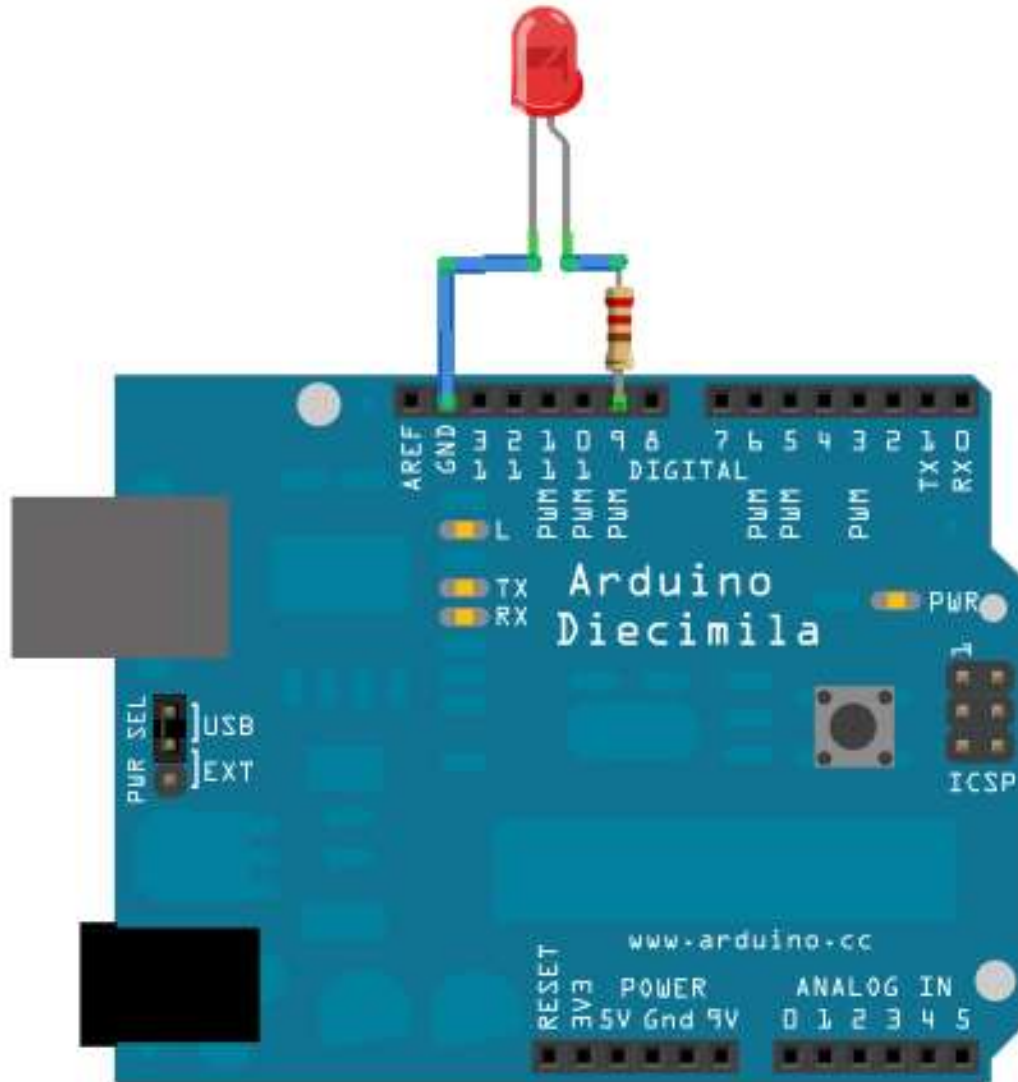


## Pulse Width Modulation (PWM)



## Pulse Width Modulation (PWM)

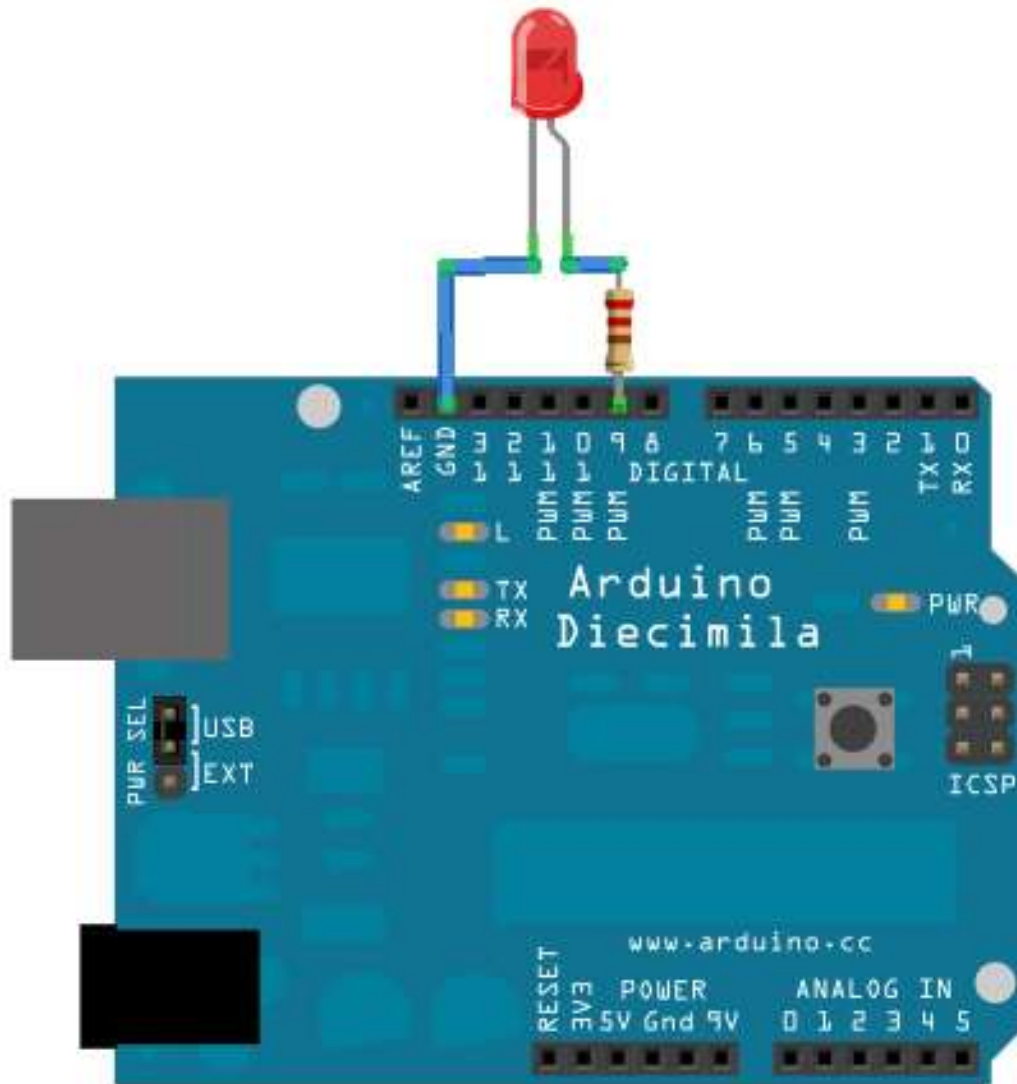
```
int ledPin = 9;    // LED connected to digital pin 9

void setup() {
    // nothing happens in setup
}

void loop() {
    // fade in from min to max in increments of 5 points:
    for (int fadeValue = 0 ; fadeValue <= 255; fadeValue += 5) {
        // sets the value (range from 0 to 255):
        analogWrite(ledPin, fadeValue);
        // wait for 30 milliseconds to see the dimming effect
        delay(30);
    }

    // fade out from max to min in increments of 5 points:
    for (int fadeValue = 255 ; fadeValue >= 0; fadeValue -= 5) {
        // sets the value (range from 0 to 255):
        analogWrite(ledPin, fadeValue);
        // wait for 30 milliseconds to see the dimming effect
        delay(30);
    }
}
```

