

Happy holiday! Remember to take care of yourself and your loved ones!

jump (generic function with 1 method)

```
• function jump()
•     return rand((-1, +1))
• end
```

bernoulli (generic function with 1 method)

```
• bernoulli(p) = rand() < p
```

0

```
• -bernoulli(0.25)
```

[-1, -1, 1, 1, 1, -1, 1, -1, 1, -1]

```
• [jump() for i in 1:10]
```

walk (generic function with 1 method)

```
• function walk(n)
•     x=0
•
•     for i in 1:n
•         x+=jump()           #x=x+jump()
•     end
•
•     return x
• end
```

-6

```
• walk(20)
```

trajectory (generic function with 1 method)

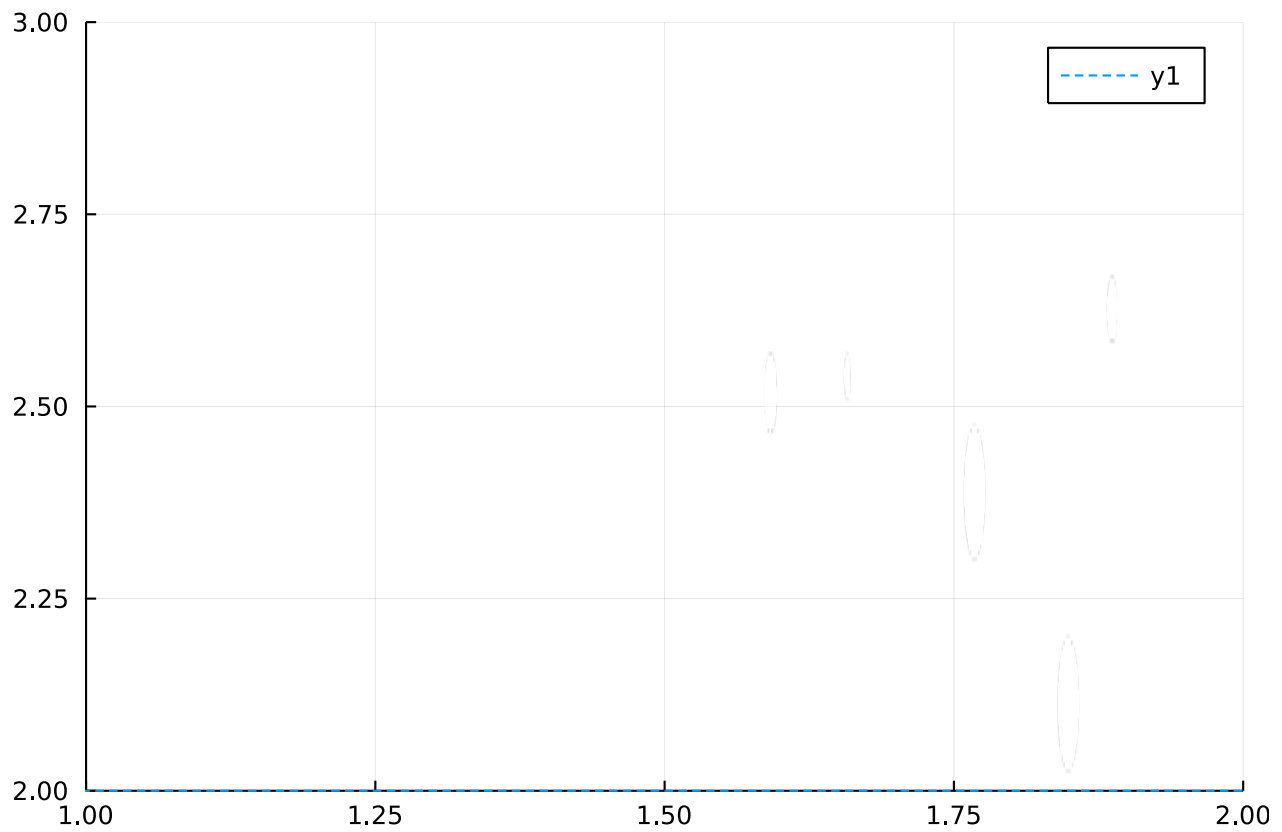
```
• function trajectory(n)
•     x=0
•     xs=[x]
•
•     for i in 1:n
•         x+= jump() #x= x+jump()
•
•         push!(xs, x)
•     end
•
•     return xs
• end
```

```
[0, 1, 2, 1, 2, 1, 2, 3, 4, 3, 4, 3, 4, 3, 2, 1, 2, 1, 0, -1, more ,15, 16, 15, 16, :
```

