/usr/bin/c++ -O2 -g -DNDEBUG -rdynamic CMakeFiles/robot\_state\_helper.dir/src/robot\_state\_helper.cpp.o CMakeFiles/robot\_state\_helper.dir/src/robot\_state\_helper\_node.cpp.o -o /home/rass/Rassul/ur\_ws/devel/lib/ur\_robot\_driver/robot\_state\_helper -Wl,-rpath,/opt/ros/melodic/lib: /opt/ros/melodic/lib/libscaled\_joint\_trajectory\_controller.so /opt/ros/melodic/lib/libjoint\_trajectory\_controller.so /opt/ros/melodic/lib/libcontrol\_toolbox.so /opt/ros/melodic/lib/libspeed\_scaling\_state\_controller.so /opt/ros/melodic/lib/librealtime\_tools.so /opt/ros/melodic/lib/libtf.so /opt/ros/melodic/lib/liborocos-kdl.so /opt/ros/melodic/lib/libtf2\_ros.so /opt/ros/melodic/lib/libmessage\_filters.so /opt/ros/melodic/lib/libtf2.so /opt/ros/melodic/lib/libpass\_through\_controllers.so /opt/ros/melodic/lib/libactionlib.so /opt/ros/melodic/lib/libcontroller\_manager.so /opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so /opt/ros/melodic/lib/libkdl\_parser.so /opt/ros/melodic/lib/liborocos-kdl.so.1.4.0 /opt/ros/melodic/lib/liburdf.so -lurdfdom\_sensor -lurdfdom\_model\_state -lurdfdom\_model -lurdfdom\_world -ltinyxml /opt/ros/melodic/lib/libclass\_loader.so -lPocoFoundation -ldl /opt/ros/melodic/lib/libroslib.so /opt/ros/melodic/lib/librospack.so -lpython2.7 -lboost\_program\_options -ltinyxml2 /opt/ros/melodic/lib/librosconsole\_bridge.so /opt/ros/melodic/lib/libroscpp.so -lboost\_filesystem /opt/ros/melodic/lib/librosconsole.so /opt/ros/melodic/lib/librosconsole\_log4cxx.so /opt/ros/melodic/lib/librosconsole\_backend\_interface.so -llog4cxx -lboost\_regex /opt/ros/melodic/lib/libroscpp\_serialization.so /opt/ros/melodic/lib/libxmlrpcpp.so /opt/ros/melodic/lib/librostime.so /opt/ros/melodic/lib/libcpp\_common.so -lboost\_system -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4 /opt/ros/melodic/lib/liburcl.so -lpthread