


Chapter 6. Classification and Prediction

- What is classification? What is prediction?
- Issues regarding classification and prediction
- Classification by decision tree induction
- Bayesian classification 
- Rule-based classification
- Classification by back propagation
- Support Vector Machines (SVM)
- Associative classification
- Lazy learners (or learning from your neighbors)
- Other classification methods
- Prediction
- Accuracy and error measures
- Ensemble methods
- Model selection
- Summary



Bayesian Classification: Why?

- A statistical classifier:
 - performs *probabilistic prediction*, i.e., predicts the membership probabilities for different classes
 - Foundation: Based on **Bayes' theorem**
- Performance:
 - A simple *naïve Bayesian classifier* has comparable performance with decision trees and neural network classifiers



Bayesian Classification: Why?

- Incremental:
 - Each training example can **incrementally increase/decrease the probability** that a hypothesis is correct
 - Prior knowledge can be combined with observed data, **rather than training from the scratch**



Bayesian Theorem: Basics

- Let **X** be a data sample (*evidence*) whose class label is unknown
- Let H be a *hypothesis* that X belongs to a class C
- Classification
 - to determine $P(H|X)$, the *probability* that the hypothesis holds when the observed data sample **X** is given



Bayesian Theorem: Basics

- $P(H)$ (*prior probability*)
 - The initial probability (independent of a specific \mathbf{X})
 - E.g., \mathbf{X} will buy computer, regardless of age, income, ...
- $P(\mathbf{X})$
 - The probability that sample data is observed
- $P(\mathbf{X}|H)$ (*posteriori probability*)
 - The probability of observing the sample \mathbf{X} , given that the hypothesis holds
 - E.g., Given that \mathbf{X} will buy computer, the prob. that \mathbf{X} is 31..40, medium income



Bayesian Theorem

- Conditional probability
 - $P(H|X) = P(H \cap \mathbf{X}) / P(X)$
 - $P(X|H) = P(H \cap \mathbf{X}) / P(H)$
 - $P(H \cap \mathbf{X}) = P(H|X) * P(X) = P(X|H) * P(H)$
- Given training data \mathbf{X} , *posteriori probability* of a hypothesis H , $P(H|\mathbf{X})$, follows the Bayes theorem

$$P(H | \mathbf{X}) = \frac{P(\mathbf{X} | H)P(H)}{P(\mathbf{X})}$$



Bayesian Theorem

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$$P(H | \mathbf{X}) = \frac{P(\mathbf{X} | H)P(H)}{P(\mathbf{X})}$$

- Informally, this can be written as

likelihood = posteriori * prior / evidence

- Predicts \mathbf{X} belongs to C_i iff the probability $P(C_i|\mathbf{X})$ is the highest among all the $P(C_k|X)$ for all the k classes
- *Practical difficulty*: require initial knowledge of many probabilities, significant computational cost



Towards Naïve Bayesian Classifier

- Let D be a training set of tuples and their associated class labels, and each tuple is represented by an n -D attribute vector $\mathbf{X} = (x_1, x_2, \dots, x_n)$
- Suppose there are m classes C_1, C_2, \dots, C_m .
- Classification is to derive the maximum posteriori, i.e., the maximum $P(C_i|\mathbf{X})$
- This can be derived from Bayes' theorem

$$P(C_i|\mathbf{X}) = \frac{P(\mathbf{X}|C_i)P(C_i)}{P(\mathbf{X})}$$

- Since $P(\mathbf{X})$ is constant for all classes, only

$$P(C_i|\mathbf{X}) = P(\mathbf{X}|C_i)P(C_i)$$

needs to be maximized



Derivation of Naïve Bayes Classifier

- A simplified assumption:
 - attributes are **conditionally independent** (i.e., no dependence relation between attributes):

$$P(\mathbf{X} | C_i) = \prod_{k=1}^n P(x_k | C_i) = P(x_1 | C_i) \times P(x_2 | C_i) \times \dots \times P(x_n | C_i)$$

- This greatly reduces the computation cost: Only counts the class distribution



Derivation of Naïve Bayes Classifier

$$P(\mathbf{X} | C_i) = \prod_{k=1}^n P(x_k | C_i) = P(x_1 | C_i) \times P(x_2 | C_i) \times \dots \times P(x_n | C_i)$$

- If A_k is categorical, $P(x_k | C_i)$ is the # of tuples in C_i having value x_k for A_k divided by $|C_i, D|$ (# of tuples of C_i in D)
- If A_k is continuous-valued, $P(x_k | C_i)$ is usually computed based on Gaussian distribution with a mean μ and standard deviation σ

$$g(x, \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

and $P(x_k | C_i)$ is $P(\mathbf{X} | C_i) = g(x_k, \mu_{C_i}, \sigma_{C_i})$



Naïve Bayesian Classifier: Training Dataset

Class:

C1:buys_computer = 'yes'

C2:buys_computer = 'no'

Data sample

X = (age <=30,

Income = medium,

Student = yes

Credit_rating = Fair)

age	income	student	credit_rating	comp
<=30	high	no	fair	no
<=30	high	no	excellent	no
31...40	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
31...40	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
31...40	medium	no	excellent	yes
31...40	high	yes	fair	yes
>40	medium	no	excellent	no

Naïve Bayesian Classifier: An Example

- $P(C_i)$:
 $P(\text{buys_computer} = \text{"yes"}) = 9/14 = 0.643$
 $P(\text{buys_computer} = \text{"no"}) = 5/14 = 0.357$
- Compute $P(X|C_i)$ for each class
 $P(\text{age} = \text{"<=30"} | \text{buys_computer} = \text{"yes"}) = 2/9 = 0.222$
 $P(\text{age} = \text{"<= 30"} | \text{buys_computer} = \text{"no"}) = 3/5 = 0.6$
 $P(\text{income} = \text{"medium"} | \text{buys_computer} = \text{"yes"}) = 4/9 = 0.444$
 $P(\text{income} = \text{"medium"} | \text{buys_computer} = \text{"no"}) = 2/5 = 0.4$
 $P(\text{student} = \text{"yes"} | \text{buys_computer} = \text{"yes"}) = 6/9 = 0.667$
 $P(\text{student} = \text{"yes"} | \text{buys_computer} = \text{"no"}) = 1/5 = 0.2$
 $P(\text{credit_rating} = \text{"fair"} | \text{buys_computer} = \text{"yes"}) = 6/9 = 0.667$
 $P(\text{credit_rating} = \text{"fair"} | \text{buys_computer} = \text{"no"}) = 2/5 = 0.4$
- **$X = (\text{age} \leq 30, \text{income} = \text{medium}, \text{student} = \text{yes}, \text{credit_rating} = \text{fair})$**

 $P(X|C_i)$: $P(X|\text{buys_computer} = \text{"yes"}) = 0.222 \times 0.444 \times 0.667 \times 0.667 = 0.044$
 $P(X|\text{buys_computer} = \text{"no"}) = 0.6 \times 0.4 \times 0.2 \times 0.4 = 0.019$

 $P(X|C_i) \cdot P(C_i)$: $P(X|\text{buys_computer} = \text{"yes"}) \cdot P(\text{buys_computer} = \text{"yes"}) = 0.028$
 $P(X|\text{buys_computer} = \text{"no"}) \cdot P(\text{buys_computer} = \text{"no"}) = 0.007$

Therefore, X belongs to class ("buys_computer = yes")



Avoiding the 0-Probability Problem

- Naïve Bayesian prediction requires **each conditional prob. be non-zero**. Otherwise, the predicted prob. will be zero

$$P(X | C_i) = \prod_{k=1}^n P(x_k | C_i)$$

- Ex. Suppose a dataset with 1000 tuples, income=low (0), income=medium (990), and income = high (10),
- Use the idea of **Laplacian correction** (or Laplacian estimator)
 - Adding 1 to each case
 - Prob(income = low) = 1/1003
 - Prob(income = medium) = 991/1003
 - Prob(income = high) = 11/1003
 - The “corrected” prob. estimates are close to their “uncorrected” counterparts, not allowing zero probability




Naïve Bayesian Classifier: Comments

- Advantages
 - Easy to implement
 - Good results obtained in most of the cases
- Disadvantages
 - Assumption: class conditional independence, therefore loss of accuracy
 - Practically, dependencies exist among variables
 - E.g., Patients' **Profiles**: age, family history; **Symptoms**: fever, cough; **Disease**: cold, lung cancer, diabetes
 - **Dependencies** among these cannot be modeled by Naïve Bayesian Classifier
- How to deal with these dependencies?
 - Bayesian Belief Networks (not dealt with here)



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Using IF-THEN Rules for Classification

- Represent the knowledge in the form of **IF-THEN** rules
 - R: IF *age* = youth AND *student* = yes
THEN *buys_computer* = yes
 - Rule antecedent/precondition vs. rule consequent
- Assessment of a rule R: *coverage* and *accuracy* (see Ex. 6.6)
 - n_{covers} = # of tuples *covered* by R
 - n_{correct} = # of tuples *correctly classified* by R

