;; Auto-generated. Do not edit!

(when (boundp 'ur\_dashboard\_msgs::RobotMode)

(if (not (find-package "UR\_DASHBOARD\_MSGS"))

(make-package "UR\_DASHBOARD\_MSGS"))

(shadow 'RobotMode (find-package "UR\_DASHBOARD\_MSGS")))

(unless (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE")

(make-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(in-package "ROS")

;;//! \htmlinclude RobotMode.msg.html

(intern "\*NO\_CONTROLLER\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*NO\_CONTROLLER\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*NO\_CONTROLLER\* -1)

(intern "\*DISCONNECTED\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*DISCONNECTED\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*DISCONNECTED\* 0)

(intern "\*CONFIRM\_SAFETY\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*CONFIRM\_SAFETY\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*CONFIRM\_SAFETY\* 1)

(intern "\*BOOTING\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*BOOTING\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*BOOTING\* 2)

(intern "\*POWER\_OFF\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*POWER\_OFF\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*POWER\_OFF\* 3)

(intern "\*POWER\_ON\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*POWER\_ON\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*POWER\_ON\* 4)

(intern "\*IDLE\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*IDLE\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*IDLE\* 5)

(intern "\*BACKDRIVE\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*BACKDRIVE\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*BACKDRIVE\* 6)

(intern "\*RUNNING\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*RUNNING\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*RUNNING\* 7)

(intern "\*UPDATING\_FIRMWARE\*" (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(shadow '\*UPDATING\_FIRMWARE\* (find-package "UR\_DASHBOARD\_MSGS::ROBOTMODE"))

(defconstant ur\_dashboard\_msgs::RobotMode::\*UPDATING\_FIRMWARE\* 8)

(defclass ur\_dashboard\_msgs::RobotMode

:super ros::object

:slots (\_mode ))

(defmethod ur\_dashboard\_msgs::RobotMode

(:init

(&key

((:mode \_\_mode) 0)

)

(send-super :init)

(setq \_mode (round \_\_mode))

self)

(:mode

(&optional \_\_mode)

(if \_\_mode (setq \_mode \_\_mode)) \_mode)

(:serialization-length

()

(+

;; int8 \_mode

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int8 \_mode

(write-byte \_mode s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int8 \_mode

(setq \_mode (sys::peek buf ptr- :char)) (incf ptr- 1)

(if (> \_mode 127) (setq \_mode (- \_mode 256)))

;;

self)

)

(setf (get ur\_dashboard\_msgs::RobotMode :md5sum-) "73b72d58742c4889c47118411b03a3b4")

(setf (get ur\_dashboard\_msgs::RobotMode :datatype-) "ur\_dashboard\_msgs/RobotMode")

(setf (get ur\_dashboard\_msgs::RobotMode :definition-)

"int8 NO\_CONTROLLER=-1

int8 DISCONNECTED=0

int8 CONFIRM\_SAFETY=1

int8 BOOTING=2

int8 POWER\_OFF=3

int8 POWER\_ON=4

int8 IDLE=5

int8 BACKDRIVE=6

int8 RUNNING=7

int8 UPDATING\_FIRMWARE=8

int8 mode

")

(provide :ur\_dashboard\_msgs/RobotMode "73b72d58742c4889c47118411b03a3b4")