 $记作 } dz = A\Delta x + B\Delta y$

多元函数在区域 D 内个点处都可微分, 函数在 D 内可微分

多元函数在点 P 可微分, 函数在该点连续

$if \quad f(x, y) \text{ 在点 } (x, y) \text{ 可微分,}$
 $then \quad \text{函数 } f(x, y) \text{ 在点 } (x, y) \text{ 偏导数 } \frac{\partial z}{\partial x}, \frac{\partial z}{\partial y} \text{ 必存在}$
 $\text{函数 } f(x, y) \text{ 在点 } (x, y) \text{ 全微分 } dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$
 $z = f(x, y) \text{ 的偏导数 } \frac{\partial z}{\partial x}, \frac{\partial z}{\partial y} \text{ 在点 } (x, y) \text{ 连续, 函数在该点可微分}$
 $\text{微分 } \mathbb{F} \text{ 加原 } \mathbb{F}, u = (x, y, z), du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy + \frac{\partial u}{\partial z} dz$

9.3.2 全微分在近似计算中的应用

$$g = \frac{4\pi^2 l}{T^2}, \Delta g \leq 4\pi^2 \left(\frac{1}{T^2} \delta_l + \frac{2l}{T^3} \delta_T \right)$$

9.4 多元复合函数的求导法则

$if \quad u = \varphi(t), v = \psi(t), \text{ 在 } t \text{ 可导,}$
 $z = f(u, v) \text{ 在 } (u, v) \text{ 具有连续偏导}$
 $, then \quad \text{复合函数 } z = f(\varphi(t), \psi(t)) \text{ 在 } t \text{ 点可导, 且 } \frac{dz}{dt} = \frac{\partial z}{\partial u} \frac{du}{dt} + \frac{\partial z}{\partial v} \frac{dv}{dt} \text{ 全导数}$

$if \quad u = \varphi(t), v = \psi(t), w = \omega(t), \text{ 在 } t \text{ 可导, } z = f(\varphi(t), \psi(t), \omega(t)),$
 $\frac{dz}{dt} = \frac{\partial z}{\partial u} \frac{du}{dt} + \frac{\partial z}{\partial v} \frac{dv}{dt} + \frac{\partial z}{\partial w} \frac{dw}{dt}$

$u = \varphi(x, y), v = \psi(x, y),$
 $if \quad \text{在 } (x, y) \text{ 具有对 } x, y \text{ 的偏导数,}$
 $z = f(u, v) \text{ 在 } (u, v) \text{ 具有连续偏导}$
 $, then \quad \frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial x}$
 $\frac{\partial z}{\partial y} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial y}$

$u = \varphi(x, y), v = \psi(x, y), w = \omega(x, y),$
 $if \quad \text{在 } (x, y) \text{ 点两偏导都存在}$
 $z = f(\varphi(x, y), \psi(x, y), \omega(x, y)),$
 $, then \quad \frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial x} + \frac{\partial z}{\partial w} \frac{\partial w}{\partial x}$
 $\frac{\partial z}{\partial y} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial y} + \frac{\partial z}{\partial w} \frac{\partial w}{\partial y}$

$u = \varphi(x, y) \text{ 在 } (x, y) \text{ 点两偏导都存在,}$
 $if \quad v = \psi(y) \text{ 在 } y \text{ 点可导,}$
 $z = f(u, v) \text{ 在 } (u, v) \text{ 具有连续偏导}$
 $, then \quad z = f(\varphi(x, y), \psi(y)) \text{ 在 } (x, y) \text{ 点两偏导都存在, 且}$
 $\frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial x}$
 $\frac{\partial z}{\partial y} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial y}$

$if \quad z = f(u, x, y) = f[\varphi(x, y), x, y] \text{ 有 } x, y \text{ 的偏导数, then}$
 $\frac{\partial z}{\partial x} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial x}$
 $\frac{\partial z}{\partial y} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial f}{\partial y}$

$$\begin{aligned}
 f'_1 &= f'_u(u, v) \\
 f'_2 &= f'_v(u, v) \\
 f(u, v), \quad f'_{11} &= f''_{uu}(u, v) \\
 f'_{12} &= f''_{uv}(u, v) \\
 f'_{21} &= f''_{vu}(u, v) \\
 f'_{22} &= f''_{vv}(u, v)
 \end{aligned}$$

$$\begin{aligned}
 dz &= \frac{\partial z}{\partial u} du + \frac{\partial z}{\partial v} dv \\
 z = f(u, v) = f(\varphi(x, y), \psi(x, y)), &= \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy \\
 &= \left(\frac{\partial z}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial x} \right) dx + \left(\frac{\partial z}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial y} \right) dy
 \end{aligned}$$

