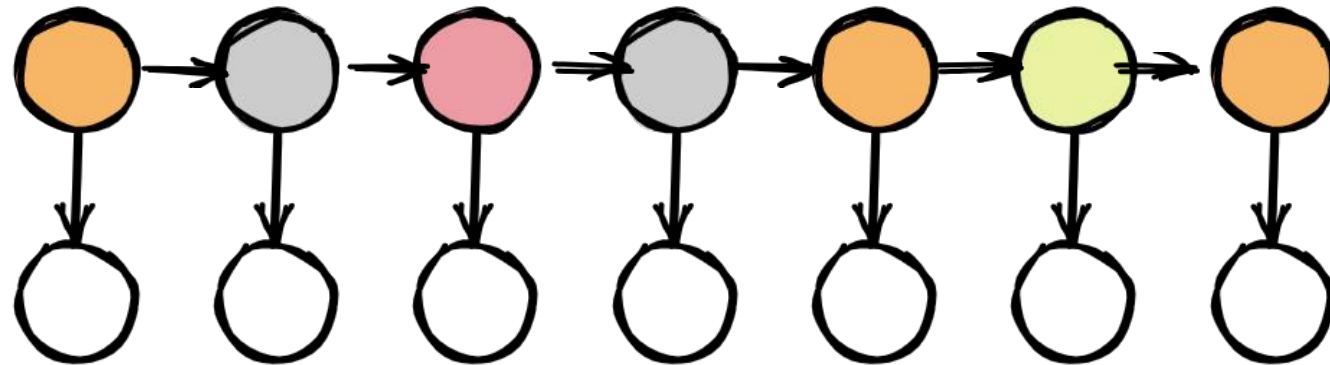


Hidden Markov Models and Sequence Data



Week 18

Middlesex University Dubai; CST4050 Fall21;
Instructor: Dr. Ivan Reznikov

Plan

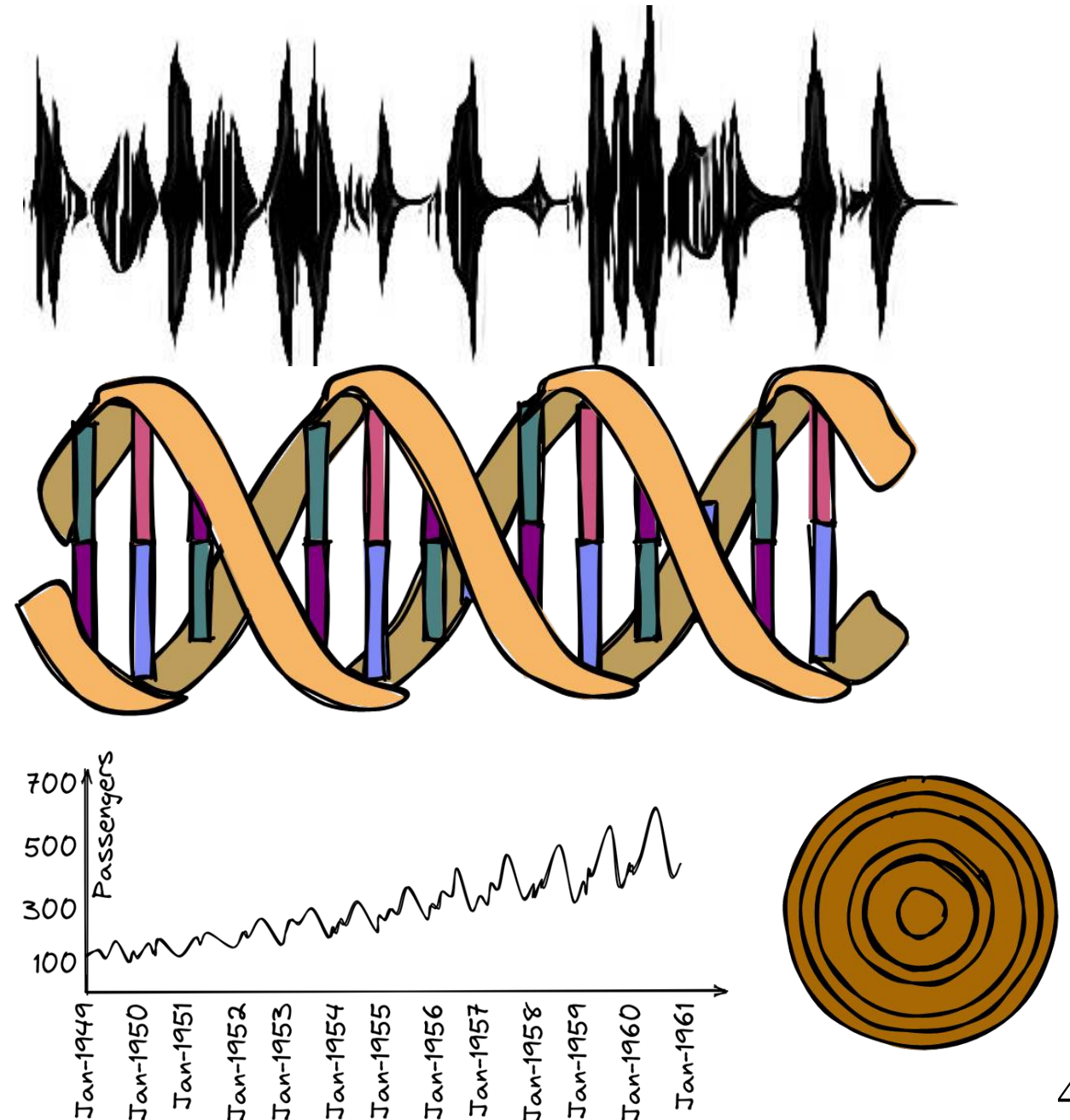
- Sequential Data
- Sequential Labeling
- Bayesian Networks
- Mixture Models
- Markov assumption
- Hidden Markov Model

What is sequence data?

- Ordered set of elements: $x = x_1, x_2, \dots, x_N$
- Order determined by time or position and could be regular or irregular
- Each element x_i could be
 - Numerical (sales, stock price, etc.)
 - Categorical (weather, part-of-speech)
 - Multiple attributes
- The length N of a sequence isn't fixed

Examples of sequence data

- Speech (sequence of phonemes)
- Language-related (sequence of words)
- Bioinformatics (genes – sequence of 4 possible nucleotides and proteins – sequence of 20 possible amino-acids)
- Telecommunications (sequence of data packets)
- Time series (sequence of events per time)
- ...