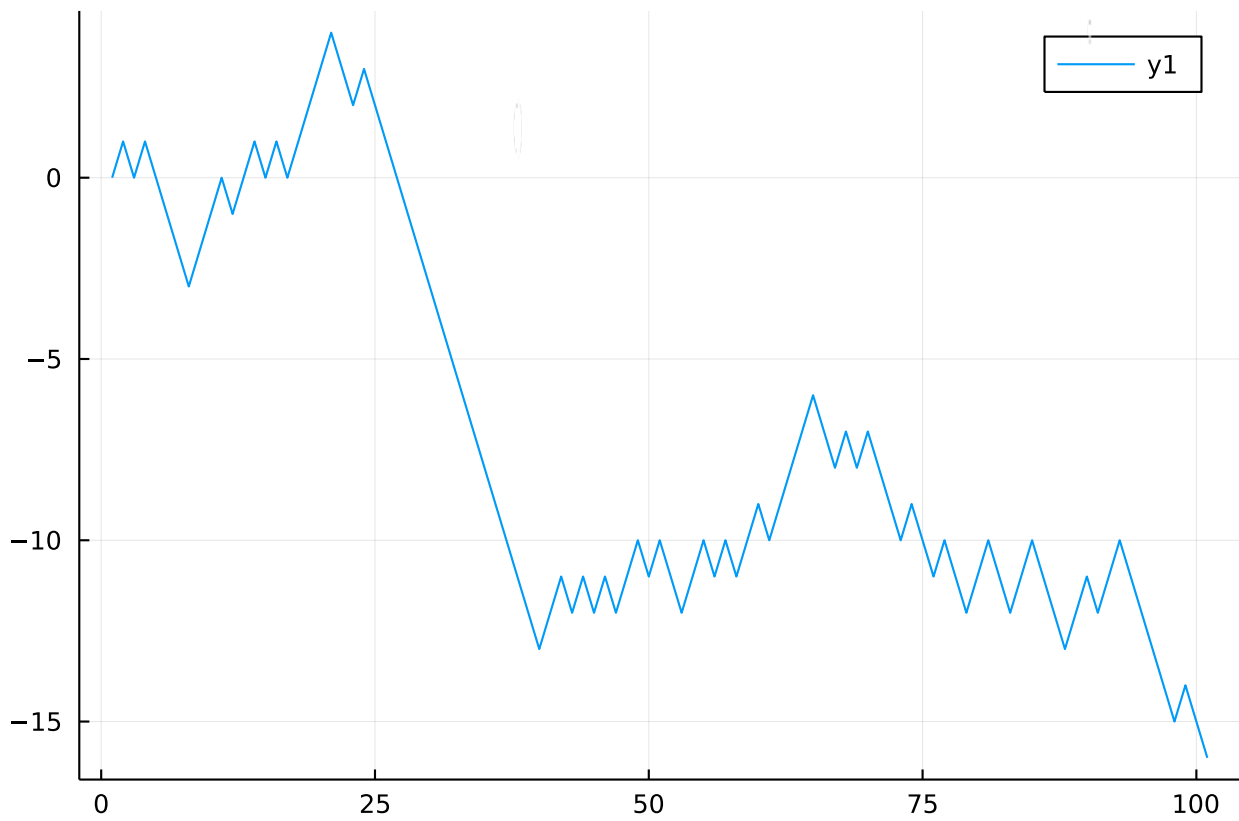
```
• trajectory(100)
```

```
• traj = trajectory(100);
```

```
• using Plots
```



```
• hline!([2], ls=:dash)
```



```
• plot(traj)
```

