

CX1104: Linear Algebra for Computing

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix}}_{A}^{m \times n} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}}_x^{n \times 1} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}_b^{m \times 1}$$

Chap. No : **6.2.4**

Lecture : **Orthogonality**

Topic : **Orthogonality**

Concept : **Orthonormal Sets & Orthogonal Matrices**

Instructor: **A/P Chng Eng Siong**

TAs: **Zhang Su, Vishal Choudhari**

Orthonormal Sets

Orthonormal Sets

A set $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an **orthonormal set** if it is an orthogonal set of unit vectors. If W is the subspace spanned by such a set, then $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an **orthonormal basis** for W , since the set is automatically linearly independent, by Theorem 4.

The simplest example of an orthonormal set is the standard basis $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ for \mathbb{R}^n . Any nonempty subset of $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ is orthonormal, too. Here is a more complicated example.

THEOREM 4 If $S = \{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an orthogonal set of nonzero vectors in \mathbb{R}^n , then S is linearly independent and hence is a basis for the subspace spanned by S .

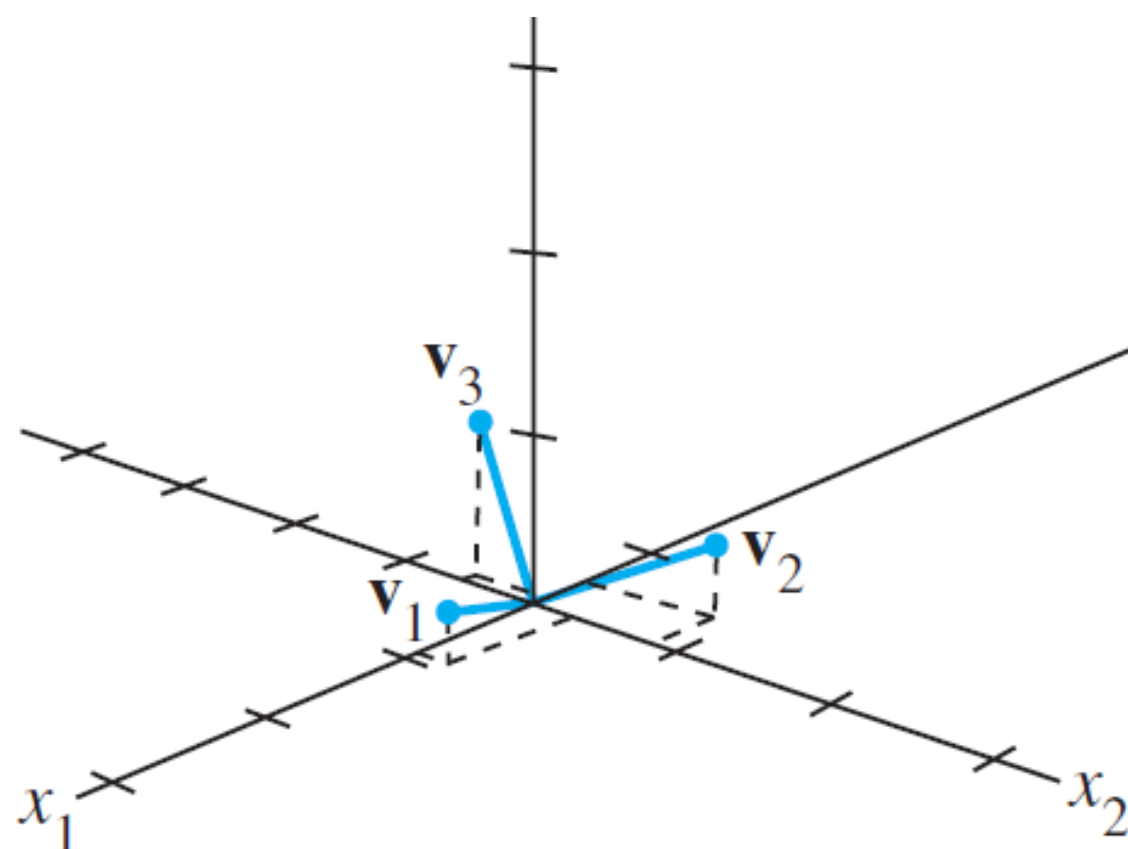


FIGURE 6

Ref: <https://www.youtube.com/watch?v=ZJu26chXEiw>

Linear Algebra: Orthonormal Basis

61,234 views • Jun 28, 2014



Worldwide Center of Mathematics
26.5K subscribers

EXAMPLE 5 Show that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthonormal basis of \mathbb{R}^3 , where

