Module 2: Transmission Lines

Lecture 6: Loss Less Transmission Line

Objectives

In this course you will learn the following

- What is a loss-less transmission line?
- Variation of voltage and current on a loss less line.
- Standing waves on a loss-less line.
- Voltage standing wave ratio (VSWR) and its relation to the voltage reflection co-efficient.
- Importance of VSWR and its values for various impedances.
- Concept of return-loss (RL). Return loss a measure of reflection on the line.

Analysis of Loss Less Transmission Line

In any electrical circuit the power loss is due to ohmic elements. A loss less transmission line therefore implies R=0 and G=0. For a loss less transmission line hence we get

Propagation constant:

$$\gamma = \sqrt{j\omega L j\omega C} = j\omega \sqrt{LC}$$
 = Purely imaginary

That is, $\alpha \equiv 0$ and $\beta = \omega \sqrt{LC}$.

The charateristic impedance

$$Z_0 = \sqrt{\frac{j\omega L}{j\omega C}} = \sqrt{\frac{L}{C}} = \text{Purely real}$$

■ The reflection coefficient at any point on the line is

$$\Gamma(l) = \Gamma_{I}e^{-j2\beta l} = \left(\frac{Z_{I} - Z_{0}}{Z_{I} + Z_{0}}\right)e^{-j2\beta l}$$

The voltage and current expressions become

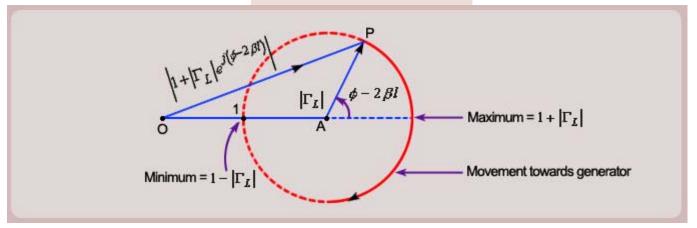
$$\begin{split} V(l) &= V^+ e^{j\beta l} \left\{ 1 + \Gamma_L e^{-j2\beta l} \right\} \\ I(l) &= \frac{V^+}{Z_0} e^{j\beta l} \left\{ 1 - \Gamma_L e^{-j2\beta l} \right\} \end{split}$$

■ Let the reflection coefficient at the load end be written in the amplitude and phase form as

$$\Gamma_L \,=\, |\Gamma_L| e^{j\phi}$$

then we have

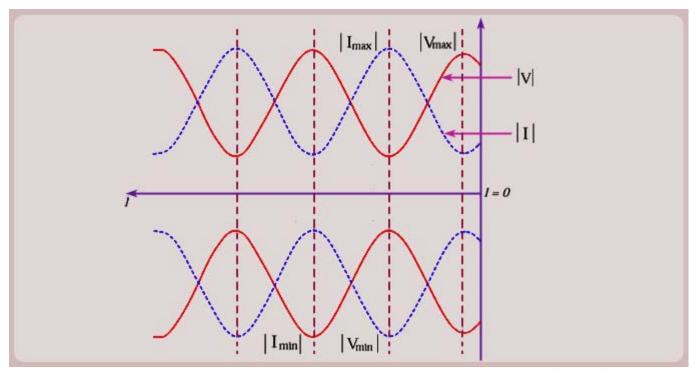
$$\begin{split} V(l) &= V^+ e^{j\beta l} \left\{ 1 + |\Gamma_L| e^{j(\phi-2\beta l)} \right\} \\ I(l) &= \frac{V^+}{Z_0} e^{j\beta l} \left\{ 1 - |\Gamma_L| e^{j(\phi-2\beta l)} \right\} \end{split}$$



As we move towards the generator the phase $(\phi - 2\beta l)$ becomes more negative and point P rotates clockwise on the dotted circle. The radius of the circle is $|\Gamma_L|$. Length of the vector OP gives the magnitude of the quantity $(1 + |\Gamma_L| e^{j(\phi - 2\beta l)})$

Spatial Variation of Current & Voltage

The previous equations indicate that the amplitudes of the voltage and current vary as a function of distance on the line.



- Wherever $\phi 2\beta l = 0$ or even multiple of π , the quantity in the brackets is maximum $\left(1 + \left|\Gamma_L\right|\right)$ in the voltage expression, and minimum $\left(1 \left|\Gamma_L\right|\right)$ in the current expression. That is wherever the voltage amplitude is maximum, the current amplitude is minimum.
- Similarly wherever $\phi 2\beta l = 0$ dd multiple of π , the voltage is minimum and the current is maximum

Note

The voltage and current variation at every point on the line is $e^{j\omega t}$ only.

■ The distance between two adjacent voltage maxima (or minima) or two adjacent current maxima (or minima) corresponds to

$$2\beta l = 2\pi$$

$$\Rightarrow 2 \cdot \frac{2\pi}{\lambda} l = 2\pi$$

$$l = \frac{\lambda}{2}$$

■ The distance between adjacent voltage and current maxima or minima corresponds to

$$2\beta l = \pi$$
$$\Rightarrow l = \frac{\lambda}{4}$$

■ We then say that the voltage and current are in space quardrature, i.e, when voltage is maximum the current is minimum and vice versa.

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Voltage Standing Wave Ratio

■ The maximum and minimum peak voltages measured on the line are

$$\left| \begin{array}{c} \left| \begin{array}{c} V \end{array} \right|_{\max} = \left| \begin{array}{c} V^+ \end{array} \right| \left(1 + \left| \Gamma_L \right| \right) \\ \left| \begin{array}{c} V \end{array} \right|_{\min} = \left| \begin{array}{c} V^+ \end{array} \right| \left(1 - \left| \Gamma_L \right| \right) \\ \end{array}$$

Let us define a quantity called 'Voltage Standing Wave Ratio (VSWR) ' as

$$\rho = \frac{|V|_{\text{max}}}{|V|_{\text{min}}}$$

Substituting for $\left| V \right|_{\max}$ and $\left| V \right|_{\min}$ we get

$$\rho = \frac{1 + |\Gamma_L|}{1 - |\Gamma_L|}$$
 or
$$|\Gamma_L| = \frac{\rho - 1}{\rho + 1}$$

- The VSWR is a measure of the reflection on the line. Higher the value of VSWR, higher is $|\Gamma_L|$ i.e., higher is the reflection and is lesser the power transfer to the load.
- Since $0 \le \left| \Gamma_L \right| \le 1$, we get

$$1 \le \rho \le \infty$$

VSWR of 1 corresponds to the $\left|\Gamma_L\right|=0$. That is the best situation.

Ideally for a perfect match VSWR = 1. However, generally a VSWR ≤ 2 is considered acceptable in all experimental works.

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Return Loss & Reflection Co-efficient

The return loss is defined as

Return loss (RL) = -20 log
$$|\Gamma_L|$$
 dB

- The return loss indicates the factor by which the reflected signal is down compared to the incident signal.
- For perfect match $\left|\Gamma_L\right|=0$ and the return loss is ∞ , whereas for the worst case of $\left|\Gamma_L\right|=1$ the return loss is 0 dB
- Higher the return loss better is the match.

For acceptable value of VSWR = 2,

$$\left|\Gamma_L\right| = \frac{\text{VSWR} - 1}{\text{VSWR} + 1} = \frac{2 \cdot 1}{2 + 1} = \frac{1}{3}$$

$$\Rightarrow \text{Return Loss RL} = -20 \log (1/3)$$

$$= 9.54$$

The return loss should be higher than 9.54

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Recap

In this course you have learnt the following

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