

Student information:

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- Assignment-1: Video Classification

Assignment objective:

Using the customized dataset "UCF-101" to perform "Action recognition" for 3 different classes to predict the correct video class (Video Classification) using Classical Machine learning and Deep Learning Models.

Task: Action recognition:

1. Using Classical Machine Learning models.
2. Using Deep Learning Models

This python notebook file contains the code for following tasks:

1. Loading the dataset for 3 classes:
 - Class-1: PullUps
 - Class-2: Punch
 - Class-3: PullUps
 - The dataset is split into Train, Test and Validation.
 - For each category there is a separate CSV file.
2. Implementation of Deep Learning Learning models like 2D-CNN and 3D-CNN etc.
3. Model hyperparameter tuning
4. Performance evaluation and comparison

Environment Setup

1. Installing required modules
 - Before running this notebook, install dependencies using:

```
pip install -r requirements.txt
```

- (Ignore if already done)

1. importing modules and basic setup

```
import os;
import torch
from torch.utils.data import DataLoader
from torchvision import transforms
from data_loader import VideoDataset2D
from models import ResNet18Temporal
from utils import train_one_epoch, eval_one_epoch, EarlyStopping
from tqdm import trange
import matplotlib.pyplot as plt
import seaborn as sns
```

```

import numpy as np
from sklearn.metrics import classification_report, confusion_matrix,
accuracy_score
import time
import random
import psutil
from data_loader import VideoDataset3D
from models import ResNet3D

from sklearn.metrics import precision_recall_fscore_support
import json
import time

```

1. Reproducibility and Random Seed Initialization

```

seed = 42
random.seed(seed)
np.random.seed(seed)
torch.manual_seed(seed)
torch.cuda.manual_seed_all(seed)

torch.backends.cudnn.deterministic = True
torch.backends.cudnn.benchmark = False

```

1. Creating required directories

```

os.makedirs("../results", exist_ok=True);
os.makedirs("../results/confusion_matrices", exist_ok=True);
os.makedirs("../results/confusion_matrices/deep_learning",
exist_ok=True);
os.makedirs("../results/performance_plots", exist_ok=True);
os.makedirs("../results/performance_plots/deep_learning",
exist_ok=True);
os.makedirs("../results/feature_visualizations", exist_ok=True);
os.makedirs("../results/saved_models", exist_ok=True);
os.makedirs("../results/saved_models/deep_learning", exist_ok=True);
os.makedirs("../results/stats_deep_learning", exist_ok=True);

```

1. Directory path for saving trained models

```

SAVE_DIR = "../results/saved_models/deep_learning";
os.makedirs(SAVE_DIR, exist_ok=True);

MODEL_2D_PATH = os.path.join(SAVE_DIR, "best_2d-cnn.pth");
MODEL_3D_PATH = os.path.join(SAVE_DIR, "best_3d-cnn.pth");

STATS_2D_PATH = "../results/stats_deep_learning/stats_2d.json";
STATS_3D_PATH = "../results/stats_deep_learning/stats_3d.json";

```

1. Transforms

```
train_tfms = transforms.Compose([
    transforms.ToPILImage(),
    transforms.RandomResizedCrop(224),
    transforms.RandomHorizontalFlip(),
    transforms.ColorJitter(brightness=0.3, contrast=0.3,
saturation=0.3),
    transforms.RandomRotation(10),
    transforms.ToTensor(),
    transforms.Normalize([0.485,0.456,0.406],[0.229,0.224,0.225])
])

val_tfms = transforms.Compose([
    transforms.ToPILImage(),
    transforms.Resize(256),
    transforms.CenterCrop(224),
    transforms.ToTensor(),
    transforms.Normalize([0.485,0.456,0.406],[0.229,0.224,0.225])
])
```

1. Dataset & loaders

```
class_map = {"PullUps": 0, "Punch": 1, "PushUps": 2}
num_classes = len(class_map)

dataset_root = "../dataset_info/dataset"

train_ds_2d =
VideoDataset2D("../dataset_info/dataset/splits/train.csv",
                dataset_root, class_map,
                num_frames=20, transform=train_tfms,
train=True)

val_ds_2d = VideoDataset2D("../dataset_info/dataset/splits/val.csv",
                dataset_root, class_map,
                num_frames=20, transform=val_tfms, train=False)

test_ds_2d = VideoDataset2D("../dataset_info/dataset/splits/test.csv",
                dataset_root, class_map,
                num_frames=20, transform=val_tfms,
train=False)

train_loader_2d = DataLoader(train_ds_2d, batch_size=4, shuffle=True,
num_workers=4)
val_loader_2d   = DataLoader(val_ds_2d, batch_size=4, shuffle=False,
num_workers=4)
test_loader_2d  = DataLoader(test_ds_2d, batch_size=4, shuffle=False,
num_workers=4)
```

Deep Learning Algorithms

Implementing following Deep Learning Models

- 2D-CNN - with temporal pooling (ResNet18 pretrained on ImageNet)
 - 3D-CNN - pre-trained 3D ResNet-18 (R3D-18), which is an I3D-style 3D CNN architecture
-

1. 2D CNN with Temporal Pooling

- Use pre-trained 2D CNN (ResNet-18, ResNet-50, or EfficientNet-B0) for frame-level features
- Extract features from sampled frames (e.g., 16-32 frames per video)

2D CNN: Model, optimizer and scheduler selection

```
device = "cuda" if torch.cuda.is_available() else "cpu"

model_2d = ResNet18Temporal(num_classes=num_classes, pooling="avg",
dropout=0.5).to(device)

criterion = torch.nn.CrossEntropyLoss(label_smoothing=0.9)

# Using Adam as optimizer
optimizer = torch.optim.Adam(model_2d.parameters(), lr=1e-4,
weight_decay=1e-4)
# Learning rate scheduling
scheduler = torch.optim.lr_scheduler.StepLR(optimizer, step_size=5,
gamma=0.5)
# Early stopping
early_stop = EarlyStopping(patience=3)
```

2D CNN: Training loop (with early stopping)