## Pulse Width Modulation (PWM)



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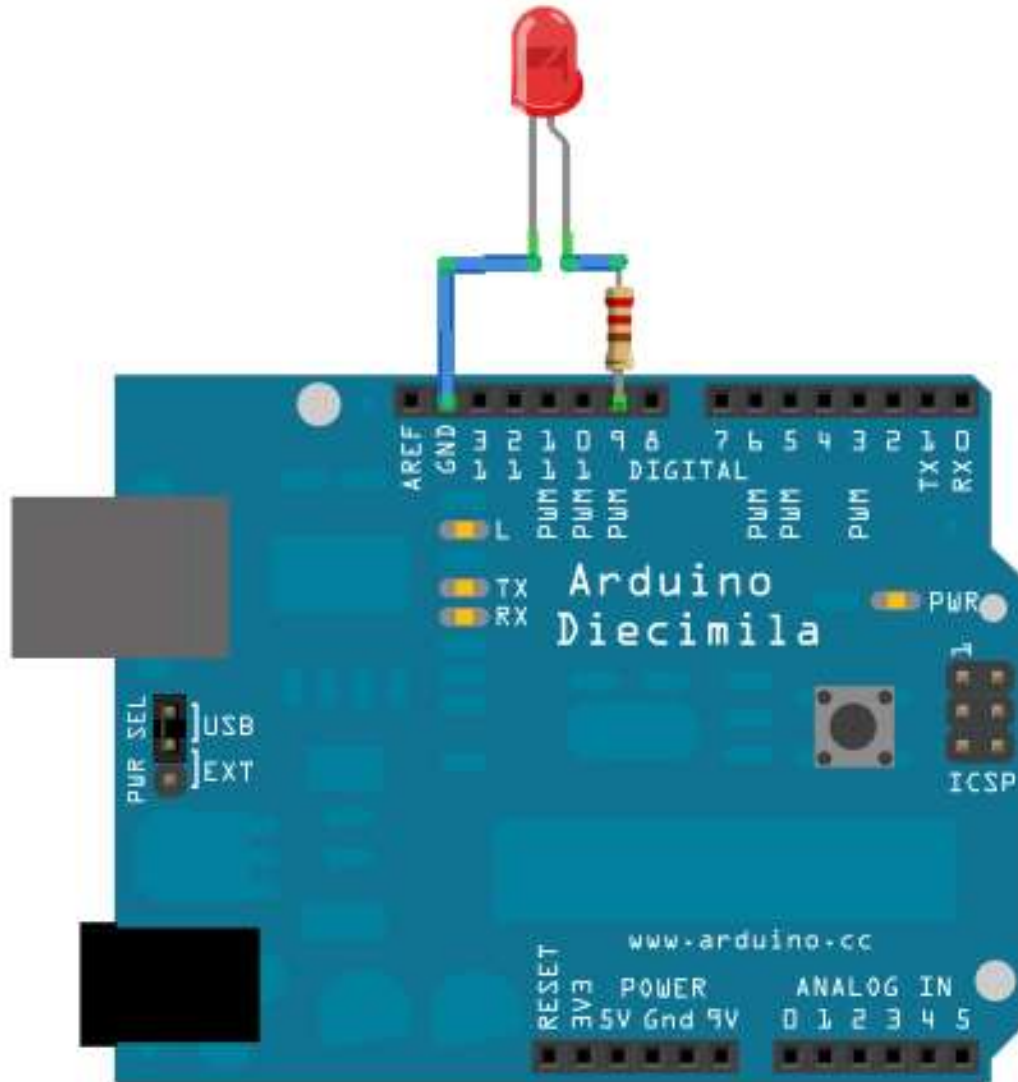
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