9.5 隱函數求導公式

9.5.1 一個方程

if $P_0(x_0, y_0), (x, y) \in U(P_0, \delta)$ 時 $F(x, y) = 0$, 在 $(x, y) \in U(P_0, \delta)$ 時,
 $F(x, y)$ 具有連續偏導, $F(x_0, y_0) = 0, F_y(x_0, y_0) \neq 0$, then 能確定唯一連續, 連續導數的函數 $y = f(x)$,
 $y_0 = f(x_0), \frac{dy}{dx} = -\frac{F_x}{F_y}$

if $P_0(x_0, y_0, z_0), (x, y, z) \in U(P_0, \delta)$ 時 $F(x, y, z) = 0$, 在 $(x, y, z) \in U(P_0, \delta)$ 時,
 $F(x, y, z)$ 具有連續偏導, $F(x_0, y_0, z_0) = 0, F_z(x_0, y_0, z_0) \neq 0$, then 能確定唯一連續, 連續導數的函數 $z = f(x, y)$,
 $z_0 = f(x_0, y_0), \frac{\partial z}{\partial x} = -\frac{F_x}{F_z}, \frac{\partial z}{\partial y} = -\frac{F_y}{F_z}$

9.5.2 方程組的情形

if $P_0(x_0, y_0, u_0, v_0), (x, y, u, v) \in U(P_0, \delta)$ 時 $F(x, y, u, v) = 0, G(x, y, u, v) = 0$,
 $F(x, y, u, v), G(x, y, u, v)$ 具有連續偏導, 在 $(x, y, u, v) \in U(P_0, \delta)$ 時,
 $F(x_0, y_0, u_0, v_0) = 0, G(x_0, y_0, u_0, v_0) = 0$, then 能確定唯一組連續, 連續偏導數的函數,
 $u = f(x, y), v = f(x, y)$
 $u_0 = f(x_0, y_0), v_0 = f(x_0, y_0)$
 $J = \begin{vmatrix} \frac{\partial F}{\partial u} & \frac{\partial F}{\partial v} \\ \frac{\partial G}{\partial u} & \frac{\partial G}{\partial v} \end{vmatrix} \neq 0 \left(\begin{array}{l} \text{雅可比式} \\ \text{偏導数组成的函数行列式} \end{array} \right)$
 $\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, v)}$
 $\frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(y, v)}$
 $\frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, x)}$
 $\frac{\partial v}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, y)}$

$$\begin{cases} F_x + F_u \frac{\partial u}{\partial x} + F_v \frac{\partial v}{\partial x} = 0 \\ G_x + G_u \frac{\partial u}{\partial x} + G_v \frac{\partial v}{\partial x} = 0 \end{cases} \Rightarrow \begin{array}{l} \frac{\partial u}{\partial x} = \frac{\begin{vmatrix} -F_x & F_v \\ -G_x & G_v \end{vmatrix}}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} = -\frac{\frac{\partial(F, G)}{\partial(x, v)}}{\frac{\partial(F, G)}{\partial(u, v)}} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, v)} \\ \frac{\partial v}{\partial x} = \frac{\begin{vmatrix} F_u & -F_x \\ G_u & -G_x \end{vmatrix}}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} = -\frac{\frac{\partial(F, G)}{\partial(u, x)}}{\frac{\partial(F, G)}{\partial(u, v)}} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, x)} \end{array} \quad \text{证明或推导}$$

$$\begin{aligned} dudv, x = \varphi(u, v), y = \psi(u, v), \\ dx = \frac{\partial \varphi}{\partial u} du + \frac{\partial \varphi}{\partial v} dv \\ dy = \frac{\partial \psi}{\partial u} du + \frac{\partial \psi}{\partial v} dv \end{aligned} \rightarrow \begin{aligned} & |(dx, dy)|_{du=0} \times |(dx, dy)|_{dv=0}| \\ & = \left| \left(\frac{\partial \varphi}{\partial u} du, \frac{\partial \psi}{\partial u} du \right) \times \left(\frac{\partial \varphi}{\partial v} dv, \frac{\partial \psi}{\partial v} dv \right) \right| \\ & = \left| \frac{\partial \varphi}{\partial u} \cdot \frac{\partial \psi}{\partial v} - \frac{\partial \psi}{\partial u} \cdot \frac{\partial \varphi}{\partial v} \right| dudv \\ & = \begin{vmatrix} \frac{\partial \varphi}{\partial u} & \frac{\partial \varphi}{\partial v} \\ \frac{\partial \psi}{\partial u} & \frac{\partial \psi}{\partial v} \end{vmatrix} dudv \\ & = \frac{\partial(\varphi, \psi)}{\partial(u, v)} dudv \end{aligned} \quad \text{二重积分换元和雅可比}$$