Sequence labeling

Address:

221B Baker Street, London, UK

House number	Street
City	Country

Citation:

Pauling, L. (1931). The nature of the chemical bond. II. The one-electron bond and the three-electron bond. Journal of the American Chemical Society, 53(9), 3225-3237.

Author	Year
Article title	Journal
Journal number	
Volume	Pages

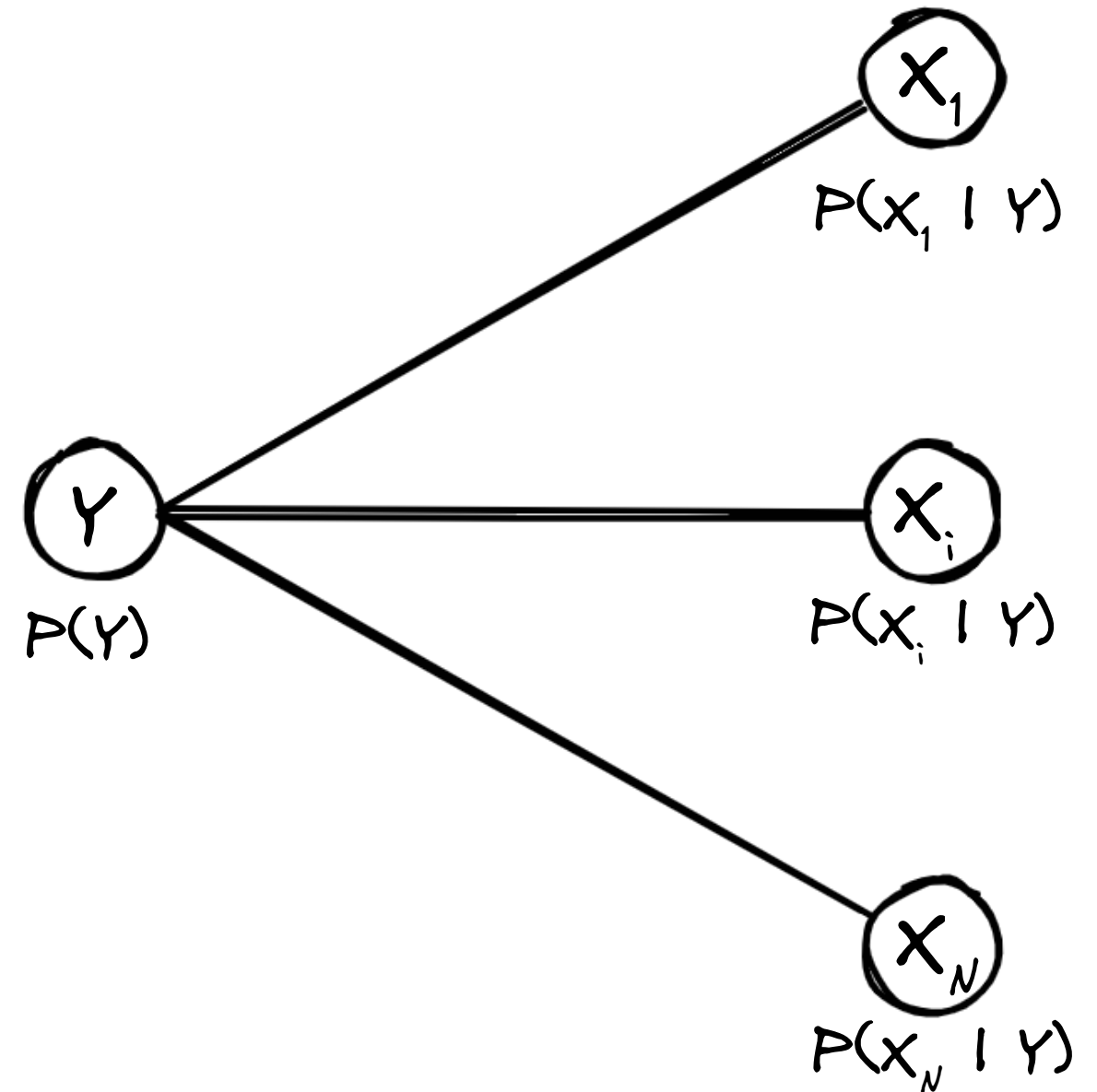
Input: a sequence $x = (x_1, \dots, x_n)$

Output: a sequence $y = (y_1, \dots, y_n)$, where y_i is a label for x_i

Graphical model

Let's assume we have a condition Y .
There are several X , that can occur with Y happening. We can draw represent our graph as a probability tree:

- Edges showing dependencies
- Each node has associated conditional
- Probability distribution, conditioned on its parent nodes
- Nodes are independent



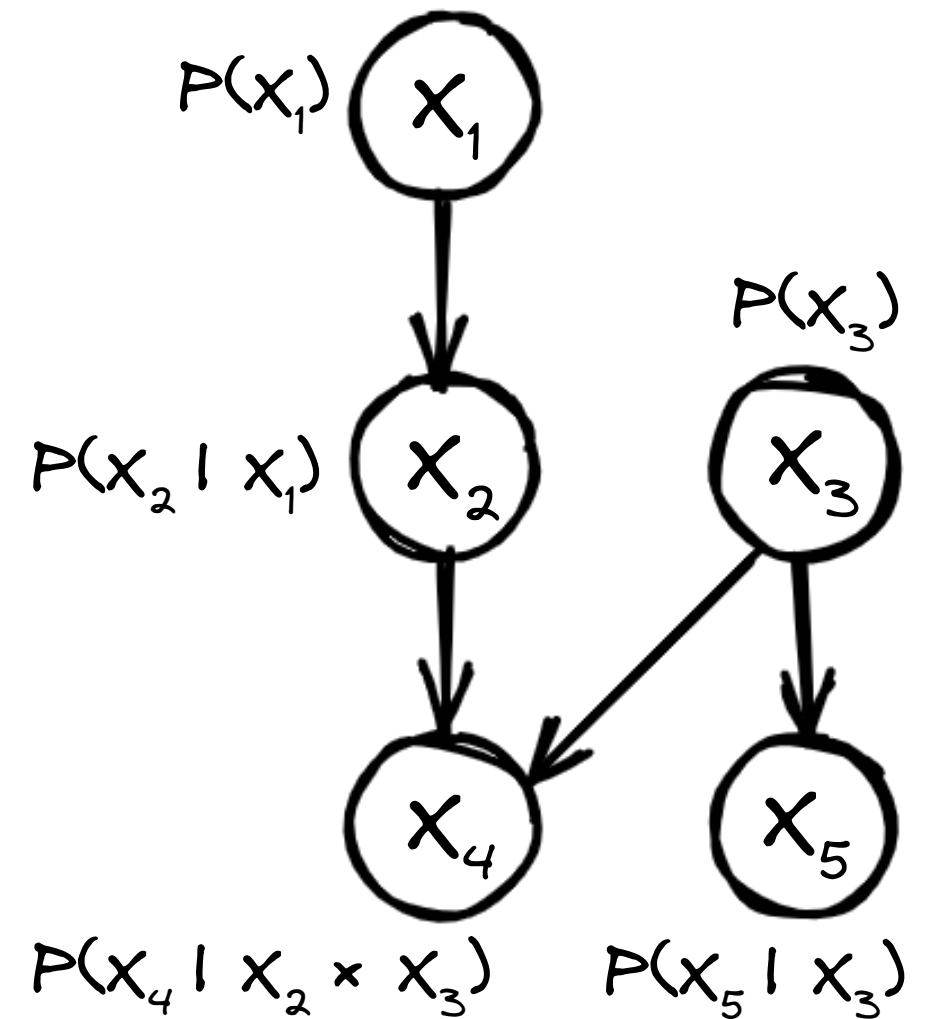
$$P(X_1, X_2, \dots, X_N, Y) = P(X_1 | Y) \times P(X_2 | Y) \dots P(X_N | Y) \times P(Y)$$