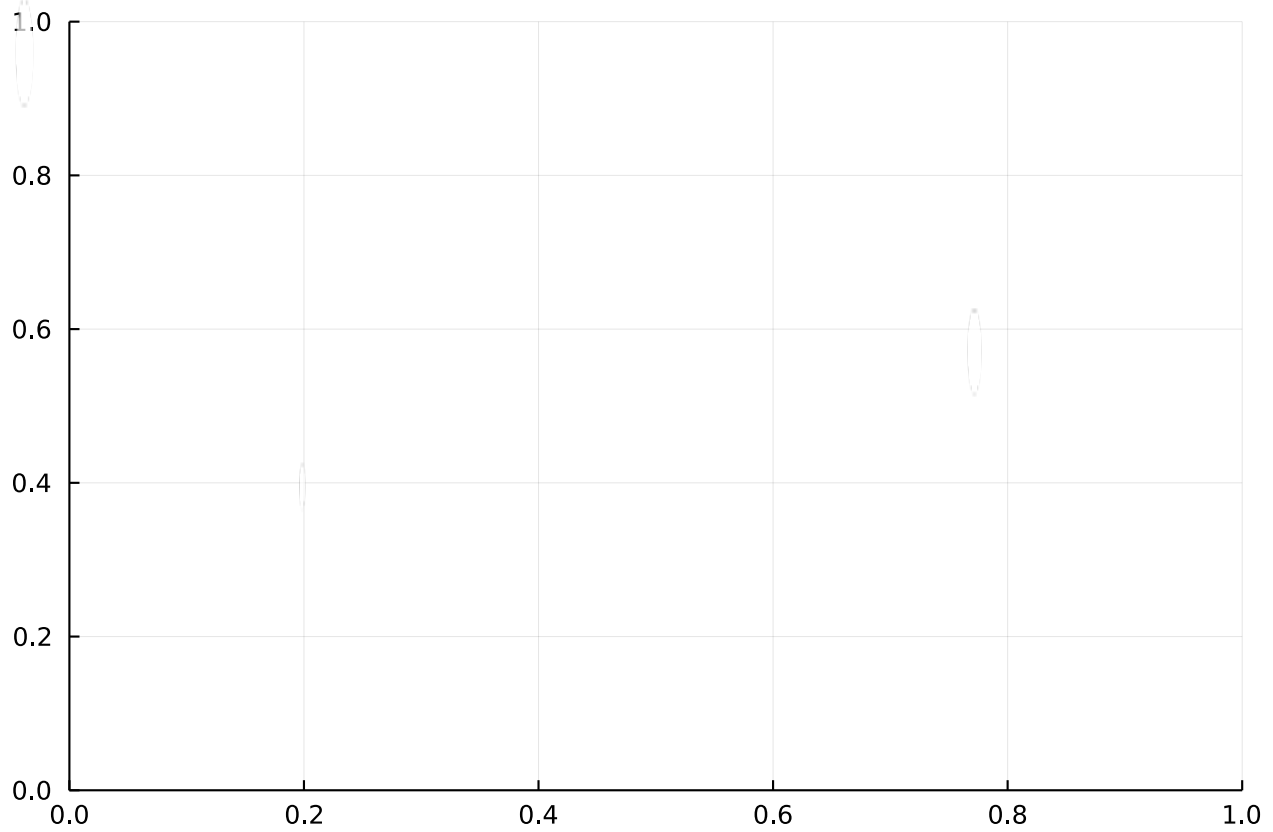
```
num_trajs = 10
```

```
• num_trajs =10
```

```
num_steps = 100
```