9.6 多元函数微分学的几何应用

9.6.1 一元向量值函数及其导数

$$\Gamma \begin{cases} x = \varphi(t), \\ y = \psi(t), \quad t \in [\alpha, \beta] \\ z = \omega(t) \end{cases}$$

記 $r = xi + yj + zk, f(t) = \varphi(t)i + \psi(t)j + \omega(t)k,$
 $r = f(t), t \in [\alpha, \beta]$

数集 $D \subset R$, 映射 $f: D \rightarrow R^n$ 一元向量值函数, 记 $\mathbb{F}r = f(t), t \in D$

$t \in U(t_0)$, 向量值函数 $f(t)$, if $\exists r_0, \forall \varepsilon > 0, \exists \delta$, when $0 < |t - t_0| < \delta, |f(t) - r_0| < \varepsilon$, then $\lim_{t \rightarrow t_0} f(t) = r_0$

$t \in u(t_0)$, 向量值函数 $f(t)$, if $\lim_{t \rightarrow t_0} f(t) = f(t_0)$, $f(t)$ 在 t_0 连续

$t \in D$, 向量值函数 $f(t)$, if $D_1 \subset D$, D_1 内每点连续, D_1 上连续

极限向量为 $r = f(t)$

$t \in U(t_0)$, 向量值函数 $f(t)$, if $\exists \lim_{\Delta t \rightarrow 0} \frac{\Delta r}{\Delta t} = \lim_{\Delta t \rightarrow 0} \frac{f(t_0 + \Delta t) - f(t_0)}{\Delta t}$, then

在 t_0 导数或导向量,

记为 $f'(t_0)$, $\frac{dr}{dt}|_{t=t_0}$

$$f'(t_0) = f'_1(t_0)i + f'_2(t_0)j + f'_3(t_0)k$$

$$\frac{d}{dt}C = 0$$

$$\frac{d}{dt}[cu(t)] = cu'(t)$$

$$\frac{d}{dt}[u(t) \pm v(t)] = u'(t) \pm v'(t)$$

$$\text{向量值函数 } u(t), v(t), \text{ 数量值函数 } \varphi(t) \Rightarrow \frac{d}{dt}[\varphi(t)v(t)] = \varphi'(t)v(t) + \varphi(t)v'(t)$$

$$\frac{d}{dt}[u(t) \cdot v(t)] = u'(t) \cdot v(t) + u(t) \cdot v'(t)$$

$$\frac{d}{dt}[u(t) \times v(t)] = u'(t) \times v(t) + u(t) \times v'(t)$$

$$\frac{d}{dt}u[\varphi(t)] = \varphi'(t)u'[\varphi(t)]$$

$$f'(t_0) = \lim_{t \rightarrow t_0} \frac{\Delta r}{\Delta t} \text{ 与曲线相切}$$

9.6.2 空间曲线的切线与法平面

$$\Gamma \begin{cases} x = \varphi(t), \\ y = \psi(t), \\ z = \omega(t), \end{cases} \quad t \in [\alpha, \beta] \Rightarrow \frac{x-x_0}{\varphi'(t)} = \frac{y-y_0}{\psi'(t)} = \frac{z-z_0}{\omega'(t)}$$

$$\varphi'(t)(x-x_0) + \psi'(t)(y-y_0) + \omega'(t)(z-z_0) = 0$$

$$\Gamma \begin{cases} y = \psi(x), \\ z = \omega(x), \end{cases} \Rightarrow \begin{cases} x = x, \\ y = \psi(x), \\ z = \omega(x), \end{cases} \Rightarrow \frac{x-x_0}{1} = \frac{y-y_0}{\psi'(x)} = \frac{z-z_0}{\omega'(x)}$$

$$(x-x_0) + \psi'(x)(y-y_0) + \omega'(x)(z-z_0) = 0$$

$$\Gamma \begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases} \Rightarrow \begin{cases} y = \psi(x), \\ z = \omega(x), \end{cases} \Rightarrow \begin{cases} F(x, \psi(x), \omega(x)) = 0 \\ G(x, \psi(x), \omega(x)) = 0 \\ \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} \frac{dy}{dx} + \frac{\partial F}{\partial z} \frac{dz}{dx} = 0 \\ \frac{\partial G}{\partial x} + \frac{\partial G}{\partial y} \frac{dy}{dx} + \frac{\partial G}{\partial z} \frac{dz}{dx} = 0 \end{cases}$$

$$\frac{dy}{dx} = \psi'(x) = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, z)} = -\frac{\frac{\partial(F, G)}{\partial(x, z)}}{\frac{\partial(F, G)}{\partial(y, z)}} = -\frac{\begin{vmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial z} \\ \frac{\partial G}{\partial x} & \frac{\partial G}{\partial z} \end{vmatrix}}{\begin{vmatrix} \frac{\partial F}{\partial y} & \frac{\partial F}{\partial z} \\ \frac{\partial G}{\partial y} & \frac{\partial G}{\partial z} \end{vmatrix}}$$