- This will take around 30 minutes to complete.

```
start_time = time.time()

EPOCHS = 12
best_val_acc = 0.0

train_losses_2d = []
val_losses_2d = []
train_accs_2d = []
val_accs_2d = []

# ===== LOAD IF EXISTS =====
if os.path.exists(MODEL_2D_PATH):

    print("Found saved 2D model. Loading...")
```

```

    model_2d.load_state_dict(torch.load(MODEL_2D_PATH,
map_location=device))
    model_2d.to(device)
    model_2d.eval()

    if os.path.exists(STATS_2D_PATH):
        with open(STATS_2D_PATH, "r") as f:
            stats = json.load(f)

            # ---- SAFE LOAD (no KeyError) ----
            train_losses_2d = stats.get("train_losses", [])
            val_losses_2d    = stats.get("val_losses", [])
            train_accs_2d    = stats.get("train_accs", [])
            val_accs_2d      = stats.get("val_accs", [])
            best_val_acc     = max(val_accs_2d) if len(val_accs_2d) > 0
    else 0.0

        print("Loaded training curves from stats_2d.json")
    else:
        print("stats_2d.json not found → curves unavailable")

# ===== TRAIN IF NOT EXISTS =====
else:
    print("No saved 2D model found. Starting training...")

    for epoch in trange(EPOCHS, desc="2D CNN Epochs"):

        train_loss, train_acc = train_one_epoch(
            model_2d, train_loader_2d, optimizer, criterion, device)

        val_loss, val_acc = eval_one_epoch(
            model_2d, val_loader_2d, criterion, device)

        scheduler.step()

        print(
            f"\nEpoch [{epoch+1}/{EPOCHS}] "
            f"Train Loss: {train_loss:.4f} | Train Acc:
{train_acc:.4f} || "
            f"Val Loss: {val_loss:.4f} | Val Acc: {val_acc:.4f}"
        )

        train_losses_2d.append(train_loss)
        val_losses_2d.append(val_loss)
        train_accs_2d.append(train_acc)
        val_accs_2d.append(val_acc)

        if val_acc > best_val_acc:
            best_val_acc = val_acc

```

```

        torch.save(model_2d.state_dict(), MODEL_2D_PATH)

    early_stop(val_loss)
    if early_stop.stop:
        print("\n Early stopping triggered")
        break

    print("2D CNN Training complete. Best Val Acc:", best_val_acc)

    # ===== SAVE TRAINING CURVES =====
    stats_2d = {
        "train_losses": train_losses_2d,
        "val_losses": val_losses_2d,
        "train_accs": train_accs_2d,
        "val_accs": val_accs_2d,
        "best_val_acc": best_val_acc
    }

    with open(STATS_2D_PATH, "w") as f:
        json.dump(stats_2d, f, indent=4)

    print("Training curves saved to stats_2d.json")

end_time = time.time()
train_time_2d = end_time - start_time

np.save("../results/stats_deep_learning/train_time_2d.npy",
train_time_2d)
print("2D CNN Training Time (seconds):", train_time_2d)

No saved 2D model found. Starting training...

2D CNN Epochs:   8%|██████          | 1/12 [03:08<34:37, 188.91s/it]

Epoch [1/12] Train Loss: 1.2187 | Train Acc: 0.4391 || Val Loss:
1.1743 | Val Acc: 0.4444

2D CNN Epochs:  17%|███████        | 2/12 [06:19<31:39, 189.95s/it]

Epoch [2/12] Train Loss: 1.1580 | Train Acc: 0.4244 || Val Loss:
1.1139 | Val Acc: 0.4000

2D CNN Epochs:  25%|███████        | 3/12 [09:23<28:03, 187.08s/it]

Epoch [3/12] Train Loss: 1.1284 | Train Acc: 0.4723 || Val Loss:
1.0944 | Val Acc: 0.8222

2D CNN Epochs:  33%|███████        | 4/12 [11:22<21:22, 160.33s/it]

```

Epoch [4/12] Train Loss: 1.1134 | Train Acc: 0.4317 || Val Loss: 1.0940 | Val Acc: 0.7556

2D CNN Epochs: 42%|██████ | 5/12 [13:02<16:09, 138.52s/it]

Epoch [5/12] Train Loss: 1.1100 | Train Acc: 0.4760 || Val Loss: 1.0928 | Val Acc: 0.8444

2D CNN Epochs: 50%|██████ | 6/12 [14:43<12:33, 125.66s/it]

Epoch [6/12] Train Loss: 1.1101 | Train Acc: 0.4613 || Val Loss: 1.0927 | Val Acc: 0.8667

2D CNN Epochs: 58%|██████ | 7/12 [16:34<10:05, 121.14s/it]

Epoch [7/12] Train Loss: 1.1074 | Train Acc: 0.5683 || Val Loss: 1.0918 | Val Acc: 0.9111

2D CNN Epochs: 67%|██████ | 8/12 [18:16<07:39, 114.79s/it]

Epoch [8/12] Train Loss: 1.1057 | Train Acc: 0.5720 || Val Loss: 1.0914 | Val Acc: 0.9111

2D CNN Epochs: 75%|██████ | 9/12 [20:19<05:52, 117.62s/it]

Epoch [9/12] Train Loss: 1.1055 | Train Acc: 0.6199 || Val Loss: 1.0916 | Val Acc: 0.9333

2D CNN Epochs: 83%|██████ | 10/12 [23:37<04:44, 142.28s/it]

Epoch [10/12] Train Loss: 1.1041 | Train Acc: 0.6310 || Val Loss: 1.0912 | Val Acc: 0.9111

2D CNN Epochs: 92%|██████ | 11/12 [27:00<02:40, 160.81s/it]

Epoch [11/12] Train Loss: 1.1022 | Train Acc: 0.6421 || Val Loss: 1.0917 | Val Acc: 0.9111

2D CNN Epochs: 100%|██████ | 12/12 [30:22<00:00, 151.89s/it]

Epoch [12/12] Train Loss: 1.1056 | Train Acc: 0.5646 || Val Loss: 1.0919 | Val Acc: 0.9333

2D CNN Training complete. Best Val Acc: 0.9333333333333333

Training curves saved to stats_2d.json

2D CNN Training Time (seconds): 1822.7417349815369

2D CNN: Loading best model

```
# Load best saved model
model_2d.load_state_dict(torch.load(MODEL_2D_PATH,
map_location=device))
model_2d.eval()

print("Model loaded successfully")
print("Backbone: ResNet-18 (ImageNet pretrained)")
print("Input: fixed-length RGB frame sequences (224x224)")
print("Temporal aggregation: Temporal pooling")
print("Classifier head: Dropout → Fully Connected (3 classes)")

print("Trainable parameters:",
      sum(p.numel() for p in model_2d.parameters() if
p.requires_grad))

print("Total parameters:",
      sum(p.numel() for p in model_2d.parameters()))

Model loaded successfully
Backbone: ResNet-18 (ImageNet pretrained)
Input: fixed-length RGB frame sequences (224x224)
Temporal aggregation: Temporal pooling
Classifier head: Dropout → Fully Connected (3 classes)
Trainable parameters: 11178051
Total parameters: 11178051
```

