# This is the CMakeCache file.

# For build in directory: /home/rass/Rassul/ur\_ws/build

# It was generated by CMake: /usr/bin/cmake

# You can edit this file to change values found and used by cmake.

# If you do not want to change any of the values, simply exit the editor.

# If you do want to change a value, simply edit, save, and exit the editor.

# The syntax for the file is as follows:

# KEY:TYPE=VALUE

# KEY is the name of a variable in the cache.

# TYPE is a hint to GUIs for the type of VALUE, DO NOT EDIT TYPE!.

# VALUE is the current value for the KEY.

########################

# EXTERNAL cache entries

########################

//Builds the googlemock subproject

BUILD\_GMOCK:BOOL=ON

//Builds the googletest subproject

BUILD\_GTEST:BOOL=OFF

//Build shared libraries (DLLs).

BUILD\_SHARED\_LIBS:BOOL=ON

//The directory containing a CMake configuration file for Boost.

Boost\_DIR:PATH=Boost\_DIR-NOTFOUND

//Path to a file.

Boost\_INCLUDE\_DIR:PATH=/usr/include

//Boost library directory DEBUG

Boost\_LIBRARY\_DIR\_DEBUG:PATH=/usr/lib/x86\_64-linux-gnu

//Boost library directory RELEASE

Boost\_LIBRARY\_DIR\_RELEASE:PATH=/usr/lib/x86\_64-linux-gnu

//Boost system library (debug)

Boost\_SYSTEM\_LIBRARY\_DEBUG:FILEPATH=/usr/lib/x86\_64-linux-gnu/libboost\_system.so

//Boost system library (release)

Boost\_SYSTEM\_LIBRARY\_RELEASE:FILEPATH=/usr/lib/x86\_64-linux-gnu/libboost\_system.so

//List of ';' separated packages to exclude

CATKIN\_BLACKLIST\_PACKAGES:STRING=

//catkin devel space

CATKIN\_DEVEL\_PREFIX:PATH=/home/rass/Rassul/ur\_ws/devel

//Catkin enable testing

CATKIN\_ENABLE\_TESTING:BOOL=ON

//Catkin skip testing

CATKIN\_SKIP\_TESTING:BOOL=OFF

//Replace the CMake install command with a custom implementation

// using symlinks instead of copying resources

CATKIN\_SYMLINK\_INSTALL:BOOL=OFF

//List of ';' separated packages to build

CATKIN\_WHITELIST\_PACKAGES:STRING=

//Path to a program.

CMAKE\_AR:FILEPATH=/usr/bin/ar

//Choose the type of build, options are: None(CMAKE\_CXX\_FLAGS or

// CMAKE\_C\_FLAGS used) Debug Release RelWithDebInfo MinSizeRel.

CMAKE\_BUILD\_TYPE:STRING=

//Enable/Disable color output during build.

CMAKE\_COLOR\_MAKEFILE:BOOL=ON

//CXX compiler

CMAKE\_CXX\_COMPILER:FILEPATH=/usr/bin/c++

//A wrapper around 'ar' adding the appropriate '--plugin' option

// for the GCC compiler

CMAKE\_CXX\_COMPILER\_AR:FILEPATH=/usr/bin/gcc-ar-7

//A wrapper around 'ranlib' adding the appropriate '--plugin' option

// for the GCC compiler

CMAKE\_CXX\_COMPILER\_RANLIB:FILEPATH=/usr/bin/gcc-ranlib-7

//Flags used by the compiler during all build types.

CMAKE\_CXX\_FLAGS:STRING=

//Flags used by the compiler during debug builds.

CMAKE\_CXX\_FLAGS\_DEBUG:STRING=-g

//Flags used by the compiler during release builds for minimum

// size.

CMAKE\_CXX\_FLAGS\_MINSIZEREL:STRING=-Os -DNDEBUG

//Flags used by the compiler during release builds.

CMAKE\_CXX\_FLAGS\_RELEASE:STRING=-O3 -DNDEBUG

//Flags used by the compiler during release builds with debug info.

CMAKE\_CXX\_FLAGS\_RELWITHDEBINFO:STRING=-O2 -g -DNDEBUG

//C compiler

CMAKE\_C\_COMPILER:FILEPATH=/usr/bin/cc

//A wrapper around 'ar' adding the appropriate '--plugin' option

// for the GCC compiler

CMAKE\_C\_COMPILER\_AR:FILEPATH=/usr/bin/gcc-ar-7

//A wrapper around 'ranlib' adding the appropriate '--plugin' option

// for the GCC compiler

CMAKE\_C\_COMPILER\_RANLIB:FILEPATH=/usr/bin/gcc-ranlib-7

//Flags used by the compiler during all build types.

CMAKE\_C\_FLAGS:STRING=

//Flags used by the compiler during debug builds.

CMAKE\_C\_FLAGS\_DEBUG:STRING=-g

//Flags used by the compiler during release builds for minimum

// size.

CMAKE\_C\_FLAGS\_MINSIZEREL:STRING=-Os -DNDEBUG

//Flags used by the compiler during release builds.

CMAKE\_C\_FLAGS\_RELEASE:STRING=-O3 -DNDEBUG

//Flags used by the compiler during release builds with debug info.

CMAKE\_C\_FLAGS\_RELWITHDEBINFO:STRING=-O2 -g -DNDEBUG

//Flags used by the linker.

CMAKE\_EXE\_LINKER\_FLAGS:STRING=

//Flags used by the linker during debug builds.

CMAKE\_EXE\_LINKER\_FLAGS\_DEBUG:STRING=

//Flags used by the linker during release minsize builds.

CMAKE\_EXE\_LINKER\_FLAGS\_MINSIZEREL:STRING=

//Flags used by the linker during release builds.

CMAKE\_EXE\_LINKER\_FLAGS\_RELEASE:STRING=

//Flags used by the linker during Release with Debug Info builds.

CMAKE\_EXE\_LINKER\_FLAGS\_RELWITHDEBINFO:STRING=

//Enable/Disable output of compile commands during generation.

CMAKE\_EXPORT\_COMPILE\_COMMANDS:BOOL=OFF

//Install path prefix, prepended onto install directories.

CMAKE\_INSTALL\_PREFIX:PATH=/home/rass/Rassul/ur\_ws/install

//Path to a program.

CMAKE\_LINKER:FILEPATH=/usr/bin/ld

//Path to a program.

CMAKE\_MAKE\_PROGRAM:FILEPATH=/usr/bin/make

//Flags used by the linker during the creation of modules.

CMAKE\_MODULE\_LINKER\_FLAGS:STRING=

//Flags used by the linker during debug builds.

CMAKE\_MODULE\_LINKER\_FLAGS\_DEBUG:STRING=

//Flags used by the linker during release minsize builds.

CMAKE\_MODULE\_LINKER\_FLAGS\_MINSIZEREL:STRING=

//Flags used by the linker during release builds.

CMAKE\_MODULE\_LINKER\_FLAGS\_RELEASE:STRING=

//Flags used by the linker during Release with Debug Info builds.

CMAKE\_MODULE\_LINKER\_FLAGS\_RELWITHDEBINFO:STRING=

//Path to a program.

CMAKE\_NM:FILEPATH=/usr/bin/nm

//Path to a program.

CMAKE\_OBJCOPY:FILEPATH=/usr/bin/objcopy

//Path to a program.

CMAKE\_OBJDUMP:FILEPATH=/usr/bin/objdump

//Value Computed by CMake

CMAKE\_PROJECT\_NAME:STATIC=Project

//Path to a program.

CMAKE\_RANLIB:FILEPATH=/usr/bin/ranlib

//Flags used by the linker during the creation of dll's.

CMAKE\_SHARED\_LINKER\_FLAGS:STRING=

//Flags used by the linker during debug builds.

