;; Auto-generated. Do not edit!

(when (boundp 'ur\_dashboard\_msgs::IsInRemoteControl)

(if (not (find-package "UR\_DASHBOARD\_MSGS"))

(make-package "UR\_DASHBOARD\_MSGS"))

(shadow 'IsInRemoteControl (find-package "UR\_DASHBOARD\_MSGS")))

(unless (find-package "UR\_DASHBOARD\_MSGS::ISINREMOTECONTROL")

(make-package "UR\_DASHBOARD\_MSGS::ISINREMOTECONTROL"))

(unless (find-package "UR\_DASHBOARD\_MSGS::ISINREMOTECONTROLREQUEST")

(make-package "UR\_DASHBOARD\_MSGS::ISINREMOTECONTROLREQUEST"))

(unless (find-package "UR\_DASHBOARD\_MSGS::ISINREMOTECONTROLRESPONSE")

(make-package "UR\_DASHBOARD\_MSGS::ISINREMOTECONTROLRESPONSE"))

(in-package "ROS")

(defclass ur\_dashboard\_msgs::IsInRemoteControlRequest

:super ros::object

:slots ())

(defmethod ur\_dashboard\_msgs::IsInRemoteControlRequest

(:init

(&key

)

(send-super :init)

self)

(:serialization-length

()

(+

0

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;;

self)

)

(defclass ur\_dashboard\_msgs::IsInRemoteControlResponse

:super ros::object

:slots (\_answer \_in\_remote\_control \_success ))

(defmethod ur\_dashboard\_msgs::IsInRemoteControlResponse

(:init

(&key

((:answer \_\_answer) "")

((:in\_remote\_control \_\_in\_remote\_control) nil)

((:success \_\_success) nil)

)

(send-super :init)

(setq \_answer (string \_\_answer))

(setq \_in\_remote\_control \_\_in\_remote\_control)

(setq \_success \_\_success)

self)

(:answer

(&optional \_\_answer)

(if \_\_answer (setq \_answer \_\_answer)) \_answer)

(:in\_remote\_control

(&optional \_\_in\_remote\_control)

(if \_\_in\_remote\_control (setq \_in\_remote\_control \_\_in\_remote\_control)) \_in\_remote\_control)

(:success

(&optional \_\_success)

(if \_\_success (setq \_success \_\_success)) \_success)

(:serialization-length

()

(+

;; string \_answer

4 (length \_answer)

;; bool \_in\_remote\_control

1

;; bool \_success

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; string \_answer

(write-long (length \_answer) s) (princ \_answer s)

;; bool \_in\_remote\_control

(if \_in\_remote\_control (write-byte -1 s) (write-byte 0 s))

;; bool \_success

(if \_success (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; string \_answer

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_answer (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;; bool \_in\_remote\_control

(setq \_in\_remote\_control (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;; bool \_success

(setq \_success (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass ur\_dashboard\_msgs::IsInRemoteControl

:super ros::object

:slots ())

(setf (get ur\_dashboard\_msgs::IsInRemoteControl :md5sum-) "032fdd19f824627299e7ba024ba3c0bc")

(setf (get ur\_dashboard\_msgs::IsInRemoteControl :datatype-) "ur\_dashboard\_msgs/IsInRemoteControl")

(setf (get ur\_dashboard\_msgs::IsInRemoteControl :request) ur\_dashboard\_msgs::IsInRemoteControlRequest)

(setf (get ur\_dashboard\_msgs::IsInRemoteControl :response) ur\_dashboard\_msgs::IsInRemoteControlResponse)

(defmethod ur\_dashboard\_msgs::IsInRemoteControlRequest

(:response () (instance ur\_dashboard\_msgs::IsInRemoteControlResponse :init)))

(setf (get ur\_dashboard\_msgs::IsInRemoteControlRequest :md5sum-) "032fdd19f824627299e7ba024ba3c0bc")

(setf (get ur\_dashboard\_msgs::IsInRemoteControlRequest :datatype-) "ur\_dashboard\_msgs/IsInRemoteControlRequest")

(setf (get ur\_dashboard\_msgs::IsInRemoteControlRequest :definition-)

"---

string answer

bool in\_remote\_control # is the robot currently in remote control mode?

bool success # Did the dashboard server call succeed?

")

(setf (get ur\_dashboard\_msgs::IsInRemoteControlResponse :md5sum-) "032fdd19f824627299e7ba024ba3c0bc")

(setf (get ur\_dashboard\_msgs::IsInRemoteControlResponse :datatype-) "ur\_dashboard\_msgs/IsInRemoteControlResponse")

(setf (get ur\_dashboard\_msgs::IsInRemoteControlResponse :definition-)

"---

string answer

bool in\_remote\_control # is the robot currently in remote control mode?

bool success # Did the dashboard server call succeed?

")

(provide :ur\_dashboard\_msgs/IsInRemoteControl "032fdd19f824627299e7ba024ba3c0bc")