Graphical model

Let's now draw a directed graph out of 5 nodes.

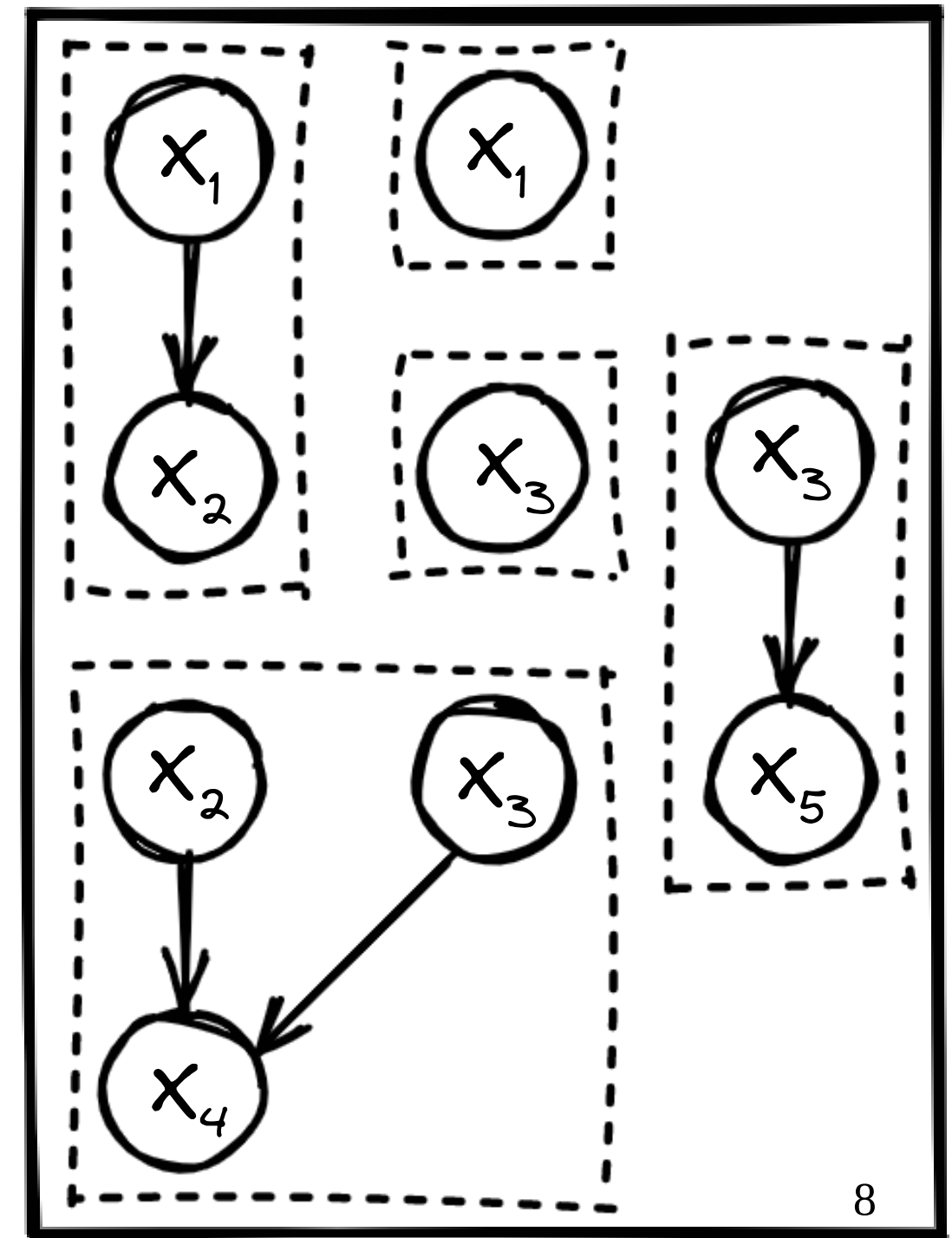
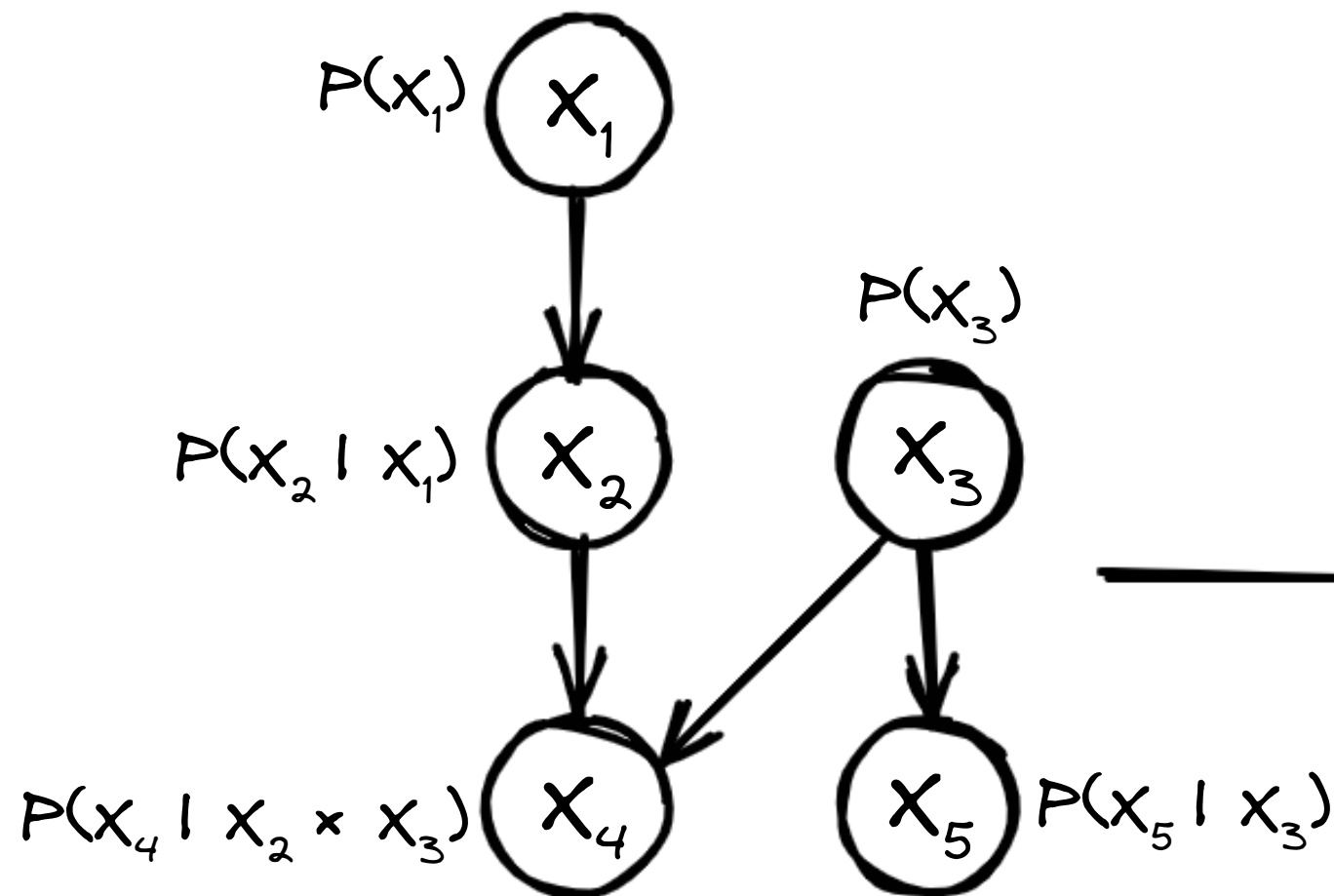
$$P(X_1 X_2 X_3 X_4 X_5) = P(X_5 | X_3) \times \\ \times P(X_4 | X_2 \times X_3) \times P(X_2 | X_1) \times \\ \times P(X_3) \times P(X_1)$$

