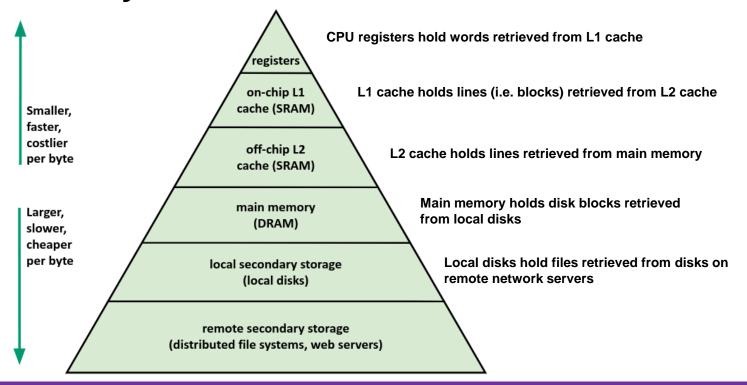
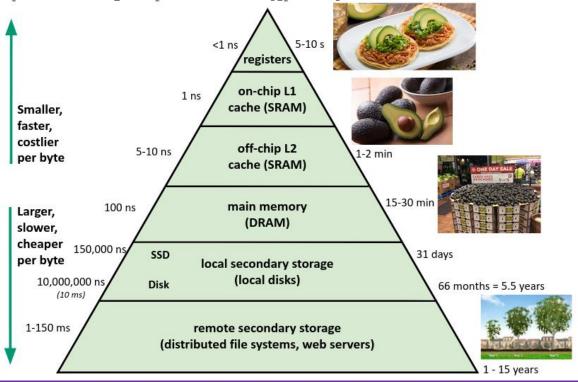
# Caches II

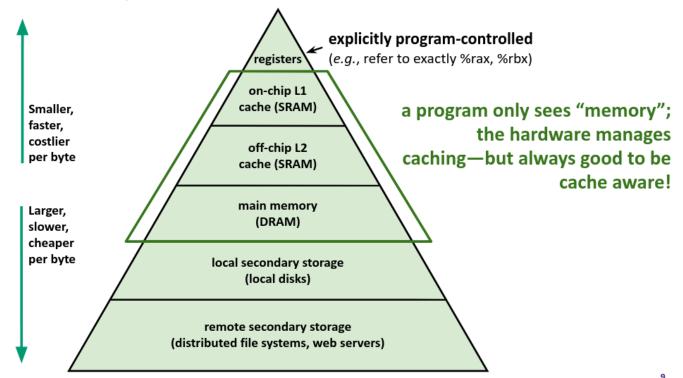
## **Memory Hierarchy Review**



**Memory Hierarchy Review (pt 2)** 

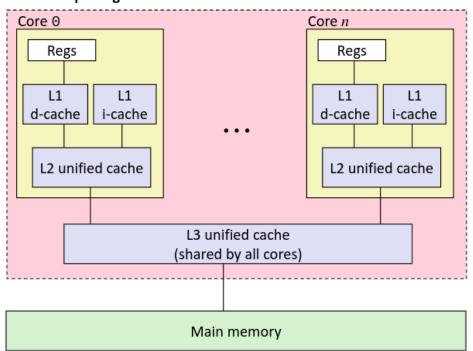


## **Memory Hierarchy Review (pt 3)**



### **Example Microarchitecture: Intel Core i7**

#### Processor package



• Block size:

64 bytes for all caches

- L1 i-cache and d-cache:
  - 32 KiB, 8-way,
  - O Access: 4 cycles
- L2 unified cache:
  - o 256 KiB, 8-way,
  - Access: 11 cycles
- L3 unified cache:
  - 8 MiB, 16-way,
  - O Access: 30-40 cycles

#### **Caches**

- Cache basics
- Principle of locality
- Memory hierarchies
- Cache organization
  - Direct-mapped (sets; index + tag)
  - Associativity (ways)
  - Replacement policy
  - Handling writes
- Program optimizations that consider caches