2D CNN: Test set evaluation

```
all_preds_2d = []
all_labels_2d = []

with torch.no_grad():
    for x, y in test_loader_2d:
        x, y = x.to(device), y.to(device)
        out = model_2d(x)
        preds = torch.argmax(out, dim=1)

        all_preds_2d.extend(preds.cpu().numpy())
        all_labels_2d.extend(y.cpu().numpy())

all_preds_2d = np.array(all_preds_2d)
all_labels_2d = np.array(all_labels_2d)
```

2D CNN: Evaluation metrics


```
print("2D CNN Test Accuracy:", accuracy_score(all_labels_2d,
all_preds_2d))
```

```
print("\nClassification Report:")
```

```
print(classification_report(all_labels_2d, all_preds_2d,
target_names=list(class_map.keys())))
```

2D CNN Test Accuracy: 0.9347826086956522

Classification Report:

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| PullUps | 1.00 | 0.92 | 0.96 | 13 |
| Punch | 0.87 | 1.00 | 0.93 | 20 |
| PushUps | 1.00 | 0.85 | 0.92 | 13 |
| | | | | |
| accuracy | | | 0.93 | 46 |
| macro avg | 0.96 | 0.92 | 0.94 | 46 |
| weighted avg | 0.94 | 0.93 | 0.93 | 46 |

2D CNN: Confusion matrix

```
conf_matrix_2d = confusion_matrix(all_labels_2d, all_preds_2d)
```

```
plt.figure(figsize=(6,5))
```

```
sns.heatmap(conf_matrix_2d, annot=True, fmt="d",
            xticklabels=class_map.keys(),
            yticklabels=class_map.keys(),
            cmap="Blues")
```

```
plt.xlabel("Predicted")
```

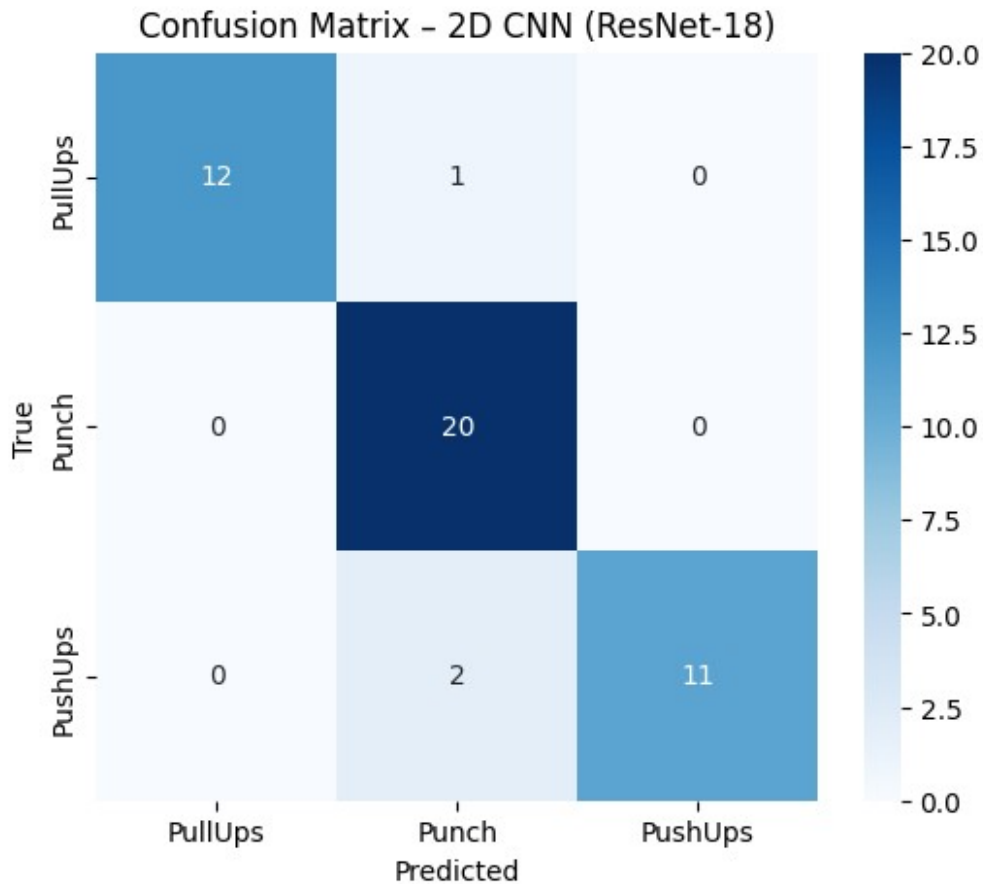
```
plt.ylabel("True")
```

```
plt.title("Confusion Matrix – 2D CNN (ResNet-18)")
```

```
plt.savefig("../results/confusion_matrices/deep_learning/2d_resnet18_c
onfusion_matrix.png")
```

```
plt.show()
```

```
plt.close();
```



2D CNN: Learning curves

```
#print("Train losses:", train_losses_2d)
#print("Val losses:", val_losses_2d)
#print("Train accs:", train_accs_2d)
#print("Val accs:", val_accs_2d)

#print(len(train_losses_2d), len(val_losses_2d), len(train_accs_2d),
      len(val_accs_2d))

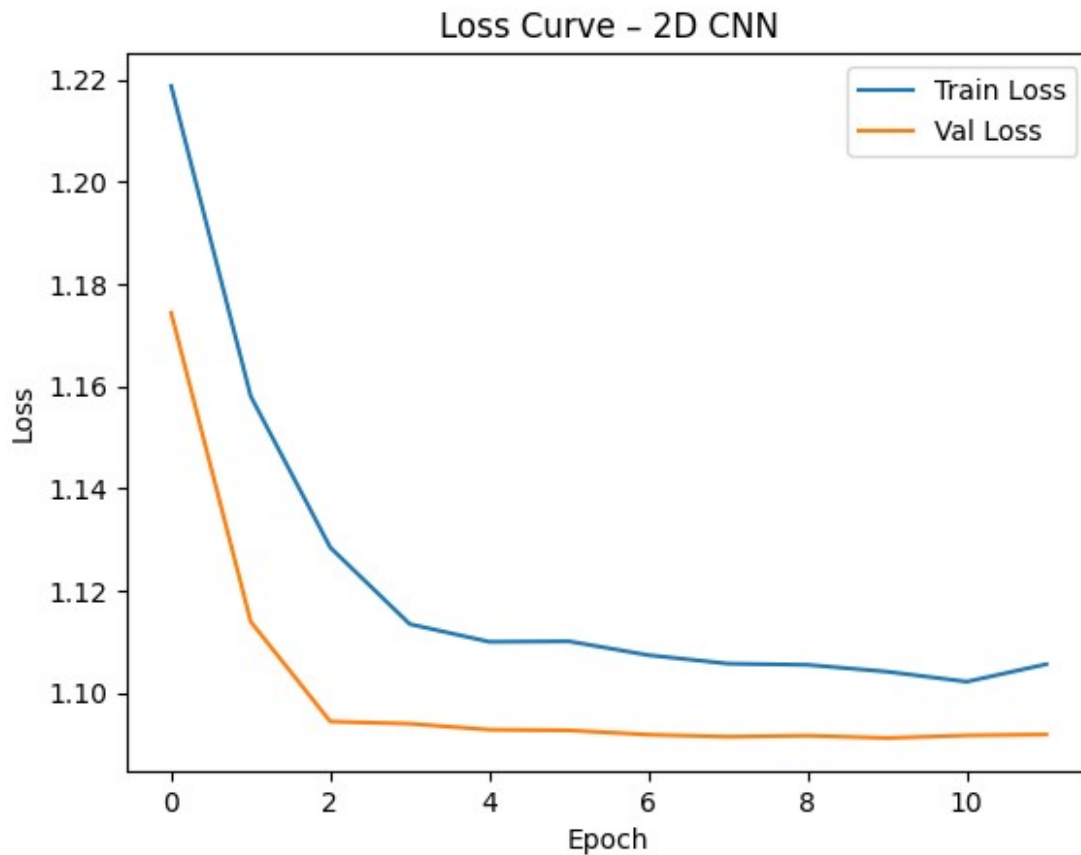
plt.figure()
plt.plot(train_losses_2d, label="Train Loss")
plt.plot(val_losses_2d, label="Val Loss")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.title("Loss Curve - 2D CNN")
plt.legend()
plt.savefig("../results/performance_plots/deep_learning/2d_cnn_loss_curve.png", dpi=300, bbox_inches="tight");
plt.show()
plt.close()
```

