# Homework Assignment 4

#### CSE 151A: Introduction to Machine Learning

Due: May 30th, 2023, 9:30am (Pacific Time)

**Instructions:** Please answer the questions below, attach your code in the document, and insert figures to create a **single PDF** file. You may search information online but you will need to write code/find solutions to answer the questions yourself.

Grade: \_\_\_\_ out of 100 points

## 1 (40 points) Naïve Bayes

In this question, we would like to build a Naïve Bayes model for a classification task. Assume there is a classification dataset  $S = \{(\mathbf{x}^{(i)}, y^{(i)}), i = 1, ..., 8\}$  where each data point  $(\mathbf{x}, y)$  contains a feature vector  $\mathbf{x} = (x_1, x_2, x_3); x_1, x_2, x_3 \in \{0, 1\}$  and a ground-truth label  $y \in \{0, 1\}$ . The dataset S can be read from the table below:

i	$x_1$	$x_2$	$x_3$	y
1	0	0	1	1
2	0	1	1	1
3	1	1	0	1
4	0	0	1	1
5	0	1	0	0
6	1	1	0	0
7	1	0	0	0
8	0	0	1	0

In Naïve Bayes model, we use random variable  $X_i \in \{0, 1\}$  to represent *i*-th dimension of the feature vector  $\mathbf{x}$ , and random variable  $Y \in \{0, 1\}$  to represent the class label y. Thus, we can estimate probabilities P(Y),  $P(X_i|Y)$  and  $P(X_i, Y)$  by counting data points in dataset S, for example:

$$P(Y = 1) = \frac{\#\{\text{data points with } y = 1\}}{\#\{\text{all data points}\}} = \frac{4}{8} = 0.5$$

$$P(X_1 = 1 | Y = 0) = \frac{\#\{\text{data points with } x_1 = 1 \text{ and } y = 0\}}{\#\{\text{data points with } y = 0\}} = \frac{2}{4} = 0.5$$

$$P(X_1 = 1, Y = 1) = P(X_1 = 1 | Y = 1) P(Y = 1)$$

$$= \frac{\#\{\text{data points with } x_1 = 1 \text{ and } y = 1\}}{\#\{\text{all data points}\}} = \frac{1}{8} = 0.125$$

It is noteworthy that **only** probabilities P(Y),  $P(X_i|Y)$  and  $P(X_i,Y)$  can be **directly** estimated from dataset S in Naïve Bayes model. Other joint probabilities (e.g.  $P(X_1, X_2)$  and  $P(X_1, X_2, X_3)$ ) should **not** be estimated by directly counting the data points.

Next, we can use the probabilities P(Y) and  $P(X_i|Y)$  to build our Naïve Bayes model for classification: For a feature vector  $\mathbf{x} = (x_1, x_2, x_3)$ , we can estimate the probability  $P(Y = y|X_1 = x_1, X_2 = x_2, X_3 = x_3)$  with the **conditional independence assumptions**:

$$P(Y = y | X_1 = x_1, X_2 = x_2, X_3 = x_3) = \frac{P(X_1 = x_1, X_2 = x_2, X_3 = x_3, Y = y)}{P(X_1 = x_1, X_2 = x_2, X_3 = x_3)}$$

$$= \frac{P(X_1 = x_1, X_2 = x_2, X_3 = x_3 | Y = y)P(Y = y)}{P(X_1 = x_1, X_2 = x_2, X_3 = x_3)}$$

$$= \frac{\left(\prod_{i=1}^3 P(X_i = x_i | Y = y)\right)P(Y = y)}{P(X_1 = x_1, X_2 = x_2, X_3 = x_3)}$$

where the joint probability  $P(X_1 = x_1, X_2 = x_2, X_3 = x_3)$  can be calculated as:

$$P(X_1 = x_1, X_2 = x_2, X_3 = x_3) = \sum_{y=0}^{1} P(X_1 = x_1, X_2 = x_2, X_3 = x_3, Y = y)$$

$$= \sum_{y=0}^{1} \left( P(X_1 = x_1, X_2 = x_2, X_3 = x_3 | Y = y) P(Y = y) \right)$$

$$= \sum_{y=0}^{1} \left( \left( \prod_{i=1}^{3} P(X_i = x_i | Y = y) \right) P(Y = y) \right)$$

