# CX1104: Linear Algebra for Computing

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}}_{A} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}}_{n \times 1} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}_{m \times 1}$$

Chap. No: **8.2.1** 

Lecture: Eigen and Singular Values

Topic: Similarity Transform and Diagonalisation

Concept: Diagonalization Symmetric Matrix

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What is symmetric matrix
When does it arise – covariance matrix, normal equation,
What nice property does it have (in diagonalization)

## Diagonalisation of Symmetric Matrices

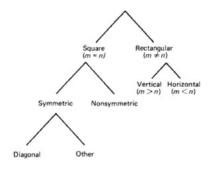
#### 1 Symmetric matrices

**Definition 1.1** A symmetric matrix is a matrix A such that  $A = A^T$ .

In other words a symmetric matrix is a square matrix A such that  $a_{ij} = a_{ji}$ .

### Example 1.2

$$\begin{pmatrix}
1 & 2 & 3 & 4 \\
2 & -1 & 0 & 5 \\
3 & 0 & 2 & -7 \\
4 & 5 & -7 & -2
\end{pmatrix}$$



#### 3.13 Eigenvalues and Eigenvectors of Symmetric Matrices

Two remarkable properties come about when we look at the eigenvalues and eigenvectors of a symmetric matrix  $A \in \mathbb{S}^n$ . First, it can be shown that all the eigenvalues of A are real. Secondly, the eigenvectors of A are orthonormal, i.e., the matrix X defined above is an orthogonal matrix (for this reason, we denote the matrix of eigenvectors as U in this case).

19

We can therefore represent A as  $A = U\Lambda U^T$ , remembering from above that the inverse of an orthogonal matrix is just its transpose.

Using this, we can show that the definiteness of a matrix depends entirely on the sign of its eigenvalues. Suppose  $A \in \mathbb{S}^n = U\Lambda U^T$ . Then

$$x^TAx = x^TU\Lambda U^Tx = y^T\Lambda y = \sum_{i=1}^n \lambda_i y_i^2$$

where  $y=U^Tx$  (and since U is full rank, any vector  $y\in\mathbb{R}^n$  can be represented in this form). Because  $y_i^2$  is always positive, the sign of this expression depends entirely on the  $\lambda_i$ 's. If all  $\lambda_i>0$ , then the matrix is positive definite; if all  $\lambda_i\geq0$ , it is positive semidefinite. Likewise, if all  $\lambda_i<0$  or  $\lambda_i\leq0$ , then A is negative definite or negative semidefinite respectively. Finally, if A has both positive and negative eigenvalues, it is indefinite.

http://cs229.stanford.edu/section/cs229-linalg.pdf

# Diagonalisation of Symmetric Matrices

#### The Spectral Theorem:

**Proposition 2.7** (The Spectral Theorem) An  $n \times n$ symmetric matrix has the following properties:

- 1. A has n real eigenvalues if we count multiplicity
- 2. For each eigenvalue the dimension of the corresponding eigenspace is equal to the algebraic multiplicity of that eigenvalue.
- 3. The eigenspaces are mutually orthogonal
- $4.\ A\ is\ orthogonally\ diagonalizable$

# Diagonalisation of Symmetric Matrices

### Takeaways:

- Symmetric matrices are always diagonalisable. More specifically, **orthogonally diagonalisable**.
- The eigenvectors [also eigenspaces] are mutually orthogonal to one another.
- When a symmetric matrix A has been diagonalised as  $A = PDP^{-1}$ , the columns of P, which are the eigenvectors of A, are mutually orthogonal.
- P can be an orthogonal matrix if its columns (eigenvectors of A) are unit normalised.

### Example:

Consider a symmetric matrix  $A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$ .