CMAKE\_SHARED\_LINKER\_FLAGS\_DEBUG:STRING=

//Flags used by the linker during release minsize builds.

CMAKE\_SHARED\_LINKER\_FLAGS\_MINSIZEREL:STRING=

//Flags used by the linker during release builds.

CMAKE\_SHARED\_LINKER\_FLAGS\_RELEASE:STRING=

//Flags used by the linker during Release with Debug Info builds.

CMAKE\_SHARED\_LINKER\_FLAGS\_RELWITHDEBINFO:STRING=

//If set, runtime paths are not added when installing shared libraries,

// but are added when building.

CMAKE\_SKIP\_INSTALL\_RPATH:BOOL=NO

//If set, runtime paths are not added when using shared libraries.

CMAKE\_SKIP\_RPATH:BOOL=NO

//Flags used by the linker during the creation of static libraries.

CMAKE\_STATIC\_LINKER\_FLAGS:STRING=

//Flags used by the linker during debug builds.

CMAKE\_STATIC\_LINKER\_FLAGS\_DEBUG:STRING=

//Flags used by the linker during release minsize builds.

CMAKE\_STATIC\_LINKER\_FLAGS\_MINSIZEREL:STRING=

//Flags used by the linker during release builds.

CMAKE\_STATIC\_LINKER\_FLAGS\_RELEASE:STRING=

//Flags used by the linker during Release with Debug Info builds.

CMAKE\_STATIC\_LINKER\_FLAGS\_RELWITHDEBINFO:STRING=

//Path to a program.

CMAKE\_STRIP:FILEPATH=/usr/bin/strip

//If this value is on, makefiles will be generated without the

// .SILENT directive, and all commands will be echoed to the console

// during the make. This is useful for debugging only. With Visual

// Studio IDE projects all commands are done without /nologo.

CMAKE\_VERBOSE\_MAKEFILE:BOOL=FALSE

//Path to a program.

DOXYGEN\_EXECUTABLE:FILEPATH=DOXYGEN\_EXECUTABLE-NOTFOUND

//Path to a program.

EMPY\_EXECUTABLE:FILEPATH=/usr/bin/empy

//Empy script

EMPY\_SCRIPT:STRING=/usr/bin/empy

//The directory containing a CMake configuration file for Eigen3.

Eigen3\_DIR:PATH=/usr/lib/cmake/eigen3

//The directory containing a CMake configuration file for GMock.

GMock\_DIR:PATH=GMock\_DIR-NOTFOUND

//Path to a file.

GTEST\_INCLUDE\_DIR:PATH=/usr/include

//Path to a library.

GTEST\_LIBRARY:FILEPATH=GTEST\_LIBRARY-NOTFOUND

//Path to a library.

GTEST\_LIBRARY\_DEBUG:FILEPATH=GTEST\_LIBRARY\_DEBUG-NOTFOUND

//Path to a library.

GTEST\_MAIN\_LIBRARY:FILEPATH=GTEST\_MAIN\_LIBRARY-NOTFOUND

//Path to a library.

GTEST\_MAIN\_LIBRARY\_DEBUG:FILEPATH=GTEST\_MAIN\_LIBRARY\_DEBUG-NOTFOUND

//lsb\_release executable was found

LSB\_FOUND:BOOL=TRUE

//Path to a program.

LSB\_RELEASE\_EXECUTABLE:FILEPATH=/usr/bin/lsb\_release

//Path to a program.

NOSETESTS:FILEPATH=/usr/bin/nosetests-2.7

//Path to a program.

PYTHON\_EXECUTABLE:FILEPATH=/usr/bin/python2

//Specify specific Python version to use ('major.minor' or 'major')

PYTHON\_VERSION:STRING=2

//Value Computed by CMake

Project\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build

//Value Computed by CMake

Project\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src

//Path to a library.

RT\_LIBRARY:FILEPATH=/usr/lib/x86\_64-linux-gnu/librt.so

//Enable debian style python package layout

SETUPTOOLS\_DEB\_LAYOUT:BOOL=ON

//Name of the computer/site where compile is being run

SITE:STRING=rass

//LSB Distrib tag

UBUNTU:BOOL=TRUE

//LSB Distrib - codename tag

UBUNTU\_BIONIC:BOOL=TRUE

//Path to a file.

\_file\_name:FILEPATH=/home/rass/Rassul/ur\_ws/src/Universal\_Robots\_ROS\_Driver/ur\_robot\_driver/test/driver.test

//Path to a file.

\_gmock\_INCLUDES:FILEPATH=/usr/include/gmock/gmock.h

//Path to a file.

\_gmock\_SOURCES:FILEPATH=/usr/src/gmock/src/gmock.cc

//Path to a file.

\_gtest\_INCLUDES:FILEPATH=/usr/include/gtest/gtest.h

//Path to a file.

\_gtest\_SOURCES:FILEPATH=/usr/src/gtest/src/gtest.cc

//The directory containing a CMake configuration file for actionlib.

actionlib\_DIR:PATH=/opt/ros/melodic/share/actionlib/cmake

//The directory containing a CMake configuration file for actionlib\_msgs.

actionlib\_msgs\_DIR:PATH=/opt/ros/melodic/share/actionlib\_msgs/cmake

//The directory containing a CMake configuration file for angles.

angles\_DIR:PATH=/opt/ros/melodic/share/angles/cmake

//The directory containing a CMake configuration file for cartesian\_control\_msgs.

cartesian\_control\_msgs\_DIR:PATH=/opt/ros/melodic/share/cartesian\_control\_msgs/cmake

//The directory containing a CMake configuration file for cartesian\_interface.

cartesian\_interface\_DIR:PATH=/opt/ros/melodic/share/cartesian\_interface/cmake

//The directory containing a CMake configuration file for catkin.

catkin\_DIR:PATH=/opt/ros/melodic/share/catkin/cmake

//The directory containing a CMake configuration file for class\_loader.

class\_loader\_DIR:PATH=/opt/ros/melodic/share/class\_loader/cmake

//The directory containing a CMake configuration file for control\_msgs.

control\_msgs\_DIR:PATH=/opt/ros/melodic/share/control\_msgs/cmake

//The directory containing a CMake configuration file for control\_toolbox.

control\_toolbox\_DIR:PATH=/opt/ros/melodic/share/control\_toolbox/cmake

//The directory containing a CMake configuration file for controller\_interface.

controller\_interface\_DIR:PATH=/opt/ros/melodic/share/controller\_interface/cmake

//The directory containing a CMake configuration file for controller\_manager.

controller\_manager\_DIR:PATH=/opt/ros/melodic/share/controller\_manager/cmake

//The directory containing a CMake configuration file for controller\_manager\_msgs.

controller\_manager\_msgs\_DIR:PATH=/opt/ros/melodic/share/controller\_manager\_msgs/cmake

//The directory containing a CMake configuration file for cpp\_common.

cpp\_common\_DIR:PATH=/opt/ros/melodic/share/cpp\_common/cmake

//The directory containing a CMake configuration file for dynamic\_reconfigure.

dynamic\_reconfigure\_DIR:PATH=/opt/ros/melodic/share/dynamic\_reconfigure/cmake

//The directory containing a CMake configuration file for eigen\_stl\_containers.

eigen\_stl\_containers\_DIR:PATH=/opt/ros/melodic/share/eigen\_stl\_containers/cmake

//The directory containing a CMake configuration file for gencpp.

gencpp\_DIR:PATH=/opt/ros/melodic/share/gencpp/cmake

//The directory containing a CMake configuration file for geneus.

geneus\_DIR:PATH=/opt/ros/melodic/share/geneus/cmake

//The directory containing a CMake configuration file for genlisp.