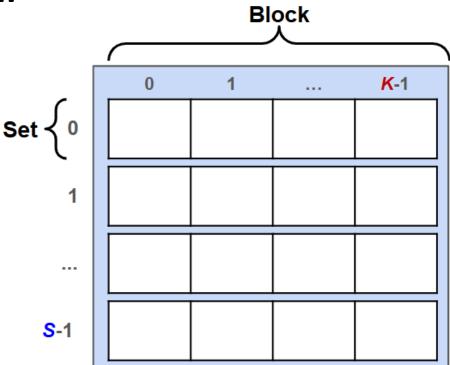
#### **Review Question**

We have a **direct-mapped cache** with the following parameters:

- Block size of 8 bytes
- Cache size of 4 KiB
- How many blocks can the cache hold?
- 2. How many bits wide is the block offset field?
- 3. Which of the following addresses (could be multiple) would fall under block 3?
  - A) 0x3
  - B) 0x1F
  - C) 0x30
  - D) 0x38

## **Reading Terminology Review**

- Cache Parameters
  - Block size (K)
  - Cache size (C bytes, or S sets)
- Address fields
  - Block offset (k bits wide)
  - Block number (also called "block address")
    - Index field (s bits wide)
    - Tag (*t* bits wide)

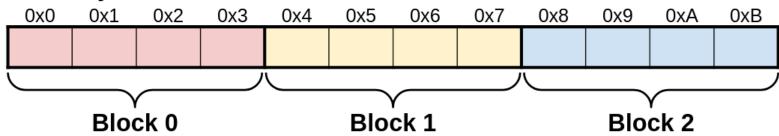


## **Cache Organization: Block Size**

- Block Size (K): unit of transfer between cache and memory
  - Given in bytes and <u>always</u> a power of 2
  - Blocks are aligned and consist of adjacent bytes
    - Spatial locality!

Example: K = 4B

#### **Memory:**



## Cache Organization: Block Size (pt 2)

- Given block size K:
  - Address ÷ K = block number (i.e. which block this address belongs to)
  - Address % K = block offset (i.e. where in the block this address is located)
- Define  $k = \log_2(K)$ 
  - Lowest k bits of address tell us the block offset

m-bit
address

m-bit
block number

block offset

Example: If we have 6-bit addresses and K = 4B, which block does address 0x15 belong to? What is its offset within that block?

## **Cache Organization: Cache Size**

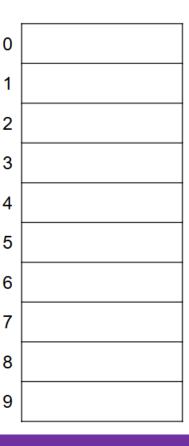
- Cache size (C) = how much data the cache can hold
  - Does not include any metadata
  - If size is (C) bytes, then the cache can hold C/K blocks
    - **Ex**: if C = 32KiB and K = 64B, then the cache can hold 512 blocks
- Where should data go in the cache?
  - We need a mapping from memory addresses to specific locations in the cache to make checking the cache for an address *fast*
- What data structure provides fast lookup?

## **Hash Tables for Fast Lookup**

- Divide cache into "buckets" (sets)
  - Apply hash function to map each block to a set
  - What's a simple hash function we can use?

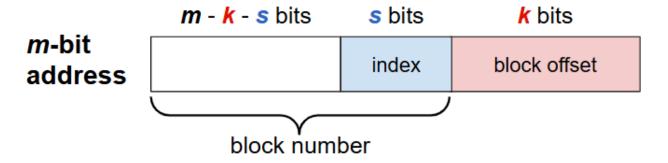
Example: If we have 10 sets, what indices should each of these blocks go into?