Finally, if we find:

$$P(Y = 1|X_1 = x_1, X_2 = x_2, X_3 = x_3) > P(Y = 0|X_1 = x_1, X_2 = x_2, X_3 = x_3)$$

then we can predict the class of feature vector  $\mathbf{x} = (x_1, x_2, x_3)$  to be 1, otherwise 0. It is noteworthy that although conditional independence assumptions are made in Naïve Bayes model,  $P(Y = 1|X_1 = x_1, X_2 = x_2, X_3 = x_3) + P(Y = 0|X_1 = x_1, X_2 = x_2, X_3 = x_3)$  should still be 1.

1. (15 pts) Please estimate the following probabilities:

(1) 
$$P(X_1 = 1, Y = 0)$$
, (2)  $P(Y = 0)$ , (3)  $P(X_1 = 1|Y = 1)$ .

Note that these probabilities can be directly estimated by counting from dataset S.

$$P(x,=1, y=0) = \frac{2}{8} = \boxed{0.25}$$

$$P(y=0) = \frac{4}{8} = \boxed{0.5}$$

$$P(x,=1|y=1) = \frac{1}{4} = \boxed{0.25}$$

2. (18 pts) Please calculate the probability  $P(Y = 1|X_1 = 1, X_2 = 1, X_3 = 0)$  in Naïve Bayes model using conditional independence assumptions.

$$P(Y=1 \mid X_1=1, X_2=1, X_3=0) = \left( \underbrace{\Pi_{i=1}^3 P(X_i=x_i \mid Y=1)) P(Y=1)}_{P(X_i=x_1, X_2=x_2, X_3=x_3)} \right)$$

$$\left(\mathsf{TT}_{i=1}^{3} P(\mathsf{x}_{i} = \mathsf{x}_{i} \mid \mathsf{Y} = 1)\right) P(\mathsf{Y} = 1) = \left(\frac{1}{4} \cdot \frac{1}{2} \cdot \frac{1}{4}\right) \cdot \frac{1}{2}$$
$$= \frac{1}{64}$$

$$P(X_{i}=x_{1}, X_{2}=x_{2}, X_{3}=x_{3}) = \sum_{q=0}^{1} \left( \left( T_{i=1}^{3} P(X_{i}=x_{i}|Y=y) \right) P(Y=y) \right)$$

$$= \left( \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{3}{4} \right) \cdot \frac{1}{2} + \frac{1}{64} = \frac{7}{64}$$

$$\frac{\left(T_{i=1}^{3} P(x_{i}=x_{i}|y=1)\right) P(y=1)}{P(x_{i}=x_{i}, x_{2}=x_{2}, x_{3}=x_{3})} = \frac{1/64}{7/64} = \boxed{\frac{1}{7}}$$

3. (7 pts) Please calculate the probability  $P(Y = 0|X_1 = 1, X_2 = 1, X_3 = 0)$  in Naïve Bayes model and predict the class of feature vector  $\mathbf{x} = (1, 1, 0)$ .

$$P(Y=0|X_1=1,X_2=1,X_3=0) = \frac{\left(\prod_{i=1}^3 P(X_i=x_i|Y=0)\right)P(Y=0)}{P(X_1=1,X_2=1,X_3=0)}$$

$$=\frac{6/64}{7/64}=\frac{6}{7}$$

$$P(Y=0|X_1=1,X_2=1,X_3=0) = \frac{6}{7} > P(Y=1|X_1=1,X_2=1,X_3=0) = \frac{1}{7}$$

$$x: y = 0$$

### 2 (40 points) Decision Tree

In this question, we would like to create a decision tree model for a binary classification task. Assume there is a classification dataset  $T = \{(\mathbf{x}^{(i)}, y^{(i)}), i = 1, ..., 5\}$  where each data point  $(\mathbf{x}, y)$  contains a feature vector  $\mathbf{x} = (x_1, x_2) \in \mathbb{R}^2$  and a ground-truth label  $y \in \{0, 1\}$ . The dataset T can be read from the table below:

i	$x_1$	$x_2$	y
1	1.0	2.0	1
2	2.0	2.0	1
3	3.0	2.0	0
4	2.0	3.0	0
5	1.0	3.0	0

To build the decision tree model, we use a simplified CART algorithm, which is a recursive procedure as follows:

- Initialize a root node with dataset T and set it as current node.
- Start a procedure for current node:
  - Step 1: Assume the dataset in current node is  $T_{\text{cur}}$ . Check if all data points in  $T_{\text{cur}}$  are in the same class:
    - \* If it is true, set current node as a leaf node to predict the common class in  $T_{\text{cur}}$ , and then terminate current procedure.
    - \* If it is false, continue the procedure.
  - Step 2: Traverse all possible splitting rules. Each splitting rule is represented by a vector (j,t), which compares feature  $x_j$  and threshold t to split the dataset  $T_{\text{cur}}$  into two subsets  $T_1, T_2$ :

$$T_1 = \{(\mathbf{x}, y) \in T_{\text{cur}} \text{ where } x_j \leq t\},\$$
  
 $T_2 = \{(\mathbf{x}, y) \in T_{\text{cur}} \text{ where } x_j > t\}.$ 

We will traverse the rules over all feature dimensions  $j \in \{0, 1\}$  and thresholds  $t \in \{x_j | (\mathbf{x}, y) \in T_{\text{cur}}\}.$ 

- Step 3: Decide the best splitting rule. The best splitting rule  $(j^*, t^*)$  minimizes the weighted sum of Gini indices of  $T_1, T_2$ :

$$(j^*, t^*) = \arg\min_{j,t} \frac{|T_1|\operatorname{Gini}(T_1) + |T_2|\operatorname{Gini}(T_2)}{|T_1| + |T_2|}$$

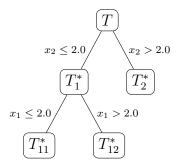
where the  $Gini(\cdot)$  is defined as:

$$Gini(T_i) = 1 - \sum_{y=0}^{1} P(Y = y)^2,$$

$$P(Y = y) = \frac{\#\{\text{data points with label } y \text{ in } T_i\}}{\#\{\text{data points in } T_i\}}.$$

- **Step 4**: We split the dataset  $T_{\text{cur}}$  into two subsets  $T_1^*, T_2^*$  following the best splitting rule  $(j^*, t^*)$ . Then we set current node as a *branch* node and create child nodes with the subsets  $T_1^*, T_2^*$  respectively. For each child node, start from **Step 1** again recursively.

If we run the above decision tree building procedure on dataset T and find the generated tree is shown below:



Please answer the questions:

1. (16 pts) Calculate the subsets  $T_1^*, T_2^*, T_{11}^*, T_{12}^*$  using the given decision tree.

$$T_{1}^{\times} = \left\{ \left( \chi^{(1)}, q^{(1)} \right), \left( \chi^{(2)}, q^{(1)} \right), \left( \chi^{(3)}, q^{(0)} \right) \right\}$$

$$T_{2}^{\times} = \left\{ \left( \chi^{(4)}, q^{(0)} \right), \left( \chi^{(5)}, q^{(0)} \right) \right\}$$

$$T_{11}^{\times} = \left\{ \left( \chi^{(1)}, q^{(1)} \right), \left( \chi^{(2)}, q^{(1)} \right) \right\}$$

$$T_{12}^{\times} = \left\{ \left( \chi^{(2)}, q^{(0)} \right) \right\}$$

2. (12 pts) Calculate  $Gini(T_1^*)$  and  $Gini(T_2^*)$ .

Gini 
$$(T,^*) = 1 - \sum_{y=0}^{l} \rho(y=y)^2$$
  
=  $1 - \left[ \left( \frac{1}{3} \right)^2 + \left( \frac{2}{3} \right)^2 \right]$   
=  $1 - \left[ \frac{1}{9} + \frac{4}{9} \right] = \left[ \frac{4}{9} \right]$ 

Gini 
$$(T_2^*) = 1 - \sum_{y=0}^{1} P(y=y)^2$$
  
=  $1 - [(1)^2 + (0)^2]$   
=  $0$ 

- 3. (12 pts) With the given tree, we can predict the class of a feature vector  $\mathbf{x} = (x_1, x_2)$ :
  - Start from the root node of the tree:
    - **Step 1**: If current node is a *branch* node, we evaluate conditions on branch edges with  $\mathbf{x}$ , choose the satisfied branch to go through, and repeat **Step 1**.
    - **Step 2**: If current node is a *leaf* node, the common class of the subset in the leaf node will be used as prediction.

