/usr/bin/c++ -rdynamic CMakeFiles/schunk\_ezn64.dir/src/ezn64\_usb\_control.cpp.o CMakeFiles/schunk\_ezn64.dir/src/ezn64\_usb\_control\_lib.cpp.o -o /home/rass/Rassul/sensor\_ws/devel/lib/schunk\_ezn64/schunk\_ezn64 -Wl,-rpath,/opt/ros/melodic/lib /opt/ros/melodic/lib/libtf.so /opt/ros/melodic/lib/libtf2\_ros.so /opt/ros/melodic/lib/libactionlib.so /opt/ros/melodic/lib/libmessage\_filters.so /opt/ros/melodic/lib/libroscpp.so -lboost\_filesystem /opt/ros/melodic/lib/libxmlrpcpp.so /opt/ros/melodic/lib/libtf2.so /opt/ros/melodic/lib/libroscpp\_serialization.so /opt/ros/melodic/lib/librosconsole.so /opt/ros/melodic/lib/librosconsole\_log4cxx.so /opt/ros/melodic/lib/librosconsole\_backend\_interface.so -llog4cxx -lboost\_regex /opt/ros/melodic/lib/librostime.so /opt/ros/melodic/lib/libcpp\_common.so -lboost\_system -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4 -lusb-1.0