$$\frac{dz}{dx} = \omega'(x) = -\frac{1}{J} \frac{\partial(F, G)}{\partial(y, x)} = -\frac{\frac{\partial(F, G)}{\partial(y, x)}}{\frac{\partial(F, G)}{\partial(y, z)}} = -\frac{\begin{vmatrix} \frac{\partial F}{\partial y} & \frac{\partial F}{\partial x} \\ \frac{\partial G}{\partial y} & \frac{\partial G}{\partial x} \end{vmatrix}}{\begin{vmatrix} \frac{\partial F}{\partial y} & \frac{\partial F}{\partial z} \\ \frac{\partial G}{\partial y} & \frac{\partial G}{\partial z} \end{vmatrix}}$$

9.6.3 曲面的切平面与法线

$$\sum F(x, y, z) = 0$$

$$\text{任意曲线} \Gamma \begin{cases} x = \varphi(t), \\ y = \psi(t), \quad (\alpha < t < \beta), \\ z = \omega(t), \end{cases}$$

$$t = t_0 \text{ 对应 } M(x_0, y_0, z_0)$$

曲线 Γ 在曲面 \sum 上, 过 M 点

$$F[\varphi(t), \psi(t), \omega(t)] = 0,$$

$$F_x|_M \varphi'(t_0) + F_y|_M \psi'(t_0) + F_z|_M \omega'(t_0)$$

$$= (F_x|_M, F_y|_M, F_z|_M) \cdot (\varphi'(t_0), \psi'(t_0), \omega'(t_0))$$

$$= n \cdot s = 0,$$

任一过 M 曲线切线垂直过 M 向量 n , 切线共面, 称为曲面切平面

$$\Rightarrow \begin{aligned} &F_x|_M(x - x_0) + F_y|_M(y - y_0) + F_z|_M(z - z_0) = 0 \\ &\frac{(x-x_0)}{F_x|_M} = \frac{(y-y_0)}{F_y|_M} = \frac{(z-z_0)}{F_z|_M} \end{aligned}$$

$$F_x|_M = f_x(x_0, y_0), F_y|_M = f_y(x_0, y_0), F_z|_M = -1$$

$$\text{记 } K = \sqrt{f_x^2 + f_y^2 + 1}, \cos \gamma > 0,$$

$$z = f(x, y) \Rightarrow F(x, y, z) = f(x, y) - z = 0 \Rightarrow \text{方向余弦 } (\cos \alpha, \cos \beta, \cos \gamma) = \left(\frac{-f_x}{K}, \frac{-f_y}{K}, \frac{1}{K} \right)$$

$$\begin{aligned} &f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) - (z - z_0) = 0 \\ &\frac{(x-x_0)}{f_x(x_0, y_0)} = \frac{(y-y_0)}{f_y(x_0, y_0)} = \frac{(z-z_0)}{-1} \end{aligned}$$

9.7 方向导数与梯度

9.7.1 方向导数

$$\text{单位向量 } e_l = (\cos \alpha, \cos \beta),$$

$$\text{过 } (x_0, y_0) \text{ 射线 } l \begin{cases} x = x_0 + t \cos \alpha \\ y = y_0 + t \cos \beta \end{cases} (t \geq 0), \Rightarrow \frac{\partial f}{\partial l}|_{(x_0, y_0)} = \lim_{t \rightarrow 0^+} \frac{f(x_0 + t \cos \alpha, y_0 + t \cos \beta) - f(x_0, y_0)}{t}$$

方向导数

$$z = f(x, y)$$

$$f(x, y) \text{ 在 } P_0(x_0, y_0) \text{ 可微分, 该点任意方向, 方向导数存在, } \frac{\partial f}{\partial l}|_{(x_0, y_0)} = f_x(x_0, y_0) \cos \alpha + f_y(x_0, y_0) \cos \beta$$

$$f(x, y, z), \frac{\partial f}{\partial l}|_{(x_0, y_0, z_0)} = f_x(x_0, y_0, z_0) \cos \alpha + f_y(x_0, y_0, z_0) \cos \beta + f_z(x_0, y_0, z_0) \cos \gamma$$