Please predict the following feature vectors using the given tree:

- $(1) \mathbf{x} = (2, 1),$
- $(2) \mathbf{x} = (3, 1),$
- $(3) \mathbf{x} = (3,3).$

$$x_1 \rightarrow T_{11}^* \rightarrow y^{-1}$$

$$x_2 \rightarrow T_{12}^* \rightarrow y^{-0}$$

$$x_3 \rightarrow T_2^* \rightarrow y^{-0}$$

4. (Bonus Question, 10 pts extra) In this question, you need to implement the decision tree algorithm. Please download the Jupyter notebook HW4\_Decision\_Tree.ipynb and fill in the blanks. Note that since the same dataset T is used in the notebook, you can use the code to check if your previous answers are correct or not. Please attach your code and results in Gradescope submission.

#### Part I. Implement a decision tree algorithm and make predictions.

```
In [ ]: import numpy as np
In [ ]: class TreeNode:
            """ Node class in the decision tree. """
            def __init__(self, T):
                self.type = 'leaf' # Type of current node. Could be 'leaf' or 'branch' (at default: 'leaf').
                self.left = None # Left branch of the tree (for leaf node, it is None).
                self.right = None # Right branch of the tree (for leaf node, it is None).
                self.dataset = T # Dataset of current node, which is a tuple (X, Y).
                                   # X is the feature array and Y is the label vector.
            def set_as_leaf(self, common_class):
                 """ Set current node as leaf node. """
                self.type = 'leaf'
                self.left = None
                self.right = None
                self.common_class = common_class
            def set_as_branch(self, left_node, right_node, split_rule):
                """ Set current node as branch node. """
                self.type = 'branch'
                self.left = left_node
                self.right = right_node
                # split_rule should be a tuple (j, t).
                # When x_j \ll t, it goes to left branch.
                    When x_j > t, it goes to right branch.
                self.split_rule = split_rule
In [ ]: # Prepare for dataset.
        def get_dataset():
            X = np.array(
                [[1.0, 2.0],
                 [2.0, 2.0],
                 [3.0, 2.0],
                  [2.0, 3.0],
                 [1.0, 3.0]
                1)
            Y = np.array(
                [1,
                 1,
                 0,
                 0.
                 0])
            T = (X, Y) # The dataset T is a tuple of feature array X and label vector Y.
            return T
        T = get_dataset()
        In this part, you are required to implement the decision tree algorithm shown in the problem description of Q2 in HW4:
```