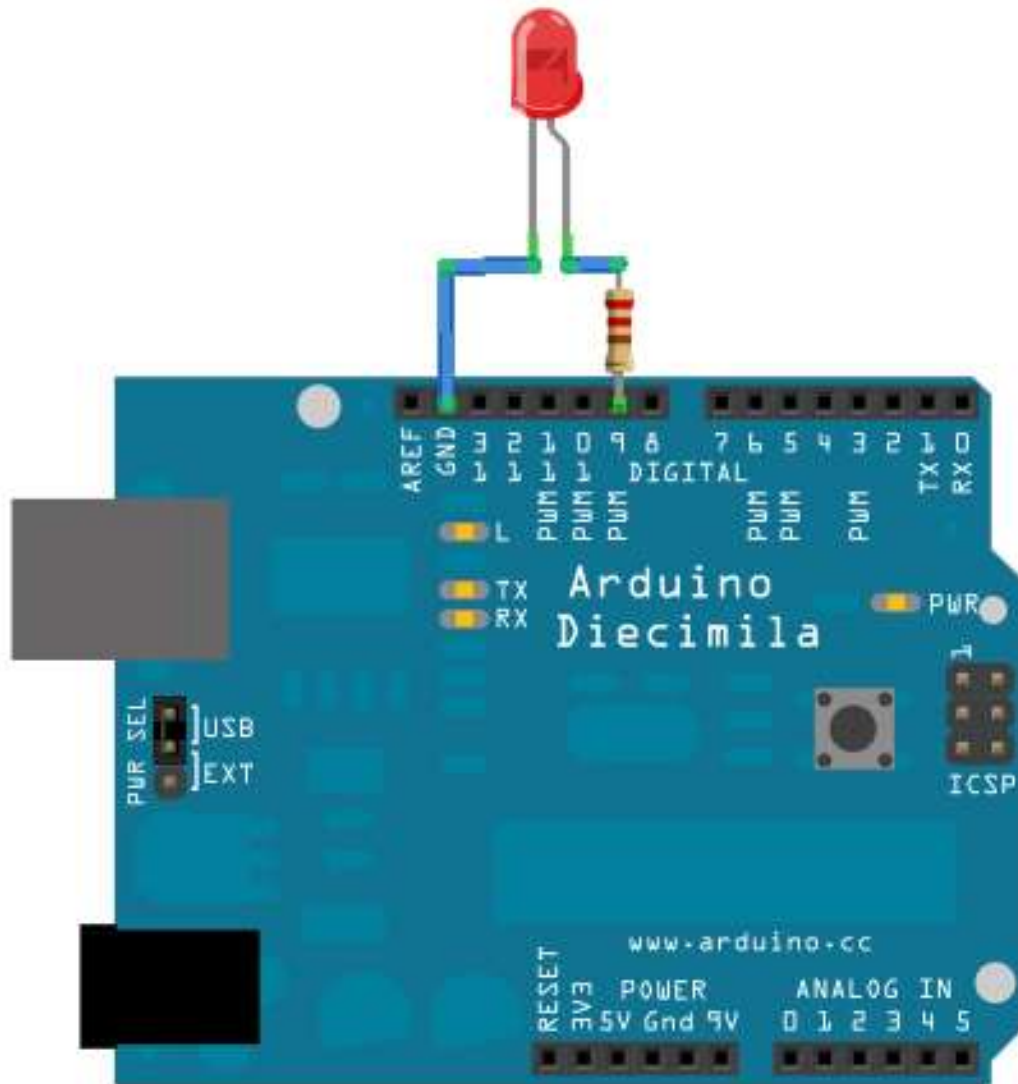
void setup() {
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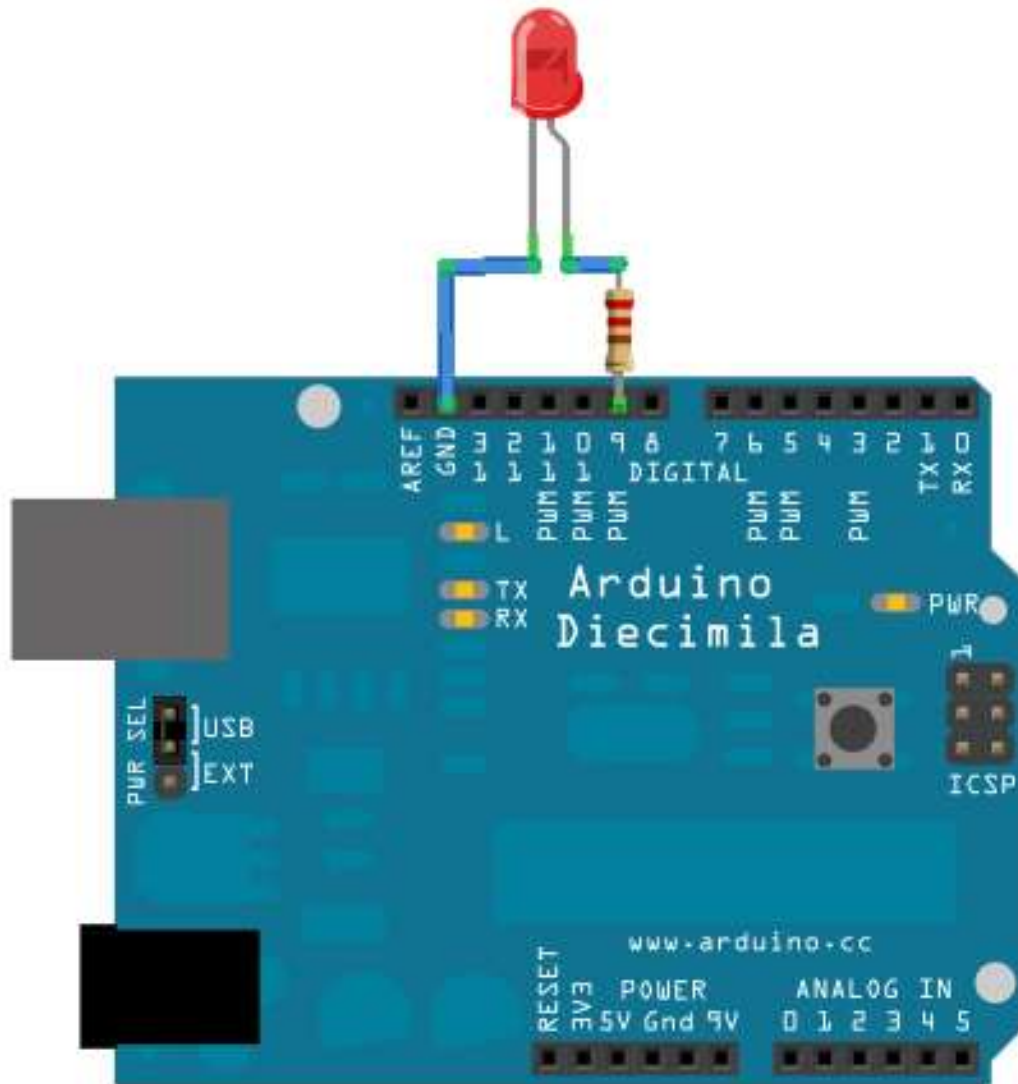
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