genlisp\_DIR:PATH=/opt/ros/melodic/share/genlisp/cmake

//The directory containing a CMake configuration file for genmsg.

genmsg\_DIR:PATH=/opt/ros/melodic/share/genmsg/cmake

//The directory containing a CMake configuration file for gennodejs.

gennodejs\_DIR:PATH=/opt/ros/melodic/share/gennodejs/cmake

//The directory containing a CMake configuration file for genpy.

genpy\_DIR:PATH=/opt/ros/melodic/share/genpy/cmake

//The directory containing a CMake configuration file for geometric\_shapes.

geometric\_shapes\_DIR:PATH=/opt/ros/melodic/share/geometric\_shapes/cmake

//The directory containing a CMake configuration file for geometry\_msgs.

geometry\_msgs\_DIR:PATH=/opt/ros/melodic/share/geometry\_msgs/cmake

//Value Computed by CMake

gmock\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/gtest/googlemock

//Dependencies for the target

gmock\_LIB\_DEPENDS:STATIC=general;-lpthread;

//Value Computed by CMake

gmock\_SOURCE\_DIR:STATIC=/usr/src/googletest/googlemock

//Build all of Google Mock's own tests.

gmock\_build\_tests:BOOL=OFF

//Dependencies for the target

gmock\_main\_LIB\_DEPENDS:STATIC=general;-lpthread;

//Value Computed by CMake

googletest-distribution\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/gtest

//Value Computed by CMake

googletest-distribution\_SOURCE\_DIR:STATIC=/usr/src/googletest

//Value Computed by CMake

gtest\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/gtest/googlemock/gtest

//Dependencies for the target

gtest\_LIB\_DEPENDS:STATIC=general;-lpthread;

//Value Computed by CMake

gtest\_SOURCE\_DIR:STATIC=/usr/src/googletest/googletest

//Build gtest's sample programs.

gtest\_build\_samples:BOOL=OFF

//Build all of gtest's own tests.

gtest\_build\_tests:BOOL=OFF

//Disable uses of pthreads in gtest.

gtest\_disable\_pthreads:BOOL=OFF

//Use shared (DLL) run-time lib even when Google Test is built

// as static lib.

gtest\_force\_shared\_crt:BOOL=OFF

//Build gtest with internal symbols hidden in shared libraries.

gtest\_hide\_internal\_symbols:BOOL=OFF

//Dependencies for the target

gtest\_main\_LIB\_DEPENDS:STATIC=general;-lpthread;general;gtest;

//The directory containing a CMake configuration file for hardware\_interface.

hardware\_interface\_DIR:PATH=/opt/ros/melodic/share/hardware\_interface/cmake

//The directory containing a CMake configuration file for industrial\_robot\_status\_interface.

industrial\_robot\_status\_interface\_DIR:PATH=/opt/ros/melodic/share/industrial\_robot\_status\_interface/cmake

//The directory containing a CMake configuration file for joint\_trajectory\_controller.

joint\_trajectory\_controller\_DIR:PATH=/opt/ros/melodic/share/joint\_trajectory\_controller/cmake

//The directory containing a CMake configuration file for kdl\_conversions.

kdl\_conversions\_DIR:PATH=/opt/ros/melodic/share/kdl\_conversions/cmake

//The directory containing a CMake configuration file for kdl\_parser.

kdl\_parser\_DIR:PATH=/opt/ros/melodic/share/kdl\_parser/cmake

//Path to a library.

lib:FILEPATH=/opt/ros/melodic/lib/libtf.so

//The directory containing a CMake configuration file for message\_filters.

message\_filters\_DIR:PATH=/opt/ros/melodic/share/message\_filters/cmake

//The directory containing a CMake configuration file for message\_generation.

message\_generation\_DIR:PATH=/opt/ros/melodic/share/message\_generation/cmake

//The directory containing a CMake configuration file for message\_runtime.

message\_runtime\_DIR:PATH=/opt/ros/melodic/share/message\_runtime/cmake

//The directory containing a CMake configuration file for moveit\_core.

moveit\_core\_DIR:PATH=/opt/ros/melodic/share/moveit\_core/cmake

//The directory containing a CMake configuration file for moveit\_kinematics.

moveit\_kinematics\_DIR:PATH=/opt/ros/melodic/share/moveit\_kinematics/cmake

//The directory containing a CMake configuration file for moveit\_msgs.

moveit\_msgs\_DIR:PATH=/opt/ros/melodic/share/moveit\_msgs/cmake

//The directory containing a CMake configuration file for moveit\_ros\_occupancy\_map\_monitor.

moveit\_ros\_occupancy\_map\_monitor\_DIR:PATH=/opt/ros/melodic/share/moveit\_ros\_occupancy\_map\_monitor/cmake

//The directory containing a CMake configuration file for moveit\_ros\_planning.

moveit\_ros\_planning\_DIR:PATH=/opt/ros/melodic/share/moveit\_ros\_planning/cmake

//The directory containing a CMake configuration file for object\_recognition\_msgs.

object\_recognition\_msgs\_DIR:PATH=/opt/ros/melodic/share/object\_recognition\_msgs/cmake

//The directory containing a CMake configuration file for octomap\_msgs.

octomap\_msgs\_DIR:PATH=/opt/ros/melodic/share/octomap\_msgs/cmake

//The directory containing a CMake configuration file for pass\_through\_controllers.

pass\_through\_controllers\_DIR:PATH=/opt/ros/melodic/share/pass\_through\_controllers/cmake

//The directory containing a CMake configuration file for pluginlib.

pluginlib\_DIR:PATH=/opt/ros/melodic/share/pluginlib/cmake

//The directory containing a CMake configuration file for random\_numbers.

random\_numbers\_DIR:PATH=/opt/ros/melodic/share/random\_numbers/cmake

//The directory containing a CMake configuration file for realtime\_tools.

realtime\_tools\_DIR:PATH=/opt/ros/melodic/share/realtime\_tools/cmake

//The directory containing a CMake configuration file for rosconsole.

rosconsole\_DIR:PATH=/opt/ros/melodic/share/rosconsole/cmake

//The directory containing a CMake configuration file for rosconsole\_bridge.

rosconsole\_bridge\_DIR:PATH=/opt/ros/melodic/share/rosconsole\_bridge/cmake

//The directory containing a CMake configuration file for roscpp.

roscpp\_DIR:PATH=/opt/ros/melodic/share/roscpp/cmake

//The directory containing a CMake configuration file for roscpp\_serialization.

roscpp\_serialization\_DIR:PATH=/opt/ros/melodic/share/roscpp\_serialization/cmake

//The directory containing a CMake configuration file for roscpp\_traits.

roscpp\_traits\_DIR:PATH=/opt/ros/melodic/share/roscpp\_traits/cmake

//The directory containing a CMake configuration file for rosgraph.

rosgraph\_DIR:PATH=/opt/ros/melodic/share/rosgraph/cmake

//The directory containing a CMake configuration file for rosgraph\_msgs.

rosgraph\_msgs\_DIR:PATH=/opt/ros/melodic/share/rosgraph\_msgs/cmake

//The directory containing a CMake configuration file for roslib.

roslib\_DIR:PATH=/opt/ros/melodic/share/roslib/cmake

//The directory containing a CMake configuration file for rospack.

rospack\_DIR:PATH=/opt/ros/melodic/share/rospack/cmake

//The directory containing a CMake configuration file for rospy.

rospy\_DIR:PATH=/opt/ros/melodic/share/rospy/cmake

//The directory containing a CMake configuration file for rostest.

rostest\_DIR:PATH=/opt/ros/melodic/share/rostest/cmake

//The directory containing a CMake configuration file for rostime.

rostime\_DIR:PATH=/opt/ros/melodic/share/rostime/cmake

//The directory containing a CMake configuration file for scaled\_joint\_trajectory\_controller.