The 4 steps are marked in comments of the following code. Please fill in the missing blanks (e.g. "...") in the TODOs:

```
In [ ]: # Initialization.
       root_node = TreeNode(T)
In [ ]: # Procedure for current node.
       def build_decision_tree_procedure(node_cur, depth=0):
          # Step 1. Check if all data points in T_cur are in the same class
           #
                   - If it is true, set current node as a *leaf node* to predict the common class in T_cur,
           #
                    and then terminate current procedure.
                    - If it is false, continue the procedure.
           T_cur = node_cur.dataset
           X_cur, Y_cur = T_cur # Get current feature array X_cur and label vector Y_cur.
           if (Y_cur == 1).all():
               print(' ' * depth + '+-> leaf node (predict 1).')
                      print('
              print('
                                          samples: {}'.format(len(X_cur)))
              node_cur.set_as_leaf(1)
               return
           elif (Y_cur == 0).all():
              ' * depth + '+-> leaf node (predict 0).')
                                       Gini: {:.3T} ...ormac(cor)
samples: {}'.format(len(X_cur)))
                                         Gini: {:.3f}'.format(Gini(T_cur)))
               print(' ' * depth + '
               node_cur.set_as_leaf(0)
```

```
# Step 2. Traverse all possible splitting rules.
             – We will traverse the rules over all feature dimensions j in \{0,\ 1\} and
              thresholds t in X_{cur}[:, j] (i.e. all x_{-}j in current feature array X_{-}cur).
   all_rules = []
   #### TODO 1 STARTS ###
   # Please traverse the rules over all feature dimensions j in {0, 1} and
   # thresholds t in X_cur[:, j] (i.e. all x_j in current feature array X_cur),
      and save all rules in all_rules variable.
   # The all_rules variable should be a list of tuples such as [(0, 1.0), (0, 2.0), \ldots]
   for j in (0,1):
       for t in X_cur[:,j]:
           all_rules.append((j,t))
   #### TODO 1 ENDS ###
   # print('All rules:', all_rules) # Code for debugging.
   # Step 3. Decide the best splitting rule.
   best_rule = (_, _)
   best_weighted_sum = 1.0
   for (j, t) in all_rules:
       #### TODO 2 STARTS ###
       # For each splitting rule (j, t), we use it to split the dataset T_cur into T1 and T2.
       # Hint: You may refer to Step 4 to understand how to set inds1, X1, Y1, len_T1 and inds2, X2, Y2, len_T2.
       # - Create subset T1.
       inds1 = [x for x in range(len(T_cur[0])) if T_cur[0][x][j] <= t]</pre>
                                                                                      # Indices vector for those data points with
       X1 = [T_cur[0][i] for i in inds1]
                                                          # Feature array with inds1 in X_cur.
       Y1 = [T_cur[1][i] for i in inds1]
                                                          # Label vector with inds1 in Y_cur.
       T1 = (X1, Y1)
                          # Subset T1 contains feature array and label vector.
       len_T1 = len(X1)
                                      # Size of subset T1.
       # - Create subset T2.
       inds2 = [x for x in range(len(T_cur[0])) if T_cur[0][x][j] > t]
                                                                                      # Indices vector for those data points with
                                                          # Feature array with inds2 in X_cur.
       X2 = [T_cur[0][i]  for i  in inds2]
       Y2 = [T_cur[1][i] for i in inds2]
                                                          # Label vector with inds2 in Y_cur.
                             # Subset T2 contains feature array and label vector.
       T2 = (X2, Y2)
       len_T2 = len(X2)
                                     # Size of subset T2.
       #### TODO 2 ENDS ###
       # Calculate weighted sum and try to find the best one.
       weighted_sum = (len_T1*Gini(T1) + len_T2*Gini(T2)) / (len_T1 + len_T2)
       # print('Rule:', (j, t), 'len_T1, len_T2:', len_T1, len_T2, 'weighted_sum:', weighted_sum) # Code for debugging.
       if weighted_sum < best_weighted_sum:</pre>
           #### TODO 3 STARTS ####
           # Update the best rule and best weighted sum with current ones.
           best_rule = (j,t)
           best_weighted_sum = weighted_sum
           #### TODO 3 ENDS ####
   # Step 4. - We split the dataset T_cur into two subsets best_T1, best_T2 following
                   the best splitting rule (best_j, best_t).
   #
             - Then we set current node as a *branch* node and create child nodes with
   #
                  the subsets best_T1, best_T2 respectively.
             - For each child node, start from *Step 1* again recursively.
   best_j, best_t = best_rule
   # - Create subset best_T1 and corresponding child node.
   best_inds1 = X_cur[:,best_j] <= best_t</pre>
   best_X1 = X_cur[best_inds1]
   best_Y1 = Y_cur[best_inds1]
   best_T1 = (best_X1, best_Y1)
   node1 = TreeNode(best_T1)
   # - Create subset best T2 and corresponding child node.
   best_inds2 = X_cur[:,best_j] > best_t
   best_X2 = X_cur[best_inds2]
   best_Y2 = Y_cur[best_inds2]
   best_T2 = (best_X2, best_Y2)
   node2 = TreeNode(best_T2)
   # - Set current node as branch node and create child nodes.
   node_cur.set_as_branch(left_node=node1, right_node=node2, split_rule=best_rule)
   print(' ' * depth + '+-> branch node')
             ' * depth + '
   print('
                               Gini: {:.3f}'.format(Gini(T_cur)))
            ' * depth + '
   print('
                                samples: {}'.format(len(X_cur)))
   # - For each child node, start from Step 1 again recursively.
   print(' '* (depth + 1) + '| \rightarrow left branch: x_{{}} <= {} (with {} data point(s)).'.format(best_j, best_t, len(best_X1)))
   build_decision_tree_procedure(node1, depth+1) # Note: The depth is only used for logging.
   build_decision_tree_procedure(node2, depth+1)
def Gini(Ti):
   """ Calculate the Gini index given dataset Ti. """
```

```
Xi, Yi = Ti  # Get the feature array Xi and label vector Yi.
if len(Yi) == 0:  # If the dataset Ti is empty, it simply returns 0.
    return 0

#### TODO 4 STARTS ###

# Implement the Gini index function.
P_Y1 = len([x for x in Yi if x == 1]) / len(Yi)  # Estimate probability P(Y=1) in Yi
P_Y0 = len([x for x in Yi if x == 0]) / len(Yi)  # Estimate probability P(Y=0) in Yi
Gini_Ti = 1 - (P_Y1 ** 2) - (P_Y0 ** 2)  # Calculate Gini index: Gini_Ti = 1 - P(Y=1)^2 - P(Y=0)^2
#### TODO 4 ENDS ###
return Gini_Ti
```