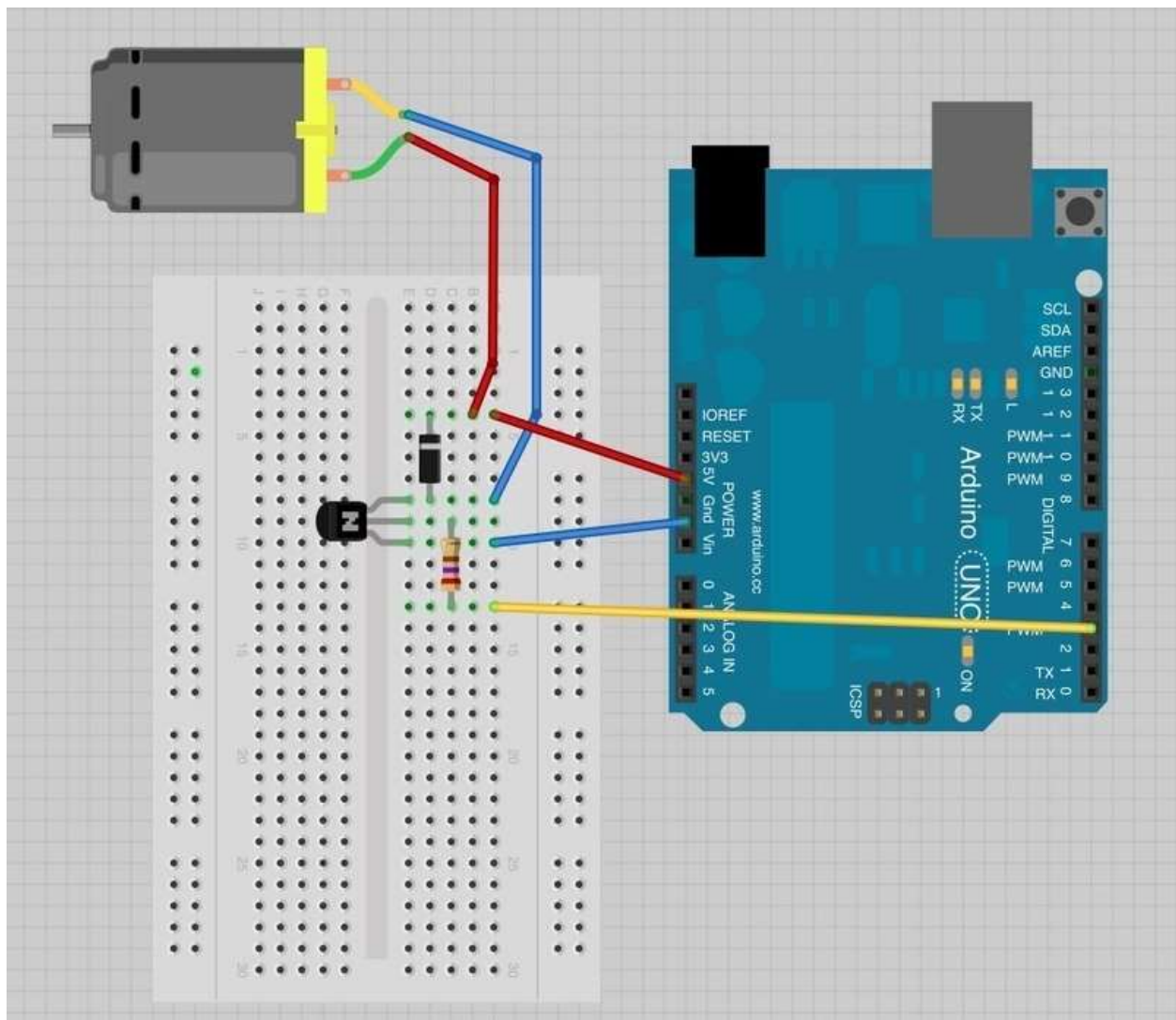
void loop() {
    // fade in from min to max in increments of 5 points:
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```

