

CX1104: Linear Algebra for Computing

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix}}_{A \quad m \times n} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}}_{x \quad n \times 1} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}_{b \quad m \times 1}$$

Chap. No : **7.2.3**

Lecture : **Least Squares**

Topic : **Reviewing Basic Matrix Algebra**

Concept : **Orthogonal Matrix and Examples**

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Orthogonal Matrix

In linear algebra, an **orthogonal matrix** is a square matrix whose columns and rows are orthogonal unit vectors (orthonormal vectors).

One way to express this is

$$Q^T Q = Q Q^T = I,$$

where Q^T is the transpose of Q and I is the identity matrix.

This leads to the equivalent characterization: a matrix Q is orthogonal if its transpose is equal to its inverse:

$$Q^T = Q^{-1},$$

where Q^{-1} is the inverse of Q .

In decomposing $A = QR$,

- Remember that Q is an orthogonal matrix.
- And R is an upper triangular matrix!

Let A be a square invertible matrix:

$$A A^{-1} = A^{-1} A = I$$

then A^{-1} is its inverse if left or right multiplication produces the identity matrix of appropriate size.

Let U be an orthogonal matrix (orthogonal matrices are usually square), then:

$$U U^T = I \text{ and } U^T U = I$$

Hence orthogonal matrix are very special because its inverse is simply its transpose!, i.e, $U^{-1} = U^T$.

Ref:

1. https://en.wikipedia.org/wiki/Orthogonal_matrix
2. Basic examples: <https://www.nagwa.com/en/explainers/476190725258/>
3. Advance: <https://mathworld.wolfram.com/OrthogonalMatrix.html>

Properties of an Orthogonal Matrix

An important property:

We know that if U is an orthogonal matrix (has orthonormal columns and is square) then $\|U^T x\| = \|x\|$ because

$$\begin{aligned}\|U^T x\|^2 &= x^T U U^T x \\ &= x^T x \quad (\text{since } U U^T = I). \\ &= \|x\|^2.\end{aligned}$$

Other properties:

Consider a linear operator $L : \mathbb{R}^n \rightarrow \mathbb{R}^n$, $L(\mathbf{x}) = A\mathbf{x}$, where A is an $n \times n$ matrix.

Theorem The following conditions are equivalent:

- (i) $\|L(\mathbf{x})\| = \|\mathbf{x}\|$ for all $\mathbf{x} \in \mathbb{R}^n$;
- (ii) $L(\mathbf{x}) \cdot L(\mathbf{y}) = \mathbf{x} \cdot \mathbf{y}$ for all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$;
- (iii) the transformation L preserves distance between points:
 $\|L(\mathbf{x}) - L(\mathbf{y})\| = \|\mathbf{x} - \mathbf{y}\|$ for all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$;
- (iv) L preserves length of vectors and angle between vectors;
- (v) the matrix A is orthogonal;

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Example 1

Solve for X , given:

$$AX(D + BX)^{-1} = C$$

For equation to agree, assume all matrixes are square and invertible.

from (1),

$$AX = C(D + BX);$$

then

$$AX = CD + CBX,$$

or

$$(A - CB)X = CD;$$

if now we know--or assume--that $A - CB$ is invertible, we have

$$X = (A - CB)^{-1}CD.$$

Sanity Check:

```
m =3; n =3;
A = rand(m,n)-0.5;
B = rand(m,n)-0.5;
D = rand(m,n)-0.5;
X = rand(m,n)-0.5;

C = A*X*(inv(D+B*X))
X_est = (inv(A-C*B)) * (C*D)

X-X_est

X_est =

-0.1326    0.3852   -0.4013
 0.4880    0.4133   -0.2381
-0.4623    0.2962   -0.1646

ans =

1.0e-13 *

-0.2254    0.0966    0.0816
-0.3597    0.2026    0.1055
 0.0344   -0.0189   -0.0017
```

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Example 2

Solve for X , given:

$$(AX)^T \left((D + BX)^{-1} \right)^T = I$$

For equation to agree, assume all matrixes are square and invertible.

$$(AX)^T = I * \left(\left((D + BX)^{-1} \right)^T \right)^{-1}$$
$$X^T A^T =$$

$$I * \left(\left((D + BX)^T \right)^{-1} \right)^{-1}$$

$$X^T A^T = I * (D + BX)^T$$

$$X^T A^T = I * D^T + X^T B^T$$

$$X^T A^T - X^T B^T = I * D^T$$

$$X^T (A^T - B^T) = I * D^T$$

$$X^T =$$

$$I * D^T * (A^T - B^T)^{-1}$$

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Sanity Check:

```
m =3; n =3;
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% Example 1

A = rand(m,n)-0.5;
B = rand(m,n)-0.5;
D = rand(m,n)-0.5;
. . . . .

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% Example 2
X_t = D*(inv(A'-B'))
X = X_t'
checkI = (A*X)'*((inv(D+B*X))')
```

```
>> checkI = (A*X)'*((inv(D+B*X))')
```

```
checkI =
```

1.0000	-0.0000	0.0000
0.0000	1.0000	-0.0000
0.0000	0.0000	1.0000

Summary

0.1 basic formulae

$$\mathbf{A}(\mathbf{B} + \mathbf{C}) = \mathbf{AB} + \mathbf{AC} \tag{1a}$$

$$(\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T \tag{1b}$$

$$(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T \tag{1c}$$

if individual inverses exist $(\mathbf{AB})^{-1} = \mathbf{B}^{-1} \mathbf{A}^{-1} \tag{1d}$

$$(\mathbf{A}^{-1})^T = (\mathbf{A}^T)^{-1} \tag{1e}$$

0.2 trace, determinant and rank

$$|\mathbf{AB}| = |\mathbf{A}||\mathbf{B}| \tag{2a}$$

$$|\mathbf{A}^{-1}| = \frac{1}{|\mathbf{A}|} \tag{2b}$$

$$|\mathbf{A}| = \prod \text{evals} \tag{2c}$$

$$\text{Tr} [\mathbf{A}] = \sum \text{evals} \tag{2d}$$

if the cyclic products are well defined,
 $\text{Tr} [\mathbf{ABC} \dots] = \text{Tr} [\mathbf{BC} \dots \mathbf{A}] = \text{Tr} [\mathbf{C} \dots \mathbf{AB}] = \dots \tag{2e}$

$$\text{rank} [\mathbf{A}] = \text{rank} [\mathbf{A}^T \mathbf{A}] = \text{rank} [\mathbf{AA}^T] \tag{2f}$$

$$\text{condition number} = \gamma = \sqrt{\frac{\text{biggest eval}}{\text{smallest eval}}} \tag{2g}$$

evals = eigenValues

Ref:

1. <https://cs.nyu.edu/~roweis/notes/matrixid.pdf>

Supplementary

- The Matrix Cookbook:
<https://www.math.uwaterloo.ca/~hwolkowi/matrixcookbook.pdf>