CX1104: Linear Algebra for Computing

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}}_{A} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}}_{n \times n} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}_{m \times 1}$$

Chap. No : **7.2.2**

Lecture: Least Squares

Topic: Reviewing Basic Matrix Algebra

Concept: Unitary Matrix Operations

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Transpose of a Matrix

What is the transpose of a matrix?

Let [A] be a $m \times n$ matrix. Then [B] is the transpose of the [A] if $b_{ji} = a_{ij}$ for all i and j. That is, the i^{th} row and the j^{th} column element of [A] is the j^{th} row and i^{th} column element of [B]. Note, [B] would be a $n \times m$ matrix. The transpose of [A] is denoted by $[A]^T$.

Example 1

Find the transpose of

$$[A] = \begin{bmatrix} 25 & 20 & 3 & 2 \\ 5 & 10 & 15 & 25 \\ 6 & 16 & 7 & 27 \end{bmatrix}$$

Solution

The transpose of [A] is

$$[A]^{\mathrm{T}} = \begin{bmatrix} 25 & 5 & 6 \\ 20 & 10 & 16 \\ 3 & 15 & 7 \\ 2 & 25 & 27 \end{bmatrix}$$

Note, the transpose of a row vector is a column vector and the transpose of a column vector is a row vector.

Also, note that the transpose of a transpose of a matrix is the matrix itself, that is, $(A^T)^T = A^T + B^T$; $(A^T)^T = A^T + B^T$; $(A^T)^T = A^T + B^T$.

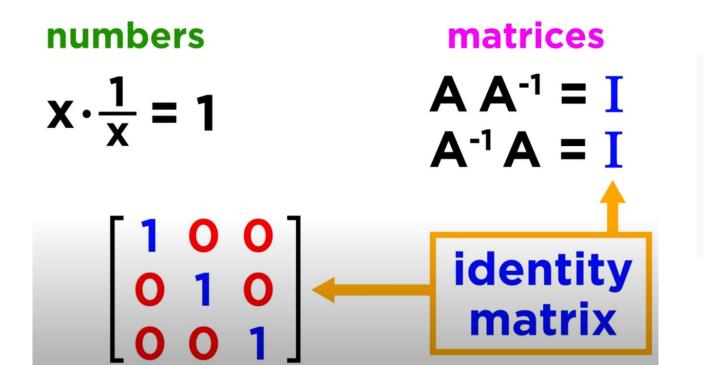
Transpose of a product: (AB)' = B'A'. Transpose of an extended product: (ABC)' = C'B'A'.

Inverse of a Matrix

- Defined only for square matrices.
- A square matrix A has an inverse if there exists a matrix A^{-1} such that:

$$AA^{-1} = I = A^{-1}A$$

Defining the Inverse Matrix



Inverse Matrices and Their Properties

25,819 views • Jan 14, 2019



Professor Dave Explains

When A has an inverse, we say:

- A is invertible
- A is non-singular
- $Det(A) \neq 0$

Three Properties of the Inverse

1. If A is a square matrix and B is the inverse of A, then A is the inverse of B, since AB = I = BA. Then we have the identity:

$$(A^{-1})^{-1} = A$$

2. Notice that $B^{-1}A^{-1}AB = B^{-1}IB = I = ABB^{-1}A^{-1}$. Then:

$$(AB)^{-1} = B^{-1}A^{-1}$$

Then much like the transpose, taking the inverse of a product *reverses* the order of the product.

3. Finally, recall that $(AB)^T = B^T A^T$. Since $I^T = I$, then $(A^{-1}A)^T = A^T (A^{-1})^T = I$. Similarly, $(AA^{-1})^T = (A^{-1})^T A^T = I$. Then:

$$(A^{-1})^T = (A^T)^{-1}$$

Inverse is NOT distributive over addition!

That is:

$$(A + B)^{-1} \neq A^{-1} + B^{-1}$$

e.g, It is NOT even correct if A and B are just real numbers (a 1x1 matrix)!

Ref:

- 1. https://people.richland.edu/james/lecture/m116/matrices/inverses.html
- 2. Prof. Dave: https://www.youtube.com/watch?v=kWorj5BBy9k

Transpose and Inverse

Is
$$(A^{-1})^T = (A^T)^{-1}$$
 you ask.