conditional distributions
marginal distributions



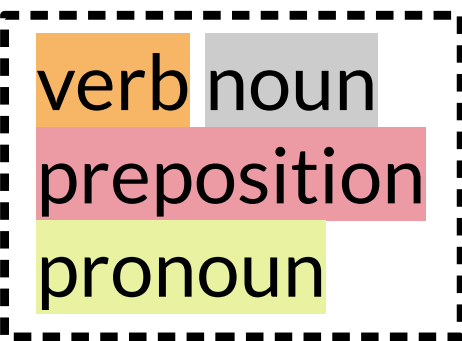
Bayesian Networks

Learning this Bayesian network is equivalent to learning 5 small/simple independent networks from the same data:

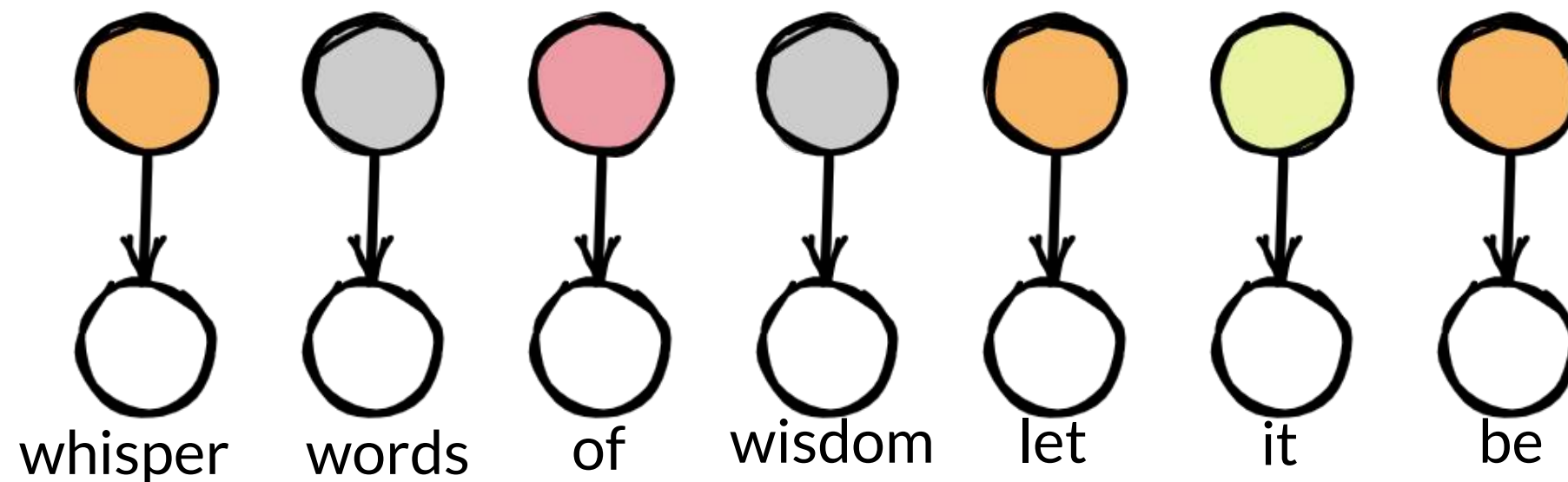


Mixture model

whisper words of wisdom let it be



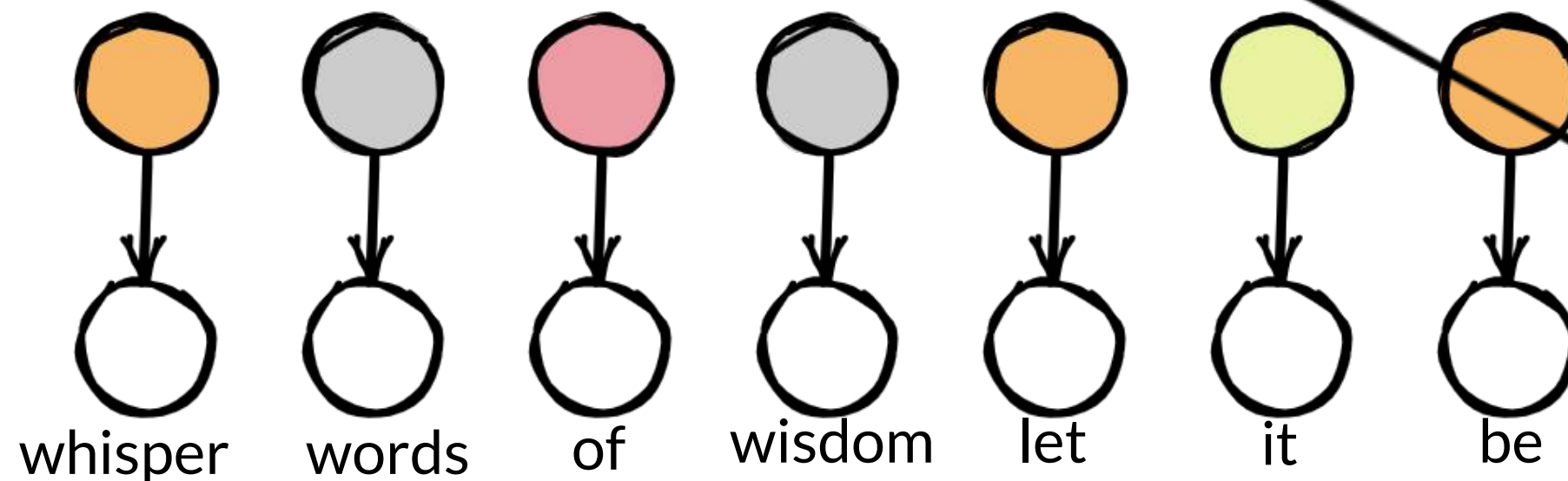
$$\begin{aligned} P(y, x) &= P(\text{verb, noun, preposition, noun, verb,} \\ &\quad \text{pronoun, verb, whisper, words, of, wisdom, let,} \\ &\quad \text{it, be}) = P(\text{verb, whisper}) \times P(\text{noun, words}) \times \\ &\quad \times \dots \\ &= P(\text{whisper} \mid \text{verb}) \times P(\text{verb}) \times \\ &\quad \times P(\text{words} \mid \text{noun}) \times P(\text{noun}) \times \\ &\quad \times \dots \end{aligned}$$



Mixture model

whisper words of wisdom let it be

	whispers	words	of	wisdom	let	it	be
verb (0.35)	<u>0.7</u>	0.2	0.1	0.05	<u>0.6</u>	0.0	<u>0.9</u>
noun (0.4)	0.3	<u>0.7</u>	0.1	<u>0.85</u>	0.3	0.15	0.0
prep (0.15)	0.0	0.0	<u>0.7</u>	0.0	0.05	0.1	0.1
pronoun (0.1)	0.0	0.1	0.1	0.1	0.05	<u>0.65</u>	0.0



$$P(y, x) = P(\text{verb, noun, preposition, noun, verb, pronoun, verb, whisper, words, of, wisdom, let, it, be}) = P(\text{verb, whisper}) \times P(\text{noun, words}) \times$$

$\times \dots$

$$= P(\text{whisper} \mid \text{verb}) \times P(\text{verb}) \times P(\text{words} \mid \text{noun}) \times P(\text{noun}) \times$$

