## **Translation Sketch**

## 1 Expressions

E translates a Chalice expression into an equivalent SIL expression. Given an scoped identifier i,  $\rho(i)$  denotes a globally unique identifier. E.g.,  $\rho(\mathsf{someField}) = \mathsf{SomeClass::someField}$ 

$$E \ [e_1? e_2: e_3]_{\text{ch}} = [E(e_1)? E(e_2): E(e_3)]_{\text{SIL}}$$
 (1)
$$E \ [e_1 = e_2]_{\text{ch}} = [= = (E(e_1), E(e_2))]_{\text{SIL}}$$
 (2)
$$E \ [e_1! = e_2]_{\text{ch}} = [! = (E(e_1), E(e_2))]_{\text{SIL}}$$
 (3)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (4)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (5)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (6)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (7)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (9)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (10)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (11)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (12)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (13)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (14)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (15)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (16)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (17)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (18)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (19)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (19)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (19)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (19)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (19)
$$E \ [e_1 \cdot e_2]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (20)
$$E \ [e_1 \cdot id]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (21)
$$E \ [e_1 \cdot id]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (22)
$$E \ [e_1 \cdot id]_{\text{ch}} = [\cdot (E(e_1), E(e_2))]_{\text{SIL}}$$
 (23)
$$E \ [e_1 \cdot id]_{\text{ch}} = [\cdot (E(e_1), E(e_1), E(e_2))]_{\text{SIL}}$$
 (24)
$$E \ [e_1 \cdot id]_{\text{ch}} = [\cdot (E(e_1), E(e_1), E(e_2))]_{\text{SIL}}$$
 (24)
$$E \ [e_1 \cdot id]_{\text{ch}} = [\cdot (E(e_1), E(e_1), E(e_1))]_{\text{SIL}}$$
 (25)
$$E \ [\cdot (E(e_1))_{\text{ch}} = [\cdot (E(e_1), E(e_1), E(e_1))]_{\text{SIL}}$$
 (26)
$$E \ [\cdot (E(e_1))_{\text{ch}} = [\cdot (E(e_1), E(e_1), E(e_1)]_{\text{ch}}$$
 (27)

## 2 Statements

S translates Chalice statements into equivalent SIL statements/expressions.  $\tau_1, \tau_2, ...$  are temporary variables unique to each rule instantiation.

$$S [[assert e_1]]_{Ch} = [[assert E(e_1)]]_{SIL}$$
(28)

$$S [assume e_1]_{Ch} = [assume E(e_1)]_{SIL}$$
(29)

$$S[\{s...\}]_{Ch} = [S(s...)]_{SIL}$$
 (30)

Need to flatten nested stmt blocks, since SIL doesn't have local variable scoping.

$$S [ spec id [e...] ]_{Ch} = What does spec do?$$
 (31)

$$S [ var id := e_1 ]_{Ch} = [ id := E(e_1) ]_{SIL}$$
 (32)

$$S \llbracket \text{ const } id := e_1 \rrbracket_{\text{Ch}} = \llbracket id := E(e_1) \rrbracket_{\text{SIL}}$$

$$(33)$$

$$S \parallel \text{ghost var } id := e_1 \parallel_{\text{Ch}} = \parallel id := E(e_1) \parallel_{\text{SIL}}$$
 Keep track of ghost? (34)

$$S \parallel \text{ghost const } id := e_1 \parallel_{\text{Ch}} = \parallel id := E(e_1) \parallel_{\text{SIL}}$$
(35)

$$S \ [\![ \ \mathsf{call} \ v \dots \ := r . m_1(e \dots) ]\!]_{\mathsf{Ch}} = [\![ \mathsf{call} \ v \dots \ := E \ (r) \ . m_1 \ (E \ (e \dots)) ]\!]$$

If SIL doesn't support multiple return values, the method will have to return a tuple containing the actual return values.

$$S [ call v_1, v_2, ..., v_n := r.m_1(e...) ]_{Ch} = [ call \tau_1 := E(r).m_1(E(e...)) ;$$
 (36)

$$S(v_1 := \tau_1.elem_1)$$
; (37)

$$S(v_1 := \tau_1.elem_1)$$
; (38)

$$S(v_n := \tau_1.elem_n)$$
; (40)