Well

$$A^{T}(A^{-1})^{T} = (A^{-1}A)^{T} = I^{T} = I$$

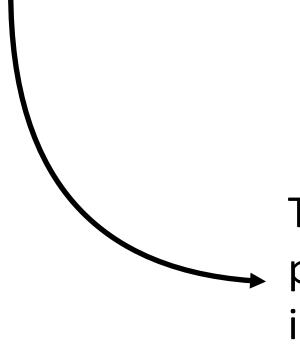
 $(A^{-1})^{T}A^{T} = (AA^{-1})^{T} = I^{T} = I$

This proves that the inverse of A^T is $(A^{-1})^T$. So the answer to your question is yes.

Here I have used that

$$A^T B^T = (BA)^T$$
.

And we have used that the inverse of a matrix A is exactly (by definition) the matrix B such that AB = BA = I.



This property has also been used in proving 2nd and 3rd properties of inverse in Slide 2.

Trace of a Matrix

What is the trace of a matrix?

The trace of a $n \times n$ matrix [A] is the sum of the diagonal entries of [A], that is,

$$\operatorname{tr}[A] = \sum_{i=1}^{n} a_{ii}$$

Find the trace of

$$[A] = \begin{bmatrix} 15 & 6 & 7 \\ 2 & -4 & 2 \\ 3 & 2 & 6 \end{bmatrix}$$

Solution

$$tr[A] = \sum_{i=1}^{3} a_{ii}$$

$$= (15) + (-4) + (6)$$

$$= 17$$

Advance References:

- 1. https://www.quora.com/What-is-a-trace-as-in-trace-of-a-matrix-and-why-is-it-used
- 2. https://math.stackexchange.com/questions/2931926/trace-of-a-matrix-when-to-use-what-is-trace-trick
- 3. https://jsteinhardt.wordpress.com/2012/12/17/algebra-trick-of-the-day/
- 4. Lorenzo Sadun: (Tricks of the Trade I: Traces and Determinants) https://www.youtube.com/watch?v=xyBPEoXqba4

Properties of Trace

The trace of a square matrix A, denoted by $\operatorname{tr}(A)$, is an operator that satisfies the following properties:

1.
$$\operatorname{tr}(A+B) = \operatorname{tr}(A) + \operatorname{tr}(B);$$

2.
$$\operatorname{tr}(kA) = k \operatorname{tr}(A)$$
;

3.
$$\operatorname{tr}(AB) = \operatorname{tr}(BA);$$

4.
$$\operatorname{tr}(I) = \dim(I)$$
.

Here, B is a matrix of the same dimension as A, k is a scalar, I is the identity matrix, and $\dim(M)$ is the dimension (size) of the matrix M.

Properties 1 and 2 tell us that $\operatorname{tr}(\cdot)$ is a linear operator.

It can be shown that the above four properties actually describe the trace operator *uniquely* — there is only one operator on matrices that satisfies properties 1, 2, 3 and 4. Let us find it.

$$\operatorname{tr}(M) = \sum_{k=1}^n m_{kk}.$$
 (†)

In other words, the trace of a square matrix is the sum of its diagonal entries.

Equation (\dagger) is the way that the trace is usually defined in textbooks. However, the properties 1,2,3 and 4 mentioned at the start of this answer generalize to infinite-dimensional vector spaces. Adam Merberg's answer in this thread contains more information in this regard. In any case, now you know *why* we define the trace of a matrix as (\dagger).

Determinant of a Matrix

Determinant: A number describing a square matrix's characteristics, such as:

1. Matrix invertibility:

If
$$det(A) \neq 0 \implies invertible$$

If $det(A) = 0 \implies non-invertible$

2. For linear transformations such as Ax, determinant determines the factor of change in length, area or volume!

See:

https://mathinsight.org/determinant linear transformation

For a matrix [A], determinant is denoted by |A| or det(A). interchangeably.

For a 2×2 matrix,

$$[A] = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$
$$\det(A) = a_{11}a_{22} - a_{12}a_{21}$$

Properties of Determinant:

- 1. det(A) = 0 when A is singular (non-invertible) A is singular when it has dependent rows/columns
- 2. $det(AB) = det(A) \times det(B)$ Note: $det(A^{-1}) = \frac{1}{det(A)}$
- 3. because $A^{-1}A = 1$. (Note that if A is singular then A^{-1} does not exist

Ref:

- 1. 3Blue 1Brown~determinant: https://www.youtube.com/watch?v=Ip3X9LOh2dk
- 2. Strang (18.06): https://ocw.mit.edu/courses/mathematics/18-06sc-linear-algebra-fall-2011/least-squares-determinants-and-eigenvalues/properties-of-determinants/MIT18_06SCF11_Ses2.5sum.pdf