

CX1104: Linear Algebra for Computing

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix}}_{A \quad m \times n} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}}_{x \quad n \times 1} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}_{b \quad m \times 1}$$

Chap. No : **8.4.1**

Lecture : **Eigen and Singular Values**

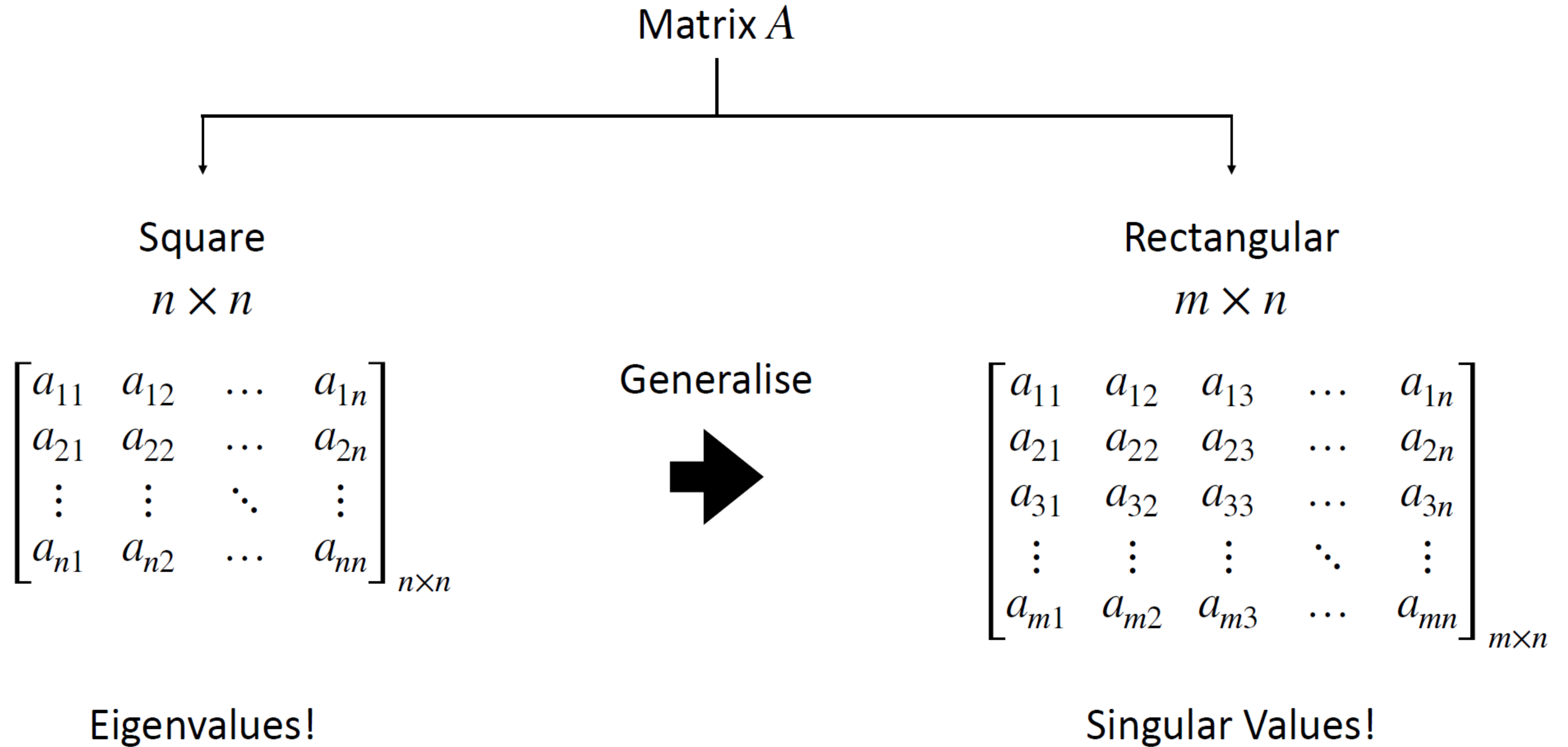
Topic : **SVD & Pseudoinverse**

Concept : **Introduction to SVD**

Instructor: **A/P Chng Eng Siong**

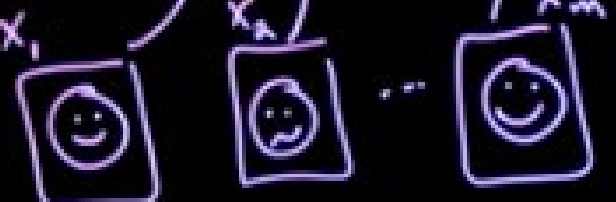
TAs: **Zhang Su, Vishal Choudhari**


Eigenvalues v/s Singular Values



Singular Value Decomposition (SVD)

