/usr/bin/c++ -rdynamic CMakeFiles/active\_position.dir/src/data\_call\_position\_control.cpp.o CMakeFiles/active\_position.dir/src/HexFT.cpp.o -o /home/rass/Rassul/sensor\_ws/devel/lib/sensor/active\_position -Wl,-rpath,/opt/ros/melodic/lib /opt/ros/melodic/lib/librosbag.so /opt/ros/melodic/lib/librosbag\_storage.so /opt/ros/melodic/lib/libclass\_loader.so -lPocoFoundation -ldl /opt/ros/melodic/lib/libroslz4.so -llz4 /opt/ros/melodic/lib/libtopic\_tools.so /opt/ros/melodic/lib/libroscpp.so /opt/ros/melodic/lib/librosconsole.so /opt/ros/melodic/lib/librosconsole\_log4cxx.so /opt/ros/melodic/lib/librosconsole\_backend\_interface.so -llog4cxx -lboost\_regex /opt/ros/melodic/lib/libxmlrpcpp.so /opt/ros/melodic/lib/libroslib.so /opt/ros/melodic/lib/librospack.so -lpython2.7 -lboost\_filesystem -lboost\_program\_options -ltinyxml2 /opt/ros/melodic/lib/libroscpp\_serialization.so /opt/ros/melodic/lib/librostime.so /opt/ros/melodic/lib/libcpp\_common.so -lboost\_system -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4