





Master's in Industrial Electronics and Computers Engineering

## University of Minho

## 5S Drifter

## Sensoring System for Surface Sea Streams

Integrative Project in Industrial Electronics and Computers

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# Acronyms

 ${\bf UART\ \, Universal\ \, asynchronous\ \, receiver/transmitter}$ 

LTE Long-Term Evolution

**ADC** Analog to Digital Converter

IMU Inertial Measurement Unit

PCB Printed Circuit Board

**CMEMS** Center for Microeletromachanical Systems

STM32

**DMA** Direct Access Memory

**IoT** Internet of Things

GPS

**JSON** 

**DB** Data Base

## Project Plan

This chapter will briefly talk about the 5S Drifter project motivations as well their function as a product developed by the Minho's University under supervision by the professors Luis Gonçalves and Sérgio Lopes.

### 1.1 Introduction

Under the course unity of Integrative Project in Industrial Electronics and Computers the students must apply for professors projects in order to integrate under their respective laboratories and start to undertand the pace demanded on the Master's final paper.

This project, given by the professor Luis Gonçalves and Sergio Lopes under the CMEMS laboratory, has the main porpouse to create a drifter for data aquisition. As a multi-themed project, this report will explore multiple areas, as the PCB design for hardware and firmware manufacture, software design under the idea to optimize the execution allowing for better performance. The main goal is to have the final product afloat at the end of the simester.

### 1.1.1 Problem Statement

The ocean is one of the man greatest mistery even before the written history. Humanity made the world ours over the water, from the Portuguese greatests discoveries, braving the raging ocean to the newst oil tanker demanding ever newer technology in order to tame the sea for safer and smother sailing.

Nowadays cientists belive only 5% of the ocean is discovered with the actual technology witch means that humanity know as much about our so grate sky as our own seas. 5S ocean drifter is a equipament made to acquire date from superficial sea streams and expand the oceangraph knowledge about it.

Better knowledge of the ocean lead to further development in diverse areas. Granting safety, security and efficiency.

5S, an acronym for Sensoring System for Surface Sea Streams is a lowcost, lowpower solution to acquire said data with the focus to last autonomously for the longest time possible. The drifter has to attain its GPS coordenates in order to track its current and avarege velocity, alongside with the water temperature and a accelerometer information to gether information about the wave intencity. All this data will be transmitted by a protocol, yet to be defined, with a JASON format in order to be read by a database that allready is implemented.



### **Transport**

Sadly, it isn't uncommon to see transport accidents being reported, and even worse, for it to be a gigantic problem. Some of these accidents are caused by poor mapping of sea conditions, tankers spilling oil, fishing vessels capsizing, leading to financial problems and even loss of life. Even when there are no accidents, poor knowledge of tides results in higher energy consumption when routes are set against the currents.

A solution would be to create optimized shipping routes, minimizing accidents and improving energy efficiency while traversing the waves. Oil tankers could follow currents with lower fuel consumption. Fishing routes could become more efficient, as their target species may swim with the tides based on temperature and speed. This would ease the workload, making the activity less reactive and more predictable, aligning expected catch rates with reduced time and energy consumption.

A well-known example of a hazardous area is the Nazaré Canyon, where its unique shape creates enormous waves. Avoiding these waters is crucial for safer navigation.

### **Ecology**

### Habitats

The placement of wave energy converters, a growing field under the energy generation, is one of the main problems the technology faces. A good positioning improves the efficiency



Renewable Energy

### Oceanograpy

Better undertanding of the Iberian Poleward Current (IPC)

#### Geology

Know where the sedimentation is leading to

#### Sports

### 1.1.2 Problem Statement Analysis

waterfall

vila do conde + ou -  $10 \mathrm{km}$  mar adentro  $2 \mathrm{g}$  4 g mapa de alcance na costa





### Chapter 1. Project Plan

atenção ao clima latencia / sampling / tamanho do cartão sd autonomia de NO MINIMO 50 DIAS consumo médio max 5mA distancia da antena e da água IMU caso tenha espaço para o consumo SD memoria local ADC a bateria sensor de temperatura database mongo db

# Analysis

### 2.1 Requirements and Constraints

### 2.1.1 Requirements

- Search and selection of hardware components.
- Software design.
- PCB design.
- 5S outer shell 3D design.
- Actual product realization.
- Laboratory tests.

### 2.1.2 Constraints

- The project must be presented for avaluation within deadline.
- The project has to be valitated at the ocean.
- The pretended autonomy has to be of a mouth at minimum.