- 5
- 27
- 34
- 102

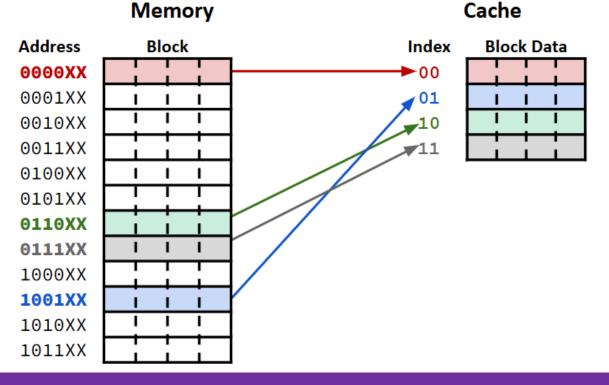


## **Cache Organization: Sets**

- Number of sets (S) = cache size (C) ÷ block size (K)
  - Always a power of 2
  - Block number % S = set index (i.e. where in the cache this block goes)
- Define  $s = log_2(s)$ 
  - Lowest S bits of the block number tell us the index



### **Memory and Cache Example**



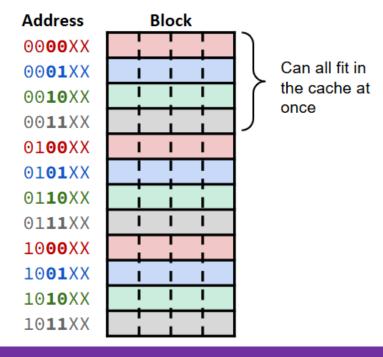
In this example:

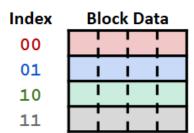
- Map blocks to cache sets
  - Block# mod S = index

## **Memory and Cache Example (pt 2)**

Memory

Cache





In this example:

$$K = 4B$$
  
 $S = 4$ 

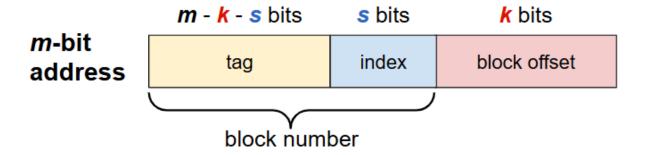
- Map blocks to cache sets
  - Block# mod S = index
- Adjacent blocks can fit into the cache at the same time!
  - Map to consecutive sets

## **Polling Question**

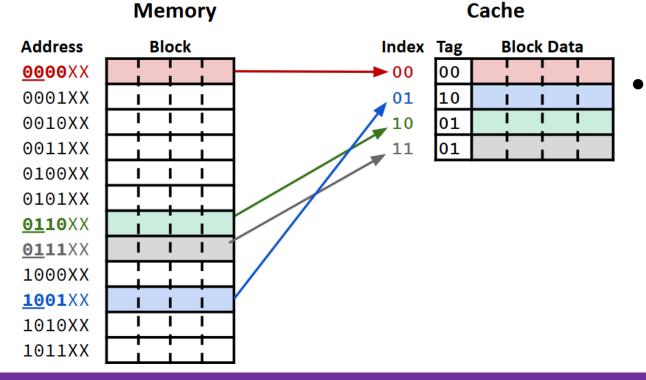
- 6-bit addresses, block size K = 4 B, and our cache holds S = 4 blocks
- The CPU requests data at address 0x2A.
  - Which index can this address be found in?
  - Which 3 other addresses can be found in the same block? (No Ed poll for this one)

## Cache Organization: Sets and Tags

- Problem: multiple blocks in memory will map to the same set
  - There will always be more blocks than sets because cache is smaller than memory
  - o If we look in a set in the cache, how can we tell which block in memory it has?
- Solution: store the remaining bits of the block number as a tag



## **Memory and Cache Example (pt 3)**



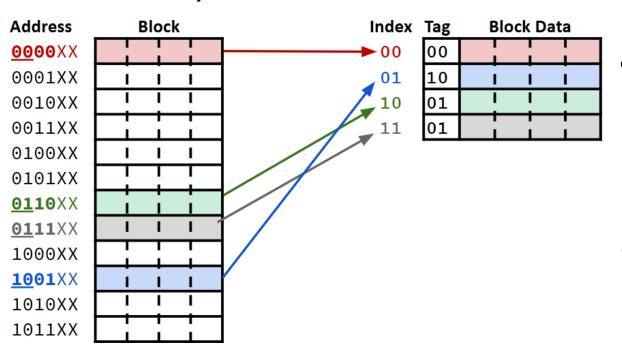
In this example:

$$K = 4B$$
  
 $S = 4$ 

- Save the tag in the cache along with the data block
  - All bits of the block#
     not used for the index

