Jnaive-softmax (
$$^{V}C, O, U$$
)

$$= -log P(Outside = O|(enter = C))$$

$$= -log \frac{exp(u_{\bullet}^{T}v_{c})}{\sum_{v \in V_{O}(Gh)} exp(u_{\bullet}^{T}v_{c})}$$

$$= -U_{\bullet}^{T}v_{c} + log \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})u_{\bullet} = -U_{\bullet} + \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})u_{\bullet} = -U_{\bullet} + \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})u_{\bullet} = -U_{\bullet} + \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})$$

$$= -U_{\bullet} + \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})$$

$$= -U_{\bullet} + U_{\bullet} exp(u_{\bullet}^{T}v_{c})$$

$$= -U_{\bullet} + U_{\bullet} exp(u_{\bullet}^{T}v_{c})$$

$$= -log \frac{exp(u_{\bullet}^{T}v_{c})}{\sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})}$$

$$= -U_{\bullet}^{T}v_{c} + log \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})$$

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$$= -U_{\bullet}^{T}v_{c} + log \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} exp(u_{\bullet}^{T}v_{c})$$

$$= -U_{\bullet}^{T}v_{c} + log \sum_{v \in V_{O}(U_{\bullet}^{T}v_{c})} ex$$

$$= -V_{c} + \sum_{w} exp[u_{x}^{T}v_{c}] \quad \sigma^{Tw}$$

$$= -V_{c} + P(C|C) - V_{c}$$

$$= (\hat{y} - y) V_{c}$$

$$= (\hat{y} - y) V_{c}$$

$$= \frac{\partial J}{\partial u_{w}} = -\frac{\partial}{\partial u_{w}} (u_{x}^{T}v_{c}) + \frac{\partial}{\partial u_{w}} (\log \sum_{w} exp(u_{w}^{T}v_{c}))$$

$$= \frac{(u_{x}^{T}v_{c})}{\sum_{w} exp[u_{w}^{T}v_{c}]} - \frac{\partial}{\partial u_{w}} (u_{x}^{T}v_{c}) + 0$$

$$= V_{c} \cdot P(c|C)$$

$$= \hat{y} V_{c}$$

$$\frac{\partial J}{\partial u_{w}} = (\hat{y} - y) V_{c} \quad (u_{w} = cutsite word)$$

$$O(x) = \frac{1}{1 + e^{-x}} = \frac{e^{x}}{e^{x} + 1}$$

$$= (-1) \frac{(1 + e^{-x})^{-2}}{e^{x}} - (-e^{-x})$$

$$= \frac{1}{(1 + e^{-x})^{-2}} - \frac{1}{(1 + e^{-x})} \times \frac{e^{x}}{(1 + e^{-x})}$$

$$= \frac{1}{1 + e^{-x}} \times \left(1 - \frac{1}{1 + e^{-x}}\right)$$

$$J_{\text{neg-sample}}\left(V_{c},Q,U\right) = -leg\left(O\left(Q_{c}^{T}V_{c}\right)\right) - \sum_{k=1}^{K} leg\left(O\left(-Q_{k}^{T}V_{c}\right)\right)$$
 f

$$O(\cdot) = Sigmaid - function$$

$$I) \frac{\partial}{\partial V_{c}} J = -\frac{1}{\delta(u_{k}^{T}v_{c})} \cdot \frac{\partial}{\partial V_{c}} \delta(y_{k}^{T}v_{c})$$

$$= -\frac{1}{\delta(u_{k}^{T}v_{c})} \cdot \delta(u_{k}^{T}v_{c}) \cdot (1 - \delta(u_{k}^{T}v_{c})) \cdot \frac{\partial}{\partial V_{c}} (u_{k}^{T}v_{c})$$

$$= -\frac{1}{\delta(u_{k}^{T}v_{c})} \cdot \delta(u_{k}^{T}v_{c}) \cdot (1 - \delta(u_{k}^{T}v_{c})) \cdot \frac{\partial}{\partial V_{c}} (u_{k}^{T}v_{c})$$

$$= -\frac{1}{\delta(u_{k}^{T}v_{c})} \cdot \delta(u_{k}^{T}v_{c}) \cdot (1 - \delta(u_{k}^{T}v_{c})) \cdot \frac{\partial}{\partial V_{c}} (u_{k}^{T}v_{c})$$

$$= -\frac{1}{\delta(u_{k}^{T}v_{c})} \cdot \frac{\partial}{\partial V_{c}} \cdot \frac{\partial}{\partial V_$$