### 2.2 State of the art

- 2.2.1 Economy
- 2.2.2 Ecology
- **2.2.3** Sports
- 2.3 Market Research
- 2.4 System Architecture

## Design

### 3.1 Analysis Review

### 3.2 Hardware Consumption

Here will be discused wicht hardware is best sued for the task. The hardware will be evaluated by their autonomy, the comunication protocol

### 3.2.1 Autonomy

As for the autonomy there are two main factors to consider, the batteries and the board consumption

#### **Batteries**

google sheets

### **Board Consumption**

```
table SIM7600 table 6 and 34 (pg 20 and ) same voltage 2 SIM7020 peak 2A 20u in sleep mode 150mA SIM7000 (GPS por NB-IoT e 2G fallback) Consome: 11mA
```

SIM7080G - Nb-IoT Quectel BG77

possible solar energy solar penel AEM10941 SM111K06L

Quectel BG95-M3

GPS MAX-M10S

tele2

IMU BMI088 IMU Sensor accelerometer 15uA / and Gyroscope 2.7mA ISM330BX 0.19mA / 0.6mA activate BDU

BMI270

Unix Steptime

### 3.2.2 Communication protocol

```
table EVKITST87M01-1 nb-iot SIM7600 2g 3g 4g LTE CAT4 simbase chip availability europe coast 2g 4g
```





Portugal	2G	3G	4G	5G	LTE	NB-IoT
Meo	V	V	V	_	_	_
Nos	V	V	_	_	_	_
Vodafone	V	_	V	V	V	_

### 3.2.3 Conclusion

### 3.3 Case Construction

Diagram

## 3.4 Hardware Specification

### **3.4.1** SDCard

### 3.4.2 STM32

STM32L010K4T6 microcontroler ADC UART SPI ONEWire

#### 3.4.3 BMI088 IMU Sensor

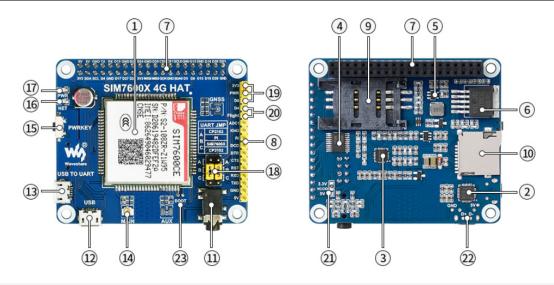
gyroscope and acelerometer

### 3.4.4 SIM7600E-H

The module SIM7600E-H, developed by SIMCom, is a 4G/3G/2G LTE module that comunicates via UART commads using an intern parser described on the module datasheet. The waveshare Board with the module, comes with a set of extra functionalities for extra support to the module normal usage.

The following image, taken from the Waveshare board datasheet, lists the hardware features.





- 1. SIM7600CE-CNSE
- 2. CP2102 USB to UART converter
- 3. NAU8810 audio decoder
- 4. TXS0108EPWR voltage translator
- translates 3.3V/5V into 1.8V
- 5. MP2128DT power chip
- 6. SPX29302 power chip
- 7. Raspberry Pi GPIO header
  - for connecting with Raspberry Pi
- 8. SIM7600 control interface
  - for connecting with host boards like Arduino/STM32
- 9. SIM card slot
  - supports 1.8V/3V SIM card
- 10. TF card slot
  - · for storing data like files, messages, etc.
- 11. 3.5mm earphone/mic jack
  - · for audio actions like making telephone call
- 12. USB interface
  - for testing AT Commands, and so on
- 13. USB TO UART interface
  - for serial debugging, or login to Raspberry Pi

- 14. MAIN antenna connector
- 15. Module power switch
- 16. Network status indicator
- 17. Power indicator
- 18. UART selection jumper
  - · A: access Raspberry Pi via USB to UART
  - B: control the SIM7600 by Raspberry Pi
  - C: control the SIM7600 via USB to UART
- 19. PWR selection jumper
  - PWR 3V3: auto startup on power-up
  - PWR D6: startup/shutdown by the Raspberry Pi D6 pin
- 20. Flight mode selection jumper
  - NC by default, no flight mode control pin
  - Flight D4: flight mode is controlled by the Raspberry Pi D4 pin
- 21. Operating voltage selection jumper
  - VCCIO 3.3V: set operating voltage as 3.3V
  - VCCIO 5V: set operating voltage as 5V
- 22. USB connector solder pads
- 23. BOOT forced programming solder pads

Figure 3.1: SIM7600 datasheet

The hardware configurations, as idicated on the datasheet should follow the leading steps. As for the UART communication, the list of commads are listed on the datasheet. As for better flow, here are listed the commadsused along the project and their functionalities.

### 3.4.5 Temperature

DS18B20





- 3.5 Tools and COTS
- 3.5.1 Tools
- 3.5.2 COTS

GPS and 4G module

Inkscape

draw.io

STM32 CUBEmx

 $\mathbf{E} \mathbf{T} \mathbf{E} \mathbf{X}$ 

- 3.6 Software Specification
- 3.7 Theorical Concepts

# Implementation

## 4.1 Hardware

### 4.2 Software

use DMA to sample withou using the cpu separar funções do IMU e GNSS para não atrapalhar um ao outro.

### 4.2.1 DataBase Comunication

Mongo db JASON

# Conclusion

- 5.1 Gantt Diagram
- 5.2 Bibliografy
- 5.3 Special Greatings

At last it's important to add the support from the CMEMS labs personal as well of the professor Tiago Matos for his support with hardware decisions and previous knowledge from similar projects.