$$\mathbf{X} = \begin{bmatrix} | & | & \dots & | \\ x_1 & x_2 & \dots & x_m \\ | & | & \dots & | \end{bmatrix} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T = \begin{bmatrix} | & | & \dots & | \\ u_1 & u_2 & \dots & u_n \\ | & | & \dots & | \end{bmatrix} \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_n \\ & & & & 0 \end{bmatrix} \begin{bmatrix} v_1 & v_2 & \dots & v_n \end{bmatrix}^T$$

$x_k \in \mathbb{R}^n$ 

$\mathbf{X} = \begin{bmatrix} | & | & \dots & | \\ x_1 & x_2 & \dots & x_m \\ | & | & \dots & | \end{bmatrix}$ 

U, V unitary

$$\mathbf{U} \mathbf{U}^T = \mathbf{U}^T \mathbf{U} = \mathbf{I}_{n \times n}$$
$$\mathbf{V} \mathbf{V}^T = \mathbf{V}^T \mathbf{V} = \mathbf{I}_{m \times m}$$

"eigen" faces

- 1) What is SVD
- 2) How to interpret U, Σ, V

Singular Value Decomposition (SVD)

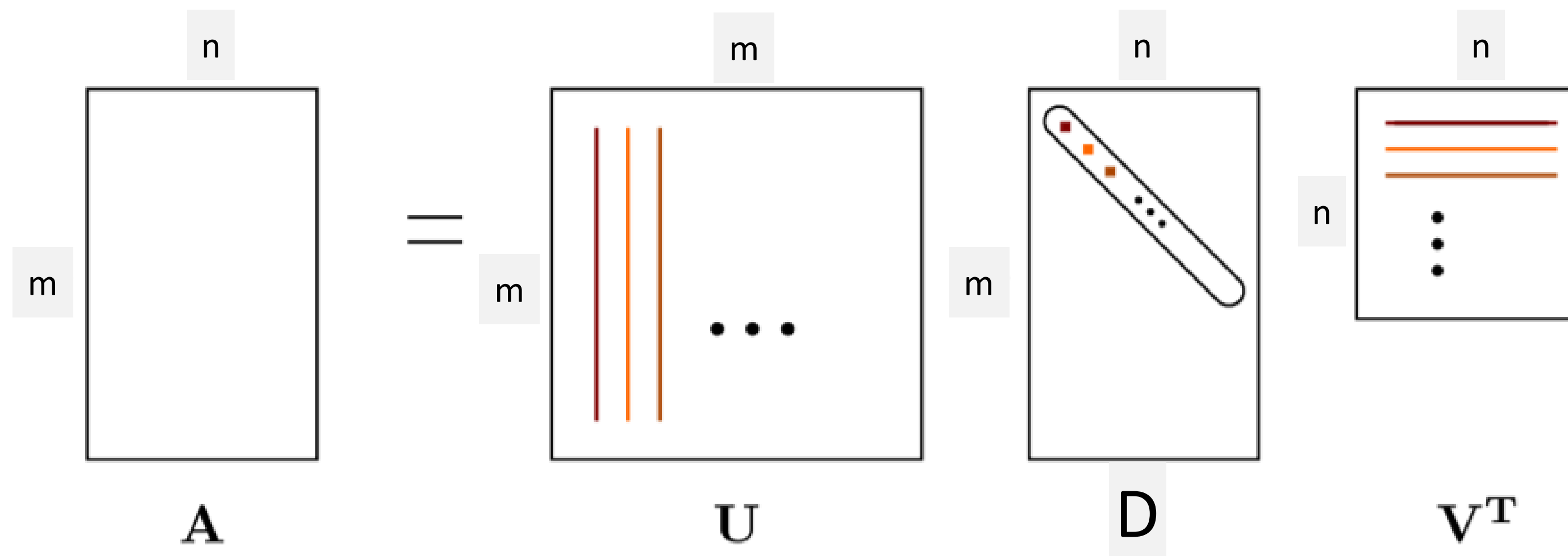


Figure 2: The singular value decomposition (SVD). Each singular value in D has an associated left singular vector in U , and right singular vector in V .

