# VIRAJ PARIMI

Email: vparimi@mit.edu \( (412) \) 626-1630 \( \) https://viraj96.github.io/

#### **EDUCATION**

Massachusetts Institute of Technology (MIT)

Pittsburgh, PA

Doctor of Philosophy in EECS

Present

Relevent Coursework: Algorithms for Inference, Robotic Manipulation

Carnegie Mellon University (CMU) - School of Computer Science

Pittsburgh, PA

Master of Science in Robotics | GPA: 4.08/4

August 2021

Relevent Coursework: Computer Vision, Mathematical Fundamentals for Robotics,

Graduate Artificial Intelligence, Statistical Techniques in Robotics,

Planning and Decision Making in Robotics, Mechanics of Manipulation

Indraprastha Institute of Information Technology (IIIT)

Delhi, India

Bachelor of Technology in Computer Science and Engineering (Honors) | GPA: 8.96/10

May 2019

Relevant Coursework: Statistical Machine Learning, Deep Learning,

Advanced Operating Systems, Graph Theory, Numerical Methods, Computer Graphics

Natural Language Processing, Network and Systems Security, Parallel Programming

#### EXPERIENCE

MERS Cambridge, MA

Research Assistant August 2021 - Present

- · Working on safe skill learning by combining multiple hybrid-constraint concurrent automata with safety constraints.
- · Developing a formalism for the framework to deploy on multi-agent systems working in shared environments.

NASA HOME STRI

Pittsburgh, PA

Research Assistant

August 2019 - August 2021

- · Developed a robust multi-agent planner by combining timeline-based planning and hierarchical task planning frameworks.
- · Designed and deployed the planner in a test-bed designed to mimic deep space habitats.

RISS Pittsburgh, PA

Research Scholar

June 2018 - August 2018

· Developed a computationally scalable bayesian sequential learning framework for time-series forecasting with up to 4 orders of magnitude speed improvement compared to other benchmarks.

Precog Delhi, India

Data Analytic Intern

May 2017 - September 2017

- · Devised data analytic tool for National Bomb Data Center (NBDC) working under National Security Guards (NSG) to generate analysis based on historic data.
- · Assembled tool that automates whole process from input stage to output stage where useful insights are passed upon user request.

### **PUBLICATIONS**

T-HTN: Timeline based HTN Planning for Multi-Agent Systems

V. Parimi

2021

Master's Thesis, CMU

On the Vulnerability of Community Structure in Complex Networks

V. Parimi, A. Pal, S. Ruj, P. Kumaraguru, T. Chakraborty

2021

Principles of Social Networking, Springer

### Hierarchical Bayesian Framework for Bus Dwell Time Prediction

I. Isukapati, C. Igoe, E. Bronstein V. Parimi, S. Smith

IEEE Transactions on Intelligent Transportation Systems

## Analysis of DSRC accuracy for pedestrian localization

A. Lakshman\*, <u>V. Parimi\*</u>, S. Smith

RISS 2018 Working Paper Journal

2018

2020

#### SELECTED PROJECTS

## Catching a Ping Pong Ball with an iiwa

MIT | November 2021

Prof. Russ Tedrake

- · Programmed the kinematics of a Kuka iiwa using Drake to catch a ping pong ball with a ping pong paddle
- · Applied finite-state machine (FSM) techniques to model the paddle's trajectory off equations of motion of projectiles while in a pre-initial-contact mode, while we switched to a PD controller with offset stabilization in the post-initial-contact mode

### Sampling-based Planning in Discrete Space

CMU | November 2020

Prof. Maxim Likhachev

- · Proposed a hierarchical decomposition algorithm where we discretize the continuous sample space of PRM/RRT algorithms in order to provide tighter completeness guarantees.
- · Demonstrated the performance improvement of the proposed approach for 6-link robotic arm.

# Lossy Compression using Neural Networks

CMU | May 2020

Prof. Zico Kolter

- · Formulated quantization techniques to generate discrete latent space representations among image and text based autoencoder models without significant performance implications.
- · Showcased that incorporating commit-loss to the learning process improved the compression ratio of both image and text based models while maintaining the quality of reconstructions.

COTTON

IIIT-Delhi | November 2018

Prof. Vivek Kumar

- · Developed a light-weight work-stealing runtime for async-finish task parallelism which was energy efficient without incurring significant impact on the performance.
- · Used different power saving drivers in combination with cpufreq to change the CPU frequency based on some task based heuristics.

## Understanding Vulnerability of Communities in Complex Networks

IIIT-Delhi | May 2018

Prof. Tanmoy Chakraborty & Prof. Ponnurangam Kumaraguru

- · Identified vulnerable nodes in communities defined in a complex network by investigating several global and community centric properties to observe their effects on underlying community structure of the network.
- · Proposed a hierarchical greedy heuristic based approach with a novel task based extrinsic evaluation strategy to measure its robustness.

### Autoencoder based Recommender System

IIIT-Delhi | November 2017

Prof. Angshul Majumdar

- · Engineered a new recommender system for GitHub where users are suggested with relevant repositories to contribute towards based on profiles while leading a group of 2.
- · Applied similar technique to single-celled RNA-seq data and showed better gene expression recovery compared to other alternatives.

## Advanced Application for Social Media Analytics (AASMA).

IIIT-Delhi | November 2016

Prof. Ponnurangam Kumaraguru

· Collaborated with a team of 7 people to extend a tool launched by CERC Lab by incorporating sentiment model along with improvements in efficient data handling and depiction using redis queue for real-time utilization by more than 75 agencies.

Smart Glasses IIIT-Delhi | April 2015

Prof. Alexander Fell

· Created a prototype to help blind people understand text and allow them to identify people they know.

· Selected as top 10 projects of the year and was showcased at the Delhi Mini-Maker Faire.

### **HONORS**

Full scholarship from advisors at CMU	2020
Robotics Institute Summer Scholar (35 selected from $\sim 800$ applicants)	2018
FICCI Scholarship, CMU	2018
GSoC Internship	2018
Dean's List, IIIT-Delhi	2017
Secured $99.7^{th}$ percentile among 1.5 million students in JEE Mains Examination	2015

## **ACTIVITIES**

Graduate Research Assistant August 2021 - Present

Model-Based Embedded and Robotics Systems Group - MIT CSAIL Research Group

Graduate Research Assistant August 2019 - August 2021

Intelligent Coordination and Logistics Laboratory - CMU Research Group

RISS Admissions Committee January 2020 - March 2020

 $\operatorname{CMU}$ 

Undergraduate Researcher August 2017 - May 2019

Laboratory for Computational Social Systems - IIIT-Delhi Research Group

Undergraduate Researcher August 2016 - May 2019

Precog - IIIT-Delhi Research Group

Teaching Assistant August 2017

Advanced Programming

#### INVITED TALKS

Planning under Uncertainty for Joint-Task Execution	October 2020
NASA HOME STRI	Pittsburgh, PA
Computationally Scalable Bayesian Inference Framework Rapid Flow Technologies	June 2020 Pittsburgh, PA
Analysis of DSRC accuracy for pedestrian localization Hi-tech Robotics Systemz Ltd.	October 2018 Delhi, India
HI-tech Rodotics Systemz Ltd.	Deini, India

## **SKILLS**

Programming Languages Python, C, C++, Lisp, Java

Tools and Technologies ROS, Tensorflow, Pytorch, Keras, HCLIB, CUDA, Git, Django, Processing,

OpenCV, Docker, MongoDB, MySQL

Languages English (Fluent), Hindi (Native), Telugu (Native)