Jan-16-2019

Droid Equinox 07

## DC Brushed Motor



Jan-16-2019

Droid Equinox 07

## DC Brushed Motor

```
int motorPin = 3;

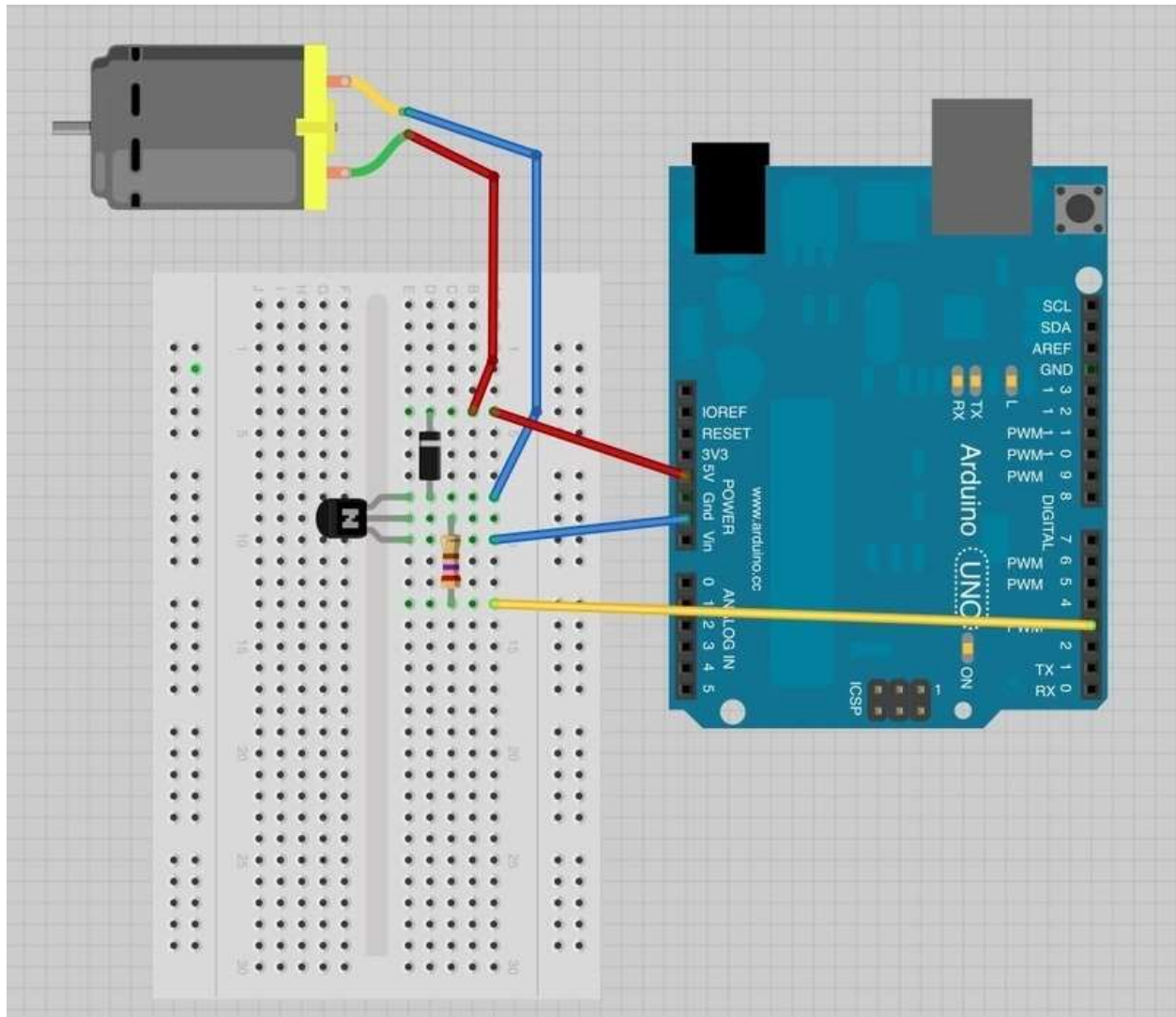
void setup() {
    pinMode(motorPin, OUTPUT);
    Serial.begin(9600);
    while (! Serial);
    Serial.println("Speed 0 to 255");
}

void loop() {
    if (Serial.available()) {
        int speed = Serial.parseInt();
        if (speed >= 0 && speed <= 255) {
            analogWrite(motorPin, speed);
        }
    }
}
```