9.7.2 梯度

$$f(x, y), D \text{ 内连续偏导数, } \forall P_0 \in D, \mathbf{grad} f(x_0, y_0) = \Delta f(x_0, y_0) = f_x|_{P_0} i + f_y|_{P_0} j, \text{ 梯度, } \Delta = \frac{\partial}{\partial x} i + \frac{\partial}{\partial y} j \text{ 向量微分算子}$$

$$\begin{aligned} f(x, y) \text{ 在 } (x_0, y_0) \text{ 可微分, } \frac{\partial f}{\partial l}|_{(x_0, y_0)} &= f_x(x_0, y_0) \cos \alpha + f_y(x_0, y_0) \cos \beta \\ &= \mathbf{grad} f(x_0, y_0) \cdot e_l \\ \text{单位向量 } e_l = (\cos \alpha, \cos \beta), &= |\mathbf{grad} f(x_0, y_0)| \cos \theta, \theta = \left(\mathbf{grad} f(x_0, y_0), e_l \right) \end{aligned}$$

$$\begin{aligned} \text{曲面 } \sum z = f(x, y), \text{ 等值线 } L f(x, y) = 0, P_0(x_0, y_0), & \text{ 单位法向量 } n = \frac{1}{k} (f_x|_P, f_y|_P) \\ \text{记 } k = \sqrt{f_x^2(x_0, y_0) + f_y^2(x_0, y_0)}, & = \frac{\Delta f(x_0, y_0)}{|\Delta f(x_0, y_0)|} \\ & \Delta f(x_0, y_0) = |\Delta f(x_0, y_0)| n = \frac{\partial f}{\partial n} n \\ & \text{梯度} = \text{梯度的模} \quad \text{梯度的方向} \end{aligned}$$

$$\mathbf{grad} f = \Delta f = f_x|_{P_0} i + f_y|_{P_0} j + f_z|_{P_0} k,$$

$$f(x, y, z), G \text{ 内连续偏导数, } P_0(x_0, y_0, z_0), \text{ 等值面 } f(x, y, z) = c$$

等值面法线方向 n

空间区域 $G \quad \forall M \in G \rightarrow$ 数量 $f(M)$, G 内数量场

空间区域 $G \quad \forall M \in G \rightarrow$ 向量 $f(M)$, G 内向量场

if $F(M)$ 是 $f(M)$ 的梯度 then $f(M)$ 势函数, $F(M)$ 势场

$\frac{m}{r}$ 引力势, $\mathbf{grad} \frac{m}{r}$ 引力场

9.8 多元函数的极值及其求法

9.8.1 多元函数的极值及最大值最小值

if $\exists U(P_0) \subset D, \forall (x, y) \neq P_0, f(x, y) < f(x_0, y_0)$, then 极大值 $f(x_0, y_0)$

$D, z = f(x, y), P_0(x_0, y_0) \in D$, if $\exists U(P_0) \subset D, \forall (x, y) \neq P_0, f(x, y) > f(x_0, y_0)$, then 极小值 $f(x_0, y_0)$

极大值, 极小值统称极值

if $z = f(x, y)$ 在 (x_0, y_0) 具有偏导数, 且在 (x_0, y_0) 点具有极值, then $f_x(x_0, y_0) = 0, f_y(x_0, y_0) = 0$

if $f_x(x_0, y_0) = 0, f_y(x_0, y_0) = 0$, then 驻点 (x_0, y_0)

$$f_x(x_0, y_0, z_0) = 0,$$

if $z = f(x, y, z)$ 在 (x_0, y_0, z_0) 具有偏导数, 且在 (x_0, y_0, z_0) 点具有极值, then $f_y(x_0, y_0, z_0) = 0,$

$$f_z(x_0, y_0, z_0) = 0$$

$z = f(x, y)$ 在 (x_0, y_0) 的某邻域内连续,

$AC - B^2 > 0$, 有极值, $A < 0$ 极大值, $A > 0$ 极小值

且有一阶及二阶偏导数, 又 $f_x(x_0, y_0) = 0, f_y(x_0, y_0) = 0$ if

$AC - B^2 < 0$, 无极值

令 $f_{xx}(x_0, y_0) = A, f_{xy}(x_0, y_0) = B, f_{yy}(x_0, y_0) = C$

$AC - B^2 = 0$, 可能有极值

驻点, 偏导不存在点

9.8.2 条件极值 拉格朗日数乘法

无条件极值, 条件极值; 条件极值到无条件极值

(x_0, y_0) 的某邻域内 $z = f(x, y), \varphi(x, y)$,

有连续一阶导数 $\varphi(x, y) = 0$ (条件) $\rightarrow y = \varphi(x)$, \Rightarrow

$z = f(x, \varphi(x))$ (函数)

$$\left. \frac{dz}{dx} \right|_{x=x_0} = 0$$

$$f_x(x_0, y_0) + f_y(x_0, y_0) \left. \frac{dy}{dx} \right|_{x=x_0} = 0$$

$$f_x(x_0, y_0) - f_y(x_0, y_0) \frac{\varphi_x(x_0, y_0)}{\varphi_y(x_0, y_0)} = 0$$

$$\text{记 } \frac{f_y(x_0, y_0)}{\varphi_y(x_0, y_0)} = -\lambda$$

$$f_y(x_0, y_0) - f_y(x_0, y_0) \frac{\lambda}{\lambda} = 0$$

$$\begin{cases} f_x(x_0, y_0) + \lambda \varphi_x(x_0, y_0) = 0 \\ f_y(x_0, y_0) + \lambda \varphi_y(x_0, y_0) = 0 \\ \varphi(x_0, y_0) = 0 \end{cases}$$

$$L(x, y) = f(x, y) + \lambda \varphi(x, y) \Rightarrow \begin{cases} L_x(x_0, y_0) = 0 \\ L_y(x_0, y_0) = 0 \\ \varphi(x_0, y_0) = 0 \end{cases}$$