7 (111)

$$= -\frac{1}{6(u_{s}^{\tau}v_{c})} - 6(u_{s}^{\tau}v_{c}) \left(1 - 6(u_{s}^{\tau}v_{c})\right) - \frac{1}{3v_{0}} \left[v_{0}^{\tau}v_{c}\right]$$

$$= V_{c} \left(6(u_{s}^{\tau}v_{c}) - 1\right)$$

$$= V_{c} \left(6(u_{s}^{\tau}v_{c}) - 1\right)$$

$$= -\frac{1}{8v_{0}} - \frac{1}{6(u_{s}^{\tau}v_{c})} - \frac{1}{9v_{0}} \left(u_{s}^{\tau}v_{c}\right) - \frac{1}{9v_{0}} \left(u_$$

$$J_{\text{Neg-Sample}}\left(V_{c}, o, V\right) = -lng\left(\delta\left(u_{o}^{\dagger} V_{c}\right)\right) - \sum_{k=1}^{K} \left(\log\left(\delta\left(-u_{k}^{\dagger} V_{c}\right)\right)\right)$$

$$\frac{\partial J}{\partial u_{k}} = -\frac{1}{6\left(u_{o}^{\dagger} V_{c}\right)} - \frac{\partial}{\partial u_{k}} \delta\left(u_{o}^{\dagger} V_{c}\right) - \sum_{k=1}^{K} \frac{1}{6\left(-u_{k}^{\dagger} V_{c}\right)} \cdot \frac{\partial}{\partial V_{c}} \delta\left(-u_{k}^{\dagger} V_{c}\right)$$

$$\frac{\partial J}{\partial u_{k}} = -\frac{k}{2} \frac{1}{6\left(-u_{k}^{\dagger} V_{c}\right)} - \frac{\partial}{\partial V_{c}} \delta\left(-u_{k}^{\dagger} V_{c}\right) \cdot \frac{\partial}{\partial u_{k}} \left(-u_{k}^{\dagger} V_{c}\right)$$

$$= -\frac{k}{2} \frac{1}{6\left(-u_{k}^{\dagger} V_{c}\right)} \cdot \delta\left(-u_{k}^{\dagger} V_{c}\right) \cdot \left(1 - \delta\left(-u_{k}^{\dagger} V_{c}\right) \cdot \frac{\partial}{\partial u_{k}} \left(-u_{k}^{\dagger} V_{c}\right) \cdot \frac{\partial}{\partial u_{k}} \left(-u_{k}^{\dagger} V_{c}\right)$$

$$= -\frac{k}{2} \frac{1}{6\left(-u_{k}^{\dagger} V_{c}\right)} \cdot \left(1 - \delta\left(-u_{k}^{\dagger} V_{c}\right) \cdot V_{c}\right)$$

$$J_{SKP-gYam} \left(V_{C}, W_{t-m}, W_{t+m}, V\right)$$

$$= \sum_{m \leq j \leq m} J\left(V_{c}, W_{t+j}, V\right)$$

$$J_{fc} = \frac{\partial}{\partial U} = \frac{\partial}{\partial V_{c}} \sum_{m \leq j \leq m} J\left(V_{c}, W_{t+j}, V\right)$$

$$iii) \frac{\partial J}{\partial V_{c}} = \frac{\partial}{\partial V_{c}} \sum_{m \leq j \leq m} J\left(V_{c}, W_{t+j}, V\right)$$

$$J_{fa} = \frac{\partial}{\partial V_{c}} \sum_{m \leq j \leq m} J\left(V_{c}, W_{t+j}, V\right)$$

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Az

 (α)

i) m = B, m + (1-B,) D D J minibatch (Q) orlM, OCB, C1 olz 3 가 결전로 Steps Size It 자아지고 특정구간의 기울기값이 O (winimum) of 77 = 77 HIL H STZ OF = TCH

ii) V = gradiant 2+ Haliett DED-XM/TO OIN THEON gradiant가 른 43 0는 자아기게 되고, 또 CH로 gradiant가 사는 수로 b는 개인 Ch

이 때무에 quatant가 작은 위치에서 떠나게 빚어난다.

ii) Dropent 是 train data = 사色是 站台小沙沿台沿 tram data on the overfrang & onless & ger Chevaluation 45 HMHE RE TOUS HREW FE 47 = 5 701 CF

2-(a)
Root I parsed this sentence correctly

Stack	Buffer	New dependency	transition
[Root]	CI, parked this, sentence		Initial Centiquiation
[Root, I]	[Parsed, this, sentence		s hift
[Root, I, parled]	(orrectly) [this, sentence, correctly]		shift
[Root, parced]		Parsed -> I	Left-arc
Reet, Parsed, this	sentence, correctly		s hift
Root, Parsed, this, soutence	correctly		shift
Rnot, parced	correctly	sentence > this	Left-Arc
Root, Parsed	correctly	Parsed-) Sentence	Right-Arc
Root , Poursed, correctly			Shift
Root,		Parsed-) Correctly	Right-Arc
		Root-) Parsed	Right-AK

-> IN 번의 연산이 된 및