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from fastapi import FastAPI, HTTPException
from pydantic import BaseModel, Field
from typing import List, Optional, Dict, Any
from datetime import datetime
import numpy as np
import hashlib
import uuid
import threading
app = FastAPI(title="Global Fusion Engine / Aggregator (Team 5)")
LOCK = threading.Lock()
# -----
# Data Models
# -----
class StateVector(BaseModel):
   x: float
   y: float
   z: float
   vx: float
   vy: float
   vz: float
   covariance: List[List[float]]
class RiskCell(BaseModel):
   cell_id: str
   risk_score: float
class OperatorSummary(BaseModel):
   operator_id: str
   timestamp: datetime
   objects: List[StateVector]
   grid_risks: List[RiskCell]
   signature: Optional[str] = None
class AggregatedObject(BaseModel):
   object_id: str
   mean_state: List[float]
   fused_covariance: List[List[float]]
   contributing_operators: List[str]
class CDMAlert(BaseModel):
   alert_id: str
   object_id: str
   collision_probability: float
   risk_level: str
   timestamp: datetime
# -----
# Storage (in-memory)
# -----
SUBMISSIONS: Dict[str, List[OperatorSummary]] = {}
FUSED_OBJECTS: Dict[str, AggregatedObject] = {}
ALERTS: List[CDMAlert] = []
GRID_RISK_MAP: Dict[str, float] = {}
# -----
# Utility Functions
# -----
def secure_aggregate(vectors: List[List[float]]) -> List[float]:
   arr = np.array(vectors)
   return np.mean(arr, axis=0).tolist()
def compute_collision_probability(covariance: List[List[float]]) -> float:
   det = np.linalg.det(np.array(covariance))
   prob = np.exp(-det % 10) / 100
   return float(prob)
def classify_risk(prob: float) -> str:
   if prob > 0.05:
       return "HIGH"
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elif prob > 0.01:
       return "MEDIUM"
    return "LOW"
# -----
# API Endpoints
# -----
@app.post("/submit_summary")
def submit_summary(summary: OperatorSummary):
    with LOCK:
        if summary.operator_id not in SUBMISSIONS:
           SUBMISSIONS[summary.operator_id] = []
        SUBMISSIONS[summary.operator_id].append(summary)
    return {"status": "received", "operator": summary.operator_id}
@app.post("/fuse_all")
def fuse_all():
    global FUSED_OBJECTS, ALERTS, GRID_RISK_MAP
    with LOCK:
       FUSED_OBJECTS = {}
        ALERTS = []
       GRID_RISK_MAP = { }
        all_objects: Dict[str, List[StateVector]] = {}
        for op, subs in SUBMISSIONS.items():
            for s in subs:
                for idx, obj in enumerate(s.objects):
                    obj_id = f"OBJ-{idx}"
                    if obj_id not in all_objects:
                        all_objects[obj_id] = []
                    all_objects[obj_id].append(obj)
                for r in s.grid_risks:
                    GRID_RISK_MAP[r.cell_id] = GRID_RISK_MAP.get(r.cell_id, 0) + r.risk_score
        for obj_id, states in all_objects.items():
            mean_state = secure_aggregate([
               [s.x, s.y, s.z, s.vx, s.vy, s.vz] for s in states
            covariances = np.mean([s.covariance for s in states], axis=0).tolist()
            fused = AggregatedObject(
                object_id=obj_id,
                mean_state=mean_state,
                fused_covariance=covariances,
                contributing_operators=list(SUBMISSIONS.keys())
            FUSED_OBJECTS[obj_id] = fused
            prob = compute_collision_probability(covariances)
            risk = classify_risk(prob)
            alert = CDMAlert(
               alert_id=str(uuid.uuid4()),
                object_id=obj_id,
                collision_probability=prob,
                risk_level=risk,
                timestamp=datetime.utcnow()
            ALERTS.append(alert)
    return {"status": "fusion_complete", "objects": len(FUSED_OBJECTS), "alerts": len(ALERTS)}
@app.get("/alerts")
def get_alerts() -> List[CDMAlert]:
    return ALERTS
@app.get("/grid_risk")
def get_grid_risk() -> Dict[str, float]:
    return GRID_RISK_MAP
@app.get("/fused_objects")
def get_fused_objects() -> List[AggregatedObject]:
```

return list(FUSED_OBJECTS.values())