拉格朗日函数 L , 拉格朗日乘子 λ
函数 $f(x, y)$, 条件 $\varphi(x, y) = 0$

$$L(x, y, z, t) = f(x, y, z, t) + \lambda \varphi(x, y, z, t) + \mu \psi(x, y, z, t) \Rightarrow \begin{cases} L_x(x_0, y_0, z_0, t_0) = 0 \\ L_y(x_0, y_0, z_0, t_0) = 0 \\ L_z(x_0, y_0, z_0, t_0) = 0 \\ L_t(x_0, y_0, z_0, t_0) = 0 \\ \varphi(x_0, y_0, z_0, t_0) = 0 \\ \psi(x_0, y_0, z_0, t_0) = 0 \end{cases}$$

拉格朗日函数 L ,
拉格朗日乘子 λ, μ
函数 $f(x, y, z, t)$,
条件 $\varphi(x, y, z, t) = 0$,
 $\psi(x, y, z, t) = 0$

9.8.3 二元函数的泰勒公式

$z = f(x, y)$ 在点 $P_0(x_0, y_0)$ 某邻域内连续,

有 $n+1$ 阶连续偏导数,

$(x_0 + h, y_0 + k) \in U(P_0, \delta)$

$$\begin{aligned} f(x_0 + h, y_0 + k) &= f(x_0, y_0) + \left(h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right) f(x_0, y_0) \\ &\Rightarrow \frac{1}{2!} \left(h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^2 f(x_0, y_0) + \cdots + \frac{1}{n!} \left(h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^n f(x_0, y_0) \\ &\quad + \frac{1}{(n+1)!} \left(h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^{n+1} f(x_0 + \theta h, y_0 + \theta k) \quad (0 < \theta < 1) \end{aligned}$$

$$\Phi(t) = f(x_0 + h, y_0 + k) \quad (0 \leq t \leq 1)$$

$$\Phi^{(n)}(t) = \left(h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^n f(x_0 + ht, y_0 + kt)$$

$$\Phi(t) = \Phi(0) + \Phi'(0) + \frac{1}{2}\Phi''(0) + \cdots + \frac{1}{n!}\Phi^{(n)}(0) + \frac{1}{(n+1)!}\Phi^{(n+1)}(\theta t) \quad (0 < \theta < 1) \quad (0)$$

$$\Phi(1) = \Phi(0) + \Phi'(0) + \frac{1}{2}\Phi''(0) + \cdots + \frac{1}{n!}\Phi^{(n)}(0) + \frac{1}{(n+1)!}\Phi^{(n+1)}(\theta) \quad (0 < \theta < 1) \quad ()$$

$$n=0 \text{ 时 } f(x_0 + h, y_0 + k) - f(x_0, y_0) = hf_x(x_0 + \theta h, y_0 + \theta k) + kf_y(x_0 + \theta h, y_0 + \theta k)$$

$$f(x, y), (x, y) \in D, f_x(x, y) \equiv 0, f_y(x, y) \equiv 0, f(x, y) = c$$

9.8.4 极值充分证明

$$\Delta f = f(x, y) - f(x_0, y_0)$$

$$= \left[h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right] f(x_0, y_0) + \frac{1}{2} \left[h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right]^2 f(x_0 + \theta h, y_0 + \theta k)$$

$$f_x(x_0, y_0) = 0, f_y(x_0, y_0) = 0$$

$$= \frac{1}{2} \left[h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right]^2 f(x_0 + \theta h, y_0 + \theta k)$$

$$= \frac{1}{2} (h^2 f_{xx} + 2hk f_{xy} + k^2 f_{yy})$$

$$= \frac{1}{2f_{xx}} (h^2 f_{xx}^2 + 2hk f_{xy} f_{xx} + k^2 f_{xy}^2 - k^2 f_{xy}^2 + k^2 f_{yy} f_{xx})$$

$$= \frac{1}{2f_{xx}} \left[(hf_{xx} + kf_{xy})^2 + k^2 (f_{xx} f_{yy} - f_{xy}^2) \right]$$