After you finish the above code blank filling, you can use the following code to build the decision tree. The following code also shows the structure of the tree.

```
# If your code is correct, you should output:
        # +-> branch node
        #
                Gini: 0.480
        #
                samples: 5
               \mid -> left branch: x_1 <= 2.0 (with 3 data point(s)).
        #
        #
              +-> branch node
        #
                   Gini: 0.444
        #
                    samples: 3
              . . . . .
        # You can also use the sklearn results to validate your decision tree
        # (the threshold could be slightly different but the structure of the tree should be the same).
       +-> branch node
             Gini: 0.480
             samples: 5
           \mid - \rangle left branch: x_1 \le 2.0 (with 3 data point(s)).
           +-> branch node
                 Gini: 0.444
                 samples: 3
               \mid - \rangle left branch: x_0 \ll 2.0 (with 2 data point(s)).
               +-> leaf node (predict 1).
                     Gini: 0.000
                     samples: 2
               |-> right branch: x_0 > 2.0 (with 1 data point(s)).
               +-> leaf node (predict 0).
                     Gini: 0.000
                      samples: 1
           |-> right branch: x_1 > 2.0 (with 2 data point(s)).
           +-> leaf node (predict 0).
                 Gini: 0.000
                 samples: 2
        With the obtained decision tree, you can predict the class of new feature vectors:
In [ ]: def decision_tree_predict(node_cur, x):
             if node_cur.type == 'leaf':
                 return node_cur.common_class
             else:
                 j, t = node_cur.split_rule
                 if x[j] <= t:
                    return decision_tree_predict(node_cur.left, x)
                 else:
                     return decision_tree_predict(node_cur.right, x)
In []: for x in [(2,1), (3,1), (3,3)]:
            y_pred = decision_tree_predict(root_node, x)
             print('Prediction of {} is {}'.format(x, y_pred))
```

#### Part II. Use Scikit-learn to build the tree and make predictions.

In []: # Build the decision tree.

Prediction of (2, 1) is 1 Prediction of (3, 1) is 0 Prediction of (3, 3) is 0

build\_decision\_tree\_procedure(root\_node)

The following code uses Scikit-learn to build the decision tree. You can use it to check if your previous implementation is correct or not.

```
In []: # Ref: https://scikit-learn.org/stable/modules/tree.html#tree-algorithms-id3-c4-5-c5-0-and-cart
    from sklearn import tree
X, Y = T
    clf = tree.DecisionTreeClassifier()
    clf = clf.fit(X, Y)
```