$\text{coverage}(R) = n_{\text{covers}} / |D|$ /* D: training data set */

$\text{accuracy}(R) = n_{\text{correct}} / n_{\text{covers}}$

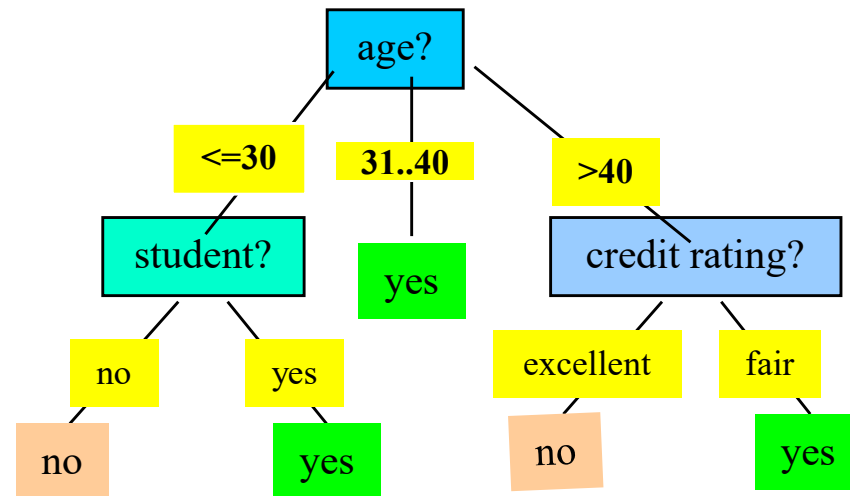


Using IF-THEN Rules for Classification

- If more than one rule is triggered, need **conflict resolution**
 - Size ordering: assign the highest priority to the triggering rules that have the “toughest” requirement (i.e., with the *most attribute test*)
 - Class-based ordering: decreasing order of *prevalence (frequency) or misclassification cost per class*
 - Rule-based ordering (**decision list**): rules are organized into one long priority list
 - According to some measure of rule quality or by experts



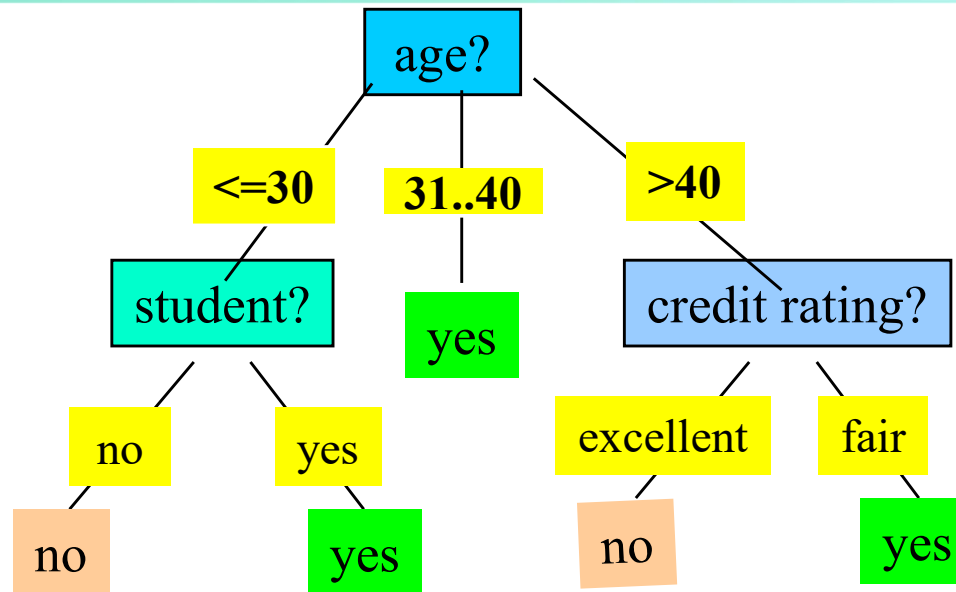
Rule Extraction from a Decision Tree



- Rules are easier to understand than a large tree
- One rule is created for each path from the root to a leaf
- Each attribute-value pair along a path forms a conjunction: the leaf holds the class prediction
- Rules are mutually exclusive and exhaustive



Rule Extraction from a Decision Tree



- Example: Rule extraction from our *buys_computer* decision-tree

IF *age* = young AND *student* = *no*, THEN *buys_computer* = *no*

IF *age* = young AND *student* = *yes*, THEN *buys_computer* = *yes*


IF *age* = mid-age, THEN *buys_computer* = *yes*

IF *age* = old AND *credit_rating* = *excellent*, THEN *buys_computer* = *yes*

IF *age* = young AND *credit_rating* = *fair*, THEN *buys_computer* = *no*



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Associative Classification

- Associative classification
 - Association rules are generated and analyzed for use in classification
 - Search for strong associations between frequent patterns (conjunctions of attribute-value pairs) and class labels
 - Classification: Based on evaluating a set of rules in the form of
$$P_1 \wedge p_2 \dots \wedge p_l \rightarrow "A_{\text{class}} = C" (\text{conf}, \text{sup})$$
- Why effective?
 - It explores highly confident associations among multiple attributes
 - May overcome some constraints introduced by decision-tree induction, which considers only one attribute at a time
 - In many studies, associative classification has been found to be more accurate than some traditional classification methods, such as C4.5



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