;;

;; DO NOT EDIT THIS FILE

;;

;; THIS FILE IS AUTOMATICALLY GENERATED

;; FROM /home/tactile/Rassul/sensor\_ws/src/ourSensor\_msgs/package.xml (1.3.2)

;; USING /opt/ros/noetic/lib/python3/dist-packages/geneus/geneus\_main.py /opt/ros/noetic/share/geneus/package.xml (3.0.0)

;;

(ros::load-ros-package "geometry\_msgs")

(ros::load-ros-package "roscpp")

(ros::load-ros-package "rosgraph\_msgs")

(ros::load-ros-package "sensor\_msgs")

(ros::load-ros-package "std\_msgs")

(ros::load-ros-package "ourSensor\_msgs")