;; Auto-generated. Do not edit!

(when (boundp 'ur\_dashboard\_msgs::GetRobotMode)

(if (not (find-package "UR\_DASHBOARD\_MSGS"))

(make-package "UR\_DASHBOARD\_MSGS"))

(shadow 'GetRobotMode (find-package "UR\_DASHBOARD\_MSGS")))

(unless (find-package "UR\_DASHBOARD\_MSGS::GETROBOTMODE")

(make-package "UR\_DASHBOARD\_MSGS::GETROBOTMODE"))

(unless (find-package "UR\_DASHBOARD\_MSGS::GETROBOTMODEREQUEST")

(make-package "UR\_DASHBOARD\_MSGS::GETROBOTMODEREQUEST"))

(unless (find-package "UR\_DASHBOARD\_MSGS::GETROBOTMODERESPONSE")

(make-package "UR\_DASHBOARD\_MSGS::GETROBOTMODERESPONSE"))

(in-package "ROS")

(defclass ur\_dashboard\_msgs::GetRobotModeRequest

:super ros::object

:slots ())

(defmethod ur\_dashboard\_msgs::GetRobotModeRequest

(:init

(&key

)

(send-super :init)

self)

(:serialization-length

()

(+

0

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;;

self)

)

(defclass ur\_dashboard\_msgs::GetRobotModeResponse

:super ros::object

:slots (\_robot\_mode \_answer \_success ))

(defmethod ur\_dashboard\_msgs::GetRobotModeResponse

(:init

(&key

((:robot\_mode \_\_robot\_mode) (instance ur\_dashboard\_msgs::RobotMode :init))

((:answer \_\_answer) "")

((:success \_\_success) nil)

)

(send-super :init)

(setq \_robot\_mode \_\_robot\_mode)

(setq \_answer (string \_\_answer))

(setq \_success \_\_success)

self)

(:robot\_mode

(&rest \_\_robot\_mode)

(if (keywordp (car \_\_robot\_mode))

(send\* \_robot\_mode \_\_robot\_mode)

(progn

(if \_\_robot\_mode (setq \_robot\_mode (car \_\_robot\_mode)))

\_robot\_mode)))

(:answer

(&optional \_\_answer)

(if \_\_answer (setq \_answer \_\_answer)) \_answer)

(:success

(&optional \_\_success)

(if \_\_success (setq \_success \_\_success)) \_success)

(:serialization-length

()

(+

;; ur\_dashboard\_msgs/RobotMode \_robot\_mode

(send \_robot\_mode :serialization-length)

;; string \_answer

4 (length \_answer)

;; bool \_success

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; ur\_dashboard\_msgs/RobotMode \_robot\_mode

(send \_robot\_mode :serialize s)

;; string \_answer

(write-long (length \_answer) s) (princ \_answer s)

;; bool \_success

(if \_success (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; ur\_dashboard\_msgs/RobotMode \_robot\_mode

(send \_robot\_mode :deserialize buf ptr-) (incf ptr- (send \_robot\_mode :serialization-length))

;; string \_answer

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_answer (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;; bool \_success

(setq \_success (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass ur\_dashboard\_msgs::GetRobotMode

:super ros::object

:slots ())

(setf (get ur\_dashboard\_msgs::GetRobotMode :md5sum-) "ef94c03da2e53bb8c576236bb003fe8a")

(setf (get ur\_dashboard\_msgs::GetRobotMode :datatype-) "ur\_dashboard\_msgs/GetRobotMode")

(setf (get ur\_dashboard\_msgs::GetRobotMode :request) ur\_dashboard\_msgs::GetRobotModeRequest)

(setf (get ur\_dashboard\_msgs::GetRobotMode :response) ur\_dashboard\_msgs::GetRobotModeResponse)

(defmethod ur\_dashboard\_msgs::GetRobotModeRequest

(:response () (instance ur\_dashboard\_msgs::GetRobotModeResponse :init)))

(setf (get ur\_dashboard\_msgs::GetRobotModeRequest :md5sum-) "ef94c03da2e53bb8c576236bb003fe8a")

(setf (get ur\_dashboard\_msgs::GetRobotModeRequest :datatype-) "ur\_dashboard\_msgs/GetRobotModeRequest")

(setf (get ur\_dashboard\_msgs::GetRobotModeRequest :definition-)

"---

RobotMode robot\_mode

string answer

bool success

================================================================================

MSG: ur\_dashboard\_msgs/RobotMode

int8 NO\_CONTROLLER=-1

int8 DISCONNECTED=0

int8 CONFIRM\_SAFETY=1

int8 BOOTING=2

int8 POWER\_OFF=3

int8 POWER\_ON=4

int8 IDLE=5

int8 BACKDRIVE=6

int8 RUNNING=7

int8 UPDATING\_FIRMWARE=8

int8 mode

")

(setf (get ur\_dashboard\_msgs::GetRobotModeResponse :md5sum-) "ef94c03da2e53bb8c576236bb003fe8a")

(setf (get ur\_dashboard\_msgs::GetRobotModeResponse :datatype-) "ur\_dashboard\_msgs/GetRobotModeResponse")

(setf (get ur\_dashboard\_msgs::GetRobotModeResponse :definition-)

"---

RobotMode robot\_mode

string answer

bool success

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int8 UPDATING\_FIRMWARE=8

int8 mode

")

(provide :ur\_dashboard\_msgs/GetRobotMode "ef94c03da2e53bb8c576236bb003fe8a")