

SoC 2023: Competitive Programming

Week-1: Basics and C++ STL

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1 Resources

- Competitive Programming: Need to solve small problems in a limited time. Most of these are based on standard concepts that we are going to cover. For acceptance, solutions must adhere to a specified time-limit and memory-limit.
- Online Platforms for contests and practice: Codeforces, Codechef, AtCoder, SPOJ, CSES, etc. We would mainly do problems from Codeforces and CSES Problem Set.
 - Can filter questions on specific topics or rating levels on Codeforces
 - CSES has topic-wise sets
- References:
 - CP: Competitive Programmer's Handbook (CSES) by Antti Laaksonen, cp-algorithms, Competitive Programming by Steven and Felix Halim, blogs on Codeforces and other websites
 - Theoretical DSA: CLRS, Kleinberg-Tardos
- Most programmers use C++ for smaller execution time and a convenient template library. Some use Python, Java, etc.

2 Basics

2.1 Template

- Starting Template
- Get VSCode to identify the path to `bits/stdc++.h`: [YT Link](#)
- VSCode user snippets
- `ios_base::sync_with_stdio(false); cin.tie(0);`
disables synchronization between streams and unties `cin` from `cout`. Buffering `cout` has a side-effect of speed improvement.
- `"\n"` vs `endl`
`endl` flushes the output. Use `"\n"` for better execution speed. Interactive Questions require flushing of output buffer. Use `cout.flush()` and the like.
- Random numbers
- File read and write for debugging and testing
- `define` macros and `typedefs`
- `long long`, `unsigned long long`

2.2 Time Complexity

- Big-O Notation: On a high level, keep the dominant (faster growing) term in a function to get the “order” with which it grows. Constant factors are ignored. Examples:
 - $3n^2 + 2n + 5 = O(n^2)$. Grows like n^2
 - $n + \log n = O(n)$, as n grows faster than $\log n$
 - $f(n) = 10^{100}n$ is $O(n)$ and $g(n) = n^2$ is $O(n^2)$. However, for all practical purposes, g is faster
- Go through this CF blog post or Chapter-2 of the Handbook. It has examples on how to compute time-complexity in terms of the inputs.
- Constraints would be mentioned in the problem: with C++, roughly $10^6 - 10^7$ operations/second. So if $n \leq 10^5$ and time limit ≤ 1 second, then $O(n^2)$ won't work (TLE). If $n \leq 20$, then brute force (2^n) might work.

2.3 Operators

- Commonly used *bitwise* operators `|`, `&`, `~`, `<<`, `>>`, `^`
- GFG Reference
- XOR
 - Exclusive OR: $0 \wedge 0 = 0$, $1 \wedge 1 = 0$, $0 \wedge 1 = 1$, $1 \wedge 0 = 1$
 - $p \wedge 0 = p$, $p \wedge (1 \dots 1) = \sim p$, $p \wedge \sim p = 1 \dots 1$. Note that $1 \dots 1$ is -1 in 2's complement notation
 - XOR is associative and commutative

3 C++ STL Data Structures

Some commonly used data structures with their methods.

1. vector

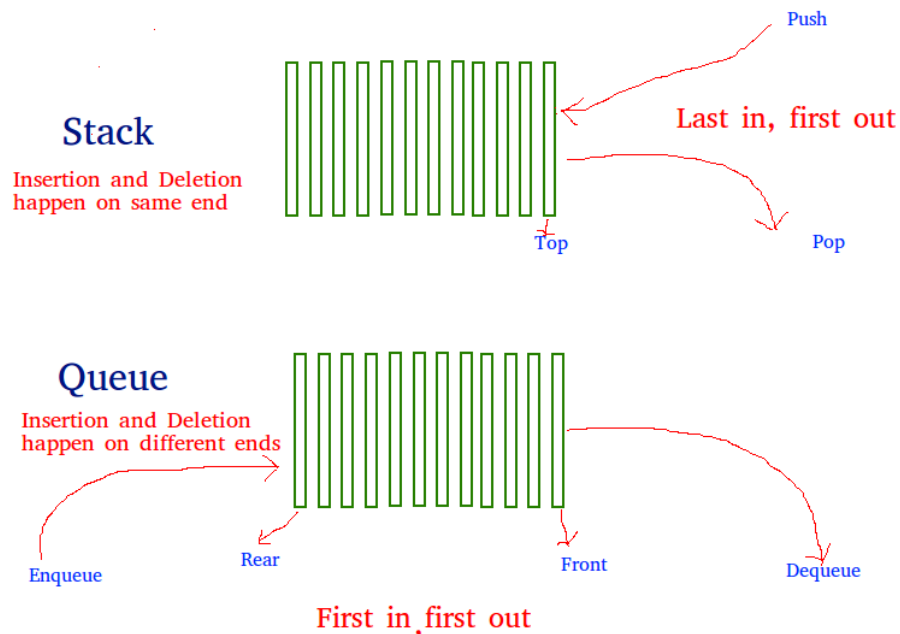
- Dynamic length array. Memory for elements is contiguously allocated on heap
- GFG Reference for methods and respective time-complexities. Constant-time access, linear-time insertion and deletion. Insertion at the end is *amortized* constant-time.
- File

2. string

- Dynamic `char` array. Many convenient STL functions
- Methods
- File

3. stack, queue, deque, priority_queue list. Images from GFG

- Stack: Last-In-First-Out
- Queue: First-In-First-Out



- Double Ended Queue: Allows insertions and deletions from either end
- Priority Queue: Top of queue is greatest/least (or custom comparison criteria)

Priority Queue		
Initial Queue = { }		
Operation	Return value	Queue Content
insert (C)		C
insert (O)		C O
insert (D)		C O D
remove max	O	C D
insert (I)		C D I
insert (N)		C D I N
remove max	N	C D I
insert (G)		C D I G

- List: Similar to `vector`, but with non-contiguous memory allocation. This allows constant-time insertions and deletions, but slower access.
- Methods and time-complexities: stack, queue, priority queue, deque, list
- File

4. `pair`, `map`, `set`

- Pair: Two elements, `first` and `second`. For example, `{int, vector<int>}`
- Set: Collection of elements. Similar to `vector`, but faster lookups, deletes. For example, `{-5, 0, 3}`
 - Ordered: Elements are ordered by some comparator. For example, default is ascending order for an ordered set of `ints`.
 - Unordered: Not ordered, allowing faster inserts, lookups, deletions. However, time-complexity constants might be higher.
 - STL: `set` and `unordered_set`
- Map: Key-value pairs. For example, `map<int, unsigned int>` with entries `{{-5, 5}, {1, 0}, {20, 10}}`.
Similar to sets, we have ordered and unordered maps: `map` and `unordered_map`. Ordering is done by keys.

	<code>map</code>	<code>unordered_map</code>
Ordering	increasing order of keys(by default)	no ordering
Implementation	Self balancing BST like Red-Black Tree	Hash Table
search time	$\log(n)$ 	$O(1)$ -> Average $O(n)$ -> Worst Case
Insertion time	$\log(n)$ + Rebalance	Same as search
Deletion time	$\log(n)$ + Rebalance	Same as search

- A popular question: Given an array of integers and a target sum, is there a pair that add up to the target sum?
 $O(n^2)$, $O(n \log n)$, $O(n)$
- File

5. Bitset. File

4 Todos

- Visit links in this document
- Start out with Chapters 1 and 4 of the CP handbook
- CSES Introductory Problems