$$A = f_{xx}, C = f_{yy}, B = f_{xy}$$

$$AC - B^2 > 0 \quad \begin{cases} A > 0, f(x, y) > f(x_0, y_0), \text{极小值} \\ A < 0, f(x, y) < f(x_0, y_0), \text{极大值} \end{cases}$$

$$AC - B^2 < 0 \quad \begin{cases} A = C = 0, k = h, \Delta f = f_{x,y} \\ A = C = 0, k = -h, \Delta f = -f_{x,y} \end{cases}$$

$$AC - B^2 = 0 \quad \begin{cases} A \neq C = 0, k = 0, \Delta f = \frac{1}{2}h^2 f_{xx} \\ A \neq C = 0, h = -f_{xy} s, k = f_{xx} s, \end{cases}$$

$$AC - B^2 = 0 \quad \begin{cases} f(x, y) = x^2 + y^4 \\ g(x, y) = x^2 + y^3 \end{cases}$$

$$\begin{aligned} \Delta f &= \frac{1}{2} \{ f_{xy}^2 f_{xx} - 2f_{xy}^2 f_{xx} + f_{xx}^2 f_{yy} \} \\ &= \frac{1}{2} f_{xx} \{ f_{xy}^2 - 2f_{xy}^2 + f_{xx} f_{yy} \} \\ &= \frac{1}{2} f_{xx} \{ -f_{xy}^2 \} \end{aligned}$$

9.8.5 最小二乘法

y_i 数据 $\Rightarrow f(t) = at + b$ 线性经验公式

$$M = \sum [y_i - f(t_i)]^2 = \sum [y_i - (at_i + b)]^2 \text{ 偏差平方和,}$$

M 最小为条件选择常数 a, b 的方法, 最小二乘法

\sqrt{M} 均方误差

$$\text{非线性到线性 } M_{\min}(a, b) \Rightarrow \begin{cases} M_a(a, b) = 0 \\ M_b(a, b) = 0 \\ \frac{\partial M}{\partial a} = -2 \sum [y_i - (at_i + b)] = 0 \\ \frac{\partial M}{\partial b} = -2 \sum [y_i - (at_i + b)] = 0 \\ \sum t_i y_i - a \sum t_i^2 - b \sum y_i = 0 \\ \sum y_i - a \sum t_i y_i - bn = 0 \end{cases} \Rightarrow \begin{cases} a = \frac{\begin{vmatrix} \sum t_i y_i & \sum y_i \\ \sum y_i & n \end{vmatrix}}{\begin{vmatrix} \sum t_i^2 & \sum y_i \\ \sum t_i y_i & n \end{vmatrix}} \\ b = \frac{\begin{vmatrix} \sum t_i^2 & \sum t_i y_i \\ \sum t_i y_i & \sum y_i \end{vmatrix}}{\begin{vmatrix} \sum t_i^2 & \sum y_i \\ \sum t_i y_i & n \end{vmatrix}} \end{cases}$$

10 重积分

10.1 二重积分的概念与性质

10.1.1 二重积分的概念

曲顶柱体的体积

$$V = \lim_{\lambda \rightarrow 0} \sum f(\xi_i, \eta_i) \Delta\sigma_i$$

平面薄片的质量

$$m = \lim_{\lambda \rightarrow 0} \sum \mu(\xi_i, \eta_i) \Delta\sigma_i$$

闭区域 D 有界函数

$$\Rightarrow \iint_D f(x, y) d\sigma = \lim_{\lambda \rightarrow 0} \sum f(\xi_i, \eta_i) \Delta\sigma_i \text{ 二重积分}$$

$$\text{分割 } D, \Delta\sigma_1, \Delta\sigma_2, \dots, \Delta\sigma_n \Rightarrow \iint_D f(x, y) d\sigma = \lim_{\lambda \rightarrow 0} \sum f(\xi_i, \eta_i) \Delta\sigma_i$$

$$\Delta\sigma_i = \Delta x_j \cdot y_k, d\sigma \rightarrow dxdy, \iint_D f(x, y) dxdy$$

10.1.2 二重积分的性质

$$\begin{aligned} \iint_D [\alpha f + \beta g] d\sigma &= \alpha \iint_D f d\sigma + \beta \iint_D g d\sigma \\ \iint_D f d\sigma &= \iint_{D_1} f d\sigma + \iint_{D_2} f d\sigma \\ g(x, y), g &\Rightarrow \iint_D 1 \cdot d\sigma = \iint_D d\sigma = \sigma \\ f(x, y), f &\Rightarrow \iint_D f d\sigma \leq \iint_D g d\sigma, f \leq g \\ m\sigma &\leq \iint_D f d\sigma \leq M\sigma, m \leq f \leq M \\ \iint_D f d\sigma &= f(\xi, \eta) \sigma \quad (\xi, \eta) \in D \end{aligned}$$