$$\mathbf{v}_1 = \begin{bmatrix} 3/\sqrt{11} \\ 1/\sqrt{11} \\ 1/\sqrt{11} \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -1/\sqrt{6} \\ 2/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} -1/\sqrt{66} \\ -4/\sqrt{66} \\ 7/\sqrt{66} \end{bmatrix}$$

SOLUTION Compute

$$\mathbf{v}_1 \cdot \mathbf{v}_2 = -3/\sqrt{66} + 2/\sqrt{66} + 1/\sqrt{66} = 0$$

$$\mathbf{v}_1 \cdot \mathbf{v}_3 = -3/\sqrt{726} - 4/\sqrt{726} + 7/\sqrt{726} = 0$$

$$\mathbf{v}_2 \cdot \mathbf{v}_3 = 1/\sqrt{396} - 8/\sqrt{396} + 7/\sqrt{396} = 0$$

Thus $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthogonal set. Also,

$$\mathbf{v}_1 \cdot \mathbf{v}_1 = 9/11 + 1/11 + 1/11 = 1$$

$$\mathbf{v}_2 \cdot \mathbf{v}_2 = 1/6 + 4/6 + 1/6 = 1$$

$$\mathbf{v}_3 \cdot \mathbf{v}_3 = 1/66 + 16/66 + 49/66 = 1$$

which shows that $\mathbf{v}_1, \mathbf{v}_2$, and \mathbf{v}_3 are unit vectors. Thus $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthonormal set. Since the set is linearly independent, its three vectors form a basis for \mathbb{R}^3 . See Fig. 6. ■

```
S3 = [ 3/sqrt(11)  -1/sqrt(6)  -1/sqrt(66);  
      1/sqrt(11)  2/sqrt(6)   -4/sqrt(66);  
      1/sqrt(11)  1/sqrt(6)   7/sqrt(66)];
```

```
S3  
checkOrthogonality = S3'*S3
```

```
S3 =  
  
    0.9045    -0.4082   -0.1231  
    0.3015     0.8165   -0.4924  
    0.3015     0.4082    0.8616
```

```
checkOrthogonality =  
  
    1.0000    0.0000    0.0000  
    0.0000    1.0000    0.0000  
    0.0000    0.0000    1.0000
```

NOTE: The 0's correspond to dot products of orthogonal vectors. See next slide for explanation of result!

Orthonormal Sets and Orthogonal Matrices

THEOREM 6

An $m \times n$ matrix U has orthonormal columns if and only if $U^T U = I$.

PROOF To simplify notation, we suppose that U has only three columns, each a vector in \mathbb{R}^m . The proof of the general case is essentially the same. Let $U = [\mathbf{u}_1 \ \mathbf{u}_2 \ \mathbf{u}_3]$ and compute

$$U^T U = \begin{bmatrix} \mathbf{u}_1^T \\ \mathbf{u}_2^T \\ \mathbf{u}_3^T \end{bmatrix} [\mathbf{u}_1 \ \mathbf{u}_2 \ \mathbf{u}_3] = \begin{bmatrix} \mathbf{u}_1^T \mathbf{u}_1 & \mathbf{u}_1^T \mathbf{u}_2 & \mathbf{u}_1^T \mathbf{u}_3 \\ \mathbf{u}_2^T \mathbf{u}_1 & \mathbf{u}_2^T \mathbf{u}_2 & \mathbf{u}_2^T \mathbf{u}_3 \\ \mathbf{u}_3^T \mathbf{u}_1 & \mathbf{u}_3^T \mathbf{u}_2 & \mathbf{u}_3^T \mathbf{u}_3 \end{bmatrix} \quad (4)$$

