

# VIRAJ PARIMI

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## EDUCATION

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**Carnegie Mellon University - School of Computer Science** Pittsburgh, PA  
Master of Science in Robotics | GPA: 4.08/4 August 2021  
*Selected Coursework:* Computer Vision, Mathematical Fundamentals for Robotics,  
Graduate Artificial Intelligence, Statistical Techniques in Robotics,  
Planning and Decision Making in Robotics, Mechanics of Manipulation

**Indraprastha Institute of Information Technology** Delhi, India  
Bachelor of Technology in Computer Science and Engineering (Honors) | GPA: 8.96/10 May 2019  
*Relevant Coursework:* Statistical Machine Learning, Deep Learning,  
Advanced Operating Systems, Graph Theory, Numerical Methods, Computer Graphics  
Natural Language Processing, Network and Systems Security, Parallel Programming

## EXPERIENCE

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**NASA HOME STRI** Pittsburgh, PA  
Research Assistant August 2019 - Present

- Developing a robust reactive planner by leveraging timeline-based planning framework and deploying it in a test-bed designed to mimic deep space habitats.
- Formulating a tight integration of multi-robot coordination with humans for joint task execution.

**Carnegie Mellon University** Pittsburgh, PA  
Research Scholar June 2018 - August 2018

- Developed a computationally scalable bayesian sequential learning framework for time-series forecasting with up to **4 orders of magnitude speed improvement** compared to other benchmarks.

**Precog** Delhi, India  
Data Analytic Intern May 2017 - September 2017

- Devised data analytic tool for National Bomb Data Center (NBDC) working under National Security Guards (NSG) to generate analysis based on historic data.
- Assembled tool that automates whole process from input stage to output stage where useful insights are passed upon user request.

## PUBLICATIONS

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**A Computationally Scalable Bayesian Sequential Learning Framework for Time-Series Forecasting** Working Paper  
V. Parimi, I. Isukapati, S. Smith 2021

**Hierarchical Bayesian Framework for Bus Dwell Time Prediction**  
I. Isukapati, C. Igoe, E. Bronstein V. Parimi, S. Smith 2020  
IEEE Transactions on Intelligent Transportation Systems

**Understanding Vulnerability of Communities in Complex Networks**  
V. Parimi, A. Pal, S. Ruj, P. Kumaraguru, T. Chakraborty 2019  
Arxiv pre-print

**Analysis of DSRC accuracy for pedestrian localization**  
A. Lakshman\*, V. Parimi\*, S. Smith 2018  
RISS 2018 Working Paper Journal

## SELECTED PROJECTS

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### Sampling-based Planning in Discrete Space

Carnegie Mellon University | November 2020

[Prof. Maxim Likhachev](#)

- Proposed a hierarchical decomposition algorithm where we discretize the continuous sample space of PRM/RRT algorithms in order to provide tighter completeness guarantees.
- Demonstrated the performance improvement of the proposed approach for 6-link robotic arm.

### Lossy Compression using Neural Networks

Carnegie Mellon University | May 2020

[Prof. Zico Kolter](#)

- Formulated quantization techniques to generate discrete latent space representations among image and text based autoencoder models without significant performance implications.
- Showcased that incorporating commit-loss to the learning process improved the compression ratio of both image and text based models while maintaining the quality of reconstructions.

### COTTON

IIIT-Delhi | November 2018

[Prof. Vivek Kumar](#)

- Developed a light-weight work-stealing runtime for async-finish task parallelism which was energy efficient without incurring significant impact on the performance.
- Used different power saving drivers in combination with `cpufreq` to change the CPU frequency based on some task based heuristics.

### Understanding Vulnerability of Communities in Complex Networks

IIIT-Delhi | May 2018

[Prof. Tanmoy Chakraborty](#) & [Prof. Ponnurangam Kumaraguru](#)

- Identified vulnerable nodes in communities defined in a complex network by investigating several global and community centric properties to observe their effects on underlying community structure of the network.
- Proposed a hierarchical greedy heuristic based approach with a novel task based extrinsic evaluation strategy to measure its robustness.

### Autoencoder based Recommender System

IIIT-Delhi | November 2017

[Prof. Angshul Majumdar](#)

- Engineered a new recommender system for GitHub where users are suggested with relevant repositories to contribute towards based on profiles while leading a group of 2.
- Applied similar technique to single-celled RNA-seq data and showed better gene expression recovery compared to other alternatives.

### Advanced Application for Social Media Analytics (AASMA).

IIIT-Delhi | November 2016

[Prof. Ponnurangam Kumaraguru](#)

- Collaborated with a team of 7 people to extend a tool launched by CERC Lab by incorporating sentiment model along with improvements in efficient data handling and depiction using redis queue for real-time utilization by more than 75 agencies.

### Smart Glasses

IIIT-Delhi | April 2015

[Prof. Alexander Fell](#)

- Created a prototype to help blind people understand text and allow them to identify people they know.
- Selected as top 10 projects of the year and was showcased at the Delhi Mini-Maker Faire.

## HONORS

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Full scholarship from advisors at Carnegie Mellon University	2020
Robotics Institute Summer Scholar (35 selected from ~ 800 applicants)	2018
FICCI Scholarship, Carnegie Mellon University	2018
GSoC Internship	2018
Dean's List, IIIT-Delhi	2017

## ACTIVITIES

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<b>Graduate Research Assistant</b> <a href="#">Intelligent Coordination and Logistics Laboratory</a> - CMU Research Group	August 2019 - Present
<b>RISS Admissions Committee</b> Carnegie Mellon University	January 2020 - March 2020
<b>Undergraduate Researcher</b> <a href="#">Laboratory for Computational Social Systems</a> - IIIT-Delhi Research Group	August 2017 - May 2019
<b>Undergraduate Researcher</b> <a href="#">Precog</a> - IIIT-Delhi Research Group	August 2016 - May 2019
<b>Teaching Assistant</b> Advanced Programming	August 2017

## INVITED TALKS

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<b>Planning under Uncertainty for Joint-Task Execution</b> <a href="#">NASA HOME STRI</a>	October 2020 Pittsburgh, PA
<b>Computationally Scalable Bayesian Inference Framework</b> <a href="#">Rapid Flow Technologies</a>	June 2020 Pittsburgh, PA
<b>Analysis of DSRC accuracy for pedestrian localization</b> <a href="#">Hi-tech Robotics Systemz Ltd.</a>	October 2018 Delhi, India

## SKILLS

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<b>Programming Languages</b>	Python, C, C++, Java
<b>Tools and Technologies</b>	ROS, Tensorflow, Pytorch, Keras, HCLIB, CUDA, Git, Django, Processing, OpenCV, Docker, MongoDB, MySQL
<b>Languages</b>	English (Fluent), Hindi (Native), Telugu (Native)