scaled\_joint\_trajectory\_controller\_DIR:PATH=/opt/ros/melodic/share/scaled\_joint\_trajectory\_controller/cmake

//The directory containing a CMake configuration file for sensor\_msgs.

sensor\_msgs\_DIR:PATH=/opt/ros/melodic/share/sensor\_msgs/cmake

//The directory containing a CMake configuration file for shape\_msgs.

shape\_msgs\_DIR:PATH=/opt/ros/melodic/share/shape\_msgs/cmake

//The directory containing a CMake configuration file for speed\_scaling\_interface.

speed\_scaling\_interface\_DIR:PATH=/opt/ros/melodic/share/speed\_scaling\_interface/cmake

//The directory containing a CMake configuration file for speed\_scaling\_state\_controller.

speed\_scaling\_state\_controller\_DIR:PATH=/opt/ros/melodic/share/speed\_scaling\_state\_controller/cmake

//The directory containing a CMake configuration file for srdfdom.

srdfdom\_DIR:PATH=/opt/ros/melodic/share/srdfdom/cmake

//The directory containing a CMake configuration file for std\_msgs.

std\_msgs\_DIR:PATH=/opt/ros/melodic/share/std\_msgs/cmake

//The directory containing a CMake configuration file for std\_srvs.

std\_srvs\_DIR:PATH=/opt/ros/melodic/share/std\_srvs/cmake

//The directory containing a CMake configuration file for tf2.

tf2\_DIR:PATH=/opt/ros/melodic/share/tf2/cmake

//The directory containing a CMake configuration file for tf2\_eigen.

tf2\_eigen\_DIR:PATH=/opt/ros/melodic/share/tf2\_eigen/cmake

//The directory containing a CMake configuration file for tf2\_geometry\_msgs.

tf2\_geometry\_msgs\_DIR:PATH=/opt/ros/melodic/share/tf2\_geometry\_msgs/cmake

//The directory containing a CMake configuration file for tf2\_msgs.

tf2\_msgs\_DIR:PATH=/opt/ros/melodic/share/tf2\_msgs/cmake

//The directory containing a CMake configuration file for tf2\_py.

tf2\_py\_DIR:PATH=/opt/ros/melodic/share/tf2\_py/cmake

//The directory containing a CMake configuration file for tf2\_ros.

tf2\_ros\_DIR:PATH=/opt/ros/melodic/share/tf2\_ros/cmake

//The directory containing a CMake configuration file for tf.

tf\_DIR:PATH=/opt/ros/melodic/share/tf/cmake

//The directory containing a CMake configuration file for tf\_conversions.

tf\_conversions\_DIR:PATH=/opt/ros/melodic/share/tf\_conversions/cmake

//The directory containing a CMake configuration file for trajectory\_msgs.

trajectory\_msgs\_DIR:PATH=/opt/ros/melodic/share/trajectory\_msgs/cmake

//Value Computed by CMake

universal\_robot\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/universal\_robot

//Value Computed by CMake

universal\_robot\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/universal\_robot

//Dependencies for target

ur10\_kin\_LIB\_DEPENDS:STATIC=

//Value Computed by CMake

ur10\_moveit\_config\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur10\_moveit\_config

//Value Computed by CMake

ur10\_moveit\_config\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur10\_moveit\_config

//Dependencies for the target

ur10\_moveit\_plugin\_LIB\_DEPENDS:STATIC=general;/opt/ros/melodic/lib/libmoveit\_rdf\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_plugin\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_model\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_constraint\_sampler\_manager\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_pipeline.so;general;/opt/ros/melodic/lib/libmoveit\_trajectory\_execution\_manager.so;general;/opt/ros/melodic/lib/libmoveit\_plan\_execution.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_scene\_monitor.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_plugin\_loader.so;general;/opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so;general;/opt/ros/melodic/lib/libmoveit\_ros\_occupancy\_map\_monitor.so;general;/opt/ros/melodic/lib/libmoveit\_exceptions.so;general;/opt/ros/melodic/lib/libmoveit\_background\_processing.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_base.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_model.so;general;/opt/ros/melodic/lib/libmoveit\_transforms.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_state.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_trajectory.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_interface.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_detection.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_detection\_fcl.so;general;/opt/ros/melodic/lib/libmoveit\_kinematic\_constraints.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_scene.so;general;/opt/ros/melodic/lib/libmoveit\_constraint\_samplers.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_request\_adapter.so;general;/opt/ros/melodic/lib/libmoveit\_profiler.so;general;/opt/ros/melodic/lib/libmoveit\_python\_tools.so;general;/opt/ros/melodic/lib/libmoveit\_trajectory\_processing.so;general;/opt/ros/melodic/lib/libmoveit\_distance\_field.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_distance\_field.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_metrics.so;general;/opt/ros/melodic/lib/libmoveit\_dynamics\_solver.so;general;/opt/ros/melodic/lib/libmoveit\_utils.so;general;/opt/ros/melodic/lib/libmoveit\_test\_utils.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_iostreams.so;general;/usr/lib/x86\_64-linux-gnu/libfcl.so;general;/opt/ros/melodic/lib/libkdl\_parser.so;general;/opt/ros/melodic/lib/liburdf.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_sensor.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model\_state.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_world.so;general;/opt/ros/melodic/lib/librosconsole\_bridge.so;general;/opt/ros/melodic/lib/libsrdfdom.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml.so;general;/opt/ros/melodic/lib/libgeometric\_shapes.so;general;/opt/ros/melodic/lib/liboctomap.so;general;/opt/ros/melodic/lib/liboctomath.so;general;/opt/ros/melodic/lib/librandom\_numbers.so;general;/opt/ros/melodic/lib/liborocos-kdl.so;general;/opt/ros/melodic/lib/libclass\_loader.so;general;/usr/lib/libPocoFoundation.so;general;/usr/lib/x86\_64-linux-gnu/libdl.so;general;/opt/ros/melodic/lib/libroslib.so;general;/opt/ros/melodic/lib/librospack.so;general;/usr/lib/x86\_64-linux-gnu/libpython2.7.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_program\_options.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml2.so;general;/opt/ros/melodic/lib/libtf\_conversions.so;general;/opt/ros/melodic/lib/libkdl\_conversions.so;general;/opt/ros/melodic/lib/liborocos-kdl.so.1.4.0;general;/opt/ros/melodic/lib/libtf.so;general;/opt/ros/melodic/lib/libtf2\_ros.so;general;/opt/ros/melodic/lib/libactionlib.so;general;/opt/ros/melodic/lib/libmessage\_filters.so;general;/opt/ros/melodic/lib/libroscpp.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_filesystem.so;general;/opt/ros/melodic/lib/libxmlrpcpp.so;general;/opt/ros/melodic/lib/libtf2.so;general;/opt/ros/melodic/lib/libroscpp\_serialization.so;general;/opt/ros/melodic/lib/librosconsole.so;general;/opt/ros/melodic/lib/librosconsole\_log4cxx.so;general;/opt/ros/melodic/lib/librosconsole\_backend\_interface.so;general;/usr/lib/x86\_64-linux-gnu/liblog4cxx.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_regex.so;general;/opt/ros/melodic/lib/librostime.so;general;/opt/ros/melodic/lib/libcpp\_common.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_thread.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_chrono.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_date\_time.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_atomic.so;general;/usr/lib/x86\_64-linux-gnu/libpthread.so;general;/usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;ur10\_kin;

//Dependencies for target

ur3\_kin\_LIB\_DEPENDS:STATIC=

//Value Computed by CMake

ur3\_moveit\_config\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur3\_moveit\_config

//Value Computed by CMake

ur3\_moveit\_config\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur3\_moveit\_config

