

## Massively parallel applications use parallel sorting



- Charm N-body Gravity solver
- Cosmological N-body simulations
- Parallel sorting in every iteration

- Cosmology code based on Chombo
- Global sorting every step for load balancing and locality

CHARM

## Problems with existing algorithms

- **Sample sort:** Pick a sample from the input, choose (p-1) splitters from the sample. Variants: Regular sampling, random sampling.  
**Problem: Required sample size is too large for good splitting**
- **Histogram sort:** Maintain a set of candidate splitters, obtain their rank in the local input by performing histogramming rounds. Refine candidate keys every round till a given threshold.  
**Problem: Required number of histogramming rounds could be large, depending upon the input distribution**

## HSS is theoretically more efficient than sample sort

Algorithm	Overall sample size	Overall sample size for $p = 10^3, \epsilon = 5\%$	Computation complexity	Communication complexity
Sample sort with regular sampling	$O(\frac{N}{\epsilon^2})$	1600 GB	$O(\frac{N}{p} \log \frac{N}{p} + \frac{p^2}{\epsilon} \log p + \frac{N}{p} \log p)$	$O(\frac{N}{\epsilon^2} + p + \frac{N}{p})$
Sample sort with random sampling	$O(\frac{p \log N}{\epsilon^2})$	8.1 GB	$O(\frac{N}{p} \log \frac{N}{p} + \frac{p \log N \log p}{\epsilon^2} + \frac{N}{p} \log p)$	$O(\frac{p \log N}{\epsilon^2} + p + \frac{N}{p})$
HSS with one round	$O(\frac{p \log p}{\epsilon})$	184 MB	$O(\frac{N}{p} \log \frac{N}{p} + \frac{p \log p \log N}{\epsilon} + \frac{N}{p} \log p)$	$O(\frac{p \log p}{\epsilon} + p + \frac{N}{p})$
HSS with two rounds	$O(p \sqrt{\log p})$	24 MB	$O(\frac{N}{p} \log \frac{N}{p} + p \sqrt{\log p} \log N + \frac{N}{p} \log p)$	$O(p \sqrt{\log p} + p + \frac{N}{p})$
HSS with k rounds	$O(k p \sqrt[k]{\log p})$	-	$O(\frac{N}{p} \log \frac{N}{p} + k p \sqrt[k]{\log p} \log N + \frac{N}{p} \log p)$	$O(k p \sqrt[k]{\log p} + p + \frac{N}{p})$
HSS with $O(\log \log p)$ rounds	$O(p \log \log p)$	10 MB	$O(\frac{N}{p} \log \frac{N}{p} + p \log \log p \log N + \frac{N}{p} \log p)$	$O(p \log \log p + p + \frac{N}{p})$

Table 1: Running time complexity and comparison of required sample sizes of HSS and sample sort.

## Parallel sorting: Goals

- Load balance after sorting
- Optimal data movement
- Generality: should work for any inputs
- Scalability and performance for massive clusters

## Our approach: Histogram sort with sampling (HSS)

- **Key Idea:** Sample keys before every histogramming round. Use information from previous rounds to sample intelligently.
- By performing histogramming on the sample, HSS reduces the sample size requirements of sample sort by multiple orders of magnitude.

**Overview:** HSS maintains "splitter intervals" for all splitter keys. A splitter interval marks the nearest key seen so far, both smaller (left) and greater (right) than the ideal splitter.  $\epsilon$  is the maximum load imbalance permitted by the application.

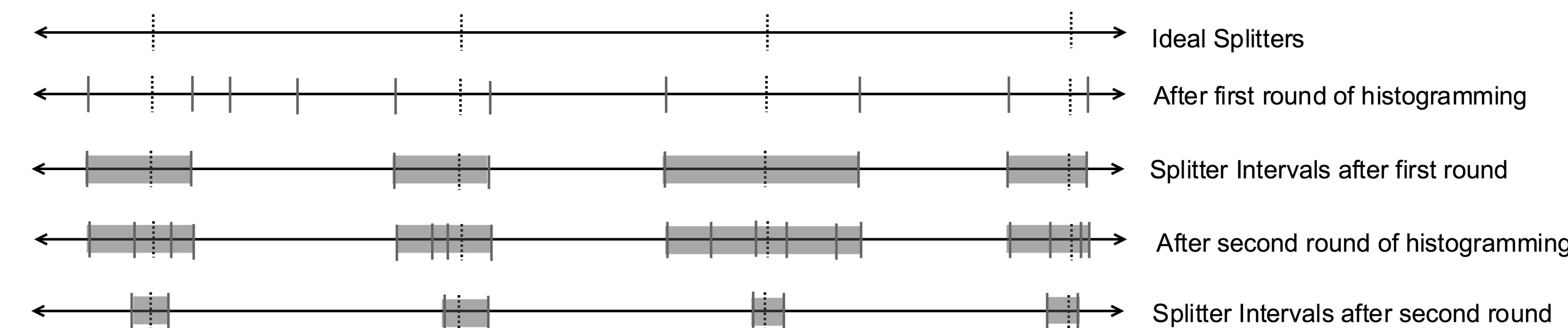


Fig 1: Figure illustrating HSS with multiple rounds. After first round, samples are picked only from the splitter intervals. Notice how the splitter intervals shrink as the algorithm progresses.