The entries in the matrix at the right are inner products, using transpose notation. The columns of U are orthogonal if and only if

$$\mathbf{u}_1^T \mathbf{u}_2 = \mathbf{u}_2^T \mathbf{u}_1 = 0, \quad \mathbf{u}_1^T \mathbf{u}_3 = \mathbf{u}_3^T \mathbf{u}_1 = 0, \quad \mathbf{u}_2^T \mathbf{u}_3 = \mathbf{u}_3^T \mathbf{u}_2 = 0 \quad (5)$$

The columns of U all have unit length if and only if

$$\mathbf{u}_1^T \mathbf{u}_1 = 1, \quad \mathbf{u}_2^T \mathbf{u}_2 = 1, \quad \mathbf{u}_3^T \mathbf{u}_3 = 1 \quad (6)$$

The theorem follows immediately from (4)–(6). ■

Orthogonal matrices.

- ▶ A matrix $Q \in \mathbb{R}^{m \times n}$ is called orthogonal if $Q^T Q = I_n$, i.e., if its columns are orthogonal and have 2-norm one.
- ▶ If $Q \in \mathbb{R}^{n \times n}$ is orthogonal, then $Q^T Q = I$ implies that $Q^{-1} = Q^T$.
- ▶ If $Q \in \mathbb{R}^{n \times n}$ is an orthogonal matrix, then Q^T is an orthogonal matrix.

Ref: https://en.wikipedia.org/wiki/Orthogonal_matrix **Important!**

Matlab Example:

```
S3 = [ 3/sqrt(11)  -1/sqrt(6)  -1/sqrt(66);  
      1/sqrt(11)  2/sqrt(6)   -4/sqrt(66);  
      1/sqrt(11)  1/sqrt(6)   7/sqrt(66)];
```

```
S3  
checkOrthogonality = S3'*S3
```

```
S3 =  
  
    0.9045    -0.4082   -0.1231  
    0.3015     0.8165   -0.4924  
    0.3015     0.4082    0.8616
```

```
checkOrthogonality =  
  
    1.0000    0.0000    0.0000  
    0.0000    1.0000    0.0000  
    0.0000    0.0000    1.0000
```


Orthonormal Sets

THEOREM 7

Let U be an $m \times n$ matrix with orthonormal columns, and let \mathbf{x} and \mathbf{y} be in \mathbb{R}^n . Then

- a. $\|U\mathbf{x}\| = \|\mathbf{x}\|$
- b. $(U\mathbf{x}) \cdot (U\mathbf{y}) = \mathbf{x} \cdot \mathbf{y}$
- c. $(U\mathbf{x}) \cdot (U\mathbf{y}) = 0$ if and only if $\mathbf{x} \cdot \mathbf{y} = 0$

Properties (a) and (c) say that the linear mapping $\mathbf{x} \mapsto U\mathbf{x}$ preserves lengths and orthogonality. These properties are crucial for many computer algorithms.

EXAMPLE 6 Let $U = \begin{bmatrix} 1/\sqrt{2} & 2/3 \\ 1/\sqrt{2} & -2/3 \\ 0 & 1/3 \end{bmatrix}$ and $\mathbf{x} = \begin{bmatrix} \sqrt{2} \\ 3 \end{bmatrix}$. Notice that U has orthonormal columns and

$$U^T U = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 2/3 & -2/3 & 1/3 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 2/3 \\ 1/\sqrt{2} & -2/3 \\ 0 & 1/3 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Verify that $\|U\mathbf{x}\| = \|\mathbf{x}\|$.

SOLUTION

$$U\mathbf{x} = \begin{bmatrix} 1/\sqrt{2} & 2/3 \\ 1/\sqrt{2} & -2/3 \\ 0 & 1/3 \end{bmatrix} \begin{bmatrix} \sqrt{2} \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

$$\|U\mathbf{x}\| = \sqrt{9 + 1 + 1} = \sqrt{11}$$

$$\|\mathbf{x}\| = \sqrt{2 + 9} = \sqrt{11}$$

Theorems 6 and 7 are particularly useful when applied to *square* matrices. An **orthogonal matrix** is a square invertible matrix U such that $U^{-1} = U^T$. By Theorem 6, such a matrix has orthonormal columns.¹ It is easy to see that any *square* matrix with orthonormal columns is an orthogonal matrix. Surprisingly, such a matrix must have orthonormal *rows*, too.

Important: Definition of Orthogonal Matrix