//Dependencies for the target

ur3\_moveit\_plugin\_LIB\_DEPENDS:STATIC=general;/opt/ros/melodic/lib/libmoveit\_rdf\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_plugin\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_model\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_constraint\_sampler\_manager\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_pipeline.so;general;/opt/ros/melodic/lib/libmoveit\_trajectory\_execution\_manager.so;general;/opt/ros/melodic/lib/libmoveit\_plan\_execution.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_scene\_monitor.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_plugin\_loader.so;general;/opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so;general;/opt/ros/melodic/lib/libmoveit\_ros\_occupancy\_map\_monitor.so;general;/opt/ros/melodic/lib/libmoveit\_exceptions.so;general;/opt/ros/melodic/lib/libmoveit\_background\_processing.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_base.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_model.so;general;/opt/ros/melodic/lib/libmoveit\_transforms.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_state.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_trajectory.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_interface.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_detection.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_detection\_fcl.so;general;/opt/ros/melodic/lib/libmoveit\_kinematic\_constraints.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_scene.so;general;/opt/ros/melodic/lib/libmoveit\_constraint\_samplers.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_request\_adapter.so;general;/opt/ros/melodic/lib/libmoveit\_profiler.so;general;/opt/ros/melodic/lib/libmoveit\_python\_tools.so;general;/opt/ros/melodic/lib/libmoveit\_trajectory\_processing.so;general;/opt/ros/melodic/lib/libmoveit\_distance\_field.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_distance\_field.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_metrics.so;general;/opt/ros/melodic/lib/libmoveit\_dynamics\_solver.so;general;/opt/ros/melodic/lib/libmoveit\_utils.so;general;/opt/ros/melodic/lib/libmoveit\_test\_utils.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_iostreams.so;general;/usr/lib/x86\_64-linux-gnu/libfcl.so;general;/opt/ros/melodic/lib/libkdl\_parser.so;general;/opt/ros/melodic/lib/liburdf.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_sensor.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model\_state.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_world.so;general;/opt/ros/melodic/lib/librosconsole\_bridge.so;general;/opt/ros/melodic/lib/libsrdfdom.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml.so;general;/opt/ros/melodic/lib/libgeometric\_shapes.so;general;/opt/ros/melodic/lib/liboctomap.so;general;/opt/ros/melodic/lib/liboctomath.so;general;/opt/ros/melodic/lib/librandom\_numbers.so;general;/opt/ros/melodic/lib/liborocos-kdl.so;general;/opt/ros/melodic/lib/libclass\_loader.so;general;/usr/lib/libPocoFoundation.so;general;/usr/lib/x86\_64-linux-gnu/libdl.so;general;/opt/ros/melodic/lib/libroslib.so;general;/opt/ros/melodic/lib/librospack.so;general;/usr/lib/x86\_64-linux-gnu/libpython2.7.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_program\_options.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml2.so;general;/opt/ros/melodic/lib/libtf\_conversions.so;general;/opt/ros/melodic/lib/libkdl\_conversions.so;general;/opt/ros/melodic/lib/liborocos-kdl.so.1.4.0;general;/opt/ros/melodic/lib/libtf.so;general;/opt/ros/melodic/lib/libtf2\_ros.so;general;/opt/ros/melodic/lib/libactionlib.so;general;/opt/ros/melodic/lib/libmessage\_filters.so;general;/opt/ros/melodic/lib/libroscpp.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_filesystem.so;general;/opt/ros/melodic/lib/libxmlrpcpp.so;general;/opt/ros/melodic/lib/libtf2.so;general;/opt/ros/melodic/lib/libroscpp\_serialization.so;general;/opt/ros/melodic/lib/librosconsole.so;general;/opt/ros/melodic/lib/librosconsole\_log4cxx.so;general;/opt/ros/melodic/lib/librosconsole\_backend\_interface.so;general;/usr/lib/x86\_64-linux-gnu/liblog4cxx.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_regex.so;general;/opt/ros/melodic/lib/librostime.so;general;/opt/ros/melodic/lib/libcpp\_common.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_thread.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_chrono.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_date\_time.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_atomic.so;general;/usr/lib/x86\_64-linux-gnu/libpthread.so;general;/usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;ur3\_kin;

//Dependencies for target

ur5\_kin\_LIB\_DEPENDS:STATIC=

//Value Computed by CMake

ur5\_moveit\_config\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur5\_moveit\_config

//Value Computed by CMake

ur5\_moveit\_config\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur5\_moveit\_config

//Dependencies for the target

ur5\_moveit\_plugin\_LIB\_DEPENDS:STATIC=general;/opt/ros/melodic/lib/libmoveit\_rdf\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_plugin\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_model\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_constraint\_sampler\_manager\_loader.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_pipeline.so;general;/opt/ros/melodic/lib/libmoveit\_trajectory\_execution\_manager.so;general;/opt/ros/melodic/lib/libmoveit\_plan\_execution.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_scene\_monitor.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_plugin\_loader.so;general;/opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so;general;/opt/ros/melodic/lib/libmoveit\_ros\_occupancy\_map\_monitor.so;general;/opt/ros/melodic/lib/libmoveit\_exceptions.so;general;/opt/ros/melodic/lib/libmoveit\_background\_processing.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_base.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_model.so;general;/opt/ros/melodic/lib/libmoveit\_transforms.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_state.so;general;/opt/ros/melodic/lib/libmoveit\_robot\_trajectory.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_interface.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_detection.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_detection\_fcl.so;general;/opt/ros/melodic/lib/libmoveit\_kinematic\_constraints.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_scene.so;general;/opt/ros/melodic/lib/libmoveit\_constraint\_samplers.so;general;/opt/ros/melodic/lib/libmoveit\_planning\_request\_adapter.so;general;/opt/ros/melodic/lib/libmoveit\_profiler.so;general;/opt/ros/melodic/lib/libmoveit\_python\_tools.so;general;/opt/ros/melodic/lib/libmoveit\_trajectory\_processing.so;general;/opt/ros/melodic/lib/libmoveit\_distance\_field.so;general;/opt/ros/melodic/lib/libmoveit\_collision\_distance\_field.so;general;/opt/ros/melodic/lib/libmoveit\_kinematics\_metrics.so;general;/opt/ros/melodic/lib/libmoveit\_dynamics\_solver.so;general;/opt/ros/melodic/lib/libmoveit\_utils.so;general;/opt/ros/melodic/lib/libmoveit\_test\_utils.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_iostreams.so;general;/usr/lib/x86\_64-linux-gnu/libfcl.so;general;/opt/ros/melodic/lib/libkdl\_parser.so;general;/opt/ros/melodic/lib/liburdf.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_sensor.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model\_state.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_world.so;general;/opt/ros/melodic/lib/librosconsole\_bridge.so;general;/opt/ros/melodic/lib/libsrdfdom.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml.so;general;/opt/ros/melodic/lib/libgeometric\_shapes.so;general;/opt/ros/melodic/lib/liboctomap.so;general;/opt/ros/melodic/lib/liboctomath.so;general;/opt/ros/melodic/lib/librandom\_numbers.so;general;/opt/ros/melodic/lib/liborocos-kdl.so;general;/opt/ros/melodic/lib/libclass\_loader.so;general;/usr/lib/libPocoFoundation.so;general;/usr/lib/x86\_64-linux-gnu/libdl.so;general;/opt/ros/melodic/lib/libroslib.so;general;/opt/ros/melodic/lib/librospack.so;general;/usr/lib/x86\_64-linux-gnu/libpython2.7.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_program\_options.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml2.so;general;/opt/ros/melodic/lib/libtf\_conversions.so;general;/opt/ros/melodic/lib/libkdl\_conversions.so;general;/opt/ros/melodic/lib/liborocos-kdl.so.1.4.0;general;/opt/ros/melodic/lib/libtf.so;general;/opt/ros/melodic/lib/libtf2\_ros.so;general;/opt/ros/melodic/lib/libactionlib.so;general;/opt/ros/melodic/lib/libmessage\_filters.so;general;/opt/ros/melodic/lib/libroscpp.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_filesystem.so;general;/opt/ros/melodic/lib/libxmlrpcpp.so;general;/opt/ros/melodic/lib/libtf2.so;general;/opt/ros/melodic/lib/libroscpp\_serialization.so;general;/opt/ros/melodic/lib/librosconsole.so;general;/opt/ros/melodic/lib/librosconsole\_log4cxx.so;general;/opt/ros/melodic/lib/librosconsole\_backend\_interface.so;general;/usr/lib/x86\_64-linux-gnu/liblog4cxx.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_regex.so;general;/opt/ros/melodic/lib/librostime.so;general;/opt/ros/melodic/lib/libcpp\_common.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_thread.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_chrono.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_date\_time.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_atomic.so;general;/usr/lib/x86\_64-linux-gnu/libpthread.so;general;/usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;ur5\_kin;

