;; Auto-generated. Do not edit!

(when (boundp 'ur\_dashboard\_msgs::SetModeFeedback)

(if (not (find-package "UR\_DASHBOARD\_MSGS"))

(make-package "UR\_DASHBOARD\_MSGS"))

(shadow 'SetModeFeedback (find-package "UR\_DASHBOARD\_MSGS")))

(unless (find-package "UR\_DASHBOARD\_MSGS::SETMODEFEEDBACK")

(make-package "UR\_DASHBOARD\_MSGS::SETMODEFEEDBACK"))

(in-package "ROS")

;;//! \htmlinclude SetModeFeedback.msg.html

(defclass ur\_dashboard\_msgs::SetModeFeedback

:super ros::object

:slots (\_current\_robot\_mode \_current\_safety\_mode ))

(defmethod ur\_dashboard\_msgs::SetModeFeedback

(:init

(&key

((:current\_robot\_mode \_\_current\_robot\_mode) 0)

((:current\_safety\_mode \_\_current\_safety\_mode) 0)

)

(send-super :init)

(setq \_current\_robot\_mode (round \_\_current\_robot\_mode))

(setq \_current\_safety\_mode (round \_\_current\_safety\_mode))

self)

(:current\_robot\_mode

(&optional \_\_current\_robot\_mode)

(if \_\_current\_robot\_mode (setq \_current\_robot\_mode \_\_current\_robot\_mode)) \_current\_robot\_mode)

(:current\_safety\_mode

(&optional \_\_current\_safety\_mode)

(if \_\_current\_safety\_mode (setq \_current\_safety\_mode \_\_current\_safety\_mode)) \_current\_safety\_mode)

(:serialization-length

()

(+

;; int8 \_current\_robot\_mode

1

;; int8 \_current\_safety\_mode

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int8 \_current\_robot\_mode

(write-byte \_current\_robot\_mode s)

;; int8 \_current\_safety\_mode

(write-byte \_current\_safety\_mode s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int8 \_current\_robot\_mode

(setq \_current\_robot\_mode (sys::peek buf ptr- :char)) (incf ptr- 1)

(if (> \_current\_robot\_mode 127) (setq \_current\_robot\_mode (- \_current\_robot\_mode 256)))

;; int8 \_current\_safety\_mode

(setq \_current\_safety\_mode (sys::peek buf ptr- :char)) (incf ptr- 1)

(if (> \_current\_safety\_mode 127) (setq \_current\_safety\_mode (- \_current\_safety\_mode 256)))

;;

self)

)

(setf (get ur\_dashboard\_msgs::SetModeFeedback :md5sum-) "d48caaba06f88e6be0ba90bf29940534")

(setf (get ur\_dashboard\_msgs::SetModeFeedback :datatype-) "ur\_dashboard\_msgs/SetModeFeedback")

(setf (get ur\_dashboard\_msgs::SetModeFeedback :definition-)

"# ====== DO NOT MODIFY! AUTOGENERATED FROM AN ACTION DEFINITION ======

# feedback

int8 current\_robot\_mode

int8 current\_safety\_mode

")

(provide :ur\_dashboard\_msgs/SetModeFeedback "d48caaba06f88e6be0ba90bf29940534")