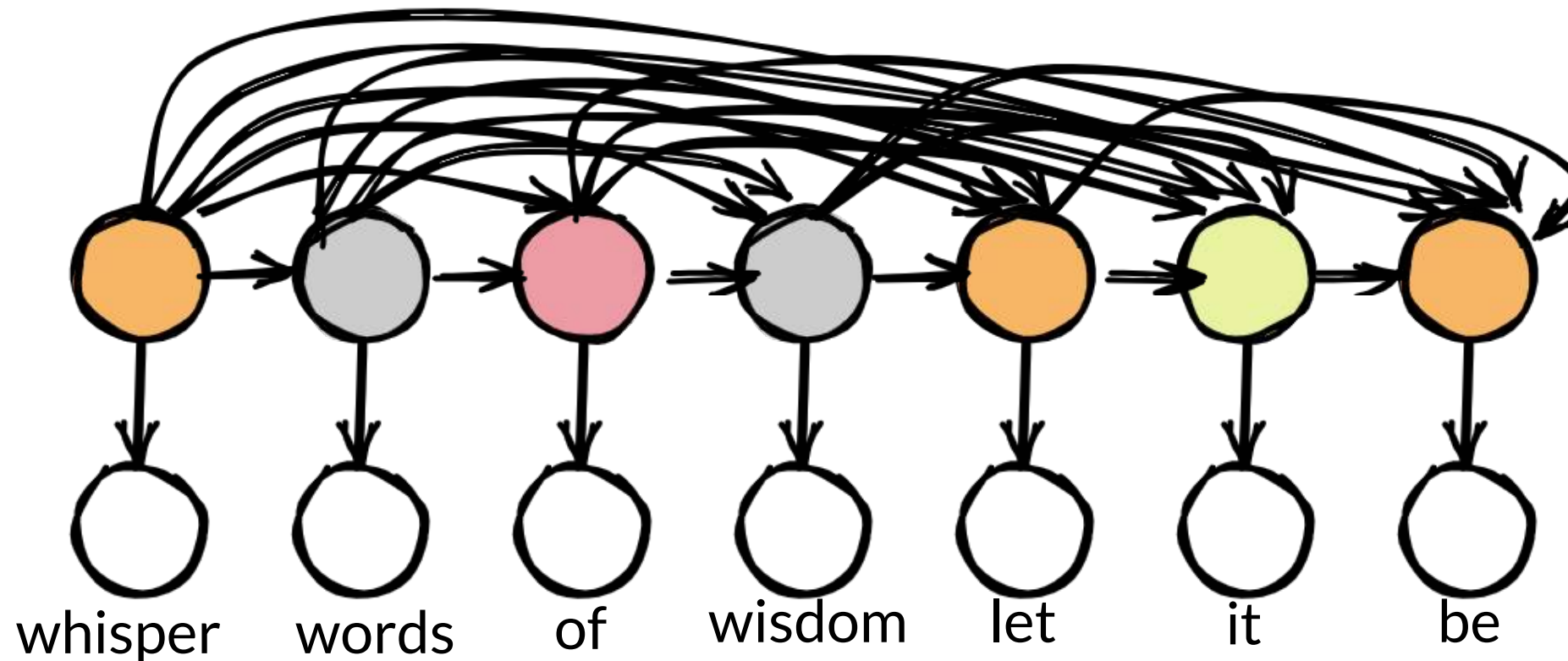
$\times \dots$

$$= (0.7 \times 0.35) \times (0.7 \times 0.4) \times (0.7 \times 0.15) \times \dots$$

Emission model

Better model

The previous probabilistic model is too simple. Context (adjacent words and labels) is essential. We'll add dependencies between labels (not between words)



$$\begin{aligned} P(y_1, x) &= P(x \mid y) \times P(y) \\ P(y) &= P(y_1) \times P(y_2 \mid y_1) \times \\ &\times P(y_3 \mid y_1, y_2) \times \dots \times \\ &\times P(y_N \mid y_1, y_2, \dots, y_{N-1}) = \\ &= P(y_1) \times \prod_{N=2} P(y_i \mid y_1, \dots, y_{i-1}) \end{aligned}$$