The following code illustrates the obtained decision tree. It should have same structure and similar rules compared with the tree in your own implementation.

```
In [ ]: # Plotting the tree.
      tree.plot_tree(clf)
Out[]: [Text(0.6, 0.83333333333333333, 'X[1] \le 2.5 \neq 0.48 = 0.48 = 5 = 5 = [3, 2]'),
       Text(0.4, 0.5, 'X[0] \le 2.5 \cdot gini = 0.444 \cdot samples = 3 \cdot value = [1, 2]'),
      Text(0.8, 0.5, 'gini = 0.0\nsamples = 2\nvalue = [2, 0]')]
                           X[1] <= 2.5
                           gini = 0.48
                           samples = 5
                          value = [3, 2]
                 X[0] <= 2.5
                                      gini = 0.0
                 gini = 0.444
                                    samples = 2
                 samples = 3
                                   value = [2, 0]
                value = [1, 2]
         gini = 0.0
                            gini = 0.0
       samples = 2
                           samples = 1
       value = [0, 2]
                          value = [1, 0]
```

Prediction of (3, 3) is 0

The following code makes the predictions using the obtained decision tree. It should have identical results as the ones for your own implementaion.

```
In []: # Predict the class.
    for x in [(2,1), (3,1), (3,3)]:
        y_pred = clf.predict(np.array([x]))[0]
        print('Prediction of {} is {}'.format(x, y_pred))

Prediction of (2, 1) is 1
Prediction of (3, 1) is 0
```

## 3 (20 points) Bagging and Boosting

Assume we obtain T linear classifiers  $\{h_t, t = 1, ..., T\}$  where each classifier  $h : \mathbb{R}^2 \to \{+1, -1\}$  predicts the class  $\hat{y} \in \{+1, -1\}$  with given feature vector  $\mathbf{x} = (x_1, x_2)$  as follows:

$$\hat{y} = h(\mathbf{x}) = \operatorname{sign}(w_1 x_1 + w_2 x_2 + b) \quad \text{where} \quad \operatorname{sign}(a) = \begin{cases} +1 & \text{if } a \ge 0, \\ -1 & \text{if } a < 0. \end{cases}$$

where  $w_1, w_2, b \in \mathbb{R}$  are the parameters.

• In a bagging model  $H_{\text{bagging}}$  of the T linear classifiers, we calculate the average prediction using classifiers  $\{h_t\}$ , and then use it to predict the class  $\hat{y}_{\text{bagging}}$ :

$$\hat{y}_{\text{bagging}} = H_{\text{bagging}}(\mathbf{x}) = \text{sign}\left(\frac{1}{T}\sum_{t=1}^{T} h_t(\mathbf{x})\right)$$

• In a boosting model  $H_{\text{boosting}}$  of the T linear classifiers, we calculate the weighted sum of predictions using classifiers  $\{h_t\}$ , and then use it to predict the class  $\hat{y}_{\text{boosting}}$ :

$$\hat{y}_{\text{boosting}} = H_{\text{boosting}}(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^{T} \alpha_t h_t(\mathbf{x})\right)$$

where  $\{\alpha_t, t = 1, ..., T\}$  are the weight coefficients.

In this problem, suppose we have 3 linear classifiers (i.e. T=3):

$$h_1(\mathbf{x}) = \operatorname{sign}(x_1 + x_2 + 1), \quad h_2(\mathbf{x}) = \operatorname{sign}(x_1 - x_2), \quad h_3(\mathbf{x}) = \operatorname{sign}(x_1 - 2x_2 + 1).$$

Please answer the questions below:

1. (10 pts) Please calculate the  $\hat{y}_{\text{bagging}}$  of feature vector  $\mathbf{x} = (1, 2)$  using bagging on these three classifiers.

$$\hat{y}_{bagg:ng} = sign\left(\frac{1}{3}\sum_{t=1}^{3}h_{t}(x)\right)$$

$$= sign\left(\frac{1}{3}\left(1+(-1)+(-1)\right)\right)$$

$$= \boxed{-1}$$

2. (10 pts) Please calculate the  $\hat{y}_{\text{boosting}}$  of feature vector  $\mathbf{x} = (1,2)$  using boosting on these three classifiers. The weight coefficients are  $\alpha_1 = 0.8, \ \alpha_2 = 0.2, \ \alpha_3 = 0.3$ .

$$\hat{y} \text{ boosting} = \text{sign} \left( \sum_{t=1}^{3} \alpha_t h_t(x) \right)$$

$$= \text{sign} \left( 0.8(4) + 0.2(-1) + 0.3(-1) \right)$$

$$= +1$$