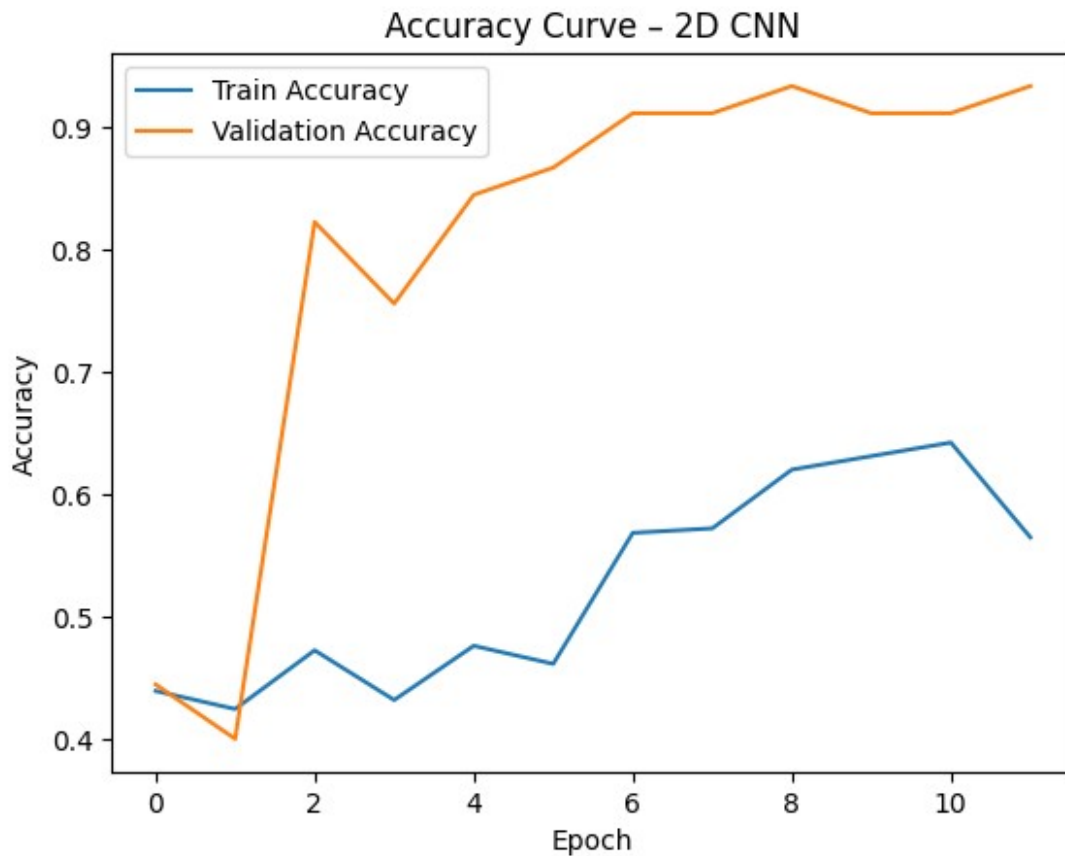
```

plt.figure()
plt.plot(train_accs_2d, label="Train Accuracy")
plt.plot(val_accs_2d, label="Validation Accuracy")
plt.xlabel("Epoch")
plt.ylabel("Accuracy")
plt.title("Accuracy Curve – 2D CNN")
plt.legend()

plt.savefig("../results/performance_plots/deep_learning/2d_cnn_accuracy_curve.png", dpi=300, bbox_inches="tight");
plt.show()
plt.close()

```





2D CNN: Inference time (computational analysis)

```
x, y = next(iter(test_loader_2d));
x = x.to(device);

start = time.time();
with torch.no_grad():
    _ = model_2d(x)
end = time.time();

inf_time_2d = (end - start) / x.size(0) ;

np.save("../results/stats_deep_learning/inf_time_2d.npy",
inf_time_2d);
print("Inference time per batch (seconds):", end-start);
print("Approx inference time per video (seconds):", inf_time_2d);

Inference time per batch (seconds): 0.935901403427124
Approx inference time per video (seconds): 0.233975350856781
```

2D CNN: Model size (parameter count)

```
total_params_2d = sum(p.numel() for p in model_2d.parameters())
trainable_params_2d = sum(p.numel() for p in model_2d.parameters() if
p.requires_grad)
```

```
print("Total parameters:", total_params_2d)
print("Trainable parameters:", trainable_params_2d)
```

```
Total parameters: 11178051
Trainable parameters: 11178051
```

2D CNN: Error analysis

```
wrong_idx = np.where(all_preds_2d != all_labels_2d)[0]
print("Wrong predictions:", len(wrong_idx))

if len(wrong_idx) > 0:
    for i in wrong_idx[:5]:

        row = test_ds_2d.data.iloc[i]    # CSV row
        video_path = row["clip_path"]

        true_label = list(class_map.keys())[all_labels_2d[i]]
        pred_label = list(class_map.keys())[all_preds_2d[i]]

        print("Video:", video_path)
        print("True:", true_label, "| Pred:", pred_label)
        print("-"*50)
```

```
Wrong predictions: 3
Video: /PullUps/v_PullUps_g07_c04.avi
True: PullUps | Pred: Punch
```

```
-----
Video: /PushUps/v_PushUps_g07_c04.avi
True: PushUps | Pred: Punch
```

```
-----
Video: /PushUps/v_PushUps_g15_c03.avi
True: PushUps | Pred: Punch
-----
```