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## DC Brushed Motor





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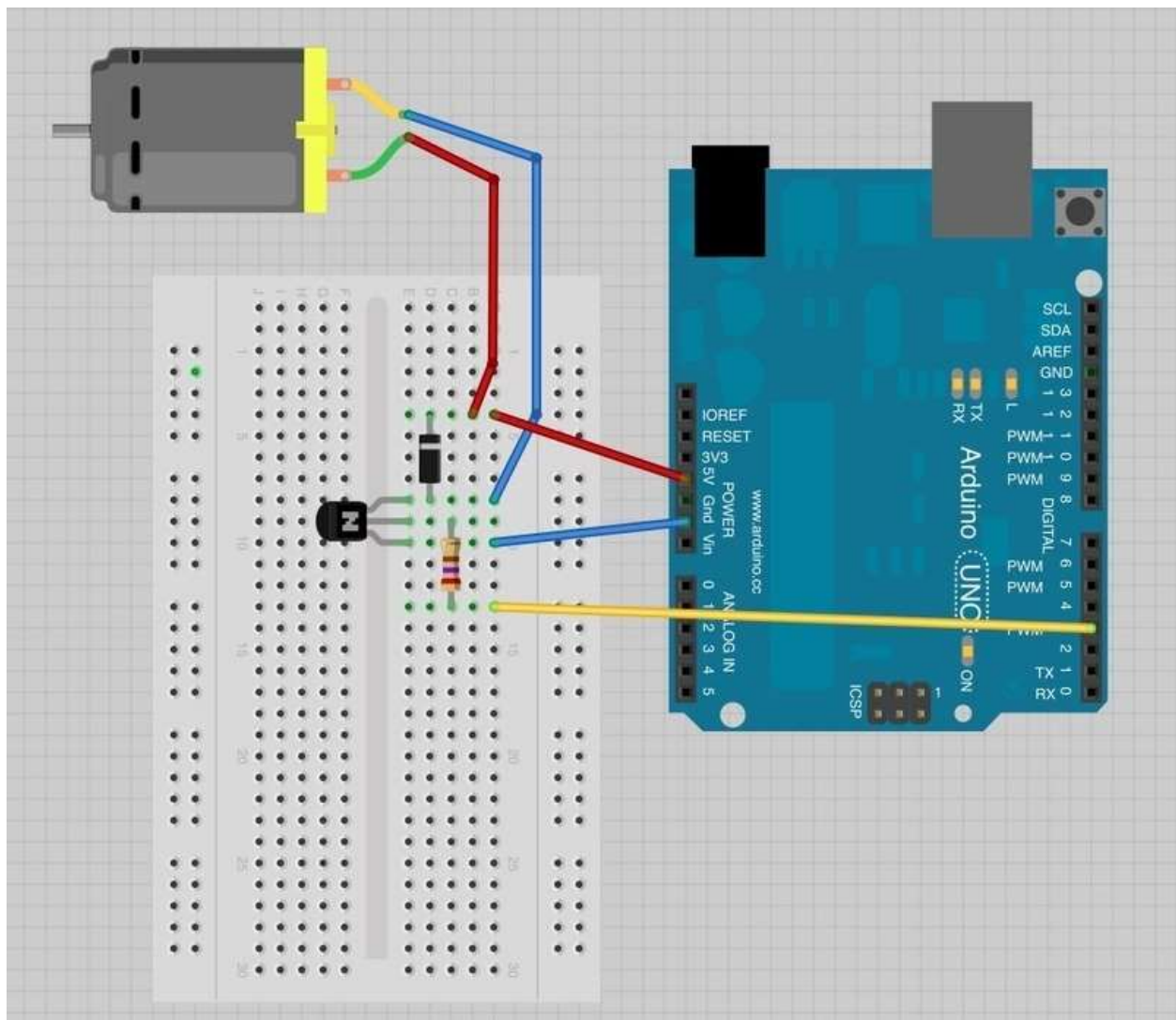
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## DC Brushed Motor



