

CS-E4830 - Kernel Methods in Machine Learning

Homework Assignment 2 – Pen and Paper

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Question 1. “Kernel Centering”

Let $k: \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ be a kernel function and $\phi: \mathcal{X} \rightarrow F$ a feature map associated with this kernel. Let $S = \{x_1, \dots, x_l\}$ be the set of training inputs.

After centering, the feature map is given by: $\phi_c(x) = \phi(x) - \frac{1}{l} \sum_{i=1}^l \phi(x_i)$.

Therefore, with $k_c(x_i, x_j) = \langle \phi_c(x_i), \phi_c(x_j) \rangle$, we can do as following:

$$\begin{aligned} k_c(x_i, x_j) &= \langle \phi_c(x_i), \phi_c(x_j) \rangle = \phi_c(x_i)^T \phi_c(x_j) \\ &= \left(\phi(x_i) - \frac{1}{l} \sum_{p=1}^l \phi(x_p) \right)^T \left(\phi(x_j) - \frac{1}{l} \sum_{q=1}^l \phi(x_q) \right) \\ &= \phi(x_i)^T \phi(x_j) - \frac{1}{l} \sum_{q=1}^l \phi(x_i)^T \phi(x_q) - \frac{1}{l} \sum_{p=1}^l \phi(x_p)^T \phi(x_j) \\ &\quad + \frac{1}{l^2} \sum_{p=1}^l \phi(x_p)^T \sum_{q=1}^l \phi(x_q) \\ &= k(x_i, x_j) - \frac{1}{l} \sum_{q=1}^l k(x_i, x_q) - \frac{1}{l} \sum_{p=1}^l k(x_p, x_j) + \frac{1}{l^2} \sum_{p,q=1}^l k(x_p, x_q) \end{aligned}$$

, which is what we need to prove.

Question 2. “Multiclass (multinomial) classification”

Let $x_i \in \mathcal{R}^d$ be an input sample, and $\mathbf{w}_k \in \mathcal{R}^d$ ($k = 1, \dots, K$) a set of parameter vectors assigned to each class in the multiclass classification. Let the probability $P(Y_i = k | X = x_i)$ of a class with respect to x_i be given by $\frac{1}{Z} \exp(\langle \mathbf{w}_k, x_i \rangle)$, called Gibbs measure, where Z is a normalization factor to guarantee that $\frac{1}{Z} \exp(\langle \mathbf{w}_k, x_i \rangle)$ is a probability.

Thus, for a multiclass problem with a fixed number of K , the prediction is made upon the value k with the highest probability from Gibbs measure function. Therefore, we can define the decision function as below:

$$f_n(x) = a, \text{ with } a \in \{1, \dots, K\} \text{ and } a = \arg \max_{k \in \{1, \dots, K\}} \frac{1}{Z} \exp(\langle \mathbf{w}_k, x_i \rangle)$$

Since Z functions as a normalization factor to make $\frac{1}{Z} \exp(\langle \mathbf{w}_k, \mathbf{x}_i \rangle)$ a probability, then:

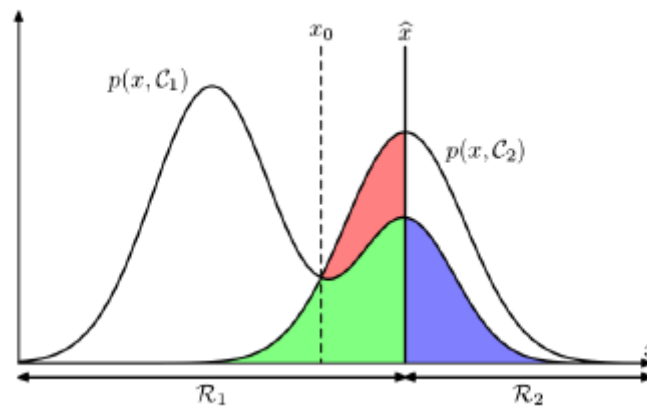
$$\frac{1}{Z} \exp(\langle \mathbf{w}_k, \mathbf{x}_i \rangle) \leq 1 \Leftrightarrow \exp(\langle \mathbf{w}_k, \mathbf{x}_i \rangle) \leq Z$$

Also, with a fixed K , we can the sum of all components being set to 1:

$$\begin{aligned} \sum_{i=1}^K P(Y_i = k | X = x_i) = 1 &\Leftrightarrow \sum_{i=1}^K \frac{1}{Z} \exp(\langle \mathbf{w}_k, \mathbf{x}_i \rangle) = 1 \Leftrightarrow \frac{1}{Z} \sum_{i=1}^K \exp(\langle \mathbf{w}_k, \mathbf{x}_i \rangle) = 1 \\ &\Leftrightarrow Z = \sum_{i=1}^K \exp(\langle \mathbf{w}_k, \mathbf{x}_i \rangle) \end{aligned}$$

Question 3.

Given a binary classification problem, in which $p(x, C_1)$ and $p(x, C_2)$ are known. This graph below is extracted from lecture 5:



At a given point, we can calculate the misclassification error as below:

$$\begin{aligned} P(\text{Misclassification Error}) &= \int_{-\infty}^{+\infty} p(\text{misclassification error}, x) dx \\ &= \int_{\mathcal{R}_1} p(x, C_2) dx + \int_{\mathcal{R}_2} p(x, C_1) dx \end{aligned}$$

The transformation above explains that the misclassification error is equal to the sum of misclassifying in each sub-graph: In the sub-graph belonging to \mathcal{R}_1 , the error is the probability of classifying as C_2 ; meanwhile in the sub-graph belonging to \mathcal{R}_2 , the error is the probability of classifying as C_1 .

Let x_0 denote the point that achieve that minimum classification error, then at $x = x_0$, our error is either the misclassification error of either C_1 or C_2 . Thus, the probability of the minimum classification error can be explained as:

$$\begin{aligned}
P(\text{Minimum Misclassification Error}) &= \int_{-\infty}^{x_0} p(x, C_2) dx + \int_{x_0}^{+\infty} p(x, C_1) dx \\
&= \min \left(\int_{-\infty}^{x_0} p(x, C_2) dx, \int_{x_0}^{+\infty} p(x, C_1) dx \right) \leq \int_{x \in \mathcal{X}} (p(x, C_1) p(x, C_2))^{\frac{1}{2}} dx
\end{aligned}$$

Which is what we need to prove.