## **Memory and Cache Example (pt 4)**

Memory



Cache

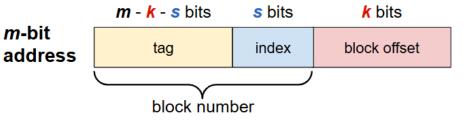
In this example:

$$K = 4B$$
  
 $S = 4$ 

- Save the tag in the cache along with the data block
  - All bits of the block#
     not used for the index
- On lookup, check the tag to make sure we have the right block

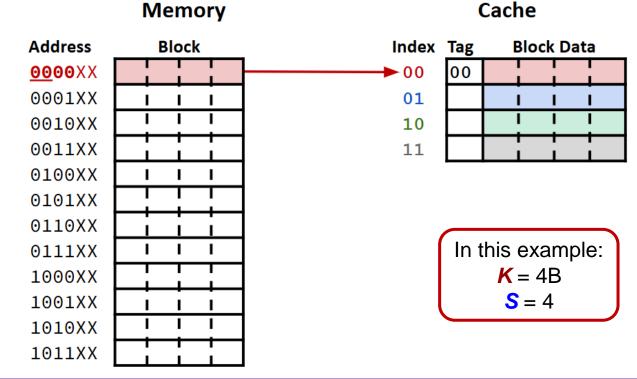
## **Accessing Data**

- CPU requests a chunk of data at some address
- 2. Break address up into Tag, Index, and Offset
  - **a.** O = lowest k bits, l = next s bits, T = remaining bits
  - b. Check set I in the cache
  - c. If the tag matches T, return the data starting at offset O
  - d. Otherwise, load block from memory
    - i. Goes into set I, update tag to match
    - Then return the data at offset O



## **Accessing Data Example: Before**

- Block 0 already loaded into the cache
- CPU requests 2B of data at address
   0b010001

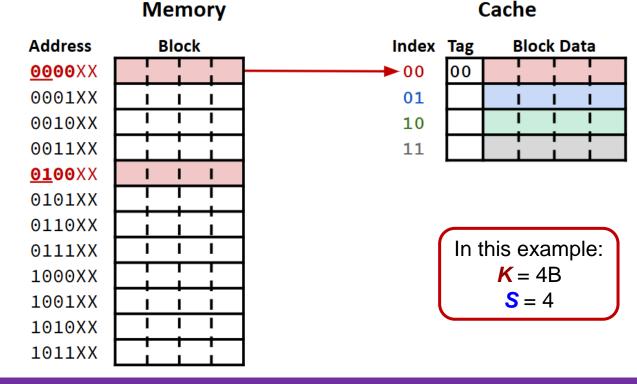


## Accessing Data Example: T/I/O breakdown

- k = 2, s = 2
- CPU requests data at address 0b010001

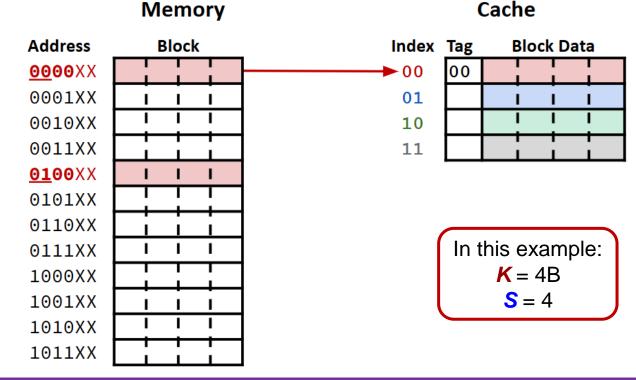
$$\circ$$
 T = 0b01

- 0000 = 0
- $\circ$  0 = 0b01



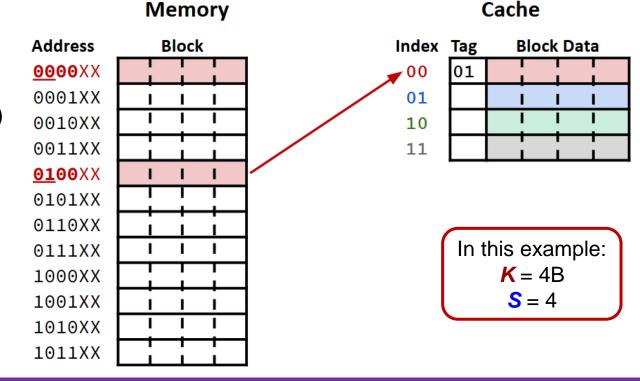
## **Accessing Data Example: Checking Set**

- T = 0b01, I = 0b00,O = 0b01
- Set 0 has tag 00, doesn't match
  - Cache miss!



