

Problem Statement

differential equation for a bungee jumper depend on whether jumper has fallen to a distance where cord is fully extended and begin to stretch. condition of spring and dampening ~~force~~ forces is encoded in following equation. Using fourth order Runge - kutta method implement computation from $t=0s$ to $t=50s$

Given,

$$L = 30$$

$$m = 68.1$$

$$c_d = 0.25$$

$$k = 40$$

$$\gamma = 8$$

$$\text{sign}(x) \rightarrow -1, 0, 1$$

v is velocity

t is time

$$g = 9.81$$

equation,

$$\frac{dv}{dt} = \begin{cases} g - \text{sign}(v) \frac{c_d v^2}{m} & ; x \leq L \\ g - \text{sign}(v) \frac{c_d v^2}{m} - \frac{k}{m} (x-L) - \frac{\gamma}{m} v & ; x > L \end{cases}$$

initialization,

$$x(0) = v(0) = 0$$

$$\text{Sig}(v) = \begin{bmatrix} -1 & v < 0 \\ 0 & v = 0 \\ 1 & v > 0 \end{bmatrix}$$

Applying Runge - kutta fourth order,

$h = 0.1$ — step size assumed

$t \Rightarrow (0 \text{ to } 50)$ — given,

$$x_{i+1} = x_i + Qh$$

$$x_{i+1} = x_i + v_i h$$

$$Y_{i+1} = Y_i + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4) h$$

where, $k_1 = f(x_i, y_i)$

$$k_2 = f(x_i + h/2, y_i + k_1 h/2)$$

$$k_3 = f(x_i + h/2, y_i + k_2 h/2)$$

$$k_4 = f(x_i + h, y_i + k_3 h)$$

So after code our final value for step size 0.1 is

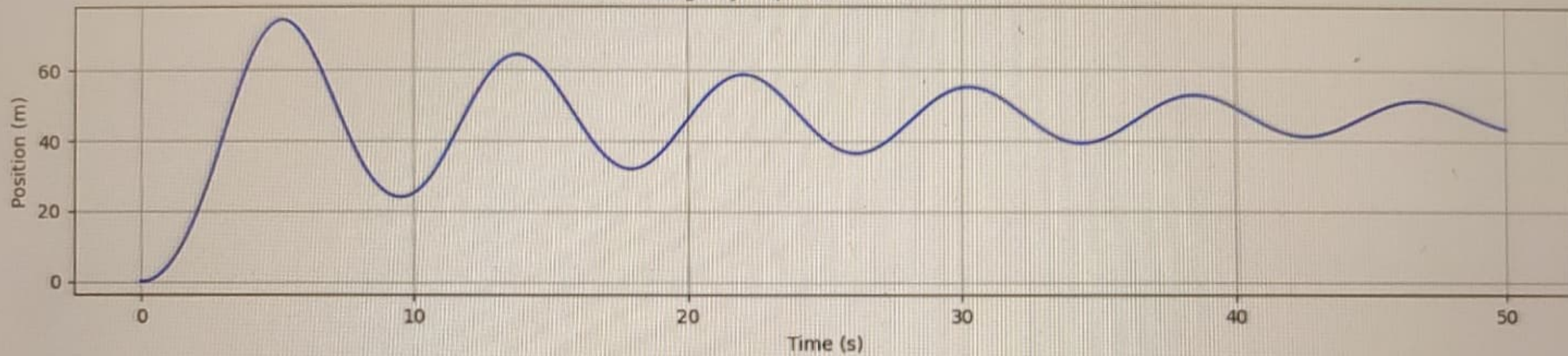
Final time = 50s,

Final Position = 43.35m,

Final Velocity = -1.76 m/s

Note : value will change if step size change
step-size \downarrow accuracy \uparrow

Bungee Jumper Position vs. Time



Bungee Jumper Velocity vs. Time