//Value Computed by CMake

ur\_bringup\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur\_bringup

//Value Computed by CMake

ur\_bringup\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur\_bringup

//Value Computed by CMake

ur\_calibration\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/Universal\_Robots\_ROS\_Driver/ur\_calibration

//Value Computed by CMake

ur\_calibration\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/Universal\_Robots\_ROS\_Driver/ur\_calibration

//The directory containing a CMake configuration file for ur\_client\_library.

ur\_client\_library\_DIR:PATH=/opt/ros/melodic/lib/cmake/ur\_client\_library

//Value Computed by CMake

ur\_dashboard\_msgs\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/Universal\_Robots\_ROS\_Driver/ur\_dashboard\_msgs

//The directory containing a CMake configuration file for ur\_dashboard\_msgs.

ur\_dashboard\_msgs\_DIR:PATH=/home/rass/Rassul/ur\_ws/devel/share/ur\_dashboard\_msgs/cmake

//Value Computed by CMake

ur\_dashboard\_msgs\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/Universal\_Robots\_ROS\_Driver/ur\_dashboard\_msgs

//Value Computed by CMake

ur\_description\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur\_description

//Value Computed by CMake

ur\_description\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur\_description

//Value Computed by CMake

ur\_driver\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur\_driver

//Value Computed by CMake

ur\_driver\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur\_driver

//Value Computed by CMake

ur\_gazebo\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur\_gazebo

//Value Computed by CMake

ur\_gazebo\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur\_gazebo

//Value Computed by CMake

ur\_kinematics\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur\_kinematics

//Value Computed by CMake

ur\_kinematics\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur\_kinematics

//Value Computed by CMake

ur\_msgs\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/universal\_robot/ur\_msgs

ur\_msgs\_DIR:PATH=

//Value Computed by CMake

ur\_msgs\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/universal\_robot/ur\_msgs

//Value Computed by CMake

ur\_robot\_driver\_BINARY\_DIR:STATIC=/home/rass/Rassul/ur\_ws/build/Universal\_Robots\_ROS\_Driver/ur\_robot\_driver

//The directory containing a CMake configuration file for ur\_robot\_driver.

ur\_robot\_driver\_DIR:PATH=/home/rass/Rassul/ur\_ws/devel/share/ur\_robot\_driver/cmake

//Value Computed by CMake

ur\_robot\_driver\_SOURCE\_DIR:STATIC=/home/rass/Rassul/ur\_ws/src/Universal\_Robots\_ROS\_Driver/ur\_robot\_driver

//Dependencies for the target

ur\_robot\_driver\_plugin\_LIB\_DEPENDS:STATIC=general;ur\_client\_library::urcl;general;/opt/ros/melodic/lib/libscaled\_joint\_trajectory\_controller.so;general;/opt/ros/melodic/lib/libjoint\_trajectory\_controller.so;general;/opt/ros/melodic/lib/libcontrol\_toolbox.so;general;/opt/ros/melodic/lib/libspeed\_scaling\_state\_controller.so;general;/opt/ros/melodic/lib/librealtime\_tools.so;general;/opt/ros/melodic/lib/libtf.so;general;/opt/ros/melodic/lib/liborocos-kdl.so;general;/opt/ros/melodic/lib/libtf2\_ros.so;general;/opt/ros/melodic/lib/libmessage\_filters.so;general;/opt/ros/melodic/lib/libtf2.so;general;/opt/ros/melodic/lib/libpass\_through\_controllers.so;general;/opt/ros/melodic/lib/libactionlib.so;general;/opt/ros/melodic/lib/libcontroller\_manager.so;general;/opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so;general;/opt/ros/melodic/lib/libkdl\_parser.so;general;/opt/ros/melodic/lib/liborocos-kdl.so.1.4.0;general;/opt/ros/melodic/lib/liburdf.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_sensor.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model\_state.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_world.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml.so;general;/opt/ros/melodic/lib/libclass\_loader.so;general;/usr/lib/libPocoFoundation.so;general;/usr/lib/x86\_64-linux-gnu/libdl.so;general;/opt/ros/melodic/lib/libroslib.so;general;/opt/ros/melodic/lib/librospack.so;general;/usr/lib/x86\_64-linux-gnu/libpython2.7.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_program\_options.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml2.so;general;/opt/ros/melodic/lib/librosconsole\_bridge.so;general;/opt/ros/melodic/lib/libroscpp.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_filesystem.so;general;/opt/ros/melodic/lib/librosconsole.so;general;/opt/ros/melodic/lib/librosconsole\_log4cxx.so;general;/opt/ros/melodic/lib/librosconsole\_backend\_interface.so;general;/usr/lib/x86\_64-linux-gnu/liblog4cxx.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_regex.so;general;/opt/ros/melodic/lib/libroscpp\_serialization.so;general;/opt/ros/melodic/lib/libxmlrpcpp.so;general;/opt/ros/melodic/lib/librostime.so;general;/opt/ros/melodic/lib/libcpp\_common.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_thread.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_chrono.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_date\_time.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_atomic.so;general;/usr/lib/x86\_64-linux-gnu/libpthread.so;general;/usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4;

//Dependencies for the target

urcl\_log\_handler\_LIB\_DEPENDS:STATIC=general;/opt/ros/melodic/lib/libscaled\_joint\_trajectory\_controller.so;general;/opt/ros/melodic/lib/libjoint\_trajectory\_controller.so;general;/opt/ros/melodic/lib/libcontrol\_toolbox.so;general;/opt/ros/melodic/lib/libspeed\_scaling\_state\_controller.so;general;/opt/ros/melodic/lib/librealtime\_tools.so;general;/opt/ros/melodic/lib/libtf.so;general;/opt/ros/melodic/lib/liborocos-kdl.so;general;/opt/ros/melodic/lib/libtf2\_ros.so;general;/opt/ros/melodic/lib/libmessage\_filters.so;general;/opt/ros/melodic/lib/libtf2.so;general;/opt/ros/melodic/lib/libpass\_through\_controllers.so;general;/opt/ros/melodic/lib/libactionlib.so;general;/opt/ros/melodic/lib/libcontroller\_manager.so;general;/opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so;general;/opt/ros/melodic/lib/libkdl\_parser.so;general;/opt/ros/melodic/lib/liborocos-kdl.so.1.4.0;general;/opt/ros/melodic/lib/liburdf.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_sensor.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model\_state.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_model.so;general;/usr/lib/x86\_64-linux-gnu/liburdfdom\_world.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml.so;general;/opt/ros/melodic/lib/libclass\_loader.so;general;/usr/lib/libPocoFoundation.so;general;/usr/lib/x86\_64-linux-gnu/libdl.so;general;/opt/ros/melodic/lib/libroslib.so;general;/opt/ros/melodic/lib/librospack.so;general;/usr/lib/x86\_64-linux-gnu/libpython2.7.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_program\_options.so;general;/usr/lib/x86\_64-linux-gnu/libtinyxml2.so;general;/opt/ros/melodic/lib/librosconsole\_bridge.so;general;/opt/ros/melodic/lib/libroscpp.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_filesystem.so;general;/opt/ros/melodic/lib/librosconsole.so;general;/opt/ros/melodic/lib/librosconsole\_log4cxx.so;general;/opt/ros/melodic/lib/librosconsole\_backend\_interface.so;general;/usr/lib/x86\_64-linux-gnu/liblog4cxx.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_regex.so;general;/opt/ros/melodic/lib/libroscpp\_serialization.so;general;/opt/ros/melodic/lib/libxmlrpcpp.so;general;/opt/ros/melodic/lib/librostime.so;general;/opt/ros/melodic/lib/libcpp\_common.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_system.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_thread.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_chrono.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_date\_time.so;general;/usr/lib/x86\_64-linux-gnu/libboost\_atomic.so;general;/usr/lib/x86\_64-linux-gnu/libpthread.so;general;/usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4;general;ur\_client\_library::urcl;