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 1 & -2 \\ -2 & \lambda - 1 \end{vmatrix} = (\lambda - 1)^2 - 4$$
$$= \lambda^2 - 2\lambda + 1 - 4 = \lambda^2 - 2\lambda - 3 = (\lambda - 3)(\lambda + 1)$$

Eigenvector corresponding to 
$$\lambda_1=3$$
: 
$$q_1=\begin{bmatrix}1\\1\end{bmatrix} \text{ Upon normalising, } \hat{q}_1=\begin{bmatrix}\frac{1}{\sqrt{2}}\\\frac{1}{\sqrt{2}}\end{bmatrix}.$$

Eigenvector corresponding to 
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: 
$$q_1=\begin{bmatrix}1\\1\end{bmatrix} \text{ Upon normalising, } \hat{q}_1=\begin{bmatrix}\frac{1}{\sqrt{2}}\\\frac{1}{\sqrt{2}}\end{bmatrix}. \qquad \boxed{ \begin{aligned} &q_2=\begin{bmatrix}-1\\1\end{bmatrix} \text{ Upon normalising, } \hat{q}_2=\begin{bmatrix}\frac{-1}{\sqrt{2}}\\\frac{1}{\sqrt{2}}\end{bmatrix}. \end{aligned}}$$

Hence, 
$$A = \underbrace{\begin{bmatrix} \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}}_{P} \underbrace{\begin{bmatrix} -1 & 0 \\ 0 & 3 \end{bmatrix}}_{D} \underbrace{\begin{bmatrix} \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}}_{P^{-1} = P^{T}}$$

# Singular Values

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}_{m \times n}$$

Let A be an  $m \times n$  matrix. Then  $A^TA$  is symmetric and can be orthogonally diagonalized. Let  $\{\mathbf{v}_1, \ldots, \mathbf{v}_n\}$  be an orthonormal basis for  $\mathbb{R}^n$  consisting of eigenvectors of  $A^TA$ , and let  $\lambda_1, \ldots, \lambda_n$  be the associated eigenvalues of  $A^TA$ . Then, for  $1 \le i \le n$ ,

$$||A\mathbf{v}_{i}||^{2} = (A\mathbf{v}_{i})^{T}A\mathbf{v}_{i} = \mathbf{v}_{i}^{T}A^{T}A\mathbf{v}_{i}$$

$$= \mathbf{v}_{i}^{T}(\lambda_{i}\mathbf{v}_{i}) \qquad \text{Since } \mathbf{v}_{i} \text{ is an eigenvector of } A^{T}A$$

$$= \lambda_{i} \qquad \text{Since } \mathbf{v}_{i} \text{ is a unit vector}$$
(2)

So the eigenvalues of  $A^{T}A$  are all nonnegative. By renumbering, if necessary, we may assume that the eigenvalues are arranged so that

$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n \geq 0$$

The **singular values** of A are the square roots of the eigenvalues of  $A^TA$ , denoted by  $\sigma_1, \ldots, \sigma_n$ , and they are arranged in decreasing order. That is,  $\sigma_i = \sqrt{\lambda_i}$  for  $1 \le i \le n$ . By equation (2), the singular values of A are the lengths of the vectors  $A\mathbf{v}_1, \ldots, A\mathbf{v}_n$ .

Lay, Linear Algebra and its Applications (4th Edition)

7.4 The Singular Value Decomposition 417

### Example: Find A's singular values.

$$A = \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix}$$

$$A^{T}A = \begin{bmatrix} 4 & 8 \\ 11 & 7 \\ 14 & -2 \end{bmatrix} \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix} = \begin{bmatrix} 80 & 100 & 40 \\ 100 & 170 & 140 \\ 40 & 140 & 200 \end{bmatrix}$$

The eigenvalues of  $A^TA$  are  $\lambda_1 = 360, \lambda_2 = 90, \text{ and } \lambda_3 = 0.$ 

(Check for yourself!)

### Hence, the singular values of A are:

$$\sigma_1 = \sqrt{360} = 6\sqrt{10}, \quad \sigma_2 = \sqrt{90} = 3\sqrt{10}, \quad \sigma_3 = 0$$