thus each y_i depends on all previous $i-1$ states

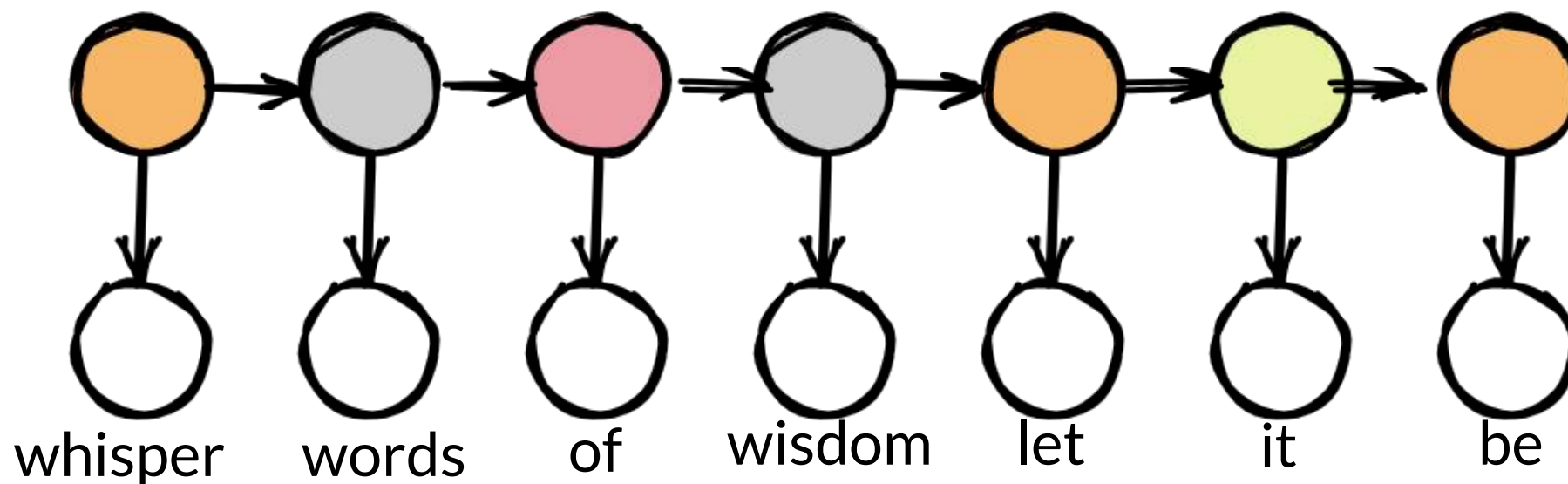
Markov assumption

Hard to believe the y_i element depends on all, including the first one.

Markov assumption allows us to consider y_i being dependent on **only** the last element (y_{i-1})

$$\begin{aligned} P(y, x) &= P(x | y) \times P(y) \\ &= P(y_1) \times P(y_2 | y_1) \times \\ &\quad \times P(y_3 | y_2) \times \dots \times P(y_N | y_{N-1}) = \end{aligned}$$

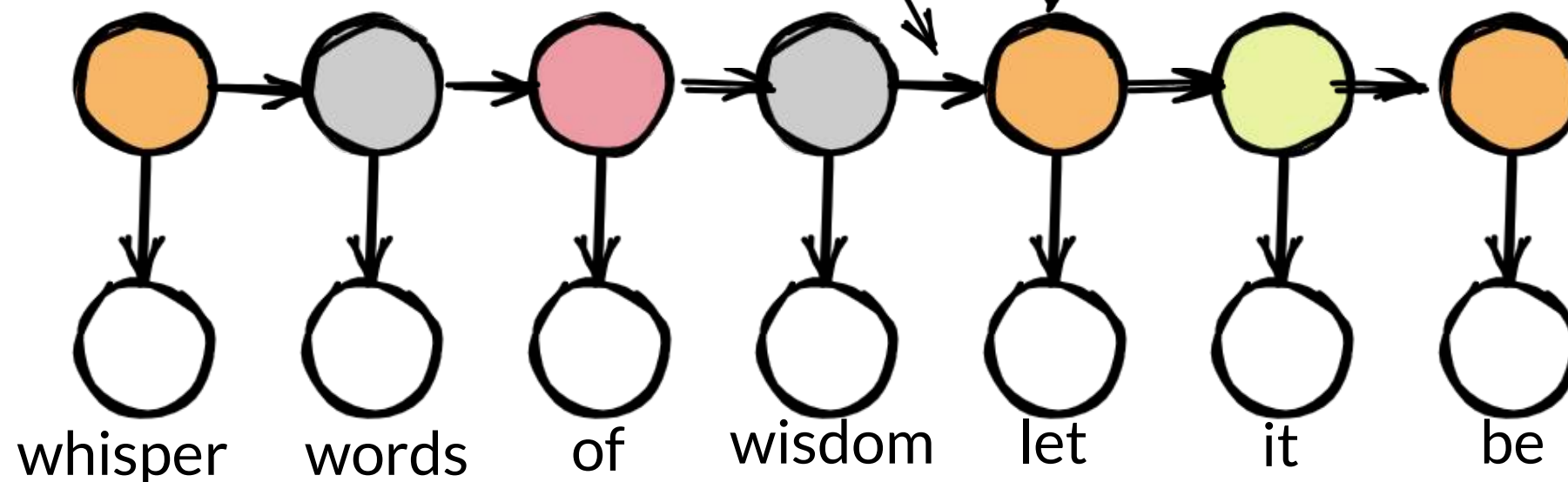
$$= P(y_1) \times \prod_{N=2} P(y_i | y_{i-1})$$