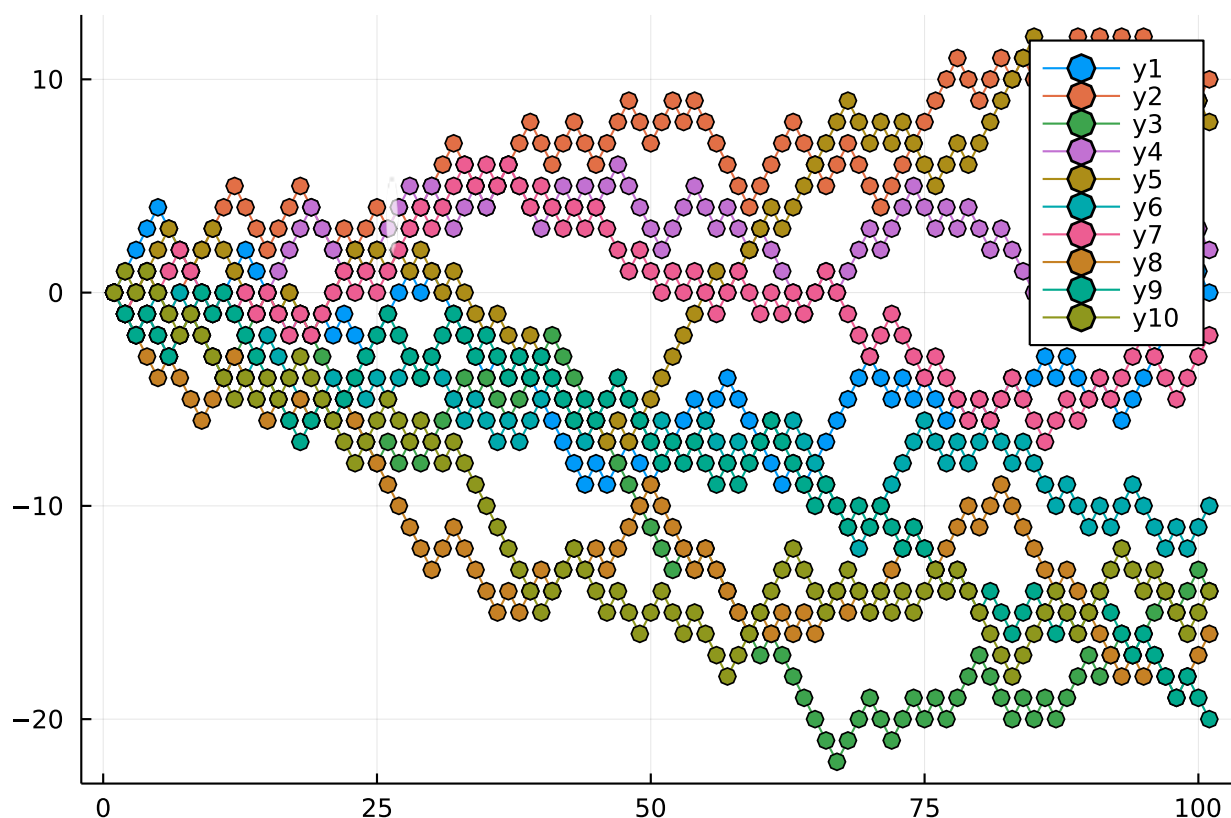
```
• num_steps =100
```

p =



```
p = plot()
```

```
for i in 1:num_trajs
    traj = trajectory(num_steps)
    plot!(traj, m=:o)
end
```



```
p
```

```
n = 20
```

```
n=20
```

```
traj1 =
```

```
[0, -1, -2, -3, -4, -3, -2, -1, 0, -1, -2, -1, -2, -3, -2, -1, 0, 1, 0, -1, -2]
```

```
traj1=trajectory(n)
```

```
using Interact
```

```
using WebIO
```

```
@manipulate for i in slider(1:n, value =1)
```

```
    plot(traj1[1:i])
```

```
end
```

```
traj_1 = [0, -1, 0, -1, 0, -1, 0, 1, 2, 3, 2, 1, 0, -1, 0, -1, 0, 1, 2, 1, 0]
```

```
traj_1 = trajectory(n)
```

```
traj_2 = [0, -1, 0, 1, 2, 1, 0, -1, 0, -1, 0, 1, 0, 1, 0, -1, -2, -3, -4, -3, -4]
```

```
traj_2 = trajectory(n)
```

```
traj_3 = [0, 1, 2, 3, 2, 1, 2, 1, 0, -1, 0, -1, -2, -3, -4, -3, -4, -5, -6, -7, -6]
```

```
• traj_3 = trajectory(n)
```

```
traj2 = [[0, 1, 0, 1, 0, -1, -2, -3, -2, more ,-6]]
```

```
• traj2=[trajectory(n)]
```

```
[0, 1, 0, 1, 0, -1, -2, -3, -2, -3, -4, -5, -4, -5, -4, -5, -6, -5, -6, -5, -6]
```

```
• traj2[1]
```

```
• Enter cell code...
```