//The directory containing a CMake configuration file for urdf.

urdf\_DIR:PATH=/opt/ros/melodic/share/urdf/cmake

//The directory containing a CMake configuration file for visualization\_msgs.

visualization\_msgs\_DIR:PATH=/opt/ros/melodic/share/visualization\_msgs/cmake

//The directory containing a CMake configuration file for xmlrpcpp.

xmlrpcpp\_DIR:PATH=/opt/ros/melodic/share/xmlrpcpp/cmake

//The directory containing a CMake configuration file for yaml-cpp.

yaml-cpp\_DIR:PATH=/usr/lib/x86\_64-linux-gnu/cmake/yaml-cpp

########################

# INTERNAL cache entries

########################

//ADVANCED property for variable: Boost\_DIR

Boost\_DIR-ADVANCED:INTERNAL=1

//ADVANCED property for variable: Boost\_INCLUDE\_DIR

Boost\_INCLUDE\_DIR-ADVANCED:INTERNAL=1

//ADVANCED property for variable: Boost\_LIBRARY\_DIR\_DEBUG

Boost\_LIBRARY\_DIR\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: Boost\_LIBRARY\_DIR\_RELEASE

Boost\_LIBRARY\_DIR\_RELEASE-ADVANCED:INTERNAL=1

//ADVANCED property for variable: Boost\_SYSTEM\_LIBRARY\_DEBUG

Boost\_SYSTEM\_LIBRARY\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: Boost\_SYSTEM\_LIBRARY\_RELEASE

Boost\_SYSTEM\_LIBRARY\_RELEASE-ADVANCED:INTERNAL=1

//catkin environment

CATKIN\_ENV:INTERNAL=/home/rass/Rassul/ur\_ws/build/catkin\_generated/env\_cached.sh

CATKIN\_TEST\_RESULTS\_DIR:INTERNAL=/home/rass/Rassul/ur\_ws/build/test\_results

//ADVANCED property for variable: CMAKE\_AR

CMAKE\_AR-ADVANCED:INTERNAL=1

//This is the directory where this CMakeCache.txt was created

CMAKE\_CACHEFILE\_DIR:INTERNAL=/home/rass/Rassul/ur\_ws/build

//Major version of cmake used to create the current loaded cache

CMAKE\_CACHE\_MAJOR\_VERSION:INTERNAL=3

//Minor version of cmake used to create the current loaded cache

CMAKE\_CACHE\_MINOR\_VERSION:INTERNAL=10

//Patch version of cmake used to create the current loaded cache

CMAKE\_CACHE\_PATCH\_VERSION:INTERNAL=2

//ADVANCED property for variable: CMAKE\_COLOR\_MAKEFILE

CMAKE\_COLOR\_MAKEFILE-ADVANCED:INTERNAL=1

//Path to CMake executable.

CMAKE\_COMMAND:INTERNAL=/usr/bin/cmake

//Path to cpack program executable.

CMAKE\_CPACK\_COMMAND:INTERNAL=/usr/bin/cpack

//Path to ctest program executable.

CMAKE\_CTEST\_COMMAND:INTERNAL=/usr/bin/ctest

//ADVANCED property for variable: CMAKE\_CXX\_COMPILER

CMAKE\_CXX\_COMPILER-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_CXX\_COMPILER\_AR

CMAKE\_CXX\_COMPILER\_AR-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_CXX\_COMPILER\_RANLIB

CMAKE\_CXX\_COMPILER\_RANLIB-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_CXX\_FLAGS

CMAKE\_CXX\_FLAGS-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_CXX\_FLAGS\_DEBUG

CMAKE\_CXX\_FLAGS\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_CXX\_FLAGS\_MINSIZEREL

CMAKE\_CXX\_FLAGS\_MINSIZEREL-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_CXX\_FLAGS\_RELEASE

CMAKE\_CXX\_FLAGS\_RELEASE-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_CXX\_FLAGS\_RELWITHDEBINFO

CMAKE\_CXX\_FLAGS\_RELWITHDEBINFO-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_COMPILER

CMAKE\_C\_COMPILER-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_COMPILER\_AR

CMAKE\_C\_COMPILER\_AR-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_COMPILER\_RANLIB

CMAKE\_C\_COMPILER\_RANLIB-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_FLAGS

CMAKE\_C\_FLAGS-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_FLAGS\_DEBUG

CMAKE\_C\_FLAGS\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_FLAGS\_MINSIZEREL

CMAKE\_C\_FLAGS\_MINSIZEREL-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_FLAGS\_RELEASE

CMAKE\_C\_FLAGS\_RELEASE-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_C\_FLAGS\_RELWITHDEBINFO

CMAKE\_C\_FLAGS\_RELWITHDEBINFO-ADVANCED:INTERNAL=1

//Executable file format

CMAKE\_EXECUTABLE\_FORMAT:INTERNAL=ELF

//ADVANCED property for variable: CMAKE\_EXE\_LINKER\_FLAGS

CMAKE\_EXE\_LINKER\_FLAGS-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_EXE\_LINKER\_FLAGS\_DEBUG

CMAKE\_EXE\_LINKER\_FLAGS\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_EXE\_LINKER\_FLAGS\_MINSIZEREL

CMAKE\_EXE\_LINKER\_FLAGS\_MINSIZEREL-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_EXE\_LINKER\_FLAGS\_RELEASE

CMAKE\_EXE\_LINKER\_FLAGS\_RELEASE-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_EXE\_LINKER\_FLAGS\_RELWITHDEBINFO

CMAKE\_EXE\_LINKER\_FLAGS\_RELWITHDEBINFO-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_EXPORT\_COMPILE\_COMMANDS

CMAKE\_EXPORT\_COMPILE\_COMMANDS-ADVANCED:INTERNAL=1

//Name of external makefile project generator.

CMAKE\_EXTRA\_GENERATOR:INTERNAL=

//Name of generator.

CMAKE\_GENERATOR:INTERNAL=Unix Makefiles

//Name of generator platform.

CMAKE\_GENERATOR\_PLATFORM:INTERNAL=

//Name of generator toolset.

