

Remember about learning dif egs

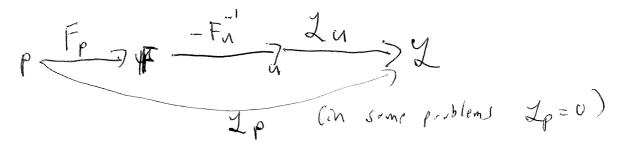
u: Diff Functions from (to, T) to IR": + 7 ult)

P: Parameters PEIR2

F: Zeros of F = Sulve the diff eq with param P  $F(u_1p) = u'(t) - F(u_1p_1t)$ To specify the ode we need F = f and boundary condition u(to) = 0

Z: Loss L(u,p) = scalar

Renember p determines Mlt) determes L(ult), p) and we wish to optimize over p.



Linear operators

Fp: takes a small change to peR2

and sees what harpens to F

(a continuous function function of R^n)

Fr: takes a small changer to u / at time t it is and sees what huspens to F / an non motor

Following chris we take

 $2(u,p) = \int_{t_0}^{T} g(u,p) dt = \int_{t_0}^{T} g(u(t),p) dt$ 

 $Z_{\rho} = \int_{t_{0}}^{\tau} g_{\rho}(u(t), \rho) dt \qquad g : \mathbb{R}^{n} + \mathbb{R}^{2} \rightarrow \mathbb{R}$ 

Zu: measures how loss function reacts to Small changes to u at time t = 2m (u(t), p) Inner product (u, v) = fu(t) v(t) dt.

We want to derive

EZ = Ip - In(Fn'Fp) = Ip - (InFn') Fp Proposition of the second of the

VIL = Ip - Fp Fr In X(t)

Easy one

Means 
$$-\frac{1}{2t} - \frac{1}{f_{u}} \lambda(t) = g_{m}^{T}(t)$$