- In general, for HSS with k rounds, sample\* required per round is  $O(p^k \sqrt[k]{\log p} / \epsilon)$
- For HSS with  $O(p)$  sample every round, #rounds required is  $O(\log((\log p) / \epsilon))$
- Sample sort requires  $O(p \log N / \epsilon^2)$  samples

\* with high probability

## HSS in practice

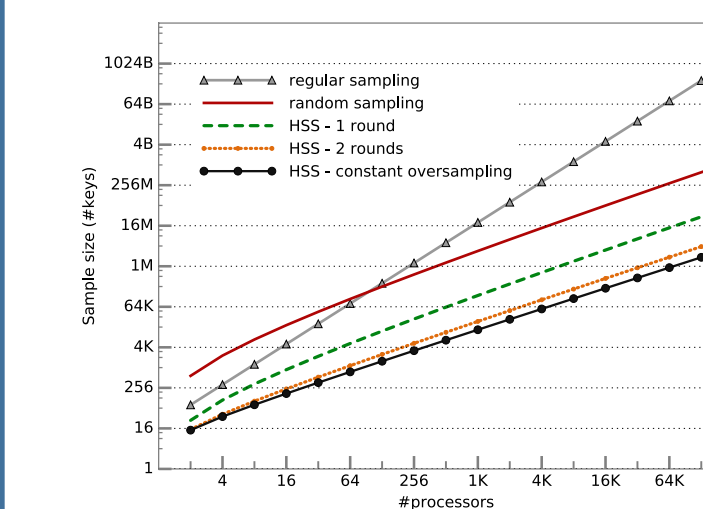


Fig 2: HSS vs Sample sort: sample size required for splitting,  $\epsilon = 5\%$

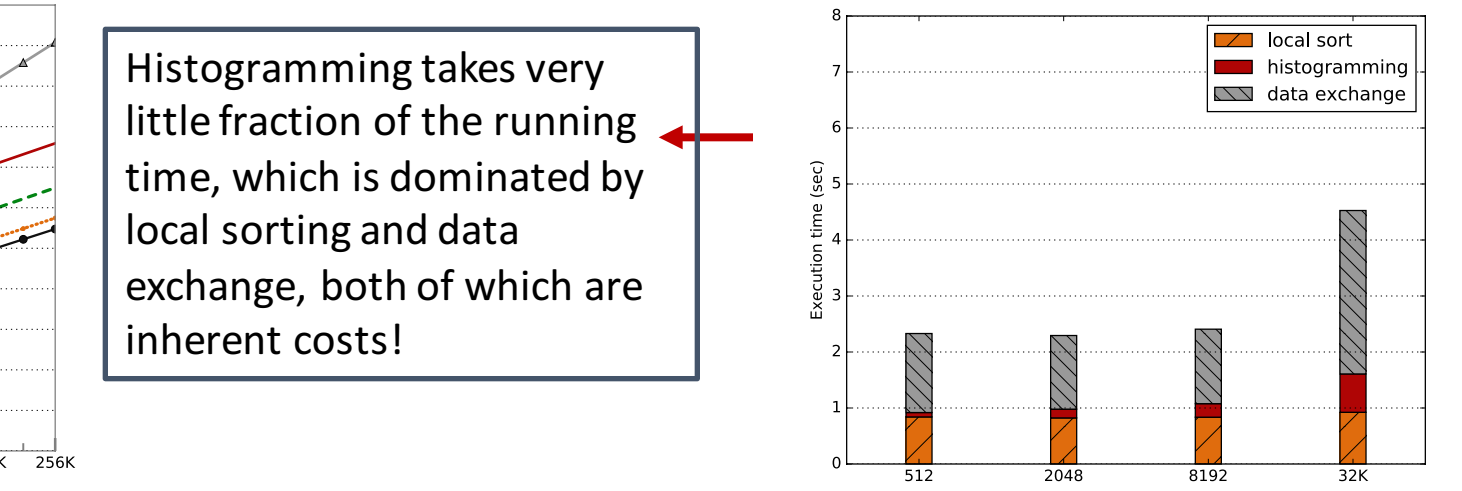


Fig 3: HSS on Mira (ALCF) BG/Q. Each processor had 1 million 8 byte keys with a 4 byte payload with each key

Histogramming takes very little fraction of the running time, which is dominated by local sorting and data exchange, both of which are inherent costs!

p (x 1000)	sample size/round (x p)	Number of rounds	Bound on number of rounds
4	5	4	8
8	5	4	8
16	5	4	8
32	5	4	8

Table 2: Number of rounds required for determining all splitters (experimentally)

## Parallel sorting : Skeleton for many algorithms

- p processors, N/p keys in each processor
- Determine (p-1) splitter keys to partition the keys into p buckets, one for each processor. Make these splitters available to all processors.
- Send all keys to destination processor depending on the which bucket it falls in.
- E.g. sample sort, histogram sort

## Conclusion

- HSS combines histogramming and sampling to achieve fast splitter determination
- HSS is extremely practical for massively parallel applications

- **Future Work**  
→ Integration in real applications; ChaNGa
- **Details:** [vharsh2.web.engr.illinois.edu/projects/parallel-sort/prelimreport.pdf](http://vharsh2.web.engr.illinois.edu/projects/parallel-sort/prelimreport.pdf)
- **Acknowledgements:** Edgar Solomnik, Omkar Thakoor, Umang Mathur