CMAKE\_GENERATOR\_TOOLSET:INTERNAL=

//Have symbol pthread\_create

CMAKE\_HAVE\_LIBC\_CREATE:INTERNAL=

//Have library pthreads

CMAKE\_HAVE\_PTHREADS\_CREATE:INTERNAL=

//Have library pthread

CMAKE\_HAVE\_PTHREAD\_CREATE:INTERNAL=1

//Have include pthread.h

CMAKE\_HAVE\_PTHREAD\_H:INTERNAL=1

//Source directory with the top level CMakeLists.txt file for this

// project

CMAKE\_HOME\_DIRECTORY:INTERNAL=/home/rass/Rassul/ur\_ws/src

//Install .so files without execute permission.

CMAKE\_INSTALL\_SO\_NO\_EXE:INTERNAL=1

//ADVANCED property for variable: CMAKE\_LINKER

CMAKE\_LINKER-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_MAKE\_PROGRAM

CMAKE\_MAKE\_PROGRAM-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_MODULE\_LINKER\_FLAGS

CMAKE\_MODULE\_LINKER\_FLAGS-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_MODULE\_LINKER\_FLAGS\_DEBUG

CMAKE\_MODULE\_LINKER\_FLAGS\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_MODULE\_LINKER\_FLAGS\_MINSIZEREL

CMAKE\_MODULE\_LINKER\_FLAGS\_MINSIZEREL-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_MODULE\_LINKER\_FLAGS\_RELEASE

CMAKE\_MODULE\_LINKER\_FLAGS\_RELEASE-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_MODULE\_LINKER\_FLAGS\_RELWITHDEBINFO

CMAKE\_MODULE\_LINKER\_FLAGS\_RELWITHDEBINFO-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_NM

CMAKE\_NM-ADVANCED:INTERNAL=1

//number of local generators

CMAKE\_NUMBER\_OF\_MAKEFILES:INTERNAL=14

//ADVANCED property for variable: CMAKE\_OBJCOPY

CMAKE\_OBJCOPY-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_OBJDUMP

CMAKE\_OBJDUMP-ADVANCED:INTERNAL=1

//Platform information initialized

CMAKE\_PLATFORM\_INFO\_INITIALIZED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_RANLIB

CMAKE\_RANLIB-ADVANCED:INTERNAL=1

//Path to CMake installation.

CMAKE\_ROOT:INTERNAL=/usr/share/cmake-3.10

//ADVANCED property for variable: CMAKE\_SHARED\_LINKER\_FLAGS

CMAKE\_SHARED\_LINKER\_FLAGS-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_SHARED\_LINKER\_FLAGS\_DEBUG

CMAKE\_SHARED\_LINKER\_FLAGS\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_SHARED\_LINKER\_FLAGS\_MINSIZEREL

CMAKE\_SHARED\_LINKER\_FLAGS\_MINSIZEREL-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_SHARED\_LINKER\_FLAGS\_RELEASE

CMAKE\_SHARED\_LINKER\_FLAGS\_RELEASE-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_SHARED\_LINKER\_FLAGS\_RELWITHDEBINFO

CMAKE\_SHARED\_LINKER\_FLAGS\_RELWITHDEBINFO-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_SKIP\_INSTALL\_RPATH

CMAKE\_SKIP\_INSTALL\_RPATH-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_SKIP\_RPATH

CMAKE\_SKIP\_RPATH-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_STATIC\_LINKER\_FLAGS

CMAKE\_STATIC\_LINKER\_FLAGS-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_STATIC\_LINKER\_FLAGS\_DEBUG

CMAKE\_STATIC\_LINKER\_FLAGS\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_STATIC\_LINKER\_FLAGS\_MINSIZEREL

CMAKE\_STATIC\_LINKER\_FLAGS\_MINSIZEREL-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_STATIC\_LINKER\_FLAGS\_RELEASE

CMAKE\_STATIC\_LINKER\_FLAGS\_RELEASE-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_STATIC\_LINKER\_FLAGS\_RELWITHDEBINFO

CMAKE\_STATIC\_LINKER\_FLAGS\_RELWITHDEBINFO-ADVANCED:INTERNAL=1

//ADVANCED property for variable: CMAKE\_STRIP

CMAKE\_STRIP-ADVANCED:INTERNAL=1

//uname command

CMAKE\_UNAME:INTERNAL=/bin/uname

//ADVANCED property for variable: CMAKE\_VERBOSE\_MAKEFILE

CMAKE\_VERBOSE\_MAKEFILE-ADVANCED:INTERNAL=1

//Details about finding PythonInterp

FIND\_PACKAGE\_MESSAGE\_DETAILS\_PythonInterp:INTERNAL=[/usr/bin/python2][v2.7.17()]

//Details about finding Threads

FIND\_PACKAGE\_MESSAGE\_DETAILS\_Threads:INTERNAL=[TRUE][v()]

GMOCK\_FROM\_SOURCE\_FOUND:INTERNAL=TRUE

GMOCK\_FROM\_SOURCE\_INCLUDE\_DIRS:INTERNAL=/usr/include

GMOCK\_FROM\_SOURCE\_LIBRARIES:INTERNAL=gmock

GMOCK\_FROM\_SOURCE\_LIBRARY\_DIRS:INTERNAL=/home/rass/Rassul/ur\_ws/build/gmock

GMOCK\_FROM\_SOURCE\_MAIN\_LIBRARIES:INTERNAL=gmock\_main

GTEST\_FROM\_SOURCE\_FOUND:INTERNAL=TRUE

GTEST\_FROM\_SOURCE\_INCLUDE\_DIRS:INTERNAL=/usr/include

GTEST\_FROM\_SOURCE\_LIBRARIES:INTERNAL=gtest

GTEST\_FROM\_SOURCE\_LIBRARY\_DIRS:INTERNAL=/home/rass/Rassul/ur\_ws/build/gtest

GTEST\_FROM\_SOURCE\_MAIN\_LIBRARIES:INTERNAL=gtest\_main

//ADVANCED property for variable: GTEST\_INCLUDE\_DIR

GTEST\_INCLUDE\_DIR-ADVANCED:INTERNAL=1

//ADVANCED property for variable: GTEST\_LIBRARY

GTEST\_LIBRARY-ADVANCED:INTERNAL=1

//ADVANCED property for variable: GTEST\_LIBRARY\_DEBUG

GTEST\_LIBRARY\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: GTEST\_MAIN\_LIBRARY

GTEST\_MAIN\_LIBRARY-ADVANCED:INTERNAL=1

//ADVANCED property for variable: GTEST\_MAIN\_LIBRARY\_DEBUG

GTEST\_MAIN\_LIBRARY\_DEBUG-ADVANCED:INTERNAL=1

//ADVANCED property for variable: PYTHON\_EXECUTABLE

PYTHON\_EXECUTABLE-ADVANCED:INTERNAL=1

//This needs to be in PYTHONPATH when 'setup.py install' is called.

// And it needs to match. But setuptools won't tell us where

// it will install things.

PYTHON\_INSTALL\_DIR:INTERNAL=lib/python2.7/dist-packages

//Components requested for this build tree.

\_Boost\_COMPONENTS\_SEARCHED:INTERNAL=system

//Last used Boost\_INCLUDE\_DIR value.

\_Boost\_INCLUDE\_DIR\_LAST:INTERNAL=/usr/include

//Last used Boost\_LIBRARY\_DIR\_DEBUG value.

\_Boost\_LIBRARY\_DIR\_DEBUG\_LAST:INTERNAL=/usr/lib/x86\_64-linux-gnu

//Last used Boost\_LIBRARY\_DIR\_RELEASE value.

\_Boost\_LIBRARY\_DIR\_RELEASE\_LAST:INTERNAL=/usr/lib/x86\_64-linux-gnu

//Last used Boost\_NAMESPACE value.

\_Boost\_NAMESPACE\_LAST:INTERNAL=boost

//Last used Boost\_USE\_MULTITHREADED value.

\_Boost\_USE\_MULTITHREADED\_LAST:INTERNAL=TRUE