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Droid Equinox 07

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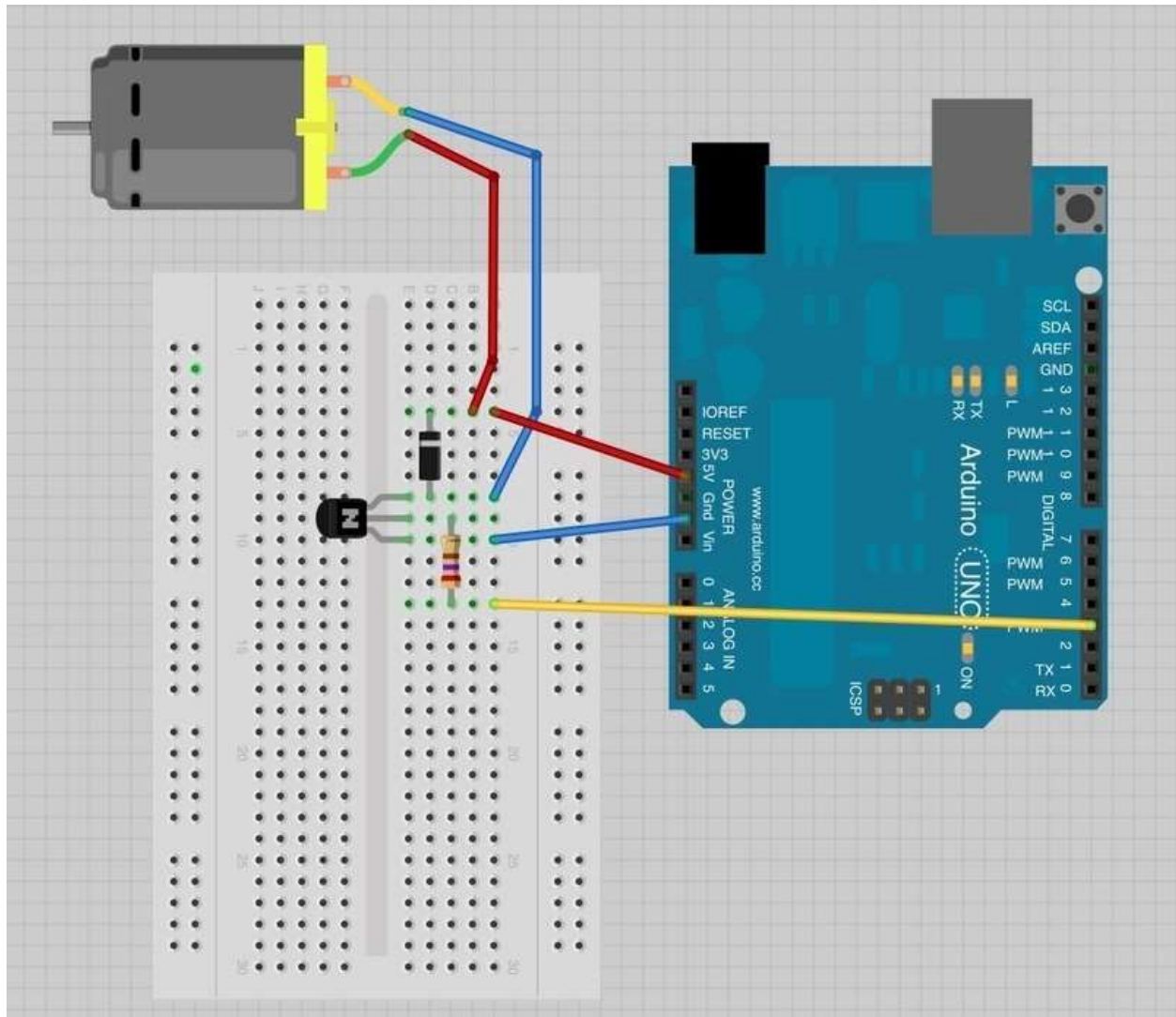
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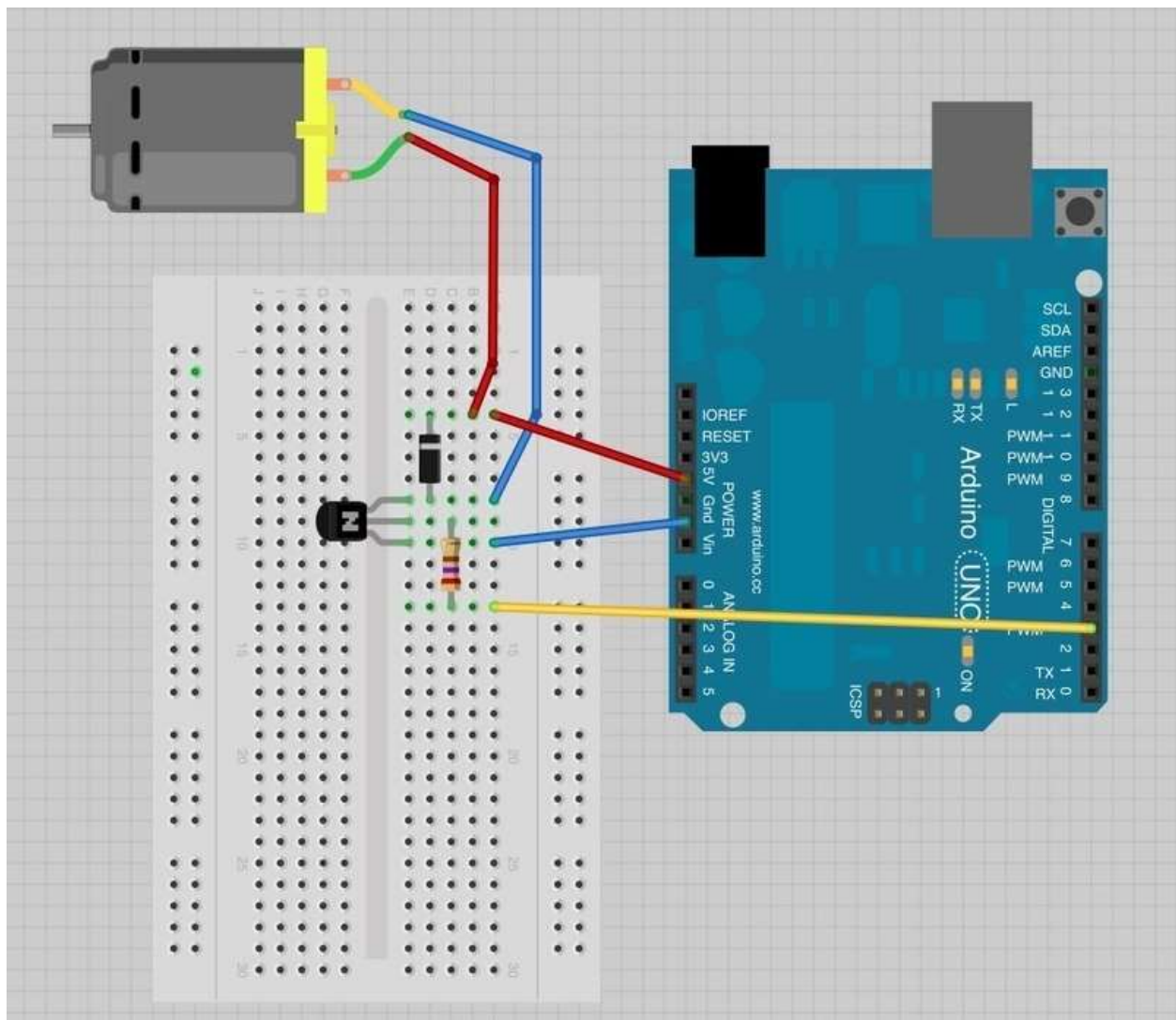
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