10.2 二重积分的计算法

10.2.1 直角坐标计算二重积分

$$\begin{aligned} x\text{型} &\begin{cases} D: \varphi_1(x) \leq y \leq \varphi_2(x), a \leq x \leq b \\ A(x) = \int_{\varphi_1(x)}^{\varphi_2(x)} f(x, y) dy \\ V = \int_a^b A(x) dx = \int_a^b \left[\int_{\varphi_1(x)}^{\varphi_2(x)} f(x, y) dy \right] dx = \int_a^b dx \int_{\varphi_1(x)}^{\varphi_2(x)} f(x, y) dy = \iint_D f(x, y) d\sigma \end{cases} \\ y\text{型} &\begin{cases} D: \psi_1(y) \leq x \leq \psi_2(y), a \leq y \leq b \\ A(y) = \int_{\psi_1(y)}^{\psi_2(y)} f(x, y) dx \\ V = \int_a^b A(y) dy = \int_a^b \left[\int_{\psi_1(y)}^{\psi_2(y)} f(x, y) dx \right] dy = \int_a^b dy \int_{\psi_1(y)}^{\psi_2(y)} f(x, y) dx = \iint_D f(x, y) d\sigma \end{cases} \end{aligned}$$

非 x 非 y 型, 分割积分面

10.2.2 极坐标计算二重积分

$$\begin{aligned} S_{\text{扇}} &= \frac{r^2 \theta}{2} \\ \Delta\sigma &= \frac{1}{2} [(r + \Delta r)^2 - r^2] \Delta\theta = \frac{1}{2} [\Delta r^2 + 2r\Delta r] \Delta\theta = \frac{1}{2} [\Delta r + 2r] \Delta r \Delta\theta = \bar{r} \Delta r \Delta\theta \\ \lim_{\lambda \rightarrow 0} \sum f(\xi_i, \eta_i) \Delta\sigma_i &= \lim_{\lambda \rightarrow 0} \sum f(\bar{r} \cos \bar{\theta}, \bar{r} \sin \bar{\theta}) \bar{r} \Delta r \Delta\theta \\ \iint_D f(x, y) d\sigma &= \iint_D f(x, y) dxdy = \iint_D f(r \cos \theta, r \sin \theta) r dr d\theta \\ \iint_D f(r \cos \theta, r \sin \theta) r dr d\theta &= \int_a^b \left[\int_{\varphi_1(\theta)}^{\varphi_2(\theta)} f(r \cos \theta, r \sin \theta) r dr \right] d\theta \\ \sigma &= \iint_D r dr d\theta = \frac{1}{2} \int_a^b [\varphi_2(\theta)^2 - \varphi_1(\theta)^2] d\theta = \frac{1}{2} \int_a^b \varphi_2(\theta)^2 d\theta \end{aligned}$$

10.2.3 二重积分换元法

$f(x, y)$, D 内连续,

变换 $T: x = x(u, v), y = y(u, v)$

uOv 面 $D' \rightarrow xOy$ 面 D , 一对一 $\Rightarrow \iint_D f(x, y) dx dy = \iint_{D'} f(x(u, v), y(u, v)) |J(u, v)| du dv$

$x(u, v), y(u, v)$ 在 D' 一阶连续偏导,

D' 上雅可比式, $J(u, v) = \frac{\partial(x, y)}{\partial(u, v)} \neq 0$,

$$c^2 = a^2 + b^2 - 2ab \cos c$$

$$\begin{cases} M_1: x_1 = x(u, v), y_1 = y(u, v) \\ M_2: x_2 = x(u+h, v) = x_1 + x_u(u, v)h + o(h) \\ y_2 = y(u+h, v) = y_1 + y_u(u, v)h + o(h) \\ M_4: x_3 = x(u, v+h) = x_1 + x_v(u, v)h + o(h) \\ y_3 = y(u, v+h) = y_1 + y_v(u, v)h + o(h) \end{cases}$$

$$\begin{aligned} s_{\text{三角形}} &= \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} = \frac{1}{2} \begin{vmatrix} x_2 - x_1 & y_2 - y_1 \\ x_3 - x_1 & y_3 - y_1 \end{vmatrix} \\ &= \frac{1}{2} \begin{vmatrix} x_u(u, v)h & y_u(u, v)h \\ x_v(u, v)h & y_v(u, v)h \end{vmatrix} = \frac{1}{2}h^2 \begin{vmatrix} x_u(u, v) & y_u(u, v) \\ x_v(u, v) & y_v(u, v) \end{vmatrix} = \frac{1}{2}h^2 \begin{vmatrix} x_u(u, v) & x_v(u, v) \\ y_u(u, v) & y_v(u, v) \end{vmatrix} = \frac{1}{2}h^2 \frac{\partial(x, y)}{\partial(u, v)} \end{aligned}$$

tikz test