2D CNN: File size on disk

```
model_path = MODEL_2D_PATH
file_size_mb_2d = os.path.getsize(model_path) / (1024 * 1024)
np.save("../results/stats_deep_learning/model_size_2d.npy",
file_size_mb_2d)
print("Saved model file size: {:.2f} MB".format(file_size_mb_2d))
```

```
Saved model file size: 42.72 MB
```

2D CNN: Memory usage

```

print("CUDA available:", torch.cuda.is_available())
print("Torch CUDA version:", torch.version.cuda)
print("GPU name:", torch.cuda.get_device_name(0) if
torch.cuda.is_available() else "No GPU detected")

if torch.cuda.is_available():
    print("GPU memory allocated:",
          torch.cuda.memory_allocated() / (1024**2), "MB")
    print("GPU memory reserved:",
          torch.cuda.memory_reserved() / (1024**2), "MB")

process = psutil.Process(os.getpid())
ram_mb = process.memory_info().rss / (1024 * 1024)

print("Current RAM usage:", ram_mb, "MB")

CUDA available: False
Torch CUDA version: None
GPU name: No GPU detected
Current RAM usage: 1109.640625 MB

```

2D CNN: Saving the results for comparative analysis

```

acc2d = accuracy_score(all_labels_2d, all_preds_2d)
p2d, r2d, f12d, _ = precision_recall_fscore_support(all_labels_2d,
all_preds_2d, average="macro")

stats_2d = {
    "accuracy": acc2d,
    "precision": p2d,
    "recall": r2d,
    "f1": f12d,
    "inference_time": inf_time_2d,
    "params": total_params_2d,
    "model_size_mb": file_size_mb_2d
}

with open("../results/stats_deep_learning/stats_2d.json", "w") as f:
    json.dump(stats_2d, f, indent=4)

```

1. 3D Convolutional Networks
 - I3D Architecture
 - Implement or use pre-trained 3D CNN
 - Process video clips (e.g., 16 frames) as 3D volumes
 - Fine-tune on your dataset

3D CNN: Dataloaders

```

train_ds_3d =
VideoDataset3D("../dataset_info/dataset/splits/train.csv",
dataset_root, class_map,
num_frames=16, transform=train_tfms,
train=True)

val_ds_3d = VideoDataset3D("../dataset_info/dataset/splits/val.csv",
dataset_root, class_map,
num_frames=16, transform=val_tfms,
train=False)

test_ds_3d =
VideoDataset3D("../dataset_info/dataset/splits/test.csv",
dataset_root, class_map,
num_frames=16, transform=val_tfms,
train=False)

train_loader_3d = DataLoader(train_ds_3d, batch_size=2, shuffle=True,
num_workers=4)
val_loader_3d = DataLoader(val_ds_3d, batch_size=2, shuffle=False,
num_workers=4)
test_loader_3d = DataLoader(test_ds_3d, batch_size=2, shuffle=False,
num_workers=4)

x3d, _ = next(iter(test_loader_3d))
print(x3d.shape)

torch.Size([2, 3, 16, 224, 224])

```

3D CNN: Model, loss, optimizer

```

class_map = {"PullUps": 0, "Punch": 1, "PushUps": 2}
num_classes = len(class_map)

device = "cuda" if torch.cuda.is_available() else "cpu"

model_3d = ResNet3D(num_classes=num_classes, dropout=0.5,
freeze_backbone=True).to(device)

criterion = torch.nn.CrossEntropyLoss(label_smoothing=0.9)
# Using Adam as optimizer
optimizer = torch.optim.Adam(model_3d.parameters(), lr=1e-4,
weight_decay=1e-4)
# Learning rate scheduling
scheduler = torch.optim.lr_scheduler.StepLR(optimizer, step_size=5,
gamma=0.5)
# Early stopping
early_stop = EarlyStopping(patience=4)

```

```

out = model_3d(x3d.to(device))
print(out.shape)

torch.Size([2, 3])

```

3D CNN: Training loop (With early stopping)

- This will take around 30 minutes to complete

```

start_time = time.time()

EPOCHS = 12
best_val_acc = 0.0

train_losses_3d = []
val_losses_3d = []
train_accs_3d = []
val_accs_3d = []

# ===== LOAD IF EXISTS =====
if os.path.exists(MODEL_3D_PATH):

    print("Found saved 3D model. Loading...")

    model_3d.load_state_dict(torch.load(MODEL_3D_PATH,
map_location=device))
    model_3d.to(device)
    model_3d.eval()

    if os.path.exists(STATS_3D_PATH):
        with open(STATS_3D_PATH, "r") as f:
            stats = json.load(f)

        # ---- SAFE LOAD ----
        train_losses_3d = stats.get("train_losses", [])
        val_losses_3d = stats.get("val_losses", [])
        train_accs_3d = stats.get("train_accs", [])
        val_accs_3d = stats.get("val_accs", [])
        best_val_acc = max(val_accs_3d) if len(val_accs_3d) > 0
    else 0.0

    print("Loaded training curves from stats_3d.json")
else:
    print("stats_3d.json not found → curves unavailable")

# ===== TRAIN IF NOT EXISTS =====
else:
    print("No saved 3D model found. Starting training...")

    for epoch in range(EPOCHS, desc="3D CNN Epochs"):

```



```

train_loss, train_acc = train_one_epoch(
    model_3d, train_loader_3d, optimizer, criterion, device)

val_loss, val_acc = eval_one_epoch(
    model_3d, val_loader_3d, criterion, device)

scheduler.step()

print(
    f"\nEpoch [{epoch+1}/{EPOCHS}] "
    f"Train Loss: {train_loss:.4f} | Train Acc:
{train_acc:.4f} || "
    f"Val Loss: {val_loss:.4f} | Val Acc: {val_acc:.4f}"
)

train_losses_3d.append(train_loss)
val_losses_3d.append(val_loss)
train_accs_3d.append(train_acc)
val_accs_3d.append(val_acc)

if val_acc > best_val_acc:
    best_val_acc = val_acc
    torch.save(model_3d.state_dict(), MODEL_3D_PATH)

early_stop(val_loss)
if early_stop.stop:
    print("□ Early stopping triggered")
    break

print("3D CNN Training complete. Best Val Acc:", best_val_acc)

# ===== SAVE TRAINING CURVES =====
stats_3d = {
    "train_losses": train_losses_3d,
    "val_losses": val_losses_3d,
    "train_accs": train_accs_3d,
    "val_accs": val_accs_3d,
    "best_val_acc": best_val_acc
}

with open(STATS_3D_PATH, "w") as f:
    json.dump(stats_3d, f, indent=4)

print("Training curves saved to stats_3d.json")

end_time = time.time()
train_time_3d = end_time - start_time

np.save("../results/stats_deep_learning/train_time_3d.npy",