Markov chain

state transition
probability $P(y_i | y_{i-1})$

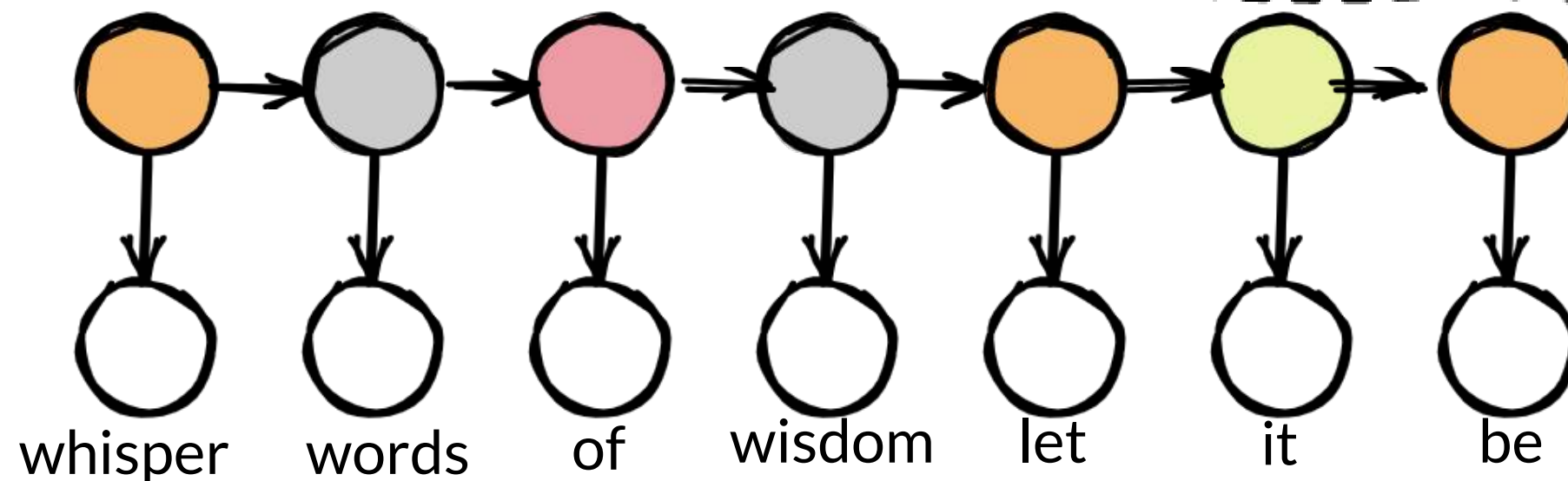
state y_i



Markov model

whisper words of wisdom let it be

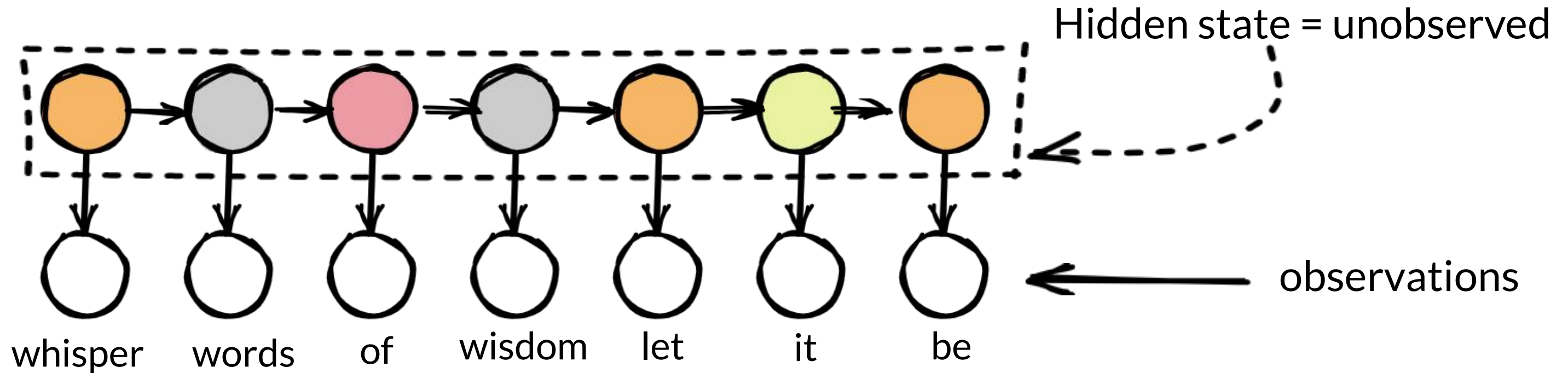
i	whispers	words	of	wisdom	let	it	be	i-1			
verb (0.35)	<u>0.7</u>	0.2	0.1	0.05	<u>0.6</u>	0.0	<u>0.9</u>	v	n	p	p
noun (0.4)	0.3	<u>0.7</u>	0.1	<u>0.85</u>	0.3	0.15	0.0	0.1	0.4	0.2	0.3
prep (0.15)	0.0	0.0	<u>0.7</u>	0.0	0.05	0.1	0.1	0.8	0.1	0.1	0.0
pronoun (0.1)	0.0	0.1	0.1	0.1	0.05	<u>0.65</u>	0.0	0.2	0.3	0.2	0.3
								0.2	0.8	0.0	0.0



$$\begin{aligned}
 P(y, x) &= \\
 &= P(\text{whisper} \mid \text{verb}) \times P(\text{verb}) \times \\
 &\times P(\text{words} \mid \text{noun}) \times P(\text{noun} \mid \text{verb}) \times \\
 &\times P(\text{of} \mid \text{prep}) \times P(\text{prep} \mid \text{noun}) \times \\
 &\times \dots = \\
 &= (0.7 \times 0.35) \times (0.7 \times 0.8) \times \\
 &\times (0.7 \times 0.3) \times \dots
 \end{aligned}$$