$A = U * D * V'$ where

- U is orthogonal, and $m \times m$;
- D is diagonal, and $m \times n$, with nonnegative diagonal entries σ_i ;
- V is orthogonal, and $n \times n$;

The $\min(m, n)$ diagonal elements of D , written σ_i , are nonnegative, and in decreasing order. The value σ_1 is the l_2 norm of A .

In MATLAB, get the factors by writing:

```
[ U, D, V ] = svd ( A );
```


Singular Value Decomposition (SVD)

The Singular Value Decomposition

Let A be an $m \times n$ matrix with rank r . Then there exists an $m \times n$ matrix Σ as in (3) for which the diagonal entries in D are the first r singular values of A , $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$, and there exist an $m \times m$ orthogonal matrix U and an $n \times n$ orthogonal matrix V such that

$$A = U \Sigma V^T$$

Any factorization $A = U \Sigma V^T$, with U and V orthogonal, Σ as in (3), and positive diagonal entries in D , is called a **singular value decomposition** (or **SVD**) of A . The matrices U and V are not uniquely determined by A , but the diagonal entries of Σ are necessarily the singular values of A . The columns of U in such a decomposition are called **left singular vectors** of A , and the columns of V are called **right singular vectors** of A .

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}_{m \times n}$$

The decomposition of A involves an $m \times n$ “diagonal” matrix Σ of the form

$$\Sigma = \begin{bmatrix} D & 0 \\ 0 & 0 \end{bmatrix} \quad \begin{array}{l} \leftarrow m - r \text{ rows} \\ \uparrow n - r \text{ columns} \end{array} \quad (3)$$

where D is an $r \times r$ diagonal matrix for some r not exceeding the smaller of m and n .

Review:

If a matrix A has a rank r , it means there are r linearly independent rows or columns in matrix A .

For any matrix A , row rank = column rank = r .

SVD(A) vs SVD(A,'econ'): Tall and Skinny A

```
>> A=[1 2; 3 4; 5 6; 7 8]
```

```
A =
```

```
     1     2
     3     4
     5     6
     7     8
```

```
>> [U,D,V] = svd(A)
```

```
U =
```

```
   -0.1525   -0.8226   -0.3945   -0.3800
   -0.3499   -0.4214    0.2428    0.8007
   -0.5474   -0.0201    0.6979   -0.4614
   -0.7448    0.3812   -0.5462    0.0407
```

```
D =
```

```
   14.2691         0
         0    0.6268
         0         0
         0         0
```

```
V =
```

```
   -0.6414    0.7672
   -0.7672   -0.6414
```

```
>> [U,D,V] = svd(A, 'econ')
```

```
U =
```

```
   -0.1525   -0.8226
   -0.3499   -0.4214
   -0.5474   -0.0201
   -0.7448    0.3812
```

```
D =
```

```
   14.2691         0
         0    0.6268
```

```
V =
```

```
   -0.6414    0.7672
   -0.7672   -0.6414
```

```
>> U*D*(V')
```

```
ans =
```

```
     1.0000     2.0000
     3.0000     4.0000
     5.0000     6.0000
     7.0000     8.0000
```

SVD Examples : Fat/Short A

```
>> FatA = A'
```

FatA =

1	3	5	7
2	4	6	8

```
>> [U,D,V] = svd(FatA)
```

U =

-0.6414	0.7672
-0.7672	-0.6414

D =

14.2691	0	0	0
0	0.6268	0	0

V =

-0.1525	-0.8226	-0.3945	-0.3800
-0.3499	-0.4214	0.2428	0.8007
-0.5474	-0.0201	0.6979	-0.4614
-0.7448	0.3812	-0.5462	0.0407

```
>> U*D*(V')
```

ans =

1.0000	3.0000	5.0000	7.0000
2.0000	4.0000	6.0000	8.0000

```
>> [U,D,V] = svd(FatA, 'econ')
```

U =

-0.6414	0.7672
-0.7672	-0.6414

D =

14.2691	0
0	0.6268

V =

-0.1525	-0.8226
-0.3499	-0.4214
-0.5474	-0.0201
-0.7448	0.3812

```
>> U*D*(V')
```

ans =

1.0000	3.0000	5.0000	7.0000
2.0000	4.0000	6.0000	8.0000