```

```
train_time_3d)
print("3D CNN Training Time (seconds):", train_time_3d)
No saved 3D model found. Starting training...
3D CNN Epochs:  8%|█          | 1/12 [04:42<51:45, 282.32s/it]

Epoch [1/12] Train Loss: 1.1684 | Train Acc: 0.3542 || Val Loss:
1.1304 | Val Acc: 0.4444
3D CNN Epochs:  17%|███       | 2/12 [06:44<31:20, 188.08s/it]

Epoch [2/12] Train Loss: 1.1656 | Train Acc: 0.4133 || Val Loss:
1.1341 | Val Acc: 0.5778
3D CNN Epochs:  25%|████      | 3/12 [08:39<23:14, 154.90s/it]

Epoch [3/12] Train Loss: 1.1555 | Train Acc: 0.3395 || Val Loss:
1.1292 | Val Acc: 0.5333
3D CNN Epochs:  33%|█████     | 4/12 [10:39<18:48, 141.01s/it]

Epoch [4/12] Train Loss: 1.1562 | Train Acc: 0.4207 || Val Loss:
1.1209 | Val Acc: 0.5556
3D CNN Epochs:  42%|██████    | 5/12 [12:36<15:25, 132.29s/it]

Epoch [5/12] Train Loss: 1.1576 | Train Acc: 0.3764 || Val Loss:
1.1230 | Val Acc: 0.4444
3D CNN Epochs:  50%|███████   | 6/12 [14:33<12:42, 127.12s/it]

Epoch [6/12] Train Loss: 1.1459 | Train Acc: 0.3616 || Val Loss:
1.1240 | Val Acc: 0.6222
3D CNN Epochs:  58%|████████  | 7/12 [16:30<10:18, 123.79s/it]

Epoch [7/12] Train Loss: 1.1465 | Train Acc: 0.3506 || Val Loss:
1.1248 | Val Acc: 0.6444
3D CNN Epochs:  58%|████████  | 7/12 [19:37<14:00, 168.17s/it]

Epoch [8/12] Train Loss: 1.1478 | Train Acc: 0.3579 || Val Loss:
1.1221 | Val Acc: 0.5556
□ Early stopping triggered
```

```
3D CNN Training complete. Best Val Acc: 0.6444444444444445
Training curves saved to stats_3d.json
3D CNN Training Time (seconds): 1177.1603894233704
```

3D CNN: Loading best model

```
model_3d.load_state_dict(torch.load(MODEL_3D_PATH,
map_location=device))
model_3d.eval()

print("Model loaded successfully")
print("Backbone: ResNet-3D (r3d_18, Kinetics pretrained)")
print("Input: video clips as 3D volumes (C x T x H x W)")
print("Temporal modeling: 3D convolutions")
print("Classifier head: Dropout → Fully Connected (3 classes)")

print("Trainable parameters:",
      sum(p.numel() for p in model_3d.parameters() if
p.requires_grad))

print("Total parameters:",
      sum(p.numel() for p in model_3d.parameters()))

Model loaded successfully
Backbone: ResNet-3D (r3d_18, Kinetics pretrained)
Input: video clips as 3D volumes (C x T x H x W)
Temporal modeling: 3D convolutions
Classifier head: Dropout → Fully Connected (3 classes)
Trainable parameters: 1539
Total parameters: 33167811
```

3D CNN: Test set evaluation

```
model_3d.load_state_dict(torch.load(MODEL_3D_PATH,
map_location=device))
model_3d.eval()

all_preds_3d, all_labels_3d = [], []

with torch.no_grad():
    for x, y in test_loader_3d:
        x, y = x.to(device), y.to(device)
        out = model_3d(x)
        preds = torch.argmax(out, dim=1)

        all_preds_3d.extend(preds.cpu().numpy())
        all_labels_3d.extend(y.cpu().numpy())
```

3D CNN: Evaluation metrics

```
print("3D CNN Test Accuracy:", accuracy_score(all_labels_3d,
all_preds_3d))
print("\nClassification Report:")
print(classification_report(all_labels_3d, all_preds_3d,
target_names=class_map.keys()))
```

3D CNN Test Accuracy: 0.5869565217391305

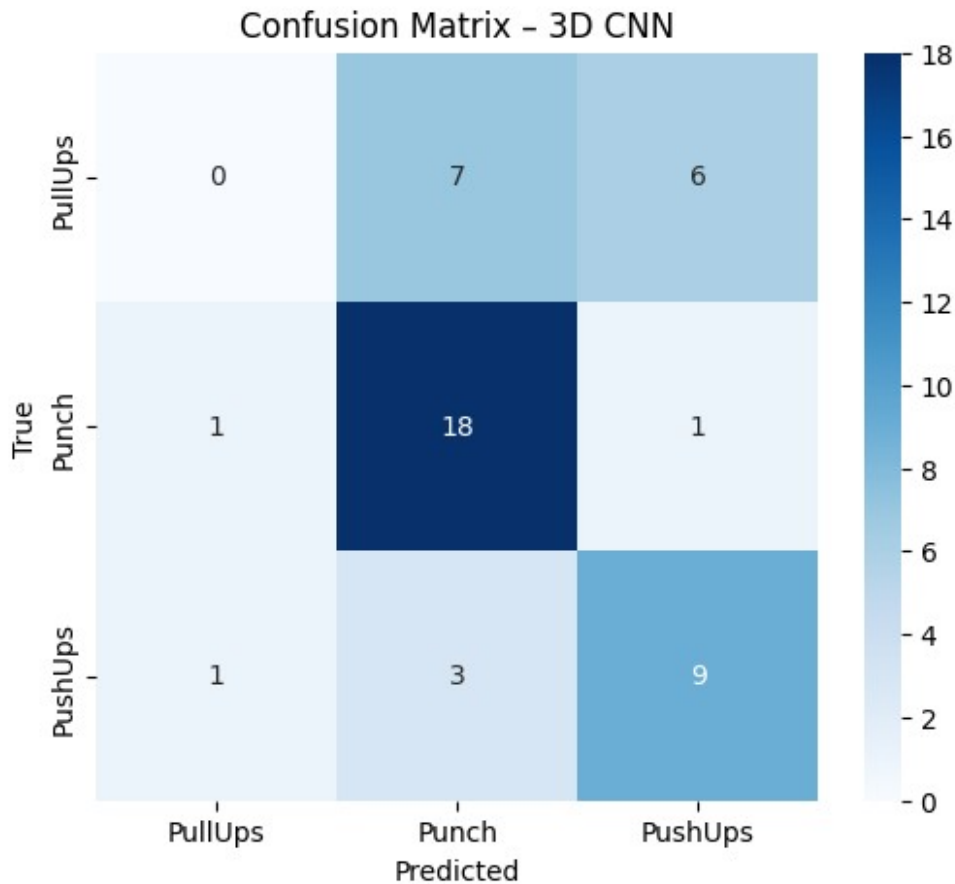
Classification Report:

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| PullUps | 0.00 | 0.00 | 0.00 | 13 |
| Punch | 0.64 | 0.90 | 0.75 | 20 |
| PushUps | 0.56 | 0.69 | 0.62 | 13 |
| | | | | |
| accuracy | | | 0.59 | 46 |
| macro avg | 0.40 | 0.53 | 0.46 | 46 |
| weighted avg | 0.44 | 0.59 | 0.50 | 46 |

3D CNN: Confusion Matrix

```
conf_matrix_3d = confusion_matrix(all_labels_3d, all_preds_3d)

plt.figure(figsize=(6,5))
sns.heatmap(conf_matrix_3d, annot=True, fmt="d", cmap="Blues",
            xticklabels=class_map.keys(),
            yticklabels=class_map.keys())
plt.title("Confusion Matrix – 3D CNN")
plt.xlabel("Predicted")
plt.ylabel("True")
plt.savefig("../results/confusion_matrices/deep_learning/3d_resnet3d_c
onfusion_matrix.png");
plt.show()
plt.close()
```

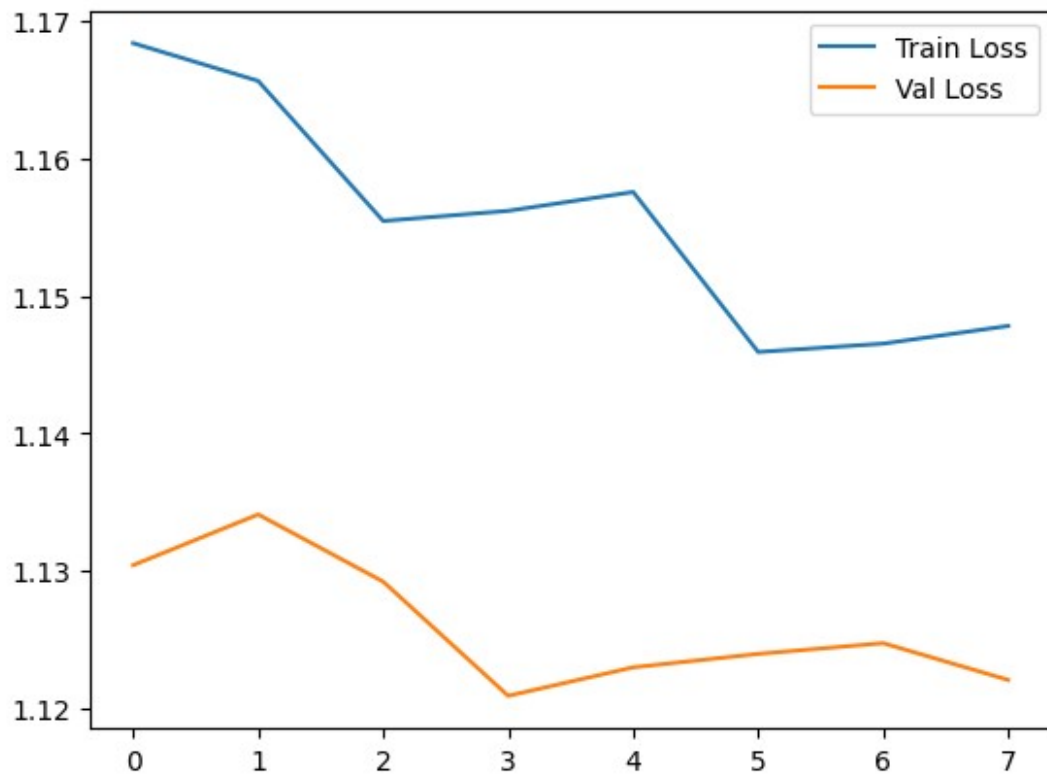


3D CNN: Learning curves

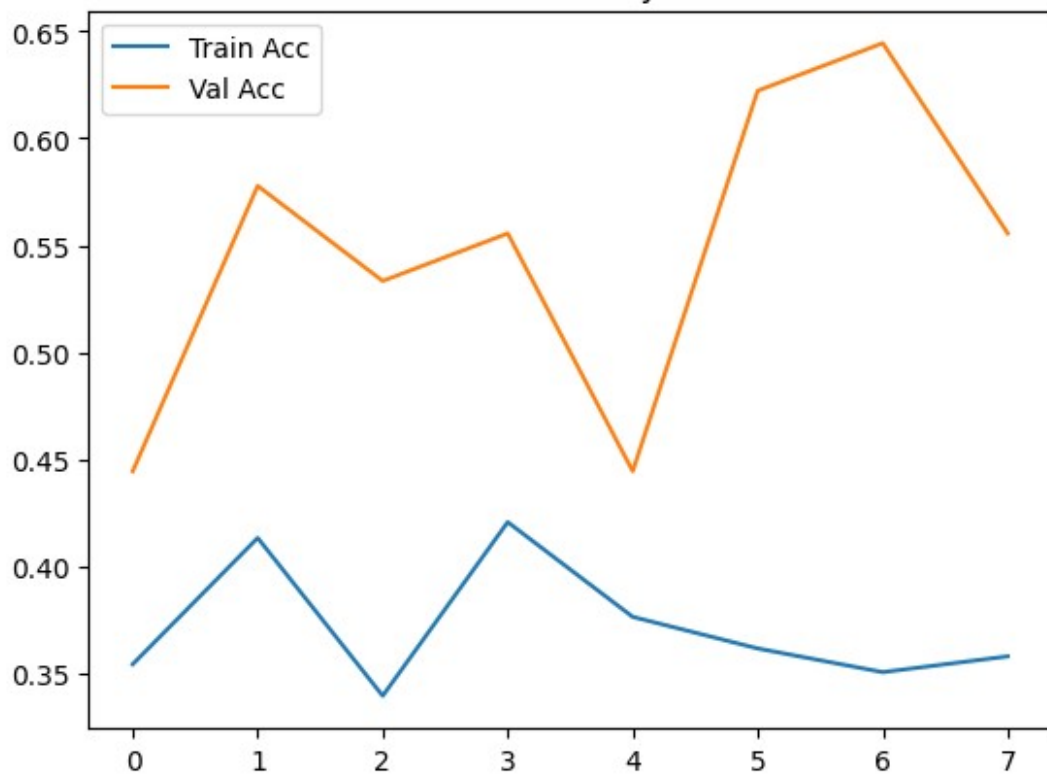
```
plt.figure()
plt.plot(train_losses_3d, label="Train Loss")
plt.plot(val_losses_3d, label="Val Loss")
plt.title("3D CNN Loss Curve")
plt.legend()
plt.savefig("../results/performance_plots/deep_learning/3d_cnn_loss_curve.png");
plt.show()
plt.close()

plt.figure()
plt.plot(train_accs_3d, label="Train Acc")
plt.plot(val_accs_3d, label="Val Acc")
plt.title("3D CNN Accuracy Curve")
plt.legend()
plt.savefig("../results/performance_plots/deep_learning/3d_cnn_accuracy_curve.png");
plt.show()
```