State transition matrix.
If constant => homogeneous
Markov model

Hidden Markov Model



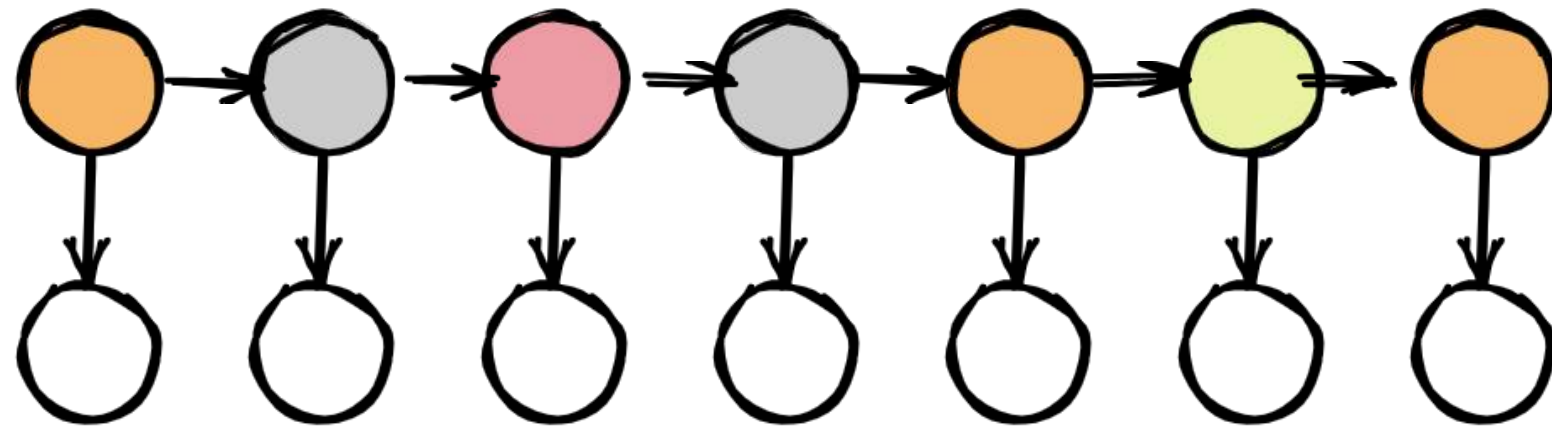
For a hidden Markov Model:

$$P(y, x) = P(x | y) \times P(y)$$

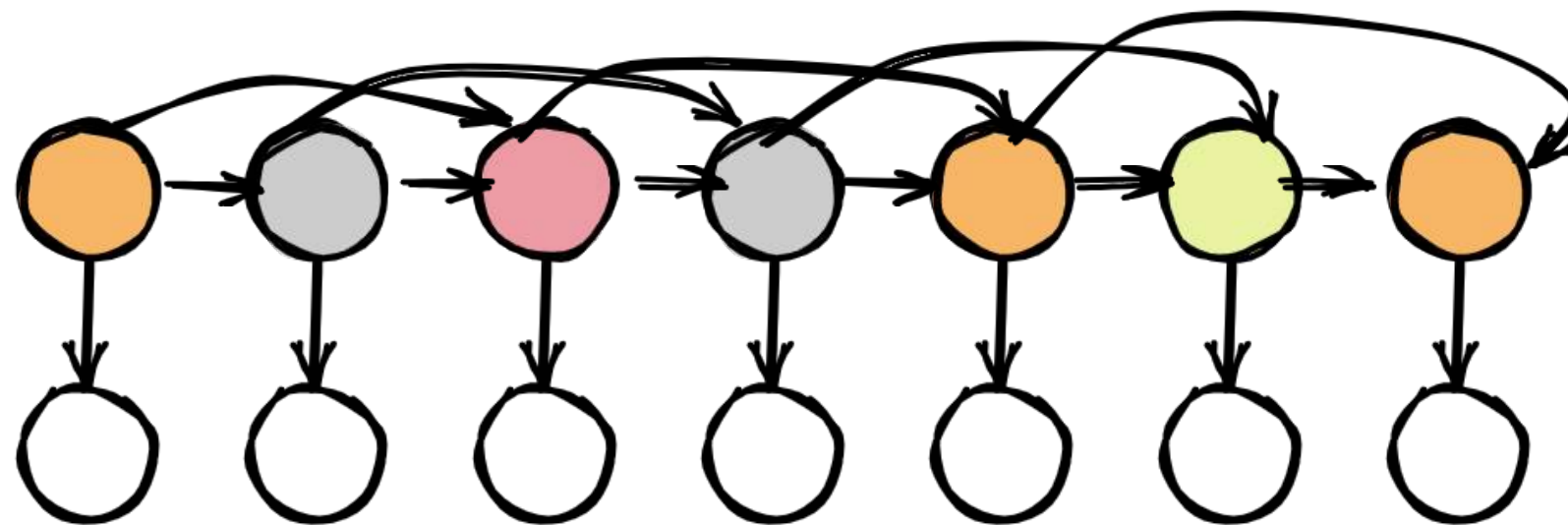
$P(y)$ is the probability of the hidden sequence. For a Markov chain y_i depends only on previous state. $P(y) = i(y_1) \times \prod_{i=2}^N s(y_i, y_{i-1})$

$P(x | y)$ is the emission model of the HMM $\Rightarrow P(y, x) = \text{Markov chain} \times \text{emission model}$

Higher-order HMMs



1st order HMM
bigram HMM



2nd order HMM
trigram HMM

Inference problems for HMMs

Given an observation sequence x and an HMM model λ , how do we efficiently compute $P(x|\lambda)$, i.e., the probability of the observation sequence given the model

Evaluation
forward algorithm

Given an observation sequence x and an HMM model λ , how do we choose a corresponding state sequence y which is optimal in some sense, i.e., best explains the observations

Decoding
(Recognition)
Viterbi algorithm

Given an observation sequence x , how do we adjust (learn) the model parameters λ , to maximise $P(x|\lambda)$

Training
Baum-Welch algorithm