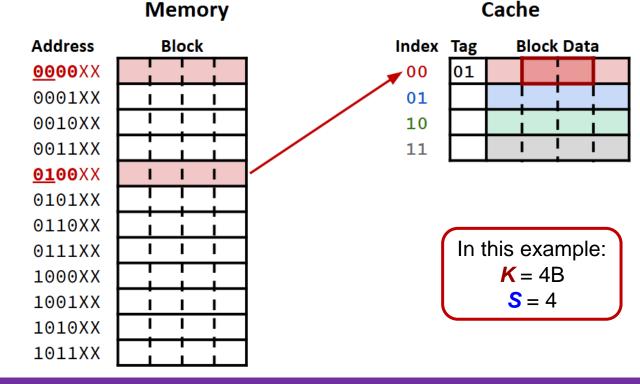
## **Accessing Data Example: Loading from Memory**

- T = 0b01, I = 0b00,O = 0b01
- Store block 4 (0b0100)
  into the cache in set 0
  Update Tag



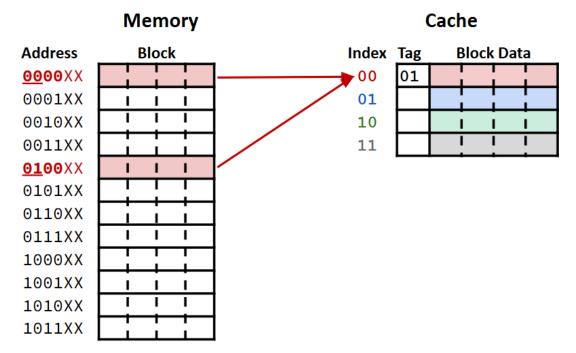
## **Accessing Data Example: Returning Data**

- T = 0b01, I = 0b00,O = 0b01
- Return data starting at offset 1



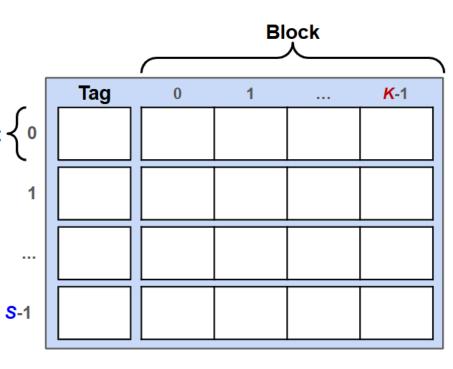
#### **Collisions**

- Problem: multiple blocks map to the same set
  - Collision occurs when we try to load a block into a set that already has data
    - Evict the old block to make room
  - How can we fix this?
    - Next lecture!



## **Summary: Cache Terminology**

- Memory is broken up into aligned blocks
- Cache is broken up into sets
  - Each set holds one block (for now) Set ≺ 0
  - Store tag along with data block
  - Sets referenced by their index
- Cache size = number of bytes of data the cache can hold
  - Number of sets \* block size



## **Summary: Address Translation**

- Block size = K
  - $\circ \quad \mathbf{k} = \log_2(\mathbf{K})$
- Cache size = C
- Number of sets = S = C÷K
  - $\circ \quad \mathbf{s} = \log_2(\mathbf{s})$
- m-k-s bits s bits

  m-bit
  address

  tag index block offset

  block number

- Divide addresses (a) into fields
  - Offset = lowest k bits = a % K
    - Starting location within a block
  - Index = next s bits = (a÷ K) % S
    - Which set the block is in
  - Tag = Remaining bits = (a÷K)÷S
    - Used to distinguish different blocks with the same index