3D CNN Loss Curve



3D CNN Accuracy Curve



3D CNN: Inference time (computational analysis)

```
x, y = next(iter(test_loader_3d))
x = x.to(device)

start = time.time()
with torch.no_grad():
    _ = model_3d(x)
end = time.time()

inf_time_3d = (end - start) / x.size(0)

np.save("../results/stats_deep_learning/inf_time_3d.npy", inf_time_3d)
print("Inference time per batch:", end-start)
print("Approx inference time per video:", inf_time_3d)

Inference time per batch: 1.4004583358764648
Approx inference time per video: 0.7002291679382324
```

3D CNN: Model size (parameter count)

```
total_params_3d = sum(p.numel() for p in model_3d.parameters())
trainable_params_3d = sum(p.numel() for p in model_3d.parameters() if
p.requires_grad)

print("3D CNN Total parameters:", total_params_3d)
print("3D CNN Trainable parameters:", trainable_params_3d)

3D CNN Total parameters: 33167811
3D CNN Trainable parameters: 1539
```

3D CNN: Error Analysis

```
wrong_idx = np.where(np.array(all_preds_3d) !=
np.array(all_labels_3d))[0]
print("Total wrong predictions (3D CNN):", len(wrong_idx))

if len(wrong_idx) > 0:
    #for i in wrong_idx[:5]:
    for i in wrong_idx:
        row = test_ds_3d.data.iloc[i]
        video_path = row["clip_path"]

        true_label = list(class_map.keys())[all_labels_3d[i]]
        pred_label = list(class_map.keys())[all_preds_3d[i]]

        print("Video:", video_path)
        print("True:", true_label, "| Pred:", pred_label)
        print("-"*50)
```

Total wrong predictions (3D CNN): 19
Video: /PullUps/v_PullUps_g14_c03.avi
True: PullUps | Pred: Punch

Video: /PullUps/v_PullUps_g19_c02.avi
True: PullUps | Pred: Punch

Video: /PullUps/v_PullUps_g02_c04.avi
True: PullUps | Pred: Punch

Video: /PullUps/v_PullUps_g16_c01.avi
True: PullUps | Pred: Punch

Video: /PullUps/v_PullUps_g09_c01.avi
True: PullUps | Pred: Punch

Video: /PullUps/v_PullUps_g12_c02.avi
True: PullUps | Pred: PushUps

Video: /PullUps/v_PullUps_g17_c01.avi
True: PullUps | Pred: PushUps

Video: /PullUps/v_PullUps_g11_c02.avi
True: PullUps | Pred: PushUps

Video: /PullUps/v_PullUps_g07_c02.avi
True: PullUps | Pred: PushUps

Video: /PullUps/v_PullUps_g09_c03.avi
True: PullUps | Pred: Punch

Video: /PullUps/v_PullUps_g07_c04.avi
True: PullUps | Pred: PushUps

Video: /PullUps/v_PullUps_g06_c04.avi
True: PullUps | Pred: Punch

Video: /PullUps/v_PullUps_g22_c02.avi
True: PullUps | Pred: PushUps

Video: /Punch/v_Punch_g14_c07.avi
True: Punch | Pred: PushUps

Video: /Punch/v_Punch_g13_c01.avi
True: Punch | Pred: PullUps

Video: /PushUps/v_PushUps_g10_c04.avi
True: PushUps | Pred: Punch

Video: /PushUps/v_PushUps_g17_c04.avi


```
True: PushUps | Pred: Punch
-----
Video: /PushUps/v_PushUps_g03_c01.avi
True: PushUps | Pred: Punch
-----
Video: /PushUps/v_PushUps_g10_c02.avi
True: PushUps | Pred: PullUps
-----
```

3D CNN: File size on disk

```
model_path = MODEL_3D_PATH
file_size_mb_3d = os.path.getsize(model_path) / (1024 * 1024)
np.save("../results/stats_deep_learning/model_size_3d.npy",
file_size_mb_3d)
print("3D CNN Saved model size: {:.2f} MB".format(file_size_mb_3d))

3D CNN Saved model size: 126.60 MB
```

3D CNN: Memory Usage

```
if torch.cuda.is_available():
    print("GPU memory allocated:",
          torch.cuda.memory_allocated() / (1024**2), "MB")
    print("GPU memory reserved:",
          torch.cuda.memory_reserved() / (1024**2), "MB")
else:
    print("GPU not available. Running on CPU.")

process = psutil.Process(os.getpid())
ram_mb = process.memory_info().rss / (1024 * 1024)

print("Current CPU RAM usage: {:.2f} MB".format(ram_mb))

GPU not available. Running on CPU.
Current CPU RAM usage: 1520.49 MB
```

3D CNN: Saving the results for comparative analysis

```
acc3d = accuracy_score(all_labels_3d, all_preds_3d)
p3d, r3d, f13d, _ = precision_recall_fscore_support(all_labels_3d,
all_preds_3d, average="macro")

stats_3d = {
    "accuracy": acc3d,
    "precision": p3d,
    "recall": r3d,
    "f1": f13d,
    "inference_time": inf_time_3d,
```

```
    "params": total_params_3d,  
    "model_size_mb": file_size_mb_3d  
}  
  
with open("../results/stats_deep_learning/stats_3d.json", "w") as f:  
    json.dump(stats_3d, f, indent=4)  
  
np.save("../results/stats_deep_learning/preds_2d.npy", all_preds_2d)  
np.save("../results/stats_deep_learning/labels_2d.npy", all_labels_2d)  
  
np.save("../results/stats_deep_learning/preds_3d.npy", all_preds_3d)  
np.save("../results/stats_deep